Mission message to C&C

This message will be sent via Socket.io to the C&C system to load a mission to the drone and immediately execute it.

Message data:

mission: array [missionPointObject]

```
// description: mission point object is an instance of mavlink COMMAND_LONG object
//              definition can be found via this link and for MAV_CMD at this link
missionPointObject :
{
        id: integer      // mission point index, starts at 1
        alt: integer     // altitude
        commandType: integer        // MAV_CMD type for various types (such as TAKE_OFF,
                                                RETURN_TO_LAUNCH, WAYPOINT etc.)

        lat: float       // latitude
        lng: float       // longitude
        param1: float  // each commandType need different params values as defined at link
        param2: float  // same as param1
        param3: float  // same as param1
        param4: float  // same as param1
}
```

Example for mission message:

```
mission: [
        {
                alt:15
                commandType:22         // TAKEOFF
                id:1
                lat:0
                long:0
                param1:1
                param2:0
                param3:0
                param4:1

        },
        {
                alt:15
```

```
            commandType:16        // WAYPOINT
            id:2
            lat:32.2918300598
            long:34.8711456977
            param1:0
            param2:1
            param3:0
            param4:1

    },
    {
            alt:15
            commandType:16        // WAYPOINT
            id:3
            lat:32.2914778520
            long:34.8711657667
            param1:0
            param2:1
            param3:0
            param4:1

    },
    {
            alt:15
            commandType:20        // RETURN_TO_LAUNCH
            id:4
            lat:0
            long:0
            param1:0
            param2:0
            param3:0
            param4:0

    }
]
```