

Mechanical System Diagram in LaTeX Tikz

CBCO

March 23, 2024

Given the mechanical system free body diagrams as shown in Figure 1, (a) Draw the free body diagram and write the equation for Figure 1 (a) and (b) Draw the free body diagram and write the equation for Figure 1 (b)

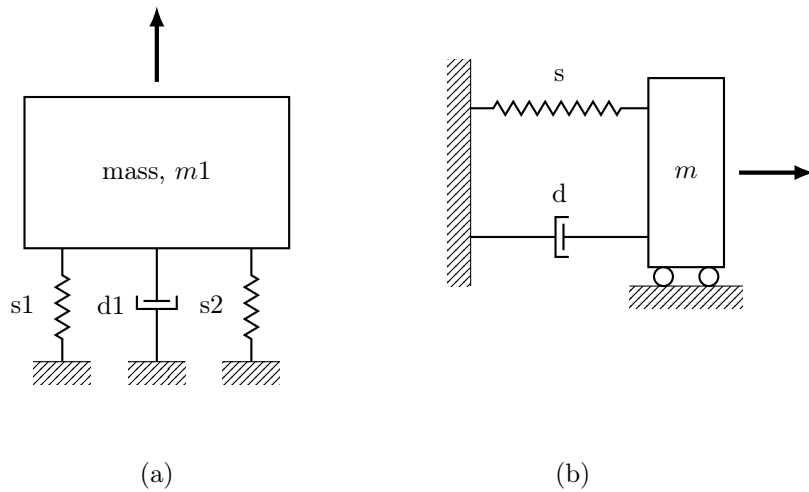


Figure 1: Mechanical System Diagram

The mechanical system in Figure 1 (a) is converted into free body diagram as shown in Figure 2.

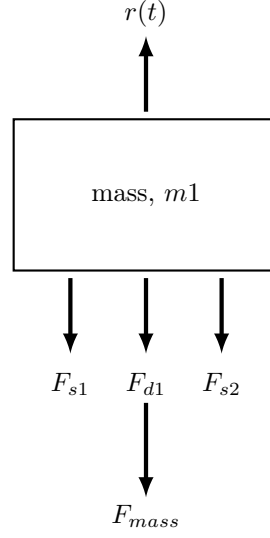


Figure 2: Mechanical System Free Body Diagram of Figure 1 (a)

Out of the free diagram in Figure 2, the system equation is generated as follows.

$$(1) \quad F_{d1} + F_{mass} + F_{s1} + F_{s2} = r(t)$$

where

$$(2) \quad F_{mass} = m_1 \frac{d^2}{dt^2} y(t)$$

$$(3) \quad F_{s1} = K_1 y(t)$$

$$(4) \quad F_{s2} = K_2 y(t)$$

$$(5) \quad F_{d1} = b_1 \frac{d}{dt} y(t)$$

Substituting (2), (3), (4), and (5),

$$(6) \quad K_1 y(t) + K_2 y(t) + b_1 \frac{d}{dt} y(t) + m_1 \frac{d^2}{dt^2} y(t) = r(t)$$

The equation (6) could be arranged for control system block diagram.

$$(7) \quad -b_1 \frac{d}{dt} y(t) - (K_1 + K_2) y(t) + r(t) = m_1 \frac{d^2}{dt^2} y(t)$$

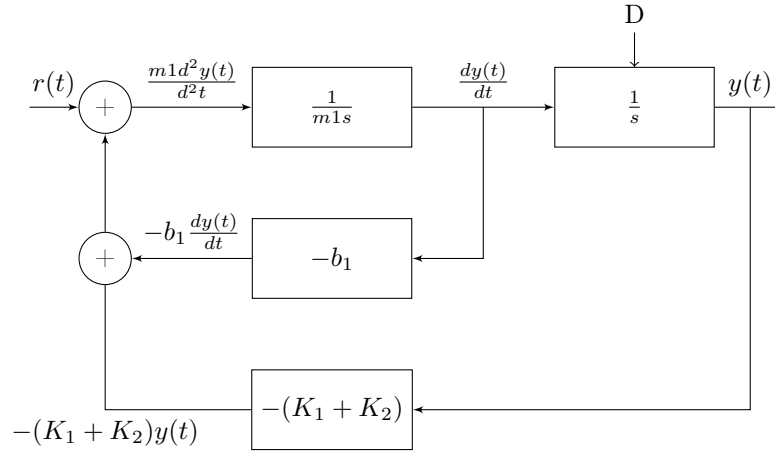


Figure 3: Control System Block Diagram

Exercise

Use latex for all your drawing. See latex codes above for your referenc.

1. Draw the free body diagram of mechanical system shown in Figure 1 (b).
2. From your free body diagram, derive the equation of the mechanical system.
3. Rearrange your equation for control system block diagram. Generate the control system block diagram.

References

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