



Machine Learning

Linear regression
with one variable

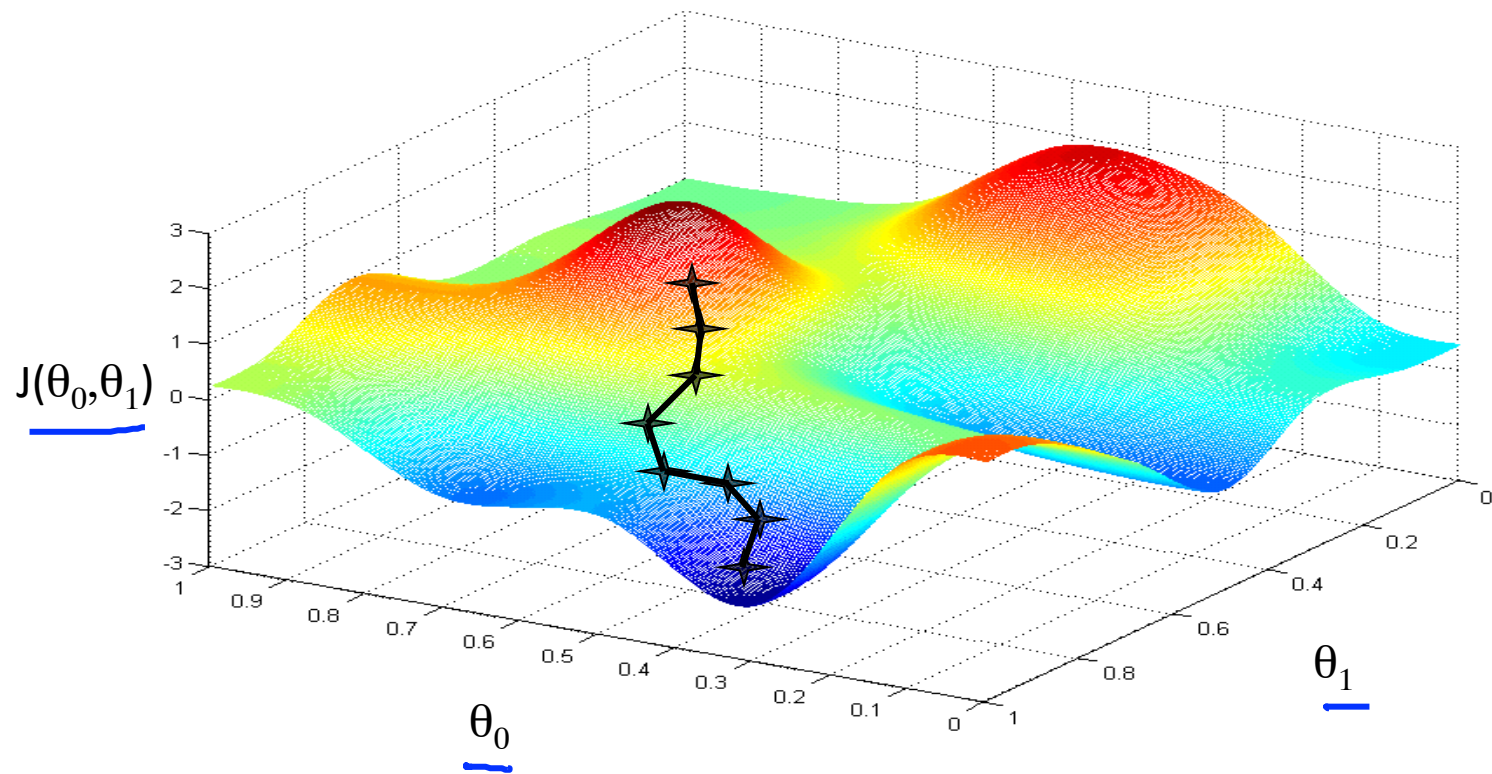
Gradient
descent

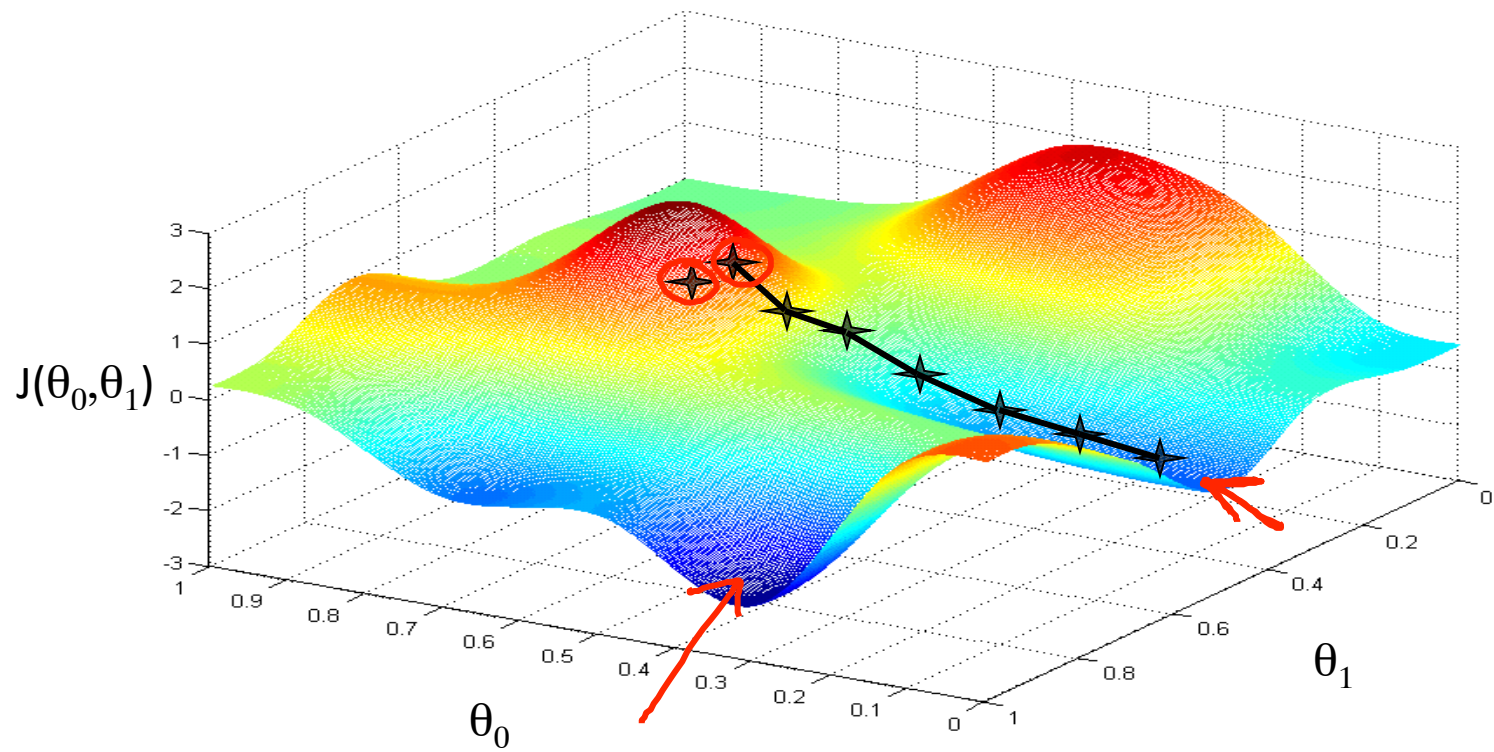
Have some function $J(\theta_0, \theta_1)$ $J(\theta_0, \theta_1, \theta_2, \dots, \theta_n)$

Want $\min_{\theta_0, \theta_1} J(\theta_0, \theta_1)$ $\min_{\theta_0, \dots, \theta_n} J(\theta_0, \dots, \theta_n)$

Outline:

- Start with some θ_0, θ_1 (say $\theta_0 = 0, \theta_1 = 0$)
- Keep changing θ_0, θ_1 to reduce $J(\theta_0, \theta_1)$
until we hopefully end up at a minimum





Gradient descent algorithm

θ_0, θ_1

repeat until convergence {

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$$

learning rate

(for $j = 0$ and $j = 1$)

Simultaneously update
 θ_0 and θ_1

Assignment

$$a := b$$

$$a := a + 1$$

Truth assertion

$$a = b$$

$$a = a + 1 \times$$

Correct: Simultaneous update

$$\rightarrow \text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$

$$\rightarrow \text{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$

$$\rightarrow \theta_0 := \text{temp0}$$

$$\rightarrow \theta_1 := \text{temp1}$$

Incorrect:

$$\rightarrow \text{temp0} := \theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$

$$\rightarrow \theta_0 := \text{temp0}$$

$$\rightarrow \text{temp1} := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$

$$\rightarrow \theta_1 := \text{temp1}$$



Machine Learning

Linear regression
with one variable

Gradient descent
intuition

Gradient descent algorithm

repeat until convergence {

→ $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$

}

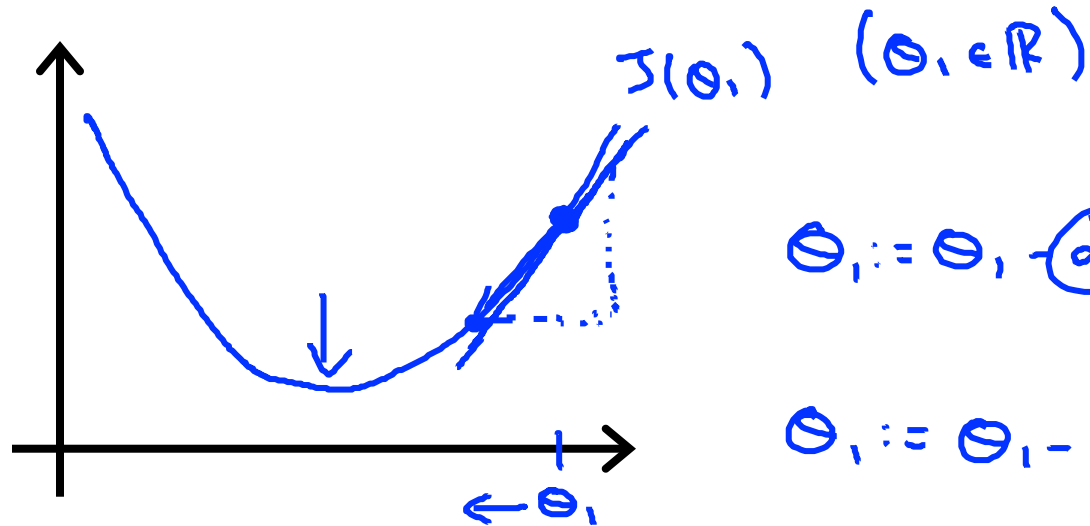
learning
rate

derivative

(simultaneously update
 $j = 0$ and $j = 1$)

$$\min_{\theta_1} J(\theta_1)$$

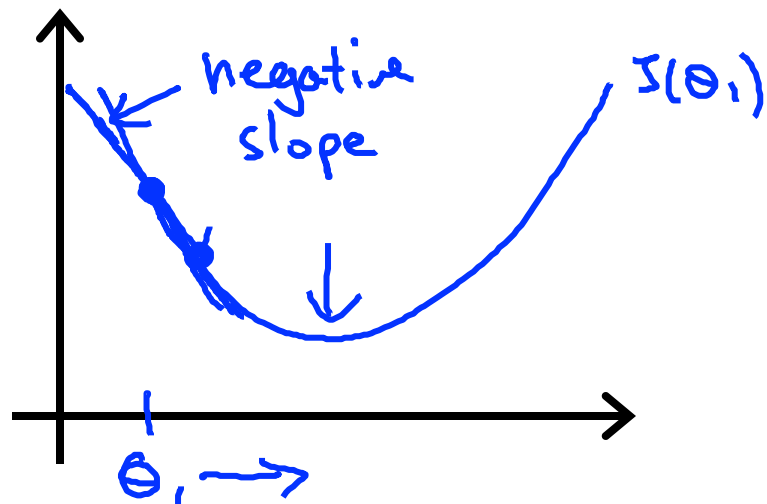
$$\theta_1 \in \mathbb{R}.$$



$$\theta_1 := \theta_1 - \alpha \left(\frac{\partial}{\partial \theta_1} J(\theta_1) \right) \geq 0$$

$\frac{\partial}{\partial \theta_1} J(\theta_1)$

$$\theta_1 := \theta_1 - \alpha \cdot (\text{positive number})$$



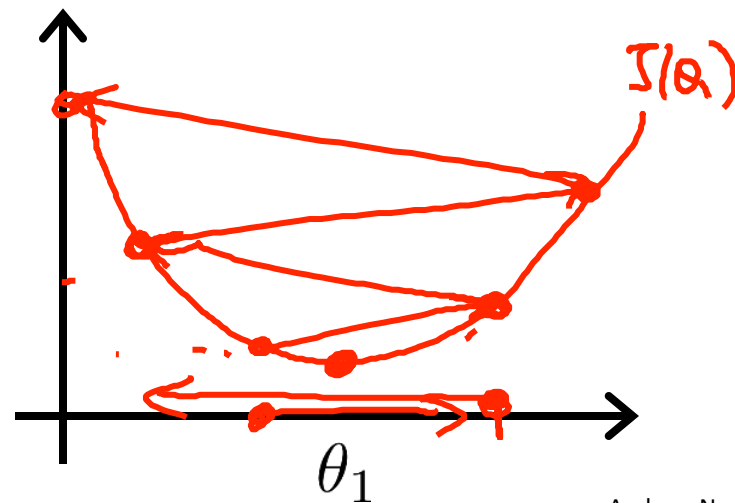
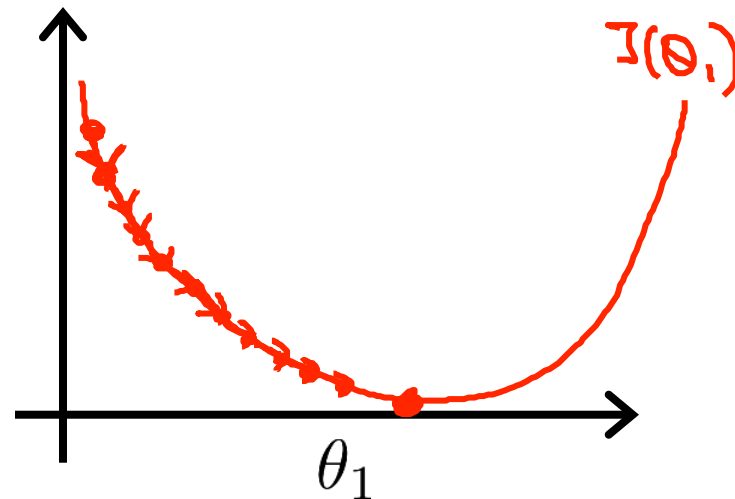
$$\frac{\partial}{\partial \theta_1} J(\theta_1) \leq 0$$

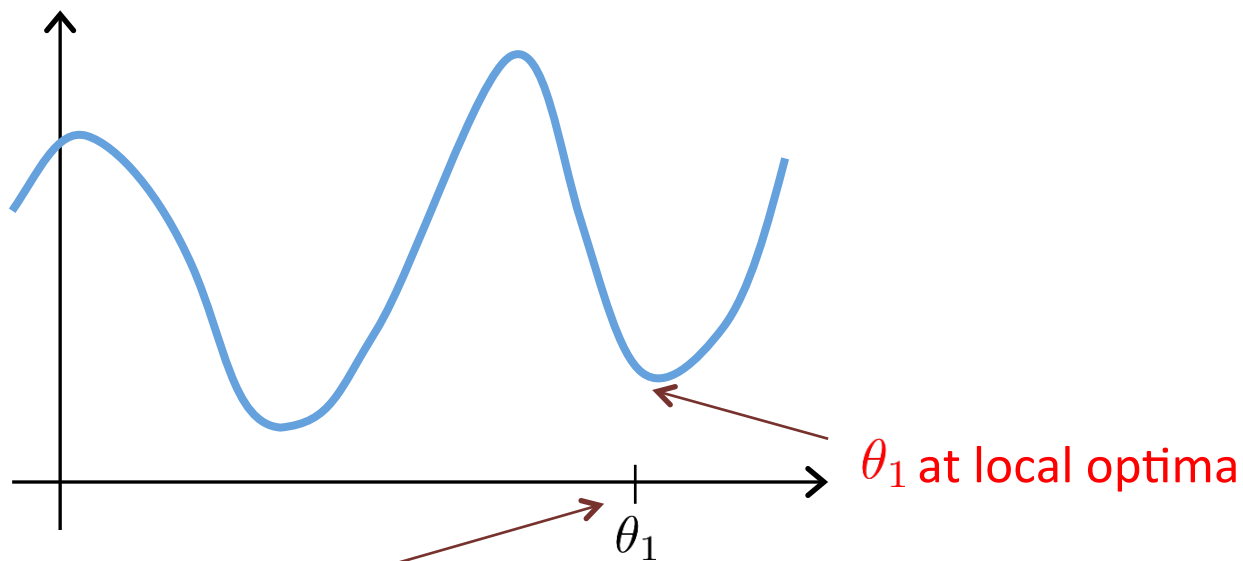
$$\theta_1 := \theta_1 - \alpha \cdot (\text{negative number})$$

$$\theta_1 := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_1)$$

If α is too small, gradient descent can be slow.

If α is too large, gradient descent can overshoot the minimum. It may fail to converge, or even diverge.





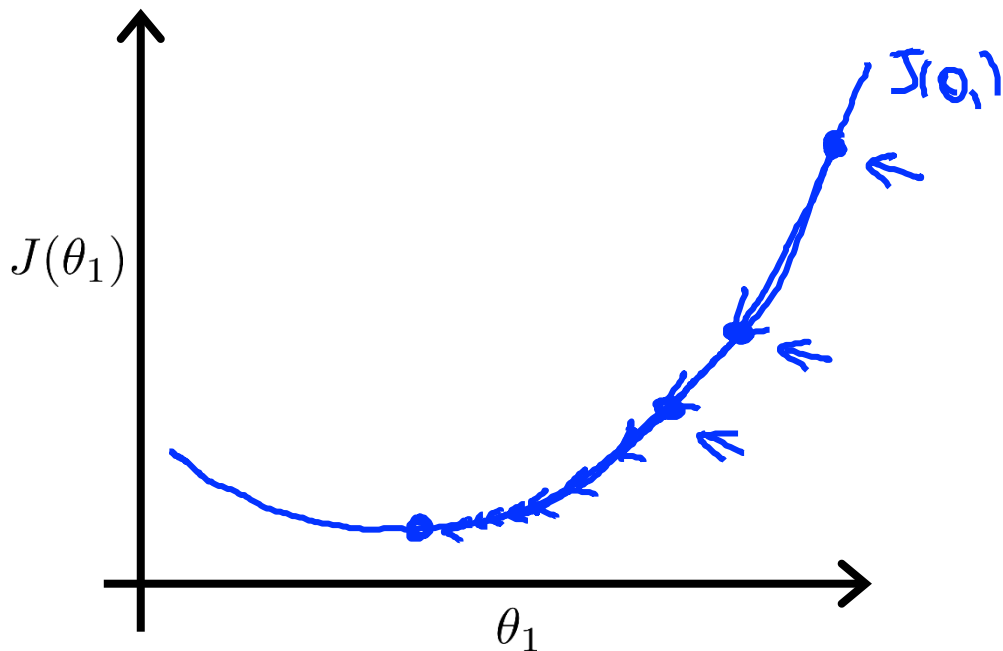
Current value of θ_1

$$\theta_1 := \theta_1 - \alpha \frac{d}{d\theta_1} J(\theta_1)$$

Gradient descent can converge to a local minimum, even with the learning rate α fixed.

$$\theta_1 := \theta_1 - \alpha \frac{d}{d\theta_1} J(\theta_1)$$

As we approach a local minimum, gradient descent will automatically take smaller steps. So, no need to decrease α over time.





Machine Learning

Linear regression with one variable

Gradient descent for linear regression

Gradient descent algorithm

repeat until convergence {
 $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$
 (for $j = 1$ and $j = 0$)
}

Linear Regression Model

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

$$\frac{\partial}{\partial \theta_j} \underline{J(\theta_0, \theta_1)} = \frac{2}{2\theta_j} \frac{1}{2m} \sum_{i=1}^m \underline{(h_0(x^{(i)}) - y^{(i)})^2}$$

$$= \frac{2}{2\theta_j} \frac{1}{2m} \sum_{i=1}^m \underline{(\theta_0 + \theta_1 x^{(i)} - y^{(i)})^2}$$

$$j = 0 : \underline{\frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)} = \frac{1}{m} \sum_{i=1}^m (h_0(x^{(i)}) - y^{(i)})$$

$$j = 1 : \underline{\frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)} = \frac{1}{m} \sum_{i=1}^m (h_0(x^{(i)}) - y^{(i)}) \cdot x^{(i)}$$

Gradient descent algorithm

repeat until convergence {

$$\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})$$

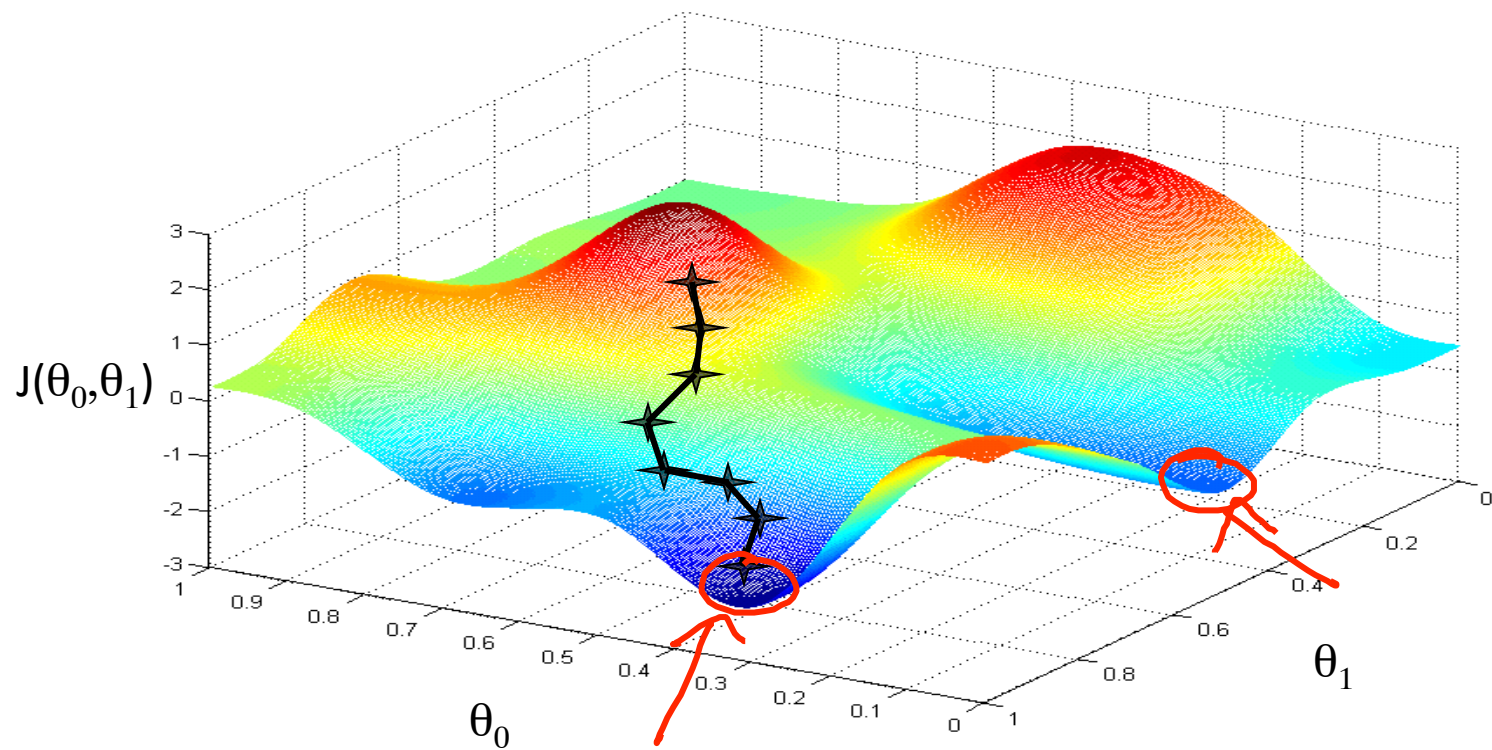
$$\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) \cdot x^{(i)}$$

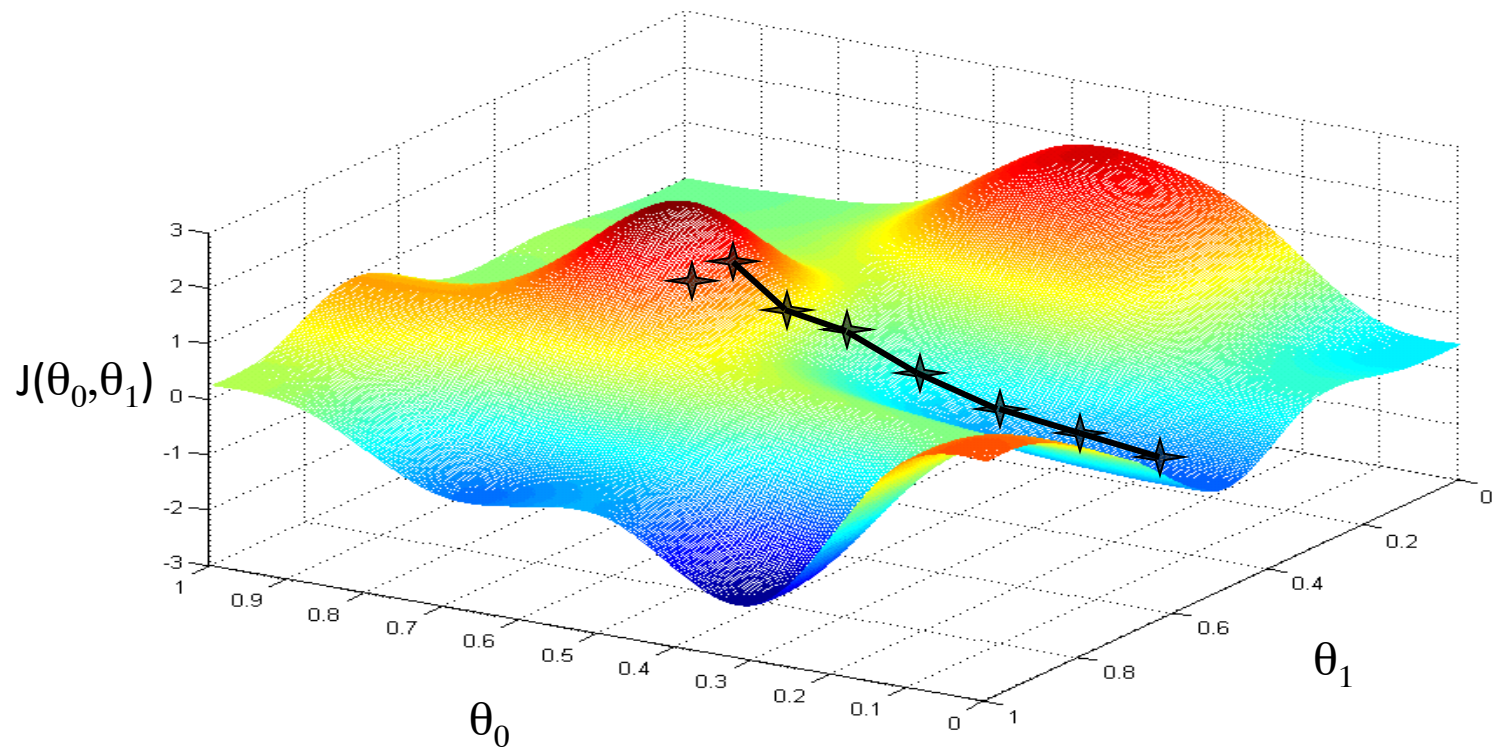
}

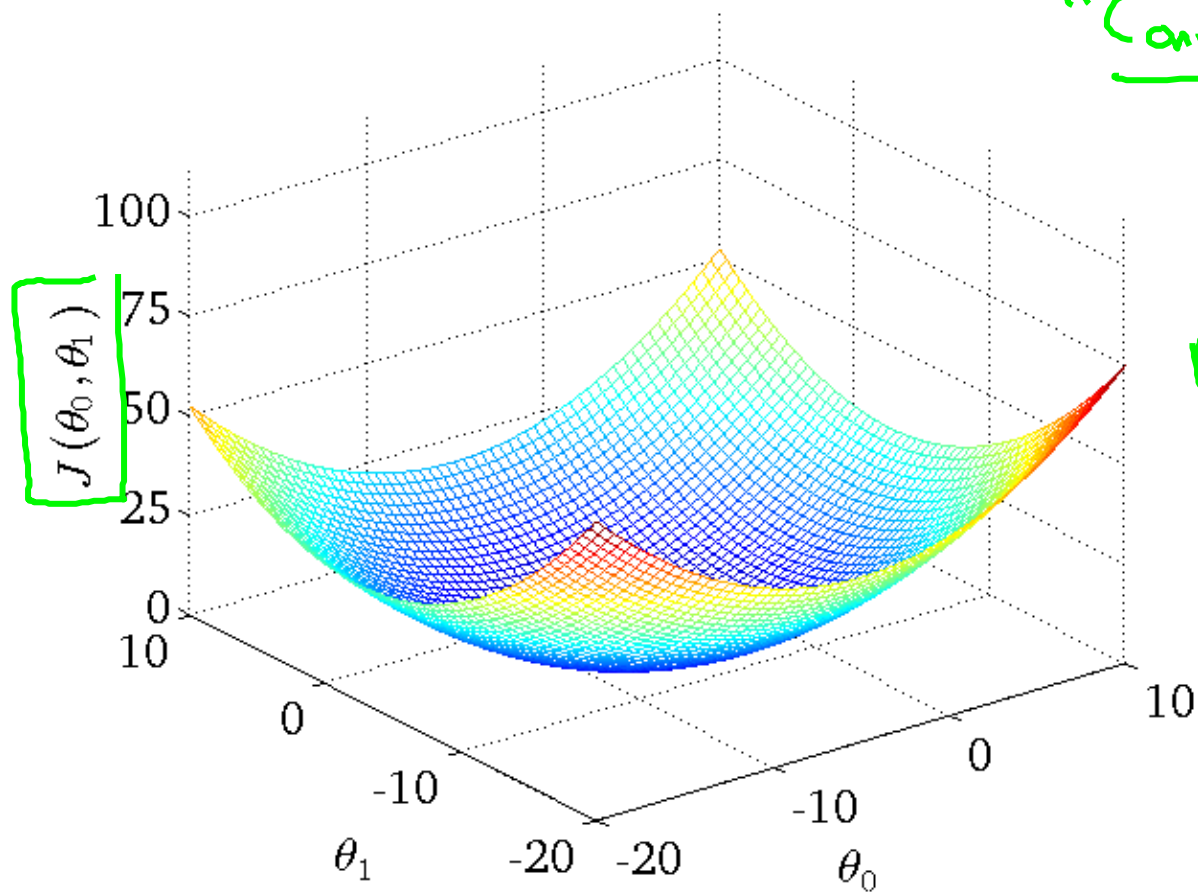
$$\frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$$

update
 θ_0 and θ_1
simultaneously

$$\frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$$





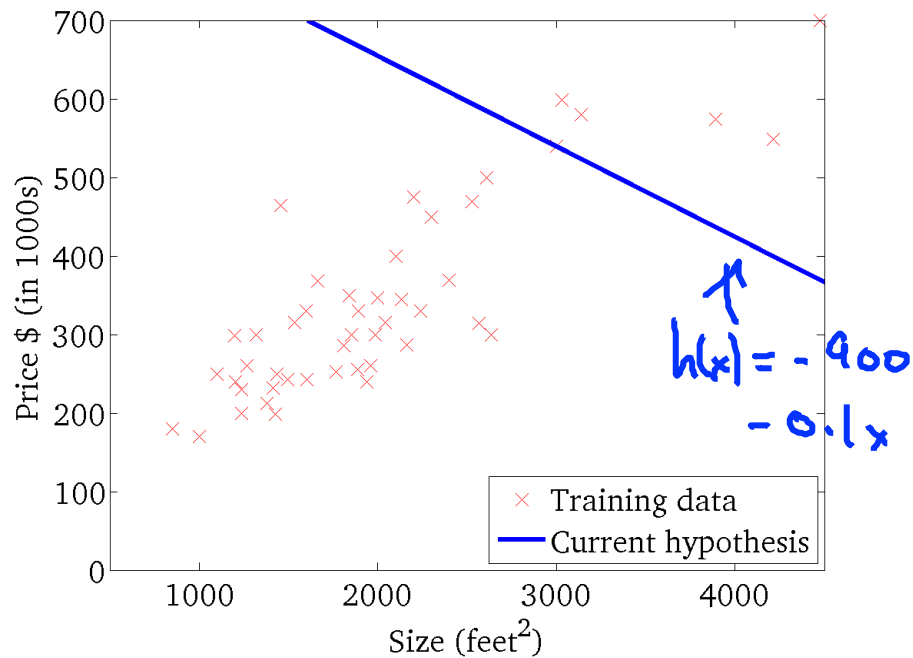


"Convex function"

Bowl-shaped

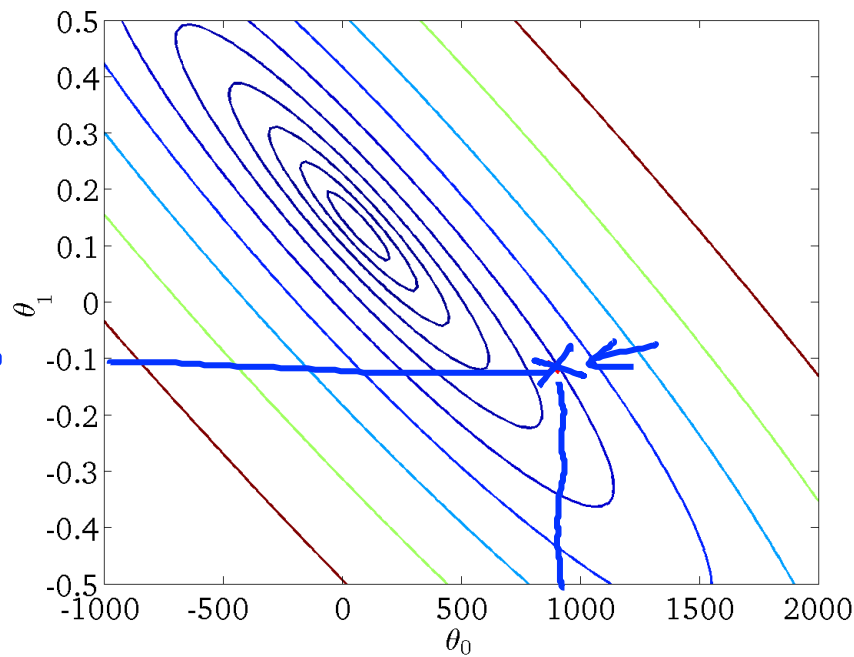
$$\underline{h_{\theta}(x)}$$

(for fixed θ_0, θ_1 , this is a function of x)



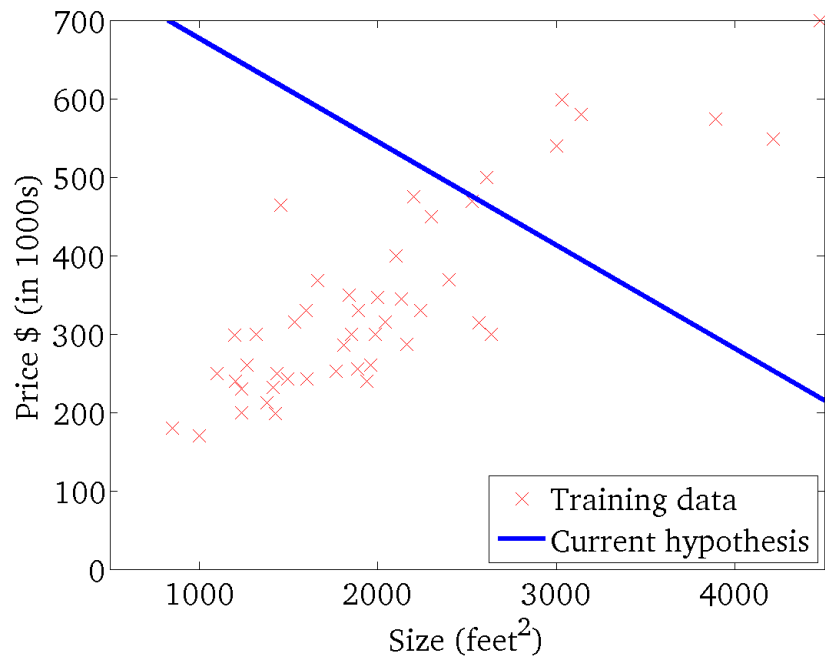
$$\underline{J(\theta_0, \theta_1)}$$

(function of the parameters θ_0, θ_1)



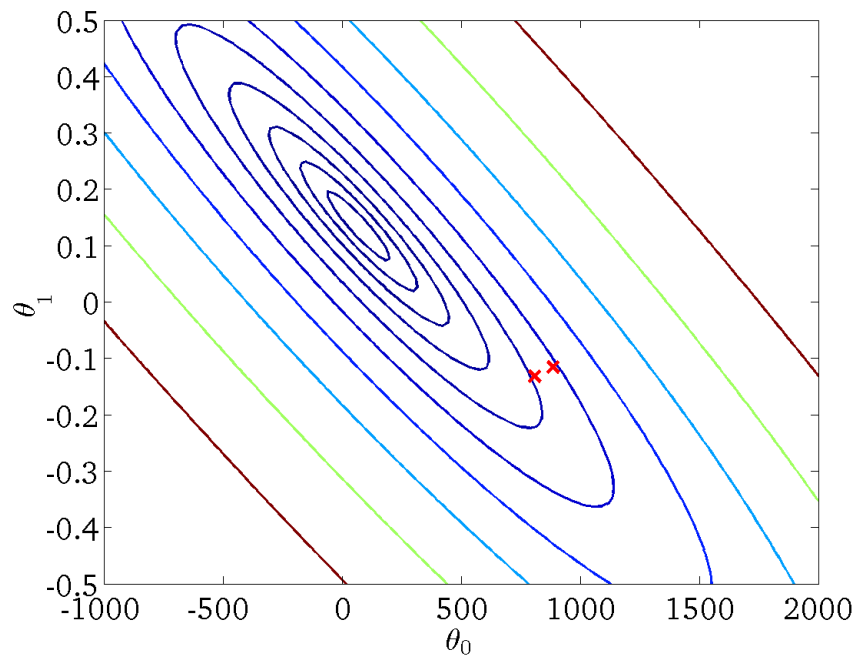
$$h_{\theta}(x)$$

(for fixed θ_0, θ_1 , this is a function of x)



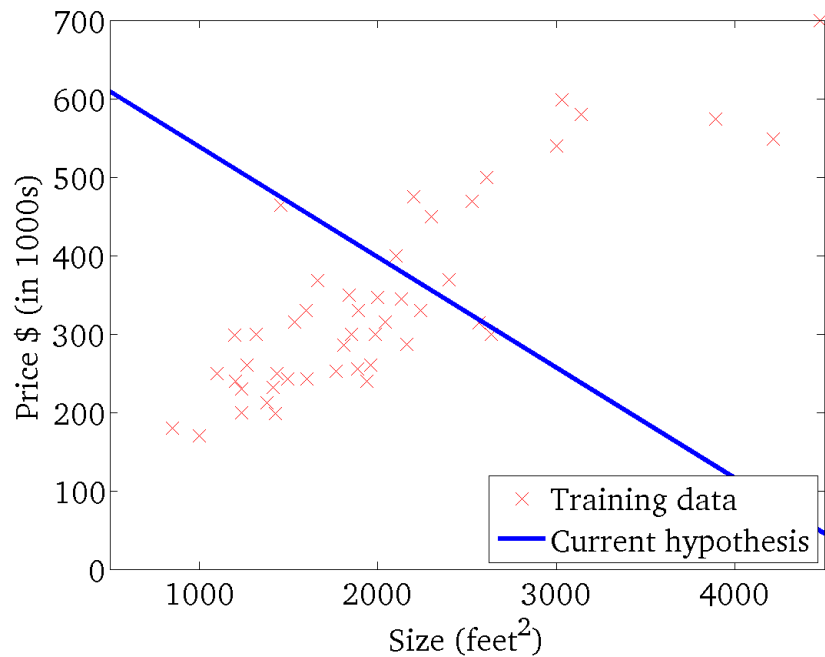
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



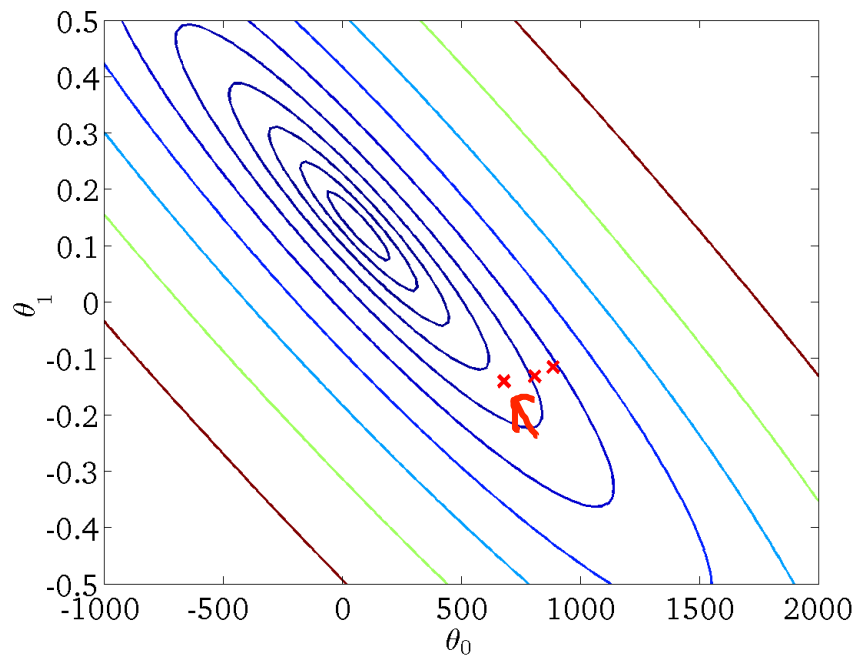
$$h_{\theta}(x)$$

(for fixed θ_0, θ_1 , this is a function of x)



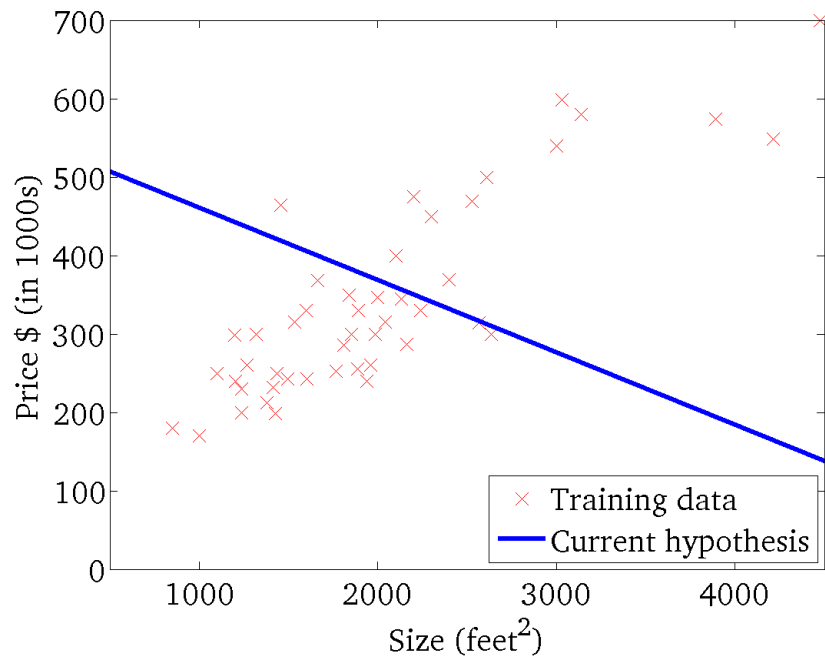
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



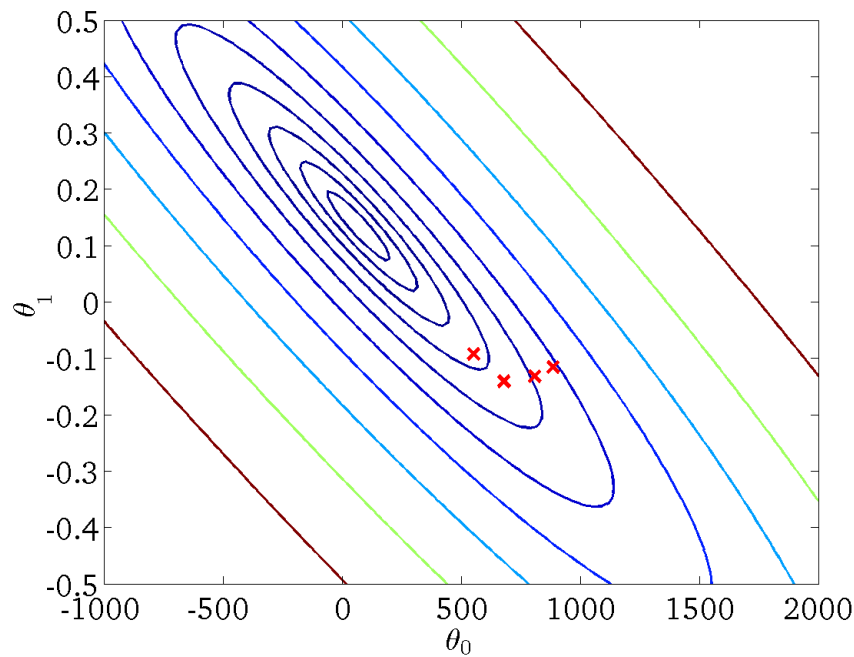
$$h_{\theta}(x)$$

(for fixed θ_0, θ_1 , this is a function of x)



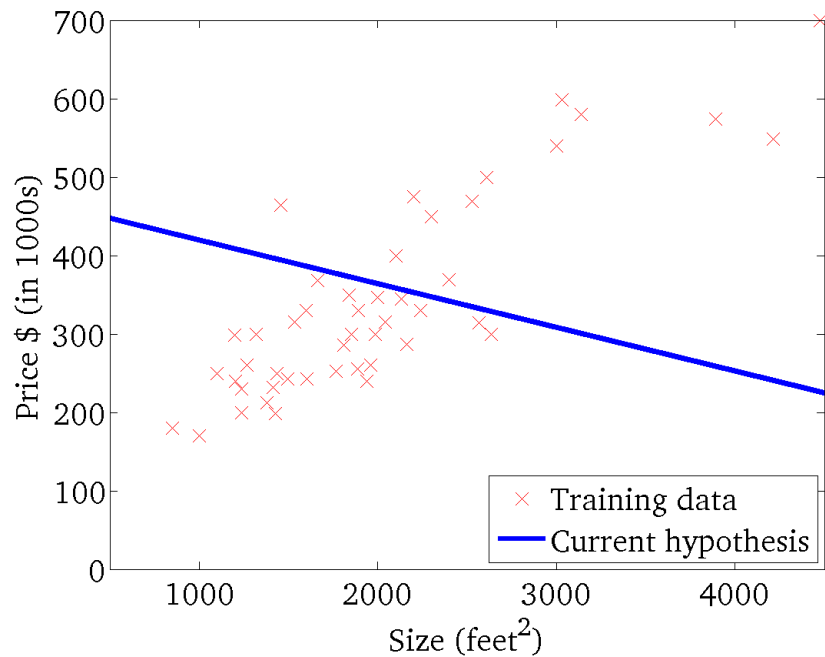
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



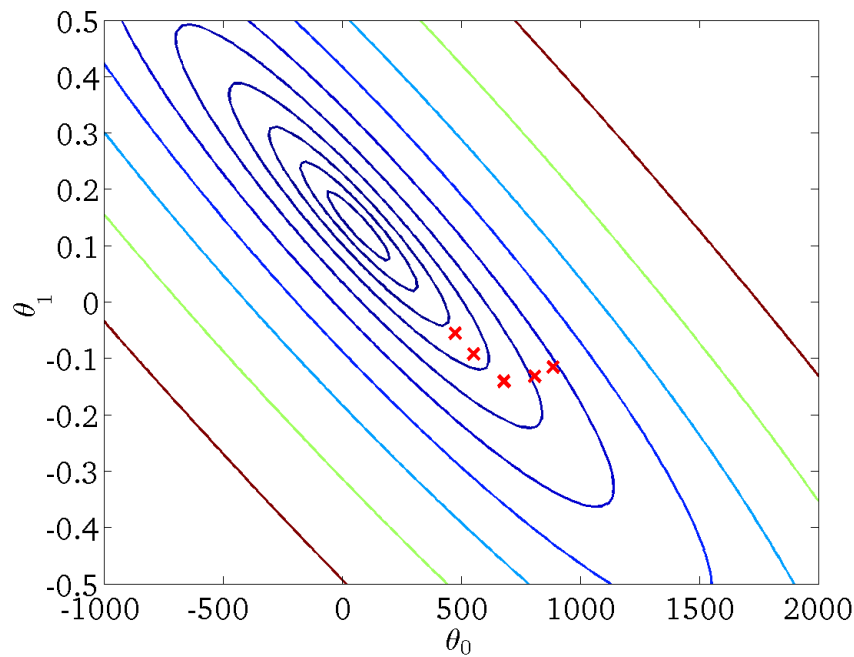
$$h_{\theta}(x)$$

(for fixed θ_0, θ_1 , this is a function of x)



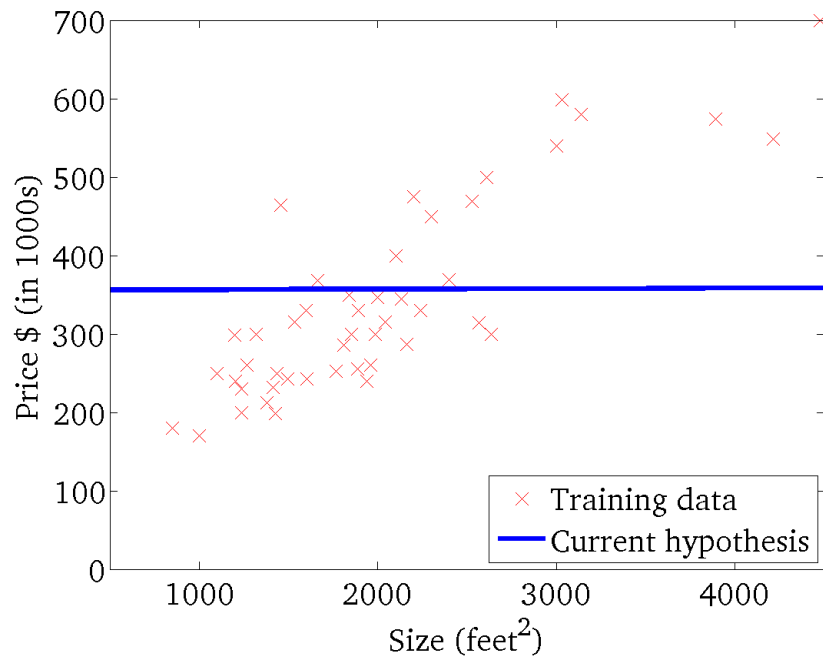
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



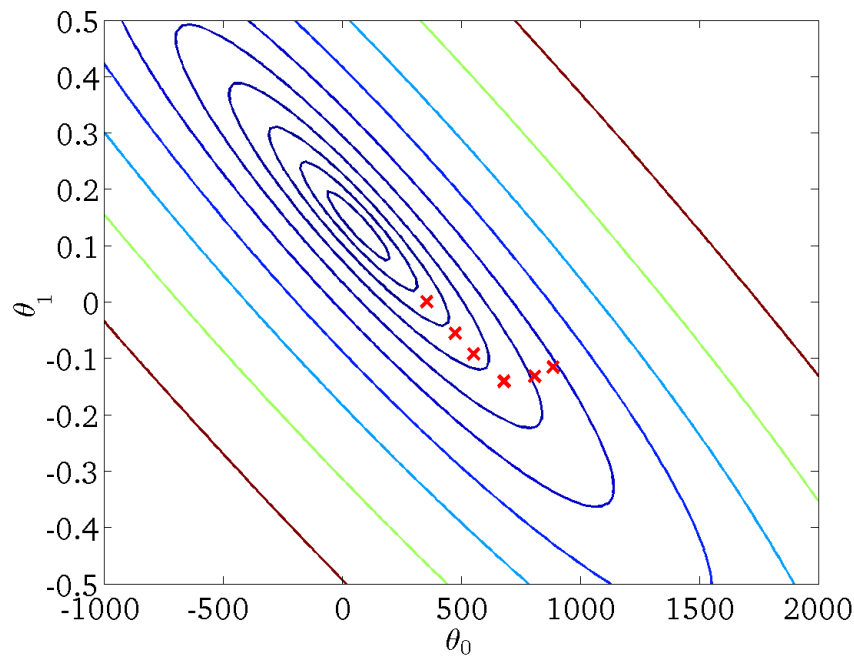
$$h_{\theta}(x)$$

(for fixed θ_0, θ_1 , this is a function of x)



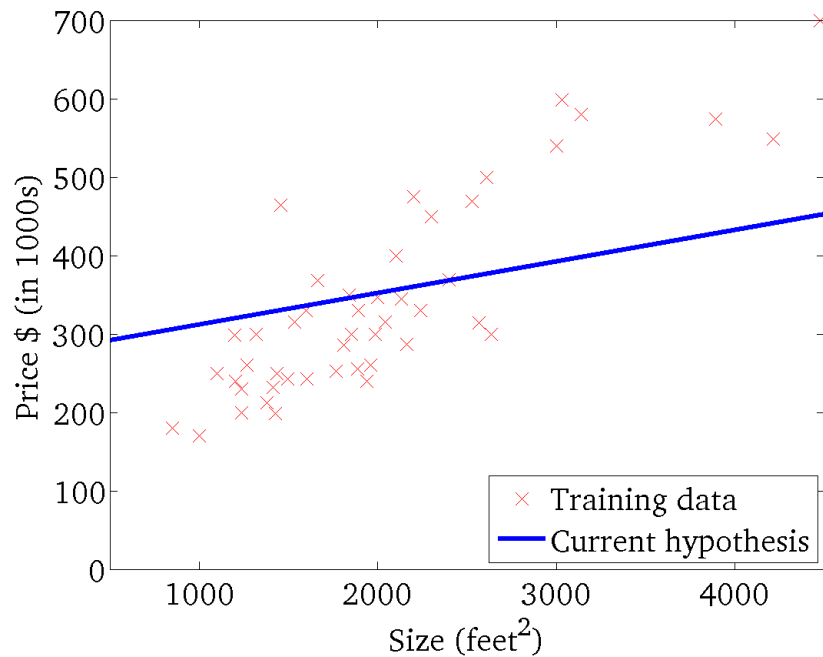
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



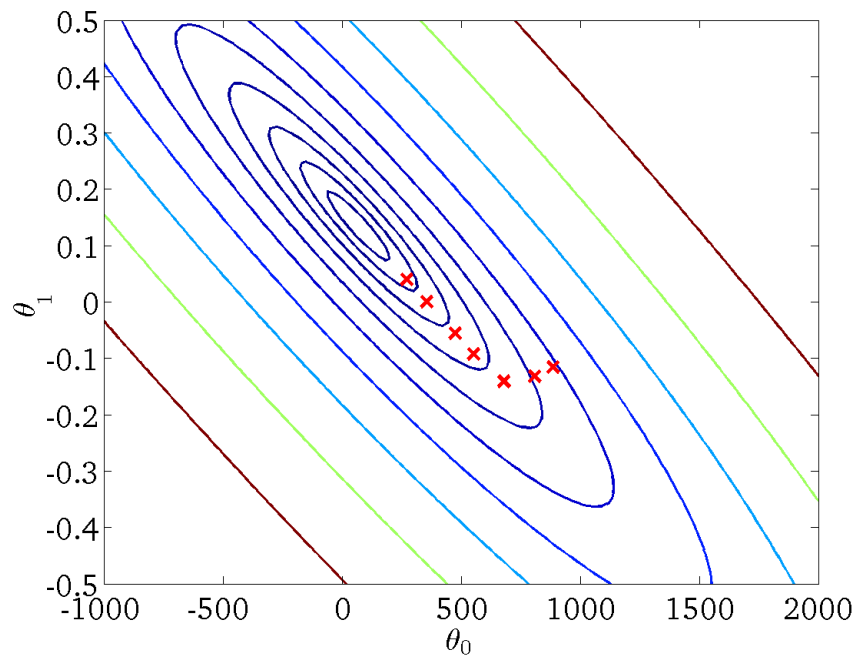
$$h_{\theta}(x)$$

(for fixed θ_0, θ_1 , this is a function of x)



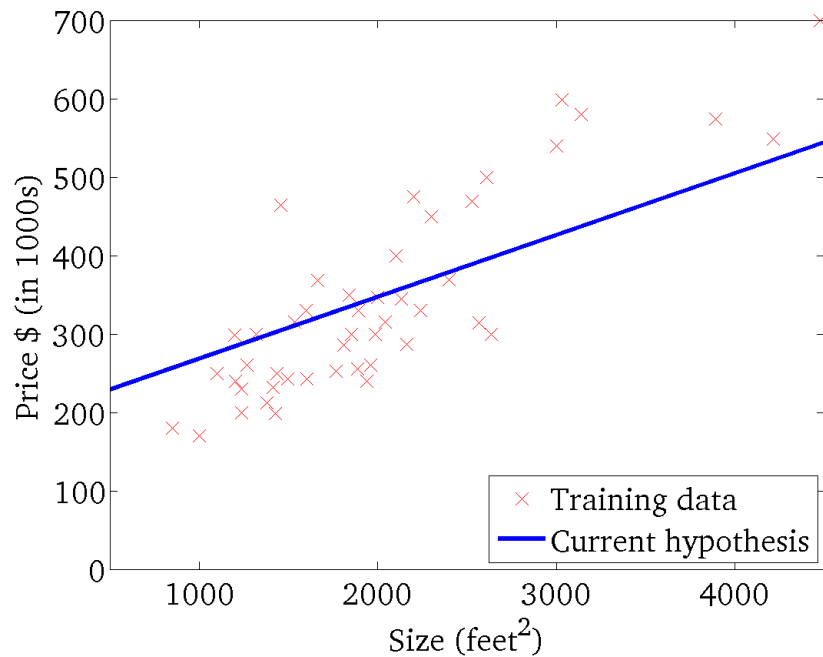
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



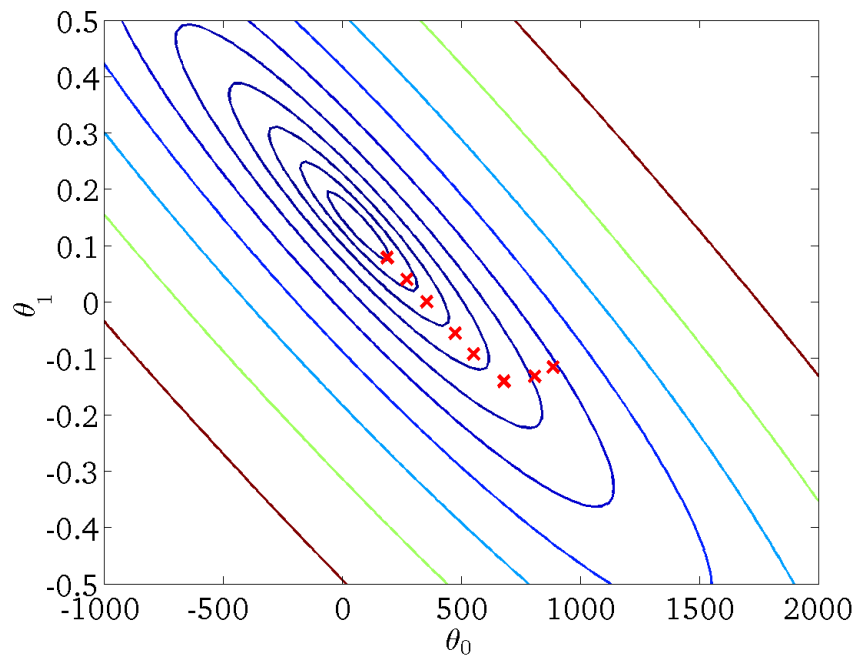
$$h_{\theta}(x)$$

(for fixed θ_0, θ_1 , this is a function of x)



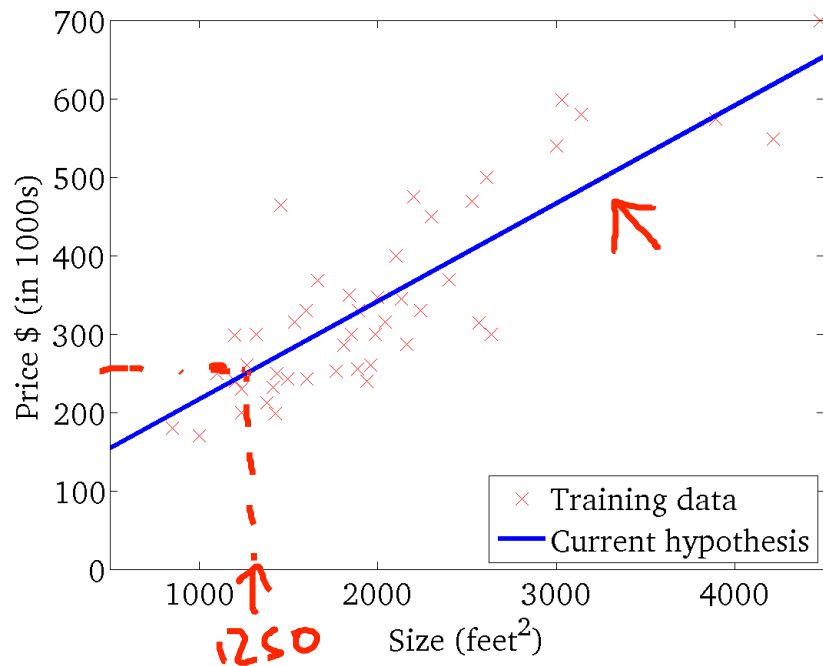
$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



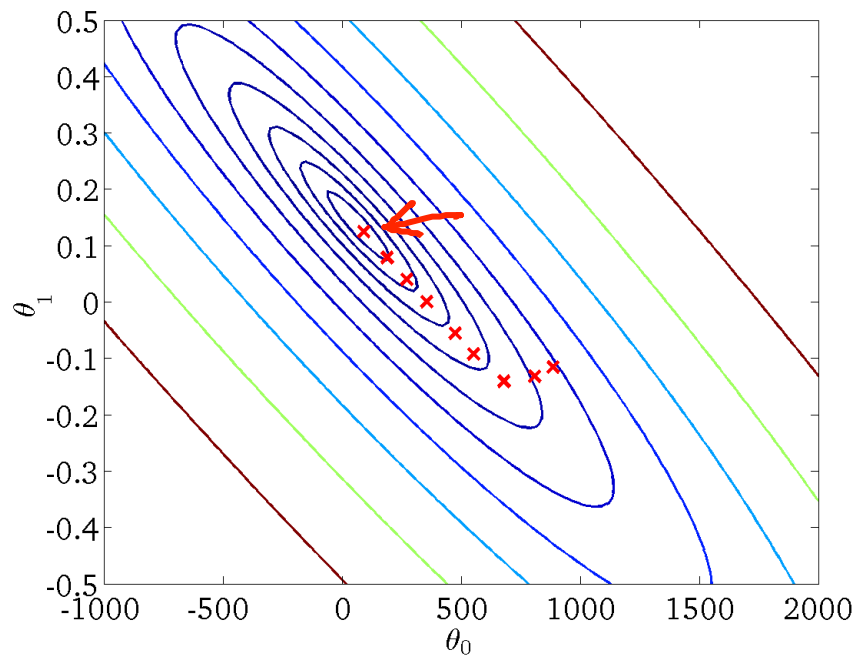
$$h_{\theta}(x)$$

(for fixed θ_0, θ_1 , this is a function of x)



$$J(\theta_0, \theta_1)$$

(function of the parameters θ_0, θ_1)



“Batch” Gradient Descent

“Batch”: Each step of gradient descent uses all the training examples.

$$\rightarrow \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})$$