

# Homogeneous Transformation Matrix

Saturday, 9 November 2024 7:48 am

$${}^0_3R = {}^0_1R {}^1_2R {}^2_3R$$

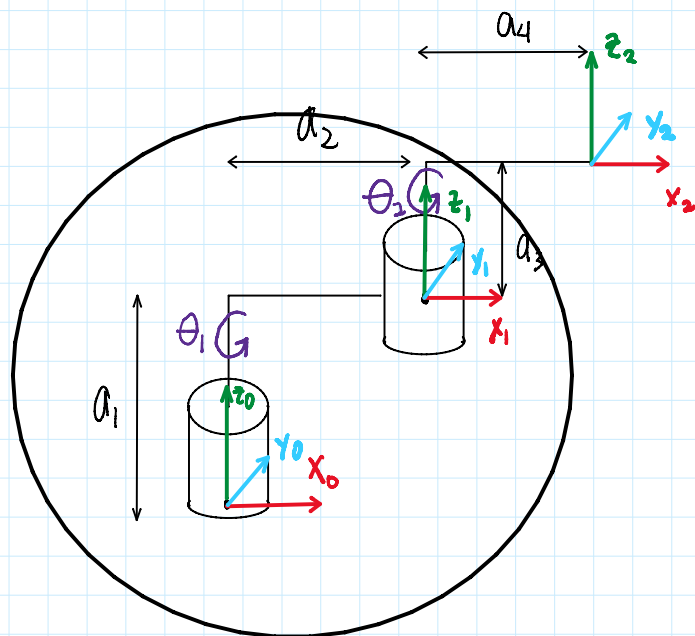
$${}^0_3P \neq {}^0_1P {}^1_2P {}^2_3P$$

$${}^0_3P \neq {}^0_1P + {}^1_2P + {}^2_3P$$

Denoted as

$${}^{n-1}_nH = {}^{n-1}_nT$$

$${}^{n-1}_nH = \left[ \begin{array}{c|c} [3 \times 3] & [3 \times 1] \\ \hline {}^B_E R & {}^B_E P \\ \hline 0 & 0 & 0 & 1 \end{array} \right]$$



$${}^0_1R = \begin{bmatrix} \cos \theta_1 & -\sin \theta_1 & 0 \\ \sin \theta_1 & \cos \theta_1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$${}^0_1P = \begin{bmatrix} a_2 \cos \theta_1 \\ a_2 \sin \theta_1 \\ a_1 \end{bmatrix}$$

$${}^0_1H = \begin{bmatrix} \cos \theta_1 & -\sin \theta_1 & 0 & a_2 \cos \theta_1 \\ \sin \theta_1 & \cos \theta_1 & 0 & a_2 \sin \theta_1 \\ 0 & 0 & 1 & a_1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$