

Problem 1

By definition:

$$a_k = \frac{1}{T} \int_T f(t) e^{2\pi i \frac{k}{T} t} dt$$

> Consider the coefficient for $k=0$

$$a_0 = \frac{1}{T} \int_T f(t) dt \leftarrow \text{It is the actual mean}$$

■ We observe that the term a_0 of the Fourier series correspond to the mean value of the signal.

PROBLEM 2

$$\begin{aligned}
 \mathcal{F}\{e^{-a|x|}\} &= \int_{-\infty}^{+\infty} e^{-a|x|} e^{-2\pi i k x} dx = \\
 &= \int_{-\infty}^0 e^{ax} e^{-2\pi i k x} dx + \int_0^{+\infty} e^{-ax} e^{-2\pi i k x} dx = \\
 &= \int_{-\infty}^0 e^{(-2\pi i k + a)x} dx + \int_0^{+\infty} e^{-(2\pi i k + a)x} dx = \\
 &= -\int_0^{+\infty} e^{(-2\pi i k + a)(-t)} dt + \int_0^{+\infty} e^{-(2\pi i k + a)x} dx = \\
 &= \int_0^{+\infty} e^{-(-2\pi i k + a)t} dt + \int_0^{+\infty} e^{-(2\pi i k + a)x} dx = (\text{see note}) = \\
 &= \frac{1}{-2\pi i k + a} + \frac{1}{2\pi i k + a} = \frac{1}{2\pi i k + a} - \frac{1}{2\pi i k - a}
 \end{aligned}$$

NOTE: $\int_0^{+\infty} e^{-\alpha x} dx = \frac{1}{\alpha}$ if $\text{Re}(\alpha) > 0$
 $(\alpha \in \mathbb{C})$

Problem 3

We can write $f(x)$ as follows:

$$f(x) = 2\Lambda(x/2) - \Lambda(x)$$

Therefore:

$$\begin{aligned} \mathcal{F}\{f(x)\}(k) &= \mathcal{F}\{2\Lambda(x/2)\} - \mathcal{F}\{\Lambda(x)\} = \\ &= 2\mathcal{F}\{\Lambda(x/2)\} - \mathcal{F}\{\Lambda\}(k) = 2 \cdot \frac{1}{(1/2)} \mathcal{F}\{\Lambda\}(k/(1/2)) - \text{sinc}^2(k) = \\ &= 4 \text{sinc}^2(2k) - \text{sinc}^2(k) \end{aligned}$$

↑ Similarity theorem

► $F(k) = 4 \text{sinc}^2(2k) - \text{sinc}^2(k)$

Problem 5

Let consider a simpler case:

$$g(x) = \text{sinc}(x) * \text{sinc}(x)$$

> Using the result of the convolution theorem:

$$\mathcal{F}\{g\} = \mathcal{F}\{\text{sinc} * \text{sinc}\} = \pi \cdot \pi = \pi$$

$$\text{However: } \mathcal{F}^{-1}\{\pi\} = \text{sinc} \Rightarrow g(x) = \text{sinc}(x)$$

→ Consequently, by induction, we have:

$$f(x) = \text{sinc}(x)$$

PROBLEM 6

$$f(t) \rightarrow \boxed{f} \rightarrow F(k)$$

- LINEARITY: YES

$$\mathcal{F}\{af(x) + bg(x)\} = a\mathcal{F}\{f(x)\} + b\mathcal{F}\{g(x)\} \quad \checkmark$$

- SHIFT-INVARIANT: NO

$$\mathcal{F}\{f(x-s)\} = e^{-2\pi i s k} \mathcal{F}\{f\}(k) \neq \mathcal{F}\{f\}(k-s)$$

↳ No shift-invariant

- NO CAUSAL AND HAS MEMORY:

→ Because the Fourier transform depends on both past and future events!

$$\mathcal{F}\{f(t)\} = \int_{-\infty}^{+\infty} f(t) e^{-2\pi i k t} dt$$

It goes over all time points

Problem 7

→ Recall that the output of a Linear Shift-Invariant system can be described as follows:

$$y(t) = x(t) * h(t)$$

where $h(t)$ is the impulse response of the system.

> If we consider the input $x(t) = e^{2\pi i k t}$ then:

$$\begin{aligned} y(t) &= x(t) * h(t) = \int_{-\infty}^{+\infty} h(x) e^{2\pi i k(t-x)} dx = \\ &= e^{2\pi i k t} \int_{-\infty}^{+\infty} h(x) e^{-2\pi i k x} dx = e^{2\pi i k t} H(k) \end{aligned}$$

$$\Rightarrow y(t) = H(k) e^{2\pi i k t}$$

Therefore, we observe that $x(t) = e^{2\pi i k t}$ is an eigenfunction of any LSI system, with eigenvalue $H(k)$.

PROBLEM 8

Let first apply the Fourier transform to the intensity:

Note that:

- WE USE THE DERIVATIVE THEOREM -

$$I(k) = \int_{-\infty}^{+\infty} i(t) e^{-2\pi i k t} dt \Rightarrow \begin{cases} \frac{di}{dt} = 2\pi i k I(k) \\ \frac{d^2 i}{dt^2} = -4\pi^2 k^2 I(k) \end{cases}$$

Then, applying the Fourier transform to the equation:

$$-4\pi^2 k^2 L I(k) + 2\pi i k R I(k) + \frac{1}{C} I(k) = 2\pi i k V(k)$$

Solving now for $I(k)$:

↑
This is also known
as the complex
Ohm's law !!

$$I(k) = \frac{2\pi i k V(k)}{C^{-1} + 2\pi i k R - 4\pi^2 k^2 L}$$

Therefore:

$$i(t) = \int_{-\infty}^{+\infty} \frac{2\pi i k V(k)}{C^{-1} + 2\pi i k R - 4\pi^2 k^2 L} e^{2\pi i k t} dt$$

