

4 (a) small diameter pipe

$$Q = 70 \times 10^{-3} \text{ m}^3/\text{s} \text{ for both}$$

$$V = \frac{Q}{A}$$

$$V_1 = \frac{70 \times 10^{-3} \text{ m}^3/\text{s}}{\frac{\pi \times 0.1^2}{4} \text{ m}^2}$$

$$= 8.91 \text{ m/s}$$

$$Re = \frac{\rho V d}{\mu}$$

$$Re_1 = \frac{1000 \text{ kg/m}^3 \times 8.91 \text{ m/s} \times 0.1 \text{ m}}{1.31 \times 10^{-3} \text{ N s/m}^2}$$

$$= 680153$$

$$\frac{e}{D_1} = \frac{0.0002 \text{ m}}{0.1 \text{ m}}$$

$$= 0.002$$

$$f_1 = 0.006$$

large diameter pipe

$$V_2 = \frac{70 \times 10^{-3} \text{ m}^3/\text{s}}{\pi \times 0.2^2 / 4 \text{ m}^2}$$

$$= 2.23 \text{ m/s}$$

$$Re_2 = \frac{1000 \text{ kg/m}^3 \times 2.23 \text{ m/s} \times 0.2 \text{ m}}{4 \times 1.31 \times 10^{-3} \text{ N s/m}^2}$$

$$= 340179$$

$$\frac{e}{D_2} = \frac{0.0002 \text{ m}}{0.2 \text{ m}}$$

$$= 0.001$$

$$f_2 = 0.005$$

$$(b) \frac{2 \times 0.005 \times (304.5 + 100) \times 2.23^2}{0.2 \times 9.8} + \frac{1}{2} \frac{(0.5) \times 2.23^2}{2 \times 9.8}$$

$$+ \frac{2 \times 0.006 (65) \times 8.91^2}{0.1 \times 9.8} + \frac{1}{2} \frac{(1 + 0.375) \times 8.91^2}{2 \times 9.8} = 79.15 \text{ m.}$$

$$K_{\text{contraction}} = \frac{1}{2} \left( 1 - \left( \frac{0.1}{0.2} \right)^2 \right)$$

$$= 0.375$$

(cd) suction side of the pump.

(cc) MEB [balance between 1 and 2]

$$\frac{\Delta P}{\rho} + \frac{1}{2} \Delta v^2 + g \Delta z + W_s + F = 0$$

$\frac{\Delta P}{\rho}$       free surface velocity  
 $P_{\text{atm}}$

$$9.8 \times 30 + W_s + 79.15 \times 9.8 = 0$$

$$-W_s = 1069.67 \text{ J/kg}$$

$$\text{Power} = -W_s G$$

$$= 1069.67 \text{ J/kg} \times 0.07 \text{ m}^3/\text{s} \times 1000 \text{ kg/m}^3 = 74876.9 \text{ W}$$

2011

$$(a) \Rightarrow Q = VA$$

$$v = Q/A$$

o free surface  $\leftarrow$  between ① and ②

$$h_{sys} = \frac{\Delta p}{\rho g} + \frac{\Delta v^2}{2\alpha g} + \Delta z + h_f \quad \alpha = 1$$

Palm

$$= 49 \text{ m} + \frac{2 \times 0.008 \times \left( \frac{Q}{\pi \times 0.4^2} \right)^2 \times 464.74}{9.8 \times 0.4}$$

$$= 49 + 120.122 Q^2 //$$

$$(b) h_{sys} = h_p \text{ at operating point}$$

$$49 + 120.122 Q^2 = 149 - 20 Q^2$$

$$140.122 Q^2 = 100$$

$$Q^2 = 0.714 \text{ m}^6/\text{s}^2$$

$$Q = 0.845 \text{ m}^3/\text{s} \quad \text{vv above } 0.5 \text{ m}^3/\text{s}$$

$$(c) NPSHA = \frac{P_1 - P_{vap}}{\rho g} + z_1 - h_{fs}$$

$$= \frac{101325 - 2333}{1000 \times 9.8} + 10 - \frac{2 \times 0.008 \times 50 \times \left( \frac{0.845}{\pi \times 0.4^2 / 4} \right)^2}{0.4 \times 9.8}$$

$$= 10.87 \text{ m}$$

as  $NPSHA > NPSHR$ , pump is within the permissible operating range

$$(d) Re = \frac{\rho v d}{\mu} = \frac{1000 \times \frac{0.845}{\pi \times 0.4^2} \times 0.4}{1 \times 10^{-3}} = 2689719$$

$$f_F = 0.008$$

$$\frac{e}{b} = 0.00625$$

$$e = 0.00625 \times 0.4 \text{ m}$$

$$= 0.0025 \text{ m}$$

2011

- (a) Flow when pressure drop along the pipe has resulted in maximum flowrate of gas and further pressure drop will not ↑ G anymore.
- (b)  $P_w$  is the critical downstream pressure when choked flow will begin to occur.

$$(c) \frac{4fL_{min}}{D} = \left(\frac{P_1}{P_w}\right)^2 - \ln\left(\frac{P_1}{P_w}\right)^2 - 1$$

$$\frac{4 \times 0.005 \times L_{min}}{55 \times 10^{-3}} = \left(\frac{6}{4}\right)^2 - \ln\left(\frac{6}{4}\right)^2 - 1$$

$$L_{min} = \frac{55 \times 10^{-3}}{4 \times 0.005} [0.439]$$

$$= 1.21 \text{ m}$$

as  $L_{pipe} > L_{min}$ , flow inside the pipe is not choked.

$$(d) \frac{(400 \times 10^3)^2 - (600 \times 10^3)^2}{2 \times 8.314 \times (273 + 180)} + \left(\frac{6}{A}\right)^2 \ln\left(\frac{600}{400}\right) + \frac{2 \times 0.005 \times 10}{55 \times 10^{-3}} \left(\frac{6}{A}\right)^2 = 0$$

$$\left(\frac{6}{A}\right)^2 [\ln(3/2) + 20/11] = 796173$$

$$\left(\frac{6}{A}\right)^2 = 358048$$

$$\frac{6}{A} = 598 \text{ kg/m}^2 \text{ s}$$

$$G = 598 \times \pi \times \frac{(55 \times 10^{-3})^2}{4}$$

$$= 1.42 \text{ kg/s}$$

$$(e) P_2 = \frac{P_1}{RT/M} = \frac{400 \times 10^3}{8.314 \times \frac{423}{28 \times 10^{-3}}} = 3.18 \text{ kg/m}^3$$

$$G = P_2 V_2 A$$

$$V_2 = \frac{1.42 \text{ kg/s}}{3.18 \text{ kg/m}^3 \times \pi \times \frac{(55 \times 10^{-3})^2}{4}} = 187.8 \text{ m/s}$$

$$\text{sonic } V = \sqrt{\frac{RT}{M}} = \left(8.314 \times \frac{423}{28 \times 10^{-3}}\right)^{1/2} = 354.4 \text{ m/s}$$

$$V_2 = \frac{187.8}{354.4} \times 100\% = 53\% //$$

2011

$$7) Re = \frac{\rho u L}{\mu}$$

$$Fr = \frac{u}{\sqrt{gL}}$$

Fr

$$\frac{u_{model}}{\sqrt{gL_{model}}} = \frac{u_{real}}{\sqrt{gL_{real}}}$$

$$L_{real} = 5 L_{model}$$

$$u_{model} \times \sqrt{5} = u_{real}$$

Re

$$\frac{\rho_m u_m L_m}{\mu_m} = \frac{\rho_R u_R L_R}{\mu_R}$$

$$\frac{\rho_m u_m L_m}{\mu_m} = \frac{900 \times \sqrt{5} u_m \times 5 L_m}{0.005}$$

$$\frac{\rho_m}{\mu_m} = \nu_m = \frac{0.005}{900 \times 5 \sqrt{5}}$$

$$= 5 \times 10^{-7} \text{ Pa s} //$$

2011  
 3 (a)  $v_x \neq v_x(x)$  as flow is steady therefore it does not change along the length of the pipe

$v_x \neq v_x(z)$  as it has no dependence on the coordinate  $z$ ,

$v_x = v_x(y)$  otherwise no flow

(b) equations of motion : conservation of momentum

in x-direction

$$\rho \left( \cancel{\frac{\partial v_x}{\partial t}} + v_x \cancel{\frac{\partial v_x}{\partial x}} + v_y \cancel{\frac{\partial v_x}{\partial y}} + v_z \cancel{\frac{\partial v_x}{\partial z}} \right) = -\frac{\partial p}{\partial x} + \mu \left( \frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right)$$

Steady  
 flow  
 x change  
 with time

$$v_y = v_z = 0$$

$$0 = -\frac{\partial p}{\partial x} + \mu \frac{\partial^2 v_x}{\partial y^2}$$

$$\frac{\partial p}{\partial x} = \mu \frac{\partial^2 v_x}{\partial y^2}$$

(c) 
$$\frac{p_2 - p_1}{L} = \mu \frac{\partial^2 v_x}{\partial y^2}$$

$$\frac{\partial v_x}{\partial y} = \frac{p_2 - p_1}{\mu L} y + C_1$$

$$v_x(y) = \frac{p_2 - p_1}{2\mu L} y^2 + C_1 y + C_2$$

boundary conditions

$$v_x(y=0) = 0 \text{ and } v_x(y=h) = v_{\text{plate}}$$

$$\hookrightarrow C_2 = 0$$

$$v_{\text{plate}} = \frac{p_2 - p_1}{2\mu L} h^2 + C_1 h$$

$$C_1 = \frac{v_{\text{plate}} - \left( \frac{p_2 - p_1}{2\mu L} \right) h^2}{h}$$

$$= \frac{v_{\text{plate}}}{h} - \left( \frac{p_2 - p_1}{2\mu L} \right) h$$

$$v_x(y) = \frac{p_2 - p_1}{2\mu L} y^2 + \left[ \frac{v_{\text{plate}}}{h} - \left( \frac{p_2 - p_1}{2\mu L} \right) h \right] y //$$