

# MAST30013 – Techniques in Operations Research

Semester 1, 2021

## Tutorial 9

1. Consider the constrained nonlinear program

$$\begin{aligned} \min \quad & \frac{1}{2}x_1^2 + \frac{1}{2}x_2^2 - x_1 + x_2 \\ \text{subject to} \quad & x_1, x_2 \leq 0. \end{aligned}$$

- (a) Write down the  $l_2$ -penalty function  $P_k(\mathbf{x})$  with penalty parameter  $k$ .
- (b) Write down  $\nabla P_k(\mathbf{x})$  and show that the stationary points for  $P_k(\mathbf{x})$  only occur when  $x_1 > 0$  and  $x_2 < 0$ .
- (c) Find all stationary points  $\mathbf{x}^k = (x_1^k, x_2^k)$  for  $P_k(\mathbf{x})$  such that  $x_1^k > 0$  and  $x_2^k < 0$ . Write down the limit  $\mathbf{x}^* = \lim_{k \rightarrow \infty} \mathbf{x}^k$ .
- (d) For each stationary point, write down an estimate  $\boldsymbol{\lambda}^k$  of the optimal Lagrange multiplier vector, and find the limit  $\boldsymbol{\lambda}^* = \lim_{k \rightarrow \infty} \boldsymbol{\lambda}^k$ .

2. Consider the non-linear program

$$\begin{aligned} \min \quad & \frac{1}{4}x_1^4 - \frac{1}{2}x_1^2 + x_2^2 \\ \text{subject to} \quad & x_1 \geq 0 \\ & x_2 \geq 2. \end{aligned}$$

- (a) Write down the  $l_2$ -penalty function  $P_k(\mathbf{x})$  with penalty parameter  $k$ .
- (b) Write down  $\nabla P_k(\mathbf{x})$  and show that the stationary points for  $P_k(\mathbf{x})$  only occur when  $x_1 \geq 0$  and  $x_2 < 2$ .
- (c) Find all stationary points  $\mathbf{x}^k = (x_1^k, x_2^k)$  for  $P_k(\mathbf{x})$  such that  $x_1^k \geq 0$  and  $x_2^k < 2$ . Write down the limit  $\mathbf{x}^* = \lim_{k \rightarrow \infty} \mathbf{x}^k$ .
- (d) For each stationary point, write down an estimate  $\boldsymbol{\lambda}^k$  of the optimal Lagrange multiplier vector, and find the limit  $\boldsymbol{\lambda}^* = \lim_{k \rightarrow \infty} \boldsymbol{\lambda}^k$ .