

A* Algorithm

I followed the pseudocode from the attachment, and produced the following agenda loop.

My function is able to run all the three algorithms, A*, BFS, and Dijkstra's, depending on the setup.

The algorithms run in the two classes Node and A_star, while the rest of the functions are helping functions such as representing the GUI and getting the input from the files.

I've noticed that since I sort my open-list (agenda here) a different place than many others the results from the BFS search differs in some of the cases.

```
def agenda_loop(self): #The A_star algorithm
    closed = []
    agenda = [self.start] #Open
    while(agenda): #Agenda Loop
        #The different sort methods, depending on algorithm chosen
        if(self.alg=="BFS"):
            pass #dont sort
        elif(self.alg=="Dijkstra"):
            agenda.sort(key=lambda n: n.path_cost)
        else:
            agenda.sort(key=lambda n: n.path_clear)

        node = agenda.pop(0) #X <- pop(OPEN)
        self.table[node.pos() [0]] [node.pos() [1]]="P" #updates the table, visited current node
        closed.append(node) #push(X,closed)

        if node.goal: #if X is a solution return (X,Succeed)
            self.update_path() #fills the path[] with it parents back to start
            print("Shortest Path Found")
            return True, self.table,self.path

        self.generate_all_children(node) #Succ <- generate_all_successors(X) + push(S,kids(X))
        for child in node.children:
            #Did not need "If node S* has previously been created, and if
            #state(S*)==state(S) then S <-S*"
            if child not in agenda and child not in closed:
                self.attach_and_eval(child,node) #attach-and-eval(S,X)
                agenda.append(child) #insert(S,OPEN)
            elif node.path_cost + child.cost < child.path_cost:
                self.attach_and_eval(child,node)
                if child in closed:
                    self.propagate_path_improvements(child)
        print("No Path Found") #if it breaks without retriving, Loop Failed
        return False,self.table,self.path
```

My program doesn't take in any files, but rather reads them from the folders. Due to this it won't run if the boards aren't structured in the directory in the following way: boards/boards/"filename".txt.

To run a file outside this structure described above, simply edit the "name" to the file path and set shortcut to false.

```
def main():
    #make sure to have the following folders:
    #outputs/BFS , outputs/A_star, outputs/Dijkstra
    names = files()
    name = names[1][3]
    shortcut = True
    #for specific file: name = "boards/boards/1-1.txt" while setting shortcut to False

    algorithm = "A_star" # "A_star", "BFS", "Dijkstra"
    t, explored_t, path_found, path = execute_board(name, alg=algorithm, shortcut=shortcut)
    create_gui(algorithm, t, explored_t, path, name, save=True, show=True)

    #To execute all files, show disabled for these
    #execute_all_files(names, "A_star")
    #execute_all_files(names, "Dijkstra")
    #execute_all_files(names, "BFS")
```

The execute_all_files execute all files in the boards/boards/ folder with the set algorithm, and saves them to a predefined folder. Hence the folder outputs/A_star/, "outputs/Dijkstra" and "outputs/BFS" must exist. See the folder structure of my zipped file for clarification.

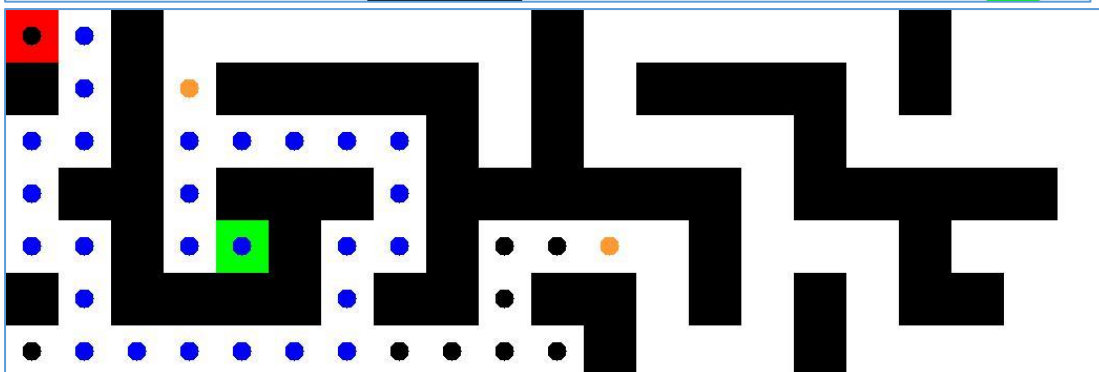
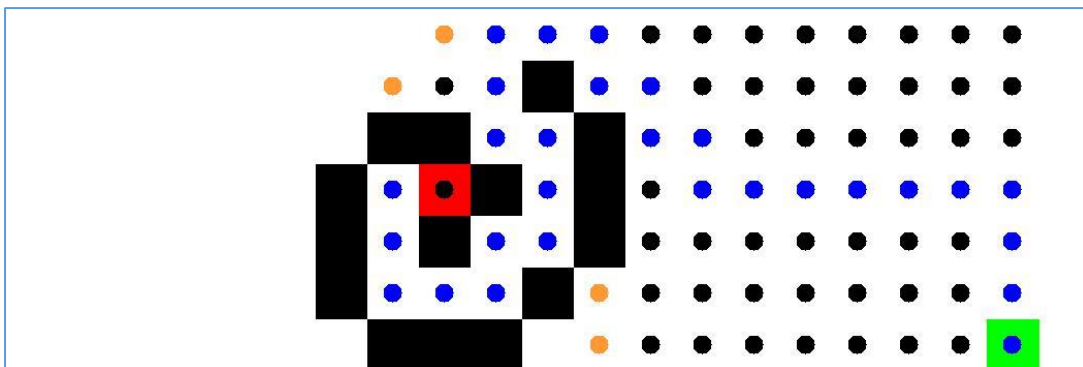
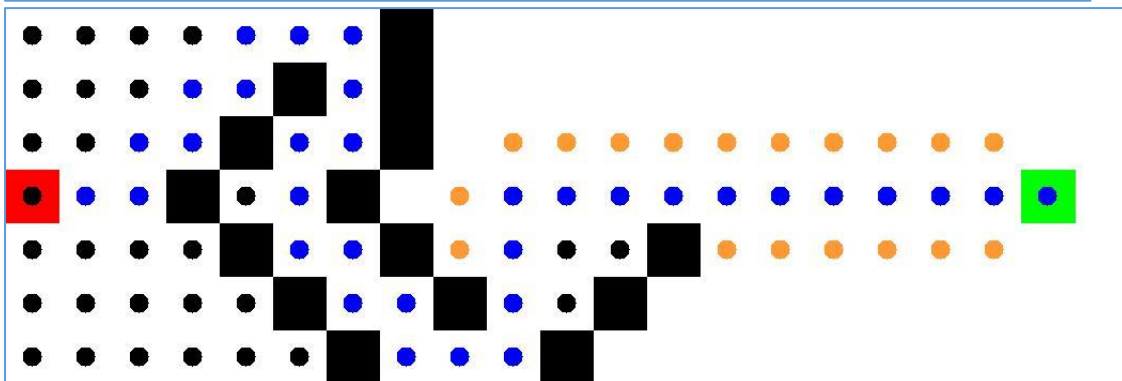
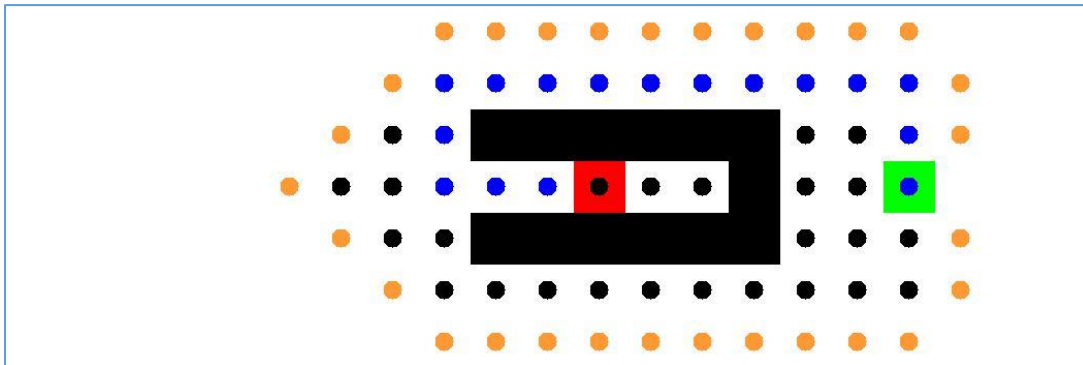
Deliverables

Paths from deliverable 1, 2 and 3. For full output look in the "outputs/A_star/" folder of the zip file.

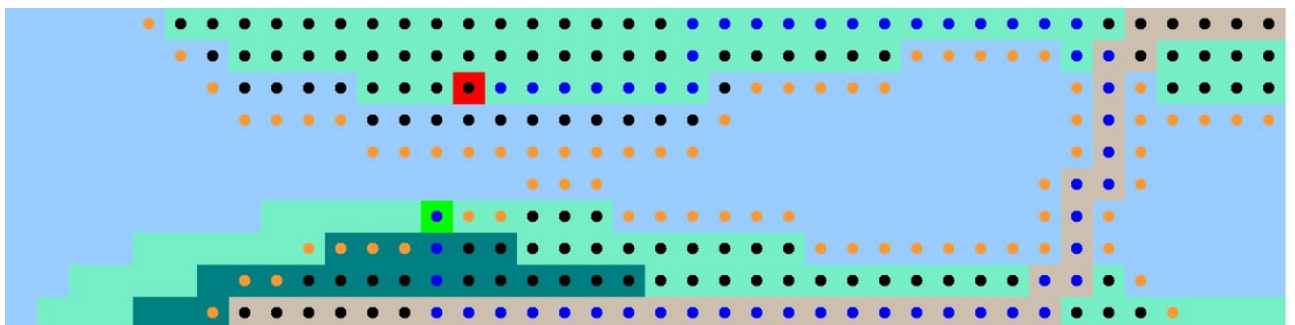
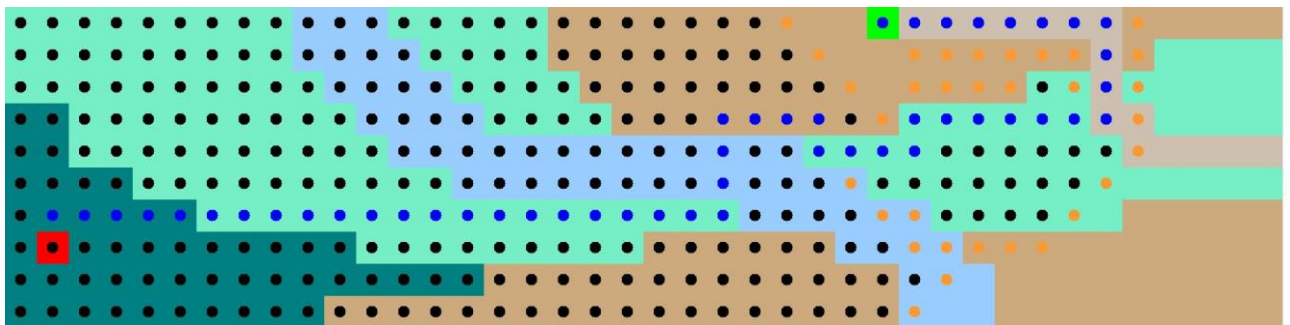
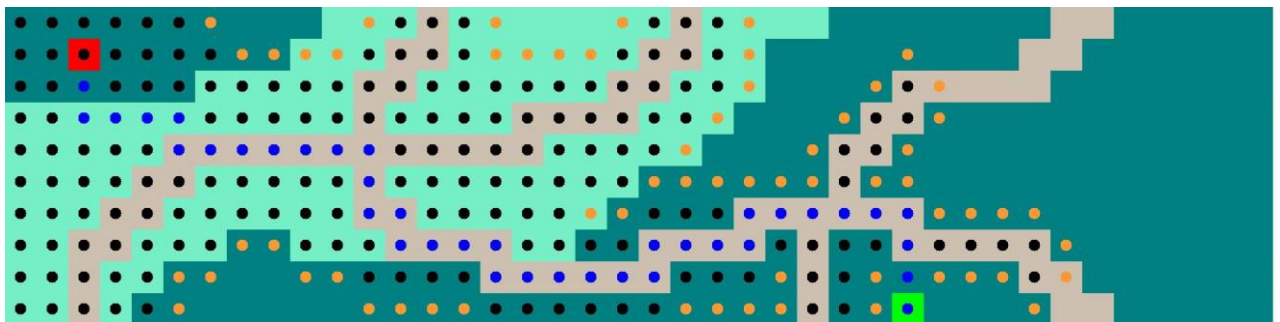
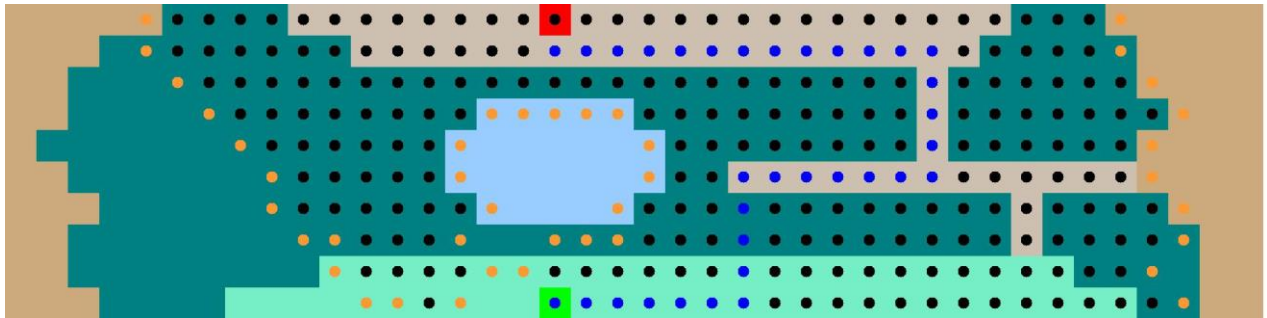
For the boards with walls the three algorithms are almost identical, but sometimes chooses to differ in the open fields.

In the weighted boards on the other hand, Dijkstra and A* always finds the similar routes. BFS only cares about the shortest path, hence takes shortcuts through costly fields and won't find the most optimal paths.

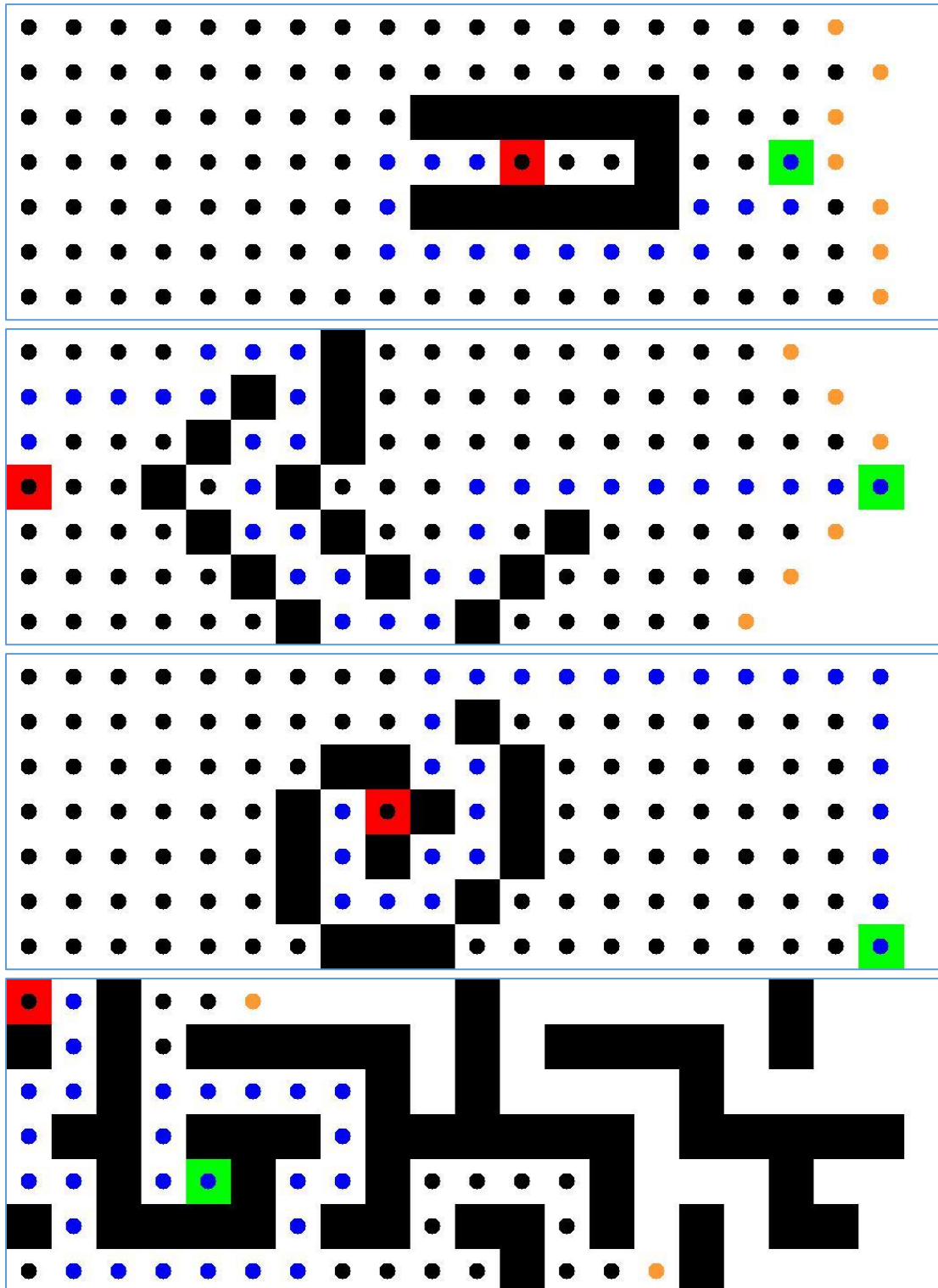
A* paths



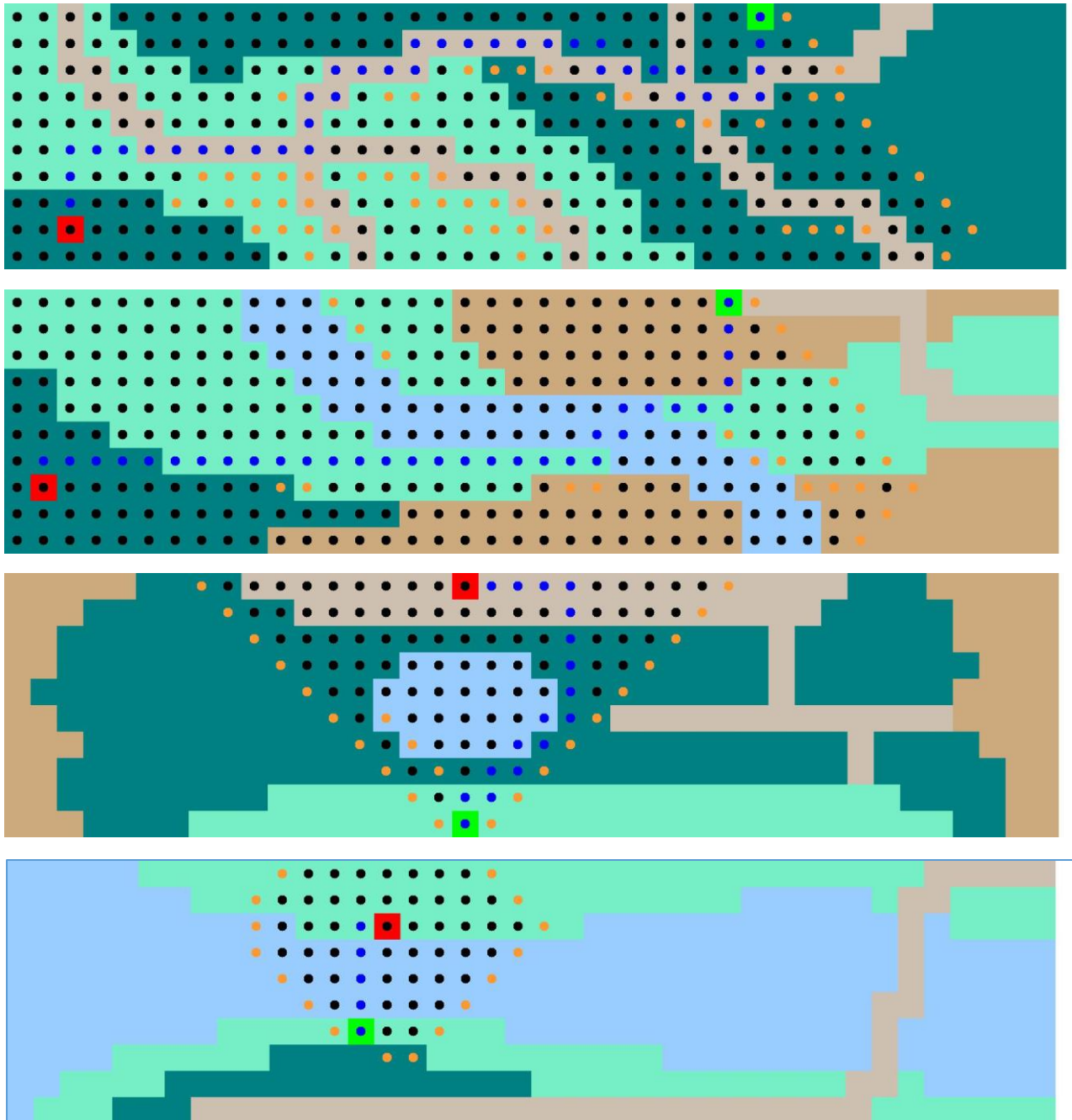
A* Paths



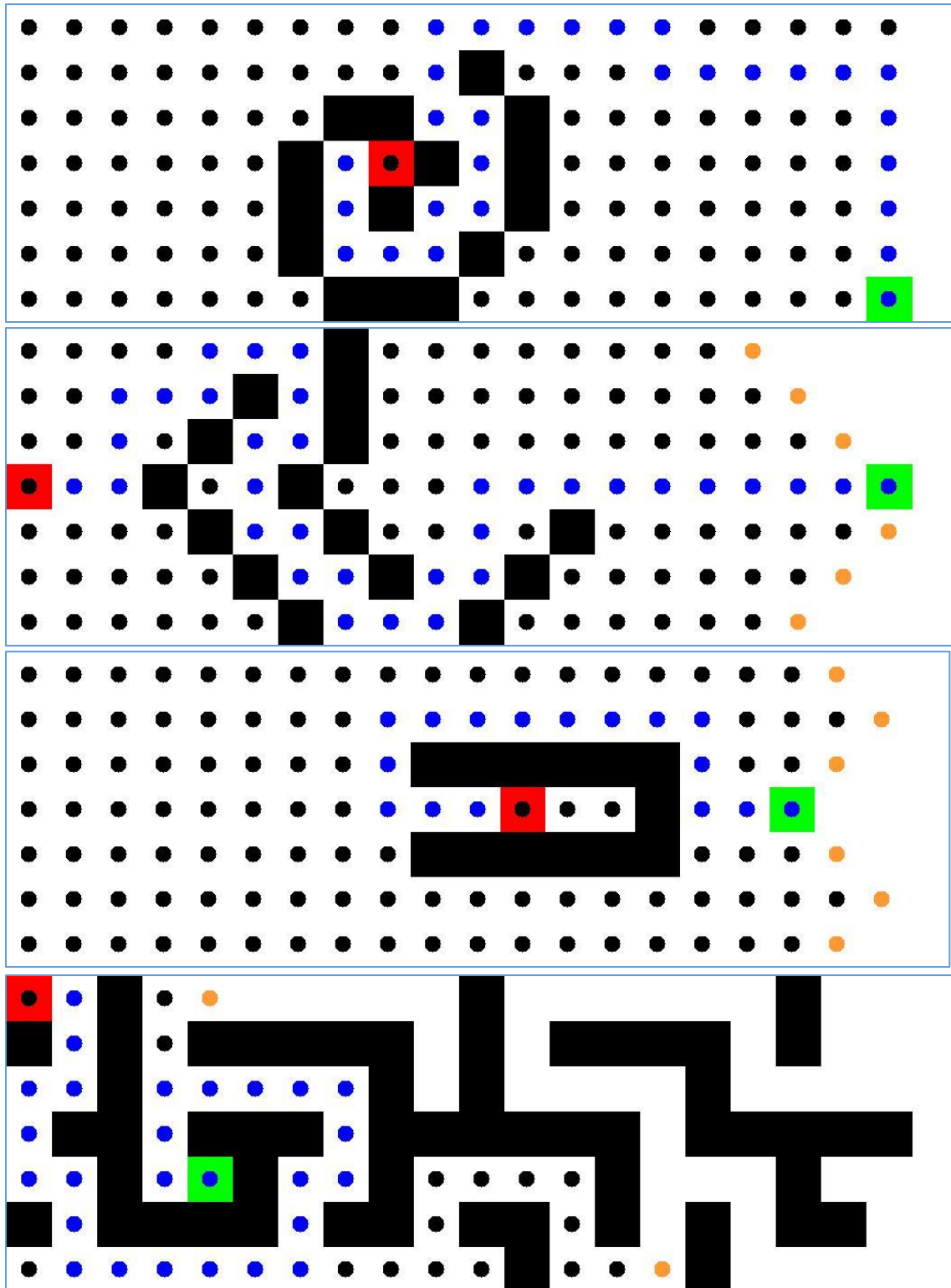
BFS's Paths



BFS's Paths



Dijkstra's Paths:



Dijkstra's Paths

