```
#include <string.h>
#define MAXPAROLA 30
#define MAXRIGA 80
   int treq[MAXPAROLA]; /* vettore di contato i
delle trequenze delle lunghezze delle parole
   char riga[MAXRIGA] ;
Int i, inizio, lunghezza ;
```

## **Synchronization**

## **Task Programming in C++**

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### Introduction

- Multi-threading in C++ has two main limitations
  - 1. The number of software threads may be higher than the number of hardware threads
    - Over-subscription occurs every time the number of software threads ready to start is higher than the number of hardware threads available in the system
    - Over-subscription implies system overhead and some performance penalty
    - One of the possibilities is to use thread pools (which is a generic methodology)



➤ To solve the problem, C++11 introduced taskbased parallel programming

### Introduction

- Multi-threading in C++ has two main limitations
  - 2. Threads (the std::thread library) do not offer any direct way to return a value to the caller
    - In POSIX
      - A simple strategy is return a value with pthread\_exit
      - More general strategies must be user-implemented (through global or local objects)
    - In native C++ only the general strategy is available (you must manipulate objects explicitly)



➤ To solve this problem, C++11 introduced **futures** and **promises** 

- A task is an entity that runs asynchronously producing output data that will become available (and useful) at a later time
  - The operating system associate a thread to a task in an automatic way
  - Balancing tasks is automatic, through workstealing features
    - The process is often implemented using a thread pool
  - Tasks have the possibility of handling return values

### ❖ In C++

Thread-based parallel programming relies on std::thread objects

```
std::thread t(thread_function);
```

Task-based parallel programming relies on std::asynch objects

```
auto fut = std::asynch(thread_function);
```

From now on, we ignore std::

```
#include <future>

future<T> async(policy, function, args...);

<T> is the type of the future

Asynchronous policy function

Parameters for the thread function

"Thread" function
```

- Function async (namespace std)
  - ➤ Is an alternative to std::thread to execute functions in parallel
  - Has and extra parameter, i.e., the policy
  - Returns a future of type T

For now, ignore it

- The user may decide the running policy
  - > There are three different types of policies
    - The deferred policy is motivated exactly by the oversubscription, as the thread is run when the OS wants

Policy	Description
launch::async	Asynchronous launch, i.e., a new thread is generated to run the new function.
launch::deferred	The call to the new function is deferred. The OS may never run it. The new function will be run when we <b>wait for</b> it or <b>get</b> its future.
Default policy launch::async   launch::deferred	The policy to run the new thread is selected by the system accordingly to the availability of concurrency in the system. It is implementation dependent.

### **Examples**

Running async tasks

```
auto f1 = std::async(std::launch::async, my f, 10);
// Thread function my f is run in a new thread
                                               For now, we do not
auto f2 = std::async(
                                              know what a future is
  std::launch::deferred, my f, 20);
// Thread function my f is not run until we get
// its results or wait for it
                Force task f2 to be associated
                 and run it within a thread
f2.wait();
// Invoke deferred function f2 (i.e., run it)
auto f3 = std::async(
   std::launch::async | std::launch::deferred,
   my f, 30);
// The system decides when running my f.
// Possibly, it never runs my f.
```

future\_status::deferred

and the program cycles

# Running policy (part A)

## **Example**

```
auto f = std::async (my_f);
while (f.wait_for(100ms)!=std::future_status::ready) {
    ...
    If it is not ready
    f.wait_for returns
Wait for 100 milliseconds.
Then, check the status
}
```

The problem is that the program can cycle forever, as the policy is deferred

### Running policy (part B)

## **Example**

```
auto f = std::async (my f);
if (f.wait for(0s)==std::future status::deferred)
                     It is deferred: Use wait to
  f.wait();
                       force the execution.
                      It is asynch, it is already
} else {
                           running.
  while (f.wait for (100ms)!=
     std::future status::ready)
     ... do something ...
                          In this case,
                     do something in parallel
```

If it is async or deferred; it may never run

> Wait for 0 seconds, i.e., do not wait, check the status

Check status every 100 milli-seconds

If it is not ready f.wait for returns future\_status::deferred

Here the future f is ready

To wait for 0s or 100ms use std::literals

### **Futures**

- An async object will eventually hold the return value of the thread function in a future
  - > A **future** is an object that can represent a value generated by some provider
  - > Function < future >:: get applied to a valid future
    - Blocks the thread until the object is ready
    - Get the object (returned with "return" by the thread setting it) once the future is ready

<T> is the type of the future

future<T> async(policy, function, args...);

## Get a future at the end of a task

### **Example**

This library allows the passage of values from the thread and the caller

```
#include <future>
bool is prime (int n) {
                                         For example: Check
  if (num <= 1) return false;</pre>
                                           if num is prime
  if (num <= 3) return true;</pre>
  return false;
int main () {
                                                    Run a new task
  std::future<bool> fut = std::async(
     std::launch::async, is prime, 117);
  // ... do other work ...
                                           Wait for function is_prime to
  bool ret = fut.get();
                                          return and make the Boolean
  cout << ret;</pre>
                                                value available
  return 0;
```

## **Example**

Get a future at the end of a task

Where the task is a lambda function

```
#include <future>
#include <iostream>
                                Run a new function
                                     thread
auto fut = std::async
  std::launch::async,
                                       lambda
  [](){
                                      expressions
    std::vector<int> v;
    for (int i=0; i<100; i++)
       v.push back(i);
    return v;
                                Wait for the future to be ready
                                   and get the return value
auto ret = fut.get();
for (auto e: ret)
  std::cout << e << std::endl;</pre>
```

### **Shared futures**

- In C++ there are two types of futures
  - > **Unique** future, i.e., std::future<T>
    - There is only one instance referring to the event
  - > **Shared** future, i.e., std::shared\_future<T>
    - A shared\_future object behaves like a future object, except that it can be copied
    - Multiple instances may refer to the same event
    - All instances will become ready at the same time and can be retrieved
    - May be used to signal multiple threads simultaneously, similarly to std::condition\_variable::notify\_all

### Unique future

## **Example (buggy)**

```
int sum(int a, int b) {
  std::this thread::sleep for(std::chrono::seconds(2));
  return a + b;
int main() {
  std::future<int> fut =
    std::async(std::launch::async, sum, 10, 20);
                                     Wait and then get the future
  int result1 = fut.get();
  std::cout << "Result: " << result1 << endl;</pre>
                                                            Result: 30
  int result2 = fut.get();
  std::cout << "Result: " << result2 << endl;</pre>
  return 0;
                         terminate called after throwing an instance of 'std::future_error'
                               what(): std::future error: No associated state
                                       Aborted (core dumped)
```

### **Example (correct)**

### Shared future

```
int sum(int a, int b) {
  std::this thread::sleep for(std::chrono::seconds(2));
  return a + b;
int main() {
  std::shared future<int> fut =
    std::async(std::launch::async, sum, 10, 20);
                                  Wait and then get the future
  int result1 = fut.get();
  std::cout << "Result: " << result1 << endl;</pre>
                                                      Result: 30
  int result2 = fut.get();
  std::cout << "Result: " << result2 << endl;</pre>
                                                      Result: 30
  return 0;
```

### **Promises**

- At the highest level, you encounter a future when an async end
  - > An async returns the future
  - ➤ The future represents a value that you do not yet have but will have eventually
- In other words, in all previous cases, the future is set when the task ends and issues a "return"
  - The std::future is associated with the return value of the function you launched
  - ➤ The future becomes "ready" when that function completes and returns its value (or throws an exception)

### **Promises**

- At the lowest level, a future comes from an associated promise
  - A promise is an object that can store a value to be retrieved by a future object
    - A promise is an object that you will eventually set
    - When the value is set, it will make it available to its corresponding future
- A promise explicitly decouples the setting of the value (exception) from the end of the task's execution
  - ➤ The thread holding the promise can set the future at any point during its execution

### **Promises**

### To summarize

- ➤ The library std::async creates tasks that automatically return a future with the return statements
- ➤ If we need a result **before** the task ends, we need to use promises and futures
  - The task set the value in the promise and client obain it in the corresponding future
- Promises and futures can be used for asynchronous communication even with manually managed thread objects (not only with tasks)

## **Promises: Overall logic**

# Promise and future "create" a one-shot channel for data

- > A promise
  - Creates the channel
  - Writes data in the channel

```
std::promise<type> pn;
pn.set_value(...);
Promise
```

Name

### > A future

- Connects to the other end of the channel
- Waits and reads the data once it has been written

```
Future
Name
```

```
auto fn = pn.get_future();
fn.get();
```

## **Promises: Implementation**

### The principal steps are

### The main thread

The working thread

- Defines a promise
- Associate a future to the promise

```
std::promise<type> pn;
auto fn = pn.get_future();
```

- Receives the promise
- Execute the function and fulfill the promise

```
pn.set_value(...);
```

Retrieves the result

```
fn.get();
```

One thread (lambda)
Promise (thread) and future (main).

```
Thread function
 int f(int x) { return x + 1;
                  Define the promise
              This is the producer-write end
                                                Define the future from the promise
                                                  This is the consumer-read end
 int main ()
    std::promise<int> promise;
    auto future = promise.get future();
                                         Get the promise in
 Launch f
                                          the capture list
asyncronously
    std::thread thread([&promise] (int x) {
       int result = f(x);
       promise.set value(result);
                                                       Set the value (to be
                                                  communicated) into the promise
               Pass the argument 5
                  to the lambda
                                                               Get the value
    std::cout << future.get() << std::endl;</pre>
```

consumer.join();

Two threads (lambda)
Promise (thread) and future (thread).

### **Example**

Define the promise and the future from the promise

```
auto promise = std::promise<std::string>();
auto future = promise.get_future();

auto producer = std::thread([&] {
    promise.set_value("Hello World");
});

auto consumer = std::thread([&] {
    std::cout << future.get();
});

producer.join();</pre>
Run thread 2
It gets the future
```

One thread (function)
Promise (thread) and future (main).

```
One-way communication:
#include <future>
                                        The thread set the promise
                                           and get the future
using namespace std;
void factorial (const int &N, promise<int>& pr) {
  int res = 1;
  for (int i=N; i> 1; i--)
  res *=i;
  pr.set value(res);
                                  Define the promise and the
                                    future from the promise
int main () {
  promise<int> p;
  future<int> f = p.get future();
  thread t = thread(factorial, 4, ref(p));
  // here we have the data
  int x = f.get();
                                    ref generates an object of
  t.join();
                                     type promise<int> to
                                      hold a reference to p
```

# One task (function) Two way synchronization

```
#include <future>
                                        Two-ways communication:
                                     The caller set the promise and get
using namespace std;
                                             the future
int factorial (std::future<int>& f ) {
  int res = 1;
  int N = f.get();
                                            The future must be passed by
  for ( int i=N; i> 1; i-- )
                                             reference, since it doesn't
  res *=i;
                                              support copy semantics
  return res;
                                      Define the promise and the
                                       future from the promise
int main () {
  std::promise<int> p;
  std::future<int> f = p.get future();
  std::future<int> fu =
    async(std::launch::async,factorial,std::ref(f));
  p.set value(4);
  int x = fu.get();
```

# Two tasks (functions) Two way synchronization

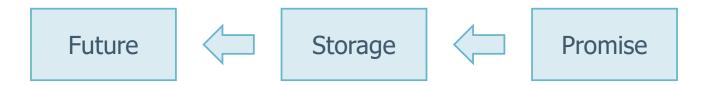
```
void func1 (promise<int> p) {
  int res = 18;
  p.set value(res);
int func2 (future<int> f) {
  int res=f.get();
  return res;
                        The move semantics is
                        achieved by std::move
int main () {
  promise<int> p;
  future<int> f = p.get future();
  future<void> fu1 = async(func1, move(p));
  future<int> fu2 = async(func2, move(f));
  int x = fu2.get();
  return 0;
```

### **Example**

#### Shared future

```
usign namespace std;
int factorial (shared future<int> f) {
  int res = 1;
  int N = f.qet();
  for (int i=N; i> 1; i--) res *=i;
  return res;
int main () {
  promise<int> p;
  future<int> f = p.get future();
  shared future<int> sf = f.share();
  future<int> fu1 = async(std::launch::async, factorial, sf);
  future<int> fu2 = async(std::launch::async, factorial, sf);
  future<int> fu3 = async(std::launch::async, factorial, sf);
  p.set value(4);
  int r1=fu1.get(); int r2=fu2.get(); int r3=fu3.get();
  return 0;
```

- If we destroy the promise without setting a value
  - The object will store an exception
    - Function get will return
  - The object associated to a promise is usually stored in the heap as it cannot be stored
    - In the setter of the promise, as the setter can die
    - In the getter of the future, as we futures can be shares among several getters



- A single promise-future pair is designed to transmit one value, exactly once
  - ➤ It's a single-use communication channel for one result
  - You cannot use one promise to send multiple, independent values sequentially to the same future
  - Calling set\_value more than once on the same promise results in an exception

- How do you "return" multiple values?
  - ➤ If a task needs to produce multiple pieces of data as its single result, you can set the promise with a type that contains multiple values, such as

```
std::promise<std::vector<int>>
std::promise<std::pair<double, std::string>>
```

- How do you "return" multiple results at different times?
  - ➤ If a task must communicate multiple results in different moments, promise and future are not the right tool for that specific pattern
  - You would typically use other concurrency mechanisms like
    - Multiple promise/future pairs (one for each distinct result)
    - A thread-safe queue (protected by a std::mutex, or a custom concurrent queue)
    - Condition variables for more complex signaling

### **Conclusions**

- The task-based approach
  - Makes the OS in charge of the parallelism
  - Makes the return value of a thread/task accessible
  - > Run threads with a smart policy
    - CPU load balancing
      - The C++ library can run the function without spawning a thread
    - Avoid the raising of std::system\_error in case the thread number reaches the system limit
  - Allows futures to catch exceptions thrown by the function
    - With std::thread the program terminates

### **Conclusions**

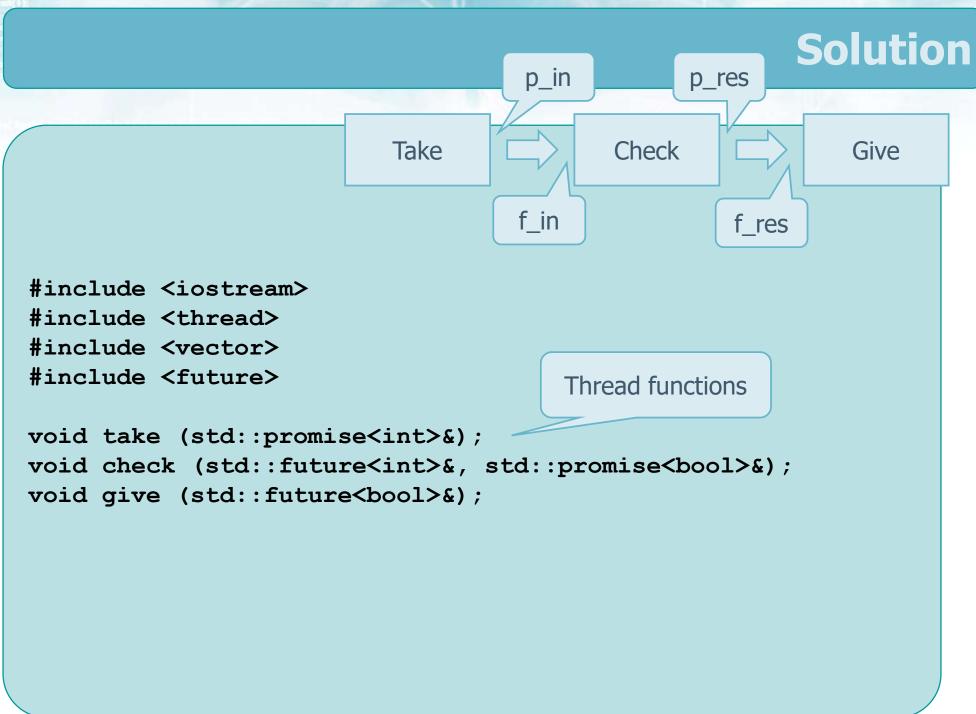
### Thread-based approach

- Is used to execute tasks that do not terminate till the end of the application
  - A thread entry point function is like a second, concurrent main
- > It is a more general concurrency model
  - Can be used for thread-based design patterns
- > Allows us to access to the pthread native handle
  - Makes the programmer in charge of the parallelism
  - Useful for advanced management (priority, affinity, scheduling policies, etc.)

### **Exercise 01**

Exam 5 July 2021

- Write a C++ program with three tasks
  - > Thread **take** reads a number from command line
  - Thread check checks whether the number is prime
  - Thread give displays the answer to standard output
- Thread communication should be made using promises and futures
  - > All functions are acyclic



```
Solution
                                   p_in
                                              p_res
                                         Check
                         Take
                                                          Give
int main(){
                                  f_in
                                                 f_res
 std::promise<int> p in;
  std::future<int> f in = p in.get_future();
 std::promise<bool> p res;
  std::future<bool> f res = p_res.get_future();
 std::thread t1(take, std::ref(p in));
  std::thread t2(check, std::ref(f_in), std::ref(p_res));
  std::thread t3(give, std::ref(f res));
 t1.join();
 t2.join();
 t3.join();
 return 0;
```

### Solution

### Reading thread

```
void take (std::promise<int> &p in) {
  int in;
  std::cout << "Insert a number" << std::endl;</pre>
  std::cin >> inp;
                             Set promise "in"
  p in.set value (in);
             Writing thread
void give (std::future<bool>& f res) {
  bool answer = f res.get();
                                                Get future "ref"
  std::string s0 (" ");
  if(!answer)
    s0=" NOT";
  std::cout << "Number is" << s0 << " prime";</pre>
```

### Solution

### Computation thread

```
void check
  std::future<int> &f_in, std::promise<bool>& p_res)
    int n = f in.get();
                                 Get future "in"
    bool prime=true;
    if (n \le 1) {
      prime = false;
    // Check from 2 to n-1
    for (int j=2; j<n; j++) {
      if (n % j == 0) {
        prime = false;
        break;
                                    Set promise
    p res.set value(prime);
                                      "res"
```