

Navier-Stokes equations in common coordinate systems

Cartesian Coordinates

$$\begin{aligned}\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} &= -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \frac{\partial^2 u}{\partial x^2} + b_x \\ \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} &= -\frac{1}{\rho} \frac{\partial p}{\partial y} + \nu \frac{\partial^2 v}{\partial y^2} + b_y \\ \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} &= -\frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \frac{\partial^2 w}{\partial z^2} + b_z \\ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} &= 0\end{aligned}$$

Polar Coordinates (suppressing body force terms)

For *cylindrical polar coordinates* σ , φ , z , with z measured along the axis of the cylinder, σ the distance from the axis of the cylinder, and φ the azimuthal angle:

$$\begin{aligned}\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial \sigma} + \frac{v}{\sigma} \frac{\partial u}{\partial \varphi} + w \frac{\partial u}{\partial z} - \frac{v^2}{\sigma} &= -\frac{1}{\rho} \frac{\partial p}{\partial \sigma} + \nu \left(\nabla^2 u - \frac{u}{\sigma^2} - \frac{2}{\sigma^2} \frac{\partial v}{\partial \varphi} \right) \\ \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial \sigma} + \frac{v}{\sigma} \frac{\partial v}{\partial \varphi} + w \frac{\partial v}{\partial z} + \frac{uv}{\sigma} &= -\frac{1}{\rho \sigma} \frac{\partial p}{\partial \varphi} + \nu \left(\nabla^2 v - \frac{v}{\sigma^2} + \frac{2}{\sigma^2} \frac{\partial u}{\partial \varphi} \right) \\ \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial \sigma} + \frac{v}{\sigma} \frac{\partial w}{\partial \varphi} + w \frac{\partial w}{\partial z} &= -\frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \nabla^2 w \\ \frac{1}{\sigma} \frac{\partial}{\partial \sigma} (\sigma u) + \frac{1}{\sigma} \frac{\partial v}{\partial \varphi} + \frac{\partial w}{\partial z} &= 0\end{aligned}$$

where

$$\nabla^2 f = \nabla \cdot \nabla f = \frac{1}{\sigma} \frac{\partial}{\partial \sigma} \left(\sigma \frac{\partial f}{\partial \sigma} \right) + \frac{1}{\sigma^2} \frac{\partial^2 f}{\partial \varphi^2} + \frac{\partial^2 f}{\partial z^2}$$

For *spherical polar coordinates* r, θ, φ , with r the distance from the origin, θ the colatitudinal angle and φ the azimuthal angle:

$$\begin{aligned} \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial r} + \frac{v}{r} \frac{\partial u}{\partial \theta} + \frac{w}{r \sin \theta} \frac{\partial u}{\partial \varphi} - \frac{v^2}{r} - \frac{w^2}{r} = \\ -\frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left(\nabla^2 u - \frac{2u}{\sigma^2} - \frac{2}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (v \sin \theta) - \frac{2}{r^2 \sin \theta} \frac{\partial w}{\partial \varphi} \right) \end{aligned}$$

$$\begin{aligned} \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial r} + \frac{v}{r} \frac{\partial v}{\partial \theta} + \frac{w}{r \sin \theta} \frac{\partial v}{\partial \varphi} + \frac{uv}{r} - \frac{w^2 \cot \theta}{r} = \\ -\frac{1}{\rho r} \frac{\partial p}{\partial \theta} + \nu \left(\nabla^2 v - \frac{v}{\sigma^2 \sin^2 \theta} + \frac{2}{r^2} \frac{\partial u}{\partial \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial w}{\partial \varphi} \right) \end{aligned}$$

$$\begin{aligned} \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial r} + \frac{v}{r} \frac{\partial w}{\partial \theta} + \frac{w}{r \sin \theta} \frac{\partial w}{\partial \varphi} + \frac{uw}{r} + \frac{vw \cot \theta}{r} = \\ -\frac{1}{\rho r \sin \theta} \frac{\partial p}{\partial \varphi} + \nu \left(\nabla^2 w + \frac{2}{r^2 \sin \theta} \frac{\partial u}{\partial \varphi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial v}{\partial \varphi} - \frac{w}{r^2 \sin^2 \theta} \right) \end{aligned}$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} (r^2 u) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta v) + \frac{1}{r \sin \theta} \frac{\partial w}{\partial \varphi} = 0$$

where

$$\nabla^2 f = \nabla \cdot \nabla f = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \varphi^2}$$