

# Neural network - easy coding in Keras

From beginner to master in less then three hours

Startit Center Belgrade,

16.11.2019,

16:00-19:00

# Milan M. Čugurović

- Enthusiast interested in DSC, especially ML
- Master Mathematician and PhD Candidate in Informatics at Faculty of Mathematics, UB
- TA @ MATF, BG
- Member of ML Group at Faculty of Mathematics, UB
- Member of CS Department at Faculty of Mathematics, UB

# Faculty of Mathematics, UB

- [matf.bg.ac.rs/eng](http://matf.bg.ac.rs/eng)
- more than 6000 graduate mathematicians
- 400 doctors of mathematics and computer sciences
- 700 Magisters of Science
- many specialists etc.



University of Belgrade

**Faculty of Mathematics**

# ML@MATF

- [machinelearning.math.rs](http://machinelearning.math.rs)
- Based at Faculty of Mathematics
- Includes researchers, students and partitioners from various research institutions and leading IT companies
- Led by professor dr Mladen Nikolić
- Lectures/talks and practical sessions are held on every 2 weeks





## Schedule:

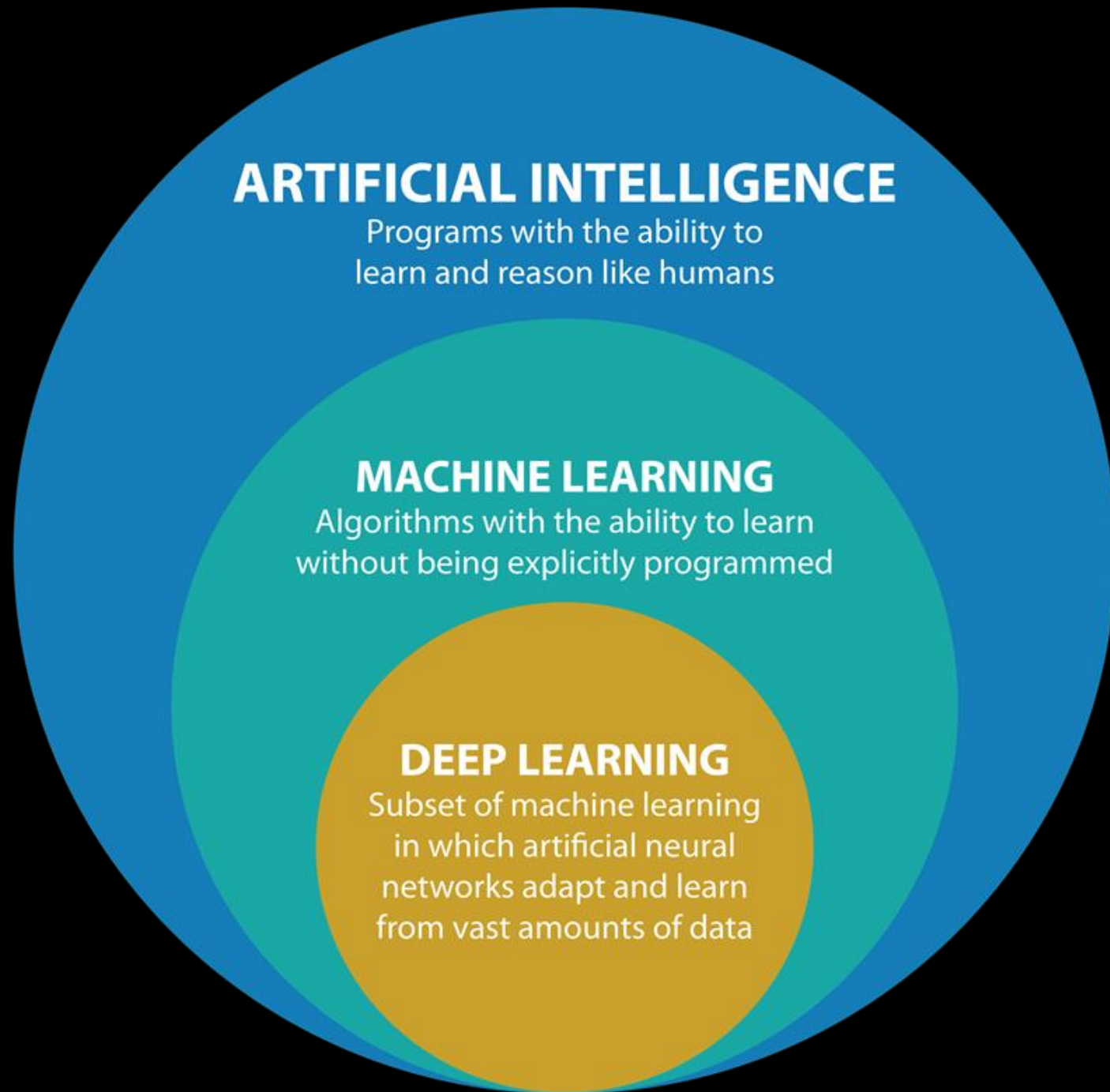
- Part I: ML basics
- Part II: NN basics
- Part III: Keras library

# ML basics

# ML basics



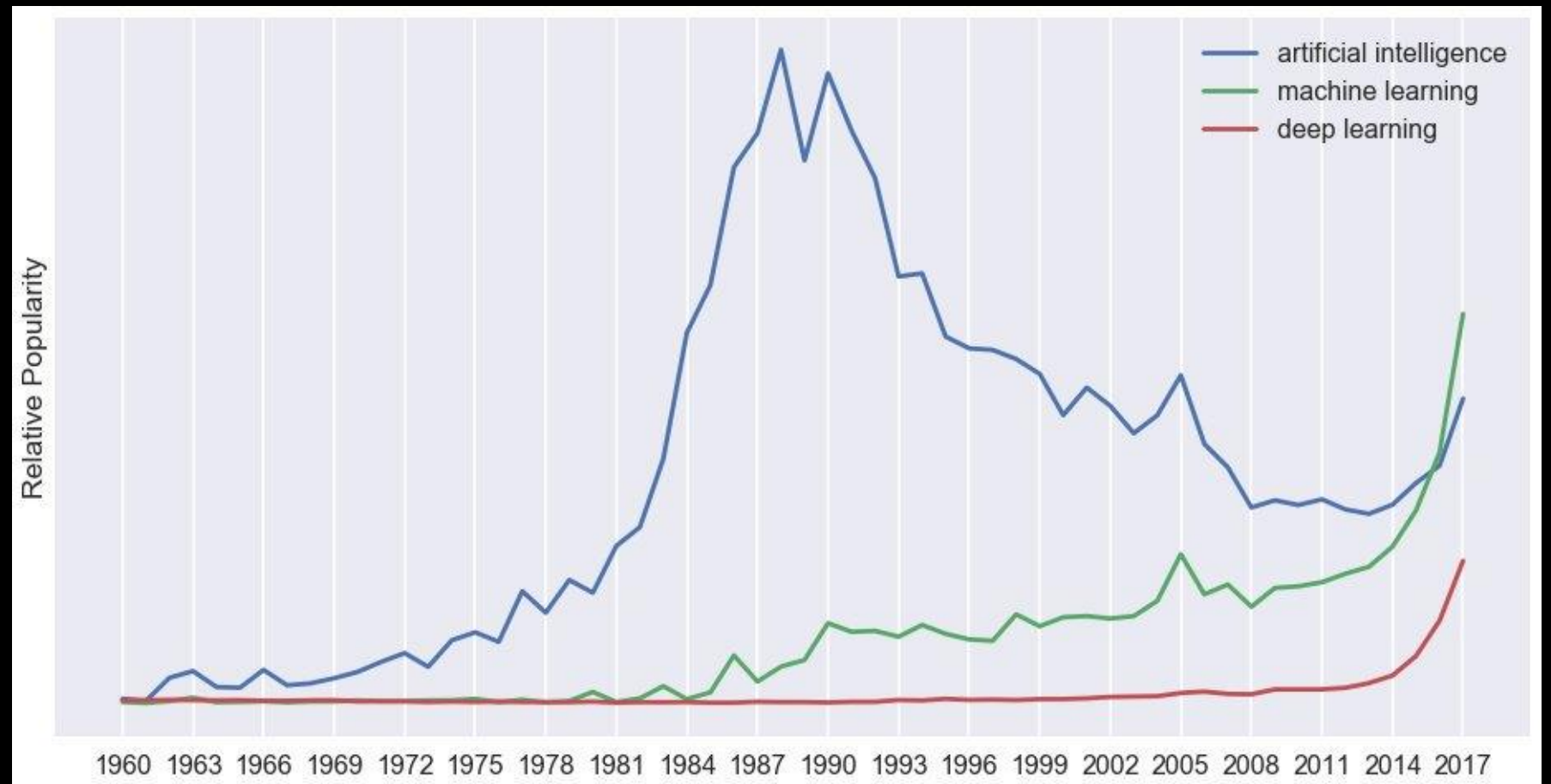
- Hottest CS topic currently
- $DL(NN) \subset ML \subset AI$
- Very active research field today
- Has accomplished amazing results
- Built on multiple mathematical disciplines





# A little bit of Rita is all I need...

- Google trends





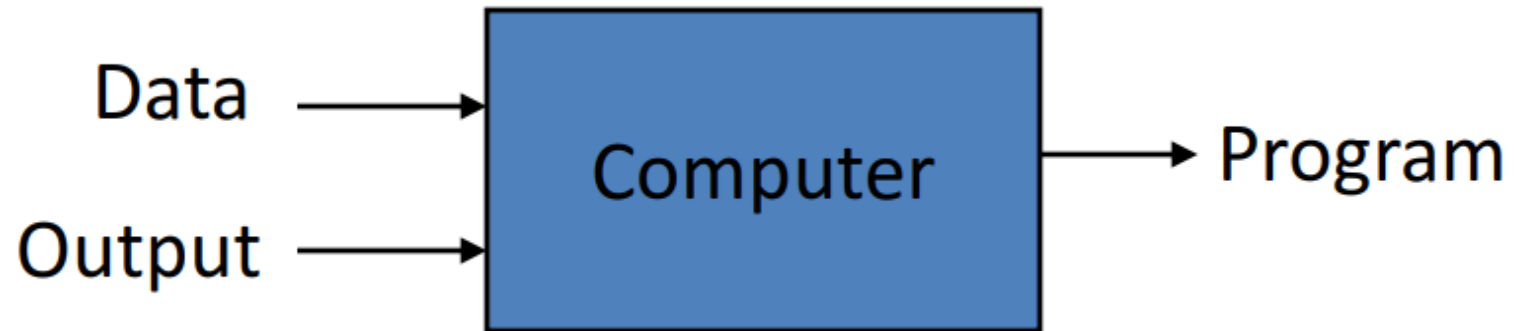
# Definition of the term “learning”

- How would you define the term “learning” ?

# Definition of the term “learning”

- Arthur Samuel (1959):
  - “Machine Learning is the field of study that gives computers the ability to learn without being explicitly programmed”
- Herbert Simon (1970):
  - “Learning is any process by which a system improves performance from experience.”
- Tom M. Mitchell (1998):
  - Machine Learning is the study of algorithms that:
    - improve their performance  $P$
    - at some task  $T$
    - with experience  $E$
  - A well-defined learning task is given by  $\langle P, T, E \rangle$

# ML vs Traditional Programming



# Focus on me, Focus on me...

- Google: processes 24 peta bytes of data per day.
- Twitter: 400 million tweets per day.
- Facebook: 10 million photos uploaded every hour.
- YouTube: 1 hour of video uploaded every second.
- Astronomy: Satellite data is in hundreds of PB.
- “By 2020 the digital universe will reach 44 zettabytes...” (44 trillion gigabytes)
  - The Digital Universe of Opportunities: Rich Data and the Increasing Value of the Internet of Things, April 2014



# Some ML results

- 1992 - TD-Gammon, computer program developed by Gerald Tesauro able to play backgammon
- 2011 - IBM's Watson wins in quiz Jeopardy!
- 2012 - Google X creates system able to recognize cats on video recordings
- 2015 - Classification error for images reduced to 3.6% (5-10% is the error made by humans)
- 2016 - Google creates AlphaGo, agent able to play Go who beats the world champion 4:1
- 2017 - AlphaGo plays against its 2016 version and wins 100/100 games
- October 2017 - AlphaGo Zero learnt to play the game of Go simply by playing games against itself, starting from scratch (40 days)
- 2018 - Humans are miserable compared to ML (any area)

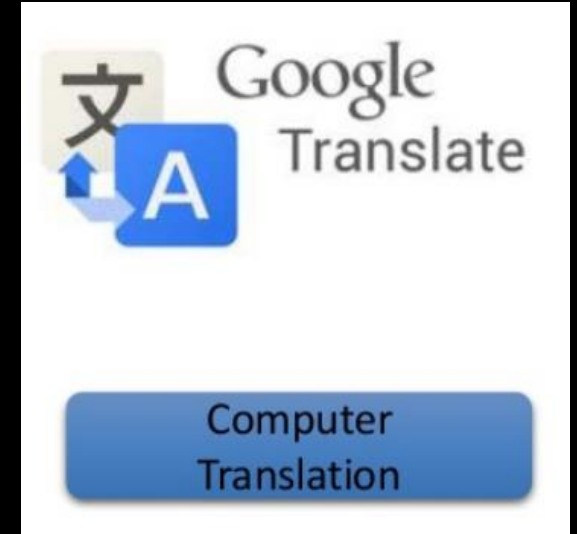
# But why is it so successful and popular today?

- There is serious amount of mathematics behind [Murphy, 2012, Bishop, 2006, Hastie et al., 2001, Shalev-Shwartz and Ben-David, 2014, Vapnik, 1995]

$$\begin{aligned}
 & P(\sup_{f \in \mathcal{F}} (R(f) - E(f)) > \varepsilon) \leq \\
 & 2P(\sup_{f \in \mathcal{F}} (E'(f) - E(f)) > \varepsilon/2) = \\
 & 2P\left(\sup_{l \in \mathcal{L}_{z_1, \dots, z_N, z'_1, \dots, z'_N}} \left(\frac{1}{N} \sum_{i=N+1}^{2N} l_i - \frac{1}{N} \sum_{i=1}^N l_i\right) > \varepsilon/2\right) \leq \\
 & 2 \sum_{l \in \mathcal{L}_{z_1, \dots, z_N, z'_1, \dots, z'_N}} P\left(\frac{1}{N} \sum_{i=N+1}^{2N} l_i - \frac{1}{N} \sum_{i=1}^N l_i > \varepsilon/2\right) = \\
 & 2 \sum_{l \in \mathcal{L}_{z_1, \dots, z_N, z'_1, \dots, z'_N}} P\left(\frac{1}{N} \sum_{i=N+1}^{2N} l_i - R(f) + R(f) - \frac{1}{N} \sum_{i=1}^N l_i > \varepsilon/2\right) \leq \\
 & 2 \sum_{l \in \mathcal{L}_{z_1, \dots, z_N, z'_1, \dots, z'_N}} \left(P\left(\frac{1}{N} \sum_{i=N+1}^{2N} l_i - R(f) > \varepsilon/2\right) + P\left(R(f) - \frac{1}{N} \sum_{i=1}^N l_i > \varepsilon/2\right)\right) \leq \\
 & 2 \sum_{l \in \mathcal{L}_{z_1, \dots, z_N, z'_1, \dots, z'_N}} (\exp(-N\varepsilon^2/2) + \exp(-N\varepsilon^2/2)) = \\
 & 4 \sum_{l \in \mathcal{L}_{z_1, \dots, z_N, z'_1, \dots, z'_N}} \exp(-N\varepsilon^2/2) =
 \end{aligned}$$

# Some ML Applications

- Web search
- Computational biology
- Finance
- E-commerce
- Space exploration
- Robotics
- Information extraction
- Social networks
- Debugging software
- [Your favorite area]





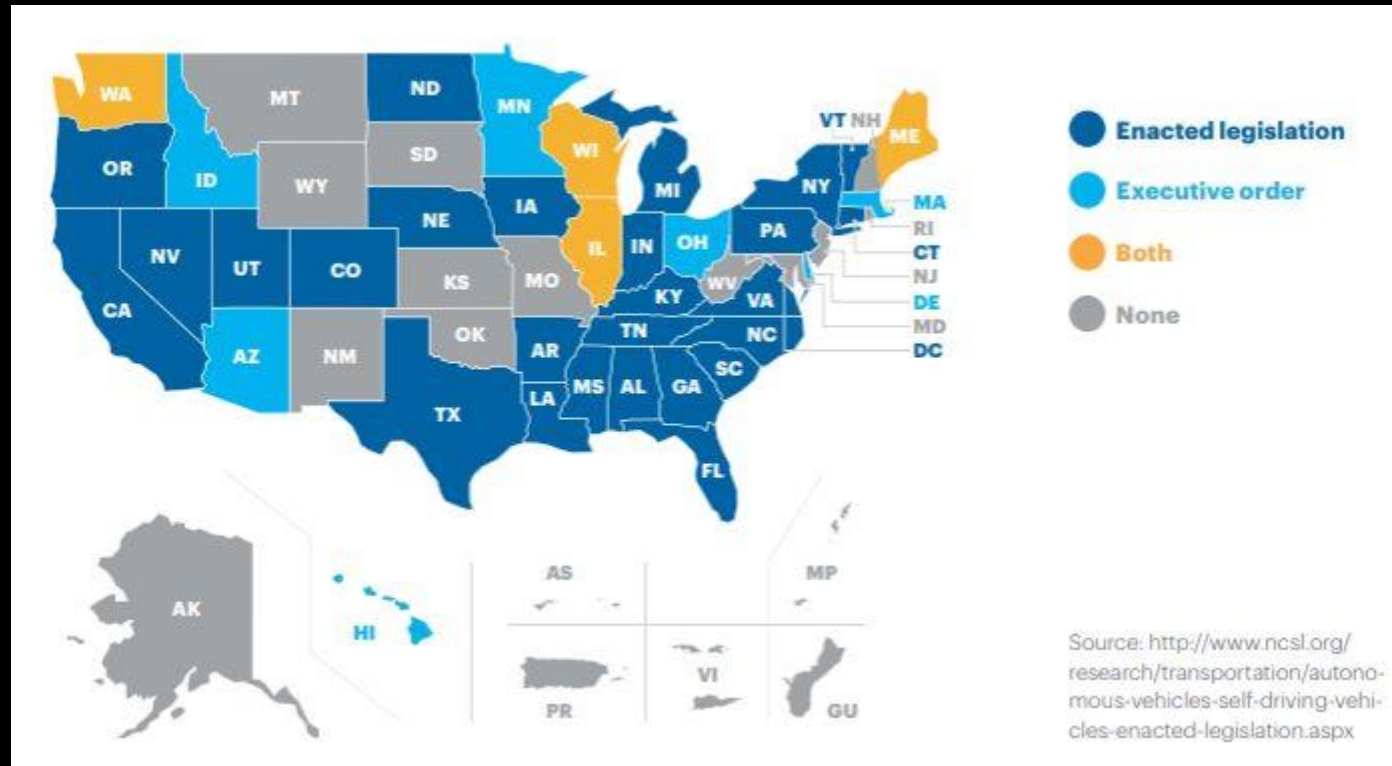
# Example 1: Autonomous Cars





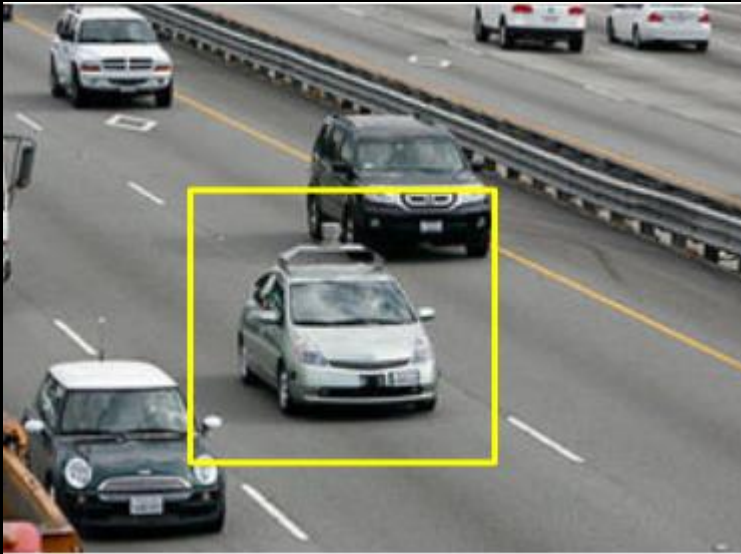
# Example 1: Autonomous Cars

- June 2011: Nevada made it legal for autonomous cars to drive on roads
- 2013: Nevada, Florida, California, and Michigan have legalized autonomous cars
- Now:



# Example 1: Autonomous Cars

- Detecting it
- Penn's Autonomous Car ((Ben Franklin Racing Team)



# Example 1: Autonomous Cars

## Under the bonnet

How a self-driving car works

Signals from **GPS (global positioning system)** satellites are combined with readings from tachometers, altimeters and gyroscopes to provide more accurate positioning than is possible with GPS alone

**Lidar (light detection and ranging)** sensors bounce pulses of light off the surroundings. These are analysed to identify lane markings and the edges of roads

**Video cameras** detect traffic lights, read road signs, keep track of the position of other vehicles and look out for pedestrians and obstacles on the road

**Radar sensor**

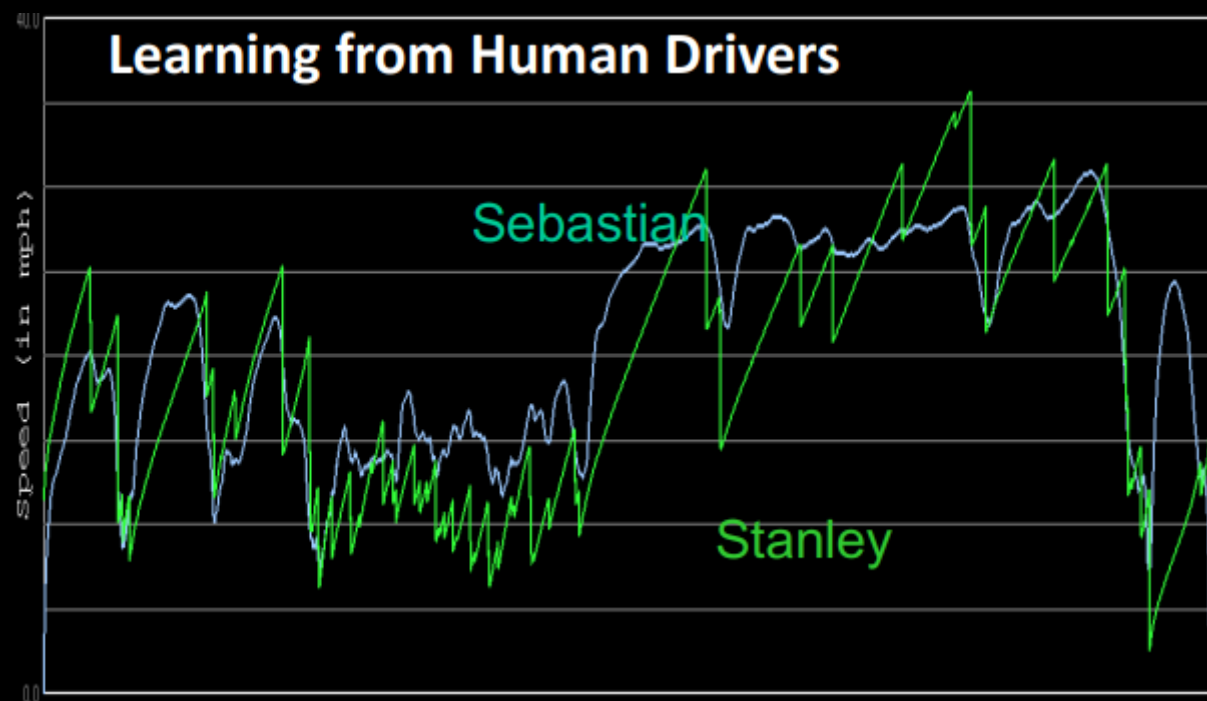
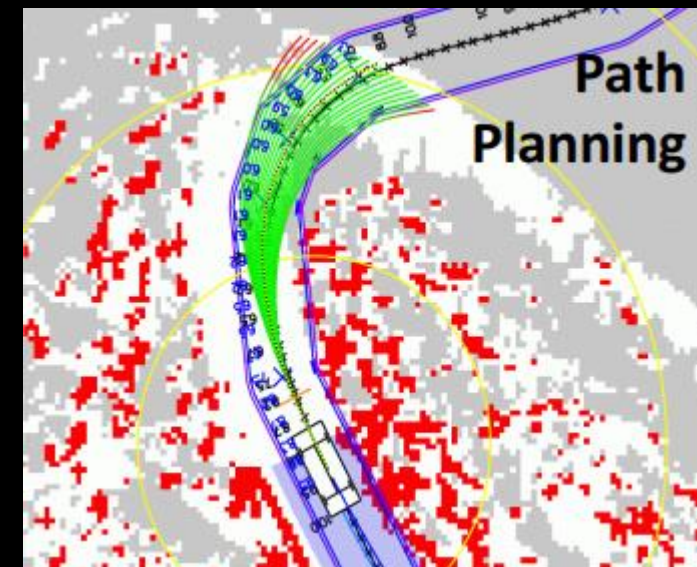
**Ultrasonic sensors** may be used to measure the position of objects very close to the vehicle, such as curbs and other vehicles when parking

The information from all of the sensors is analysed by a **central computer** that manipulates the steering, accelerator and brakes. Its software must understand the rules of the road, both formal and informal

**Radar sensors** monitor the position of other vehicles nearby. Such sensors are already used in adaptive cruise-control systems

Source: *The Economist*





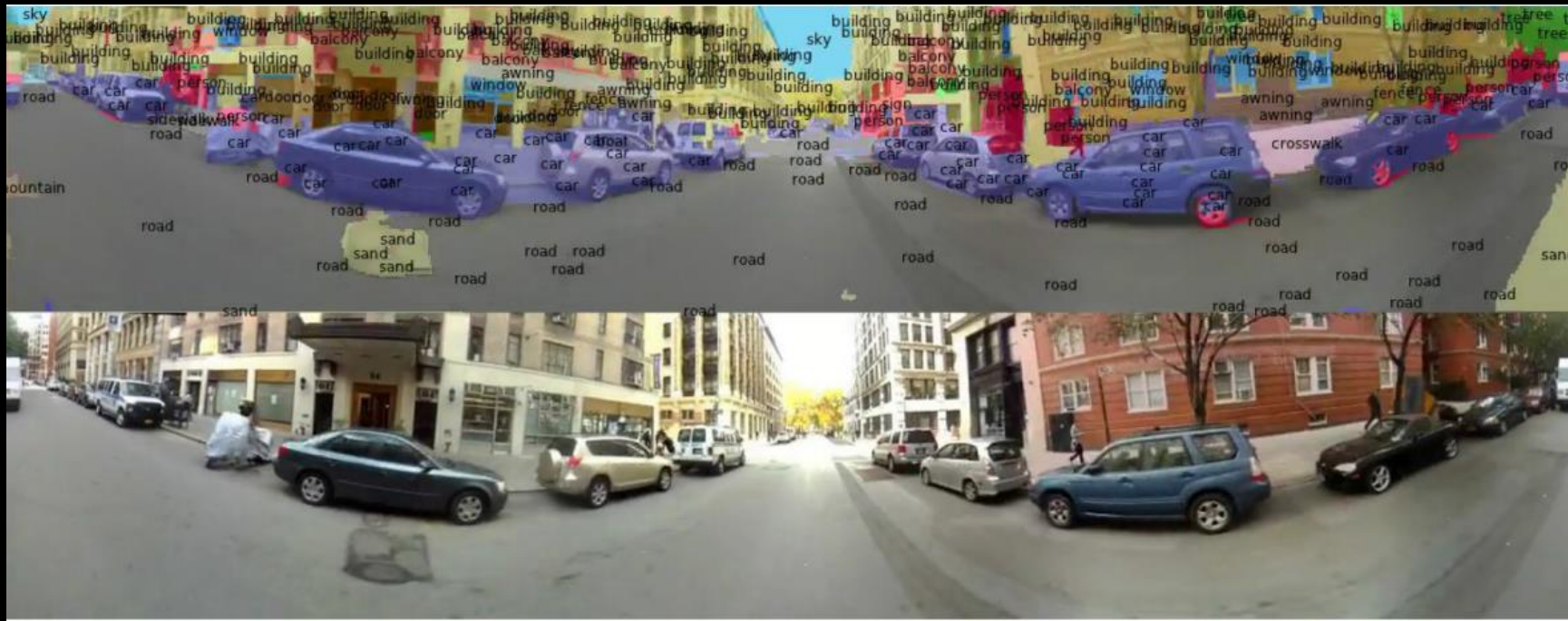


# Example 1: Autonomous Cars

- Tesla: <https://www.youtube.com/watch?v=tlThdr3O5Qo>
- Wayve: <https://www.youtube.com/watch?v=26Or4QbLbMM>
- Audi A8 Parking: <https://www.youtube.com/watch?v=Cwcoi-HlZ-M>

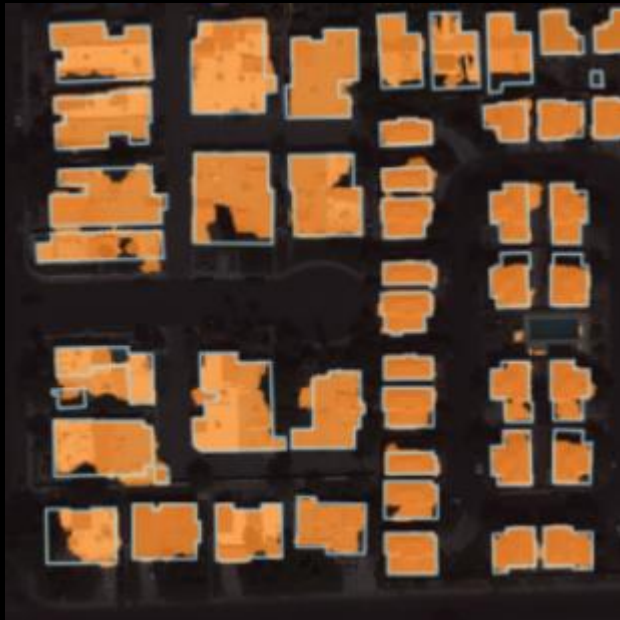
## Example 2: Scene Parsing/Labeling via DL

- Background/Motivation?
- Scene parsing: labeling each pixel in the image with category of the object to which it belongs
- Important step toward image understanding



## Example 2: Scene Parsing/Labeling via DL

- Image -> Video
  - <https://www.youtube.com/watch?v=N1f7i-oItWU>
- To Train DL Models on Satellite Imagery
- Image captioning

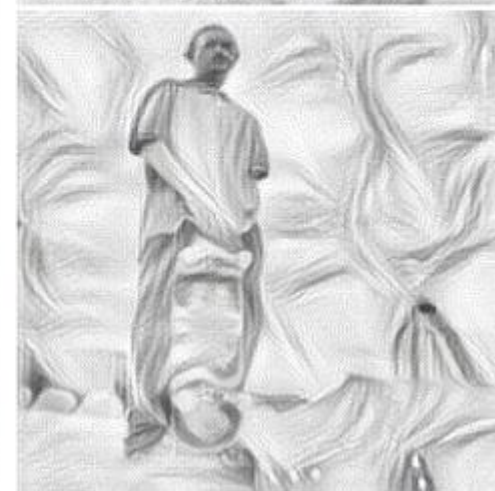
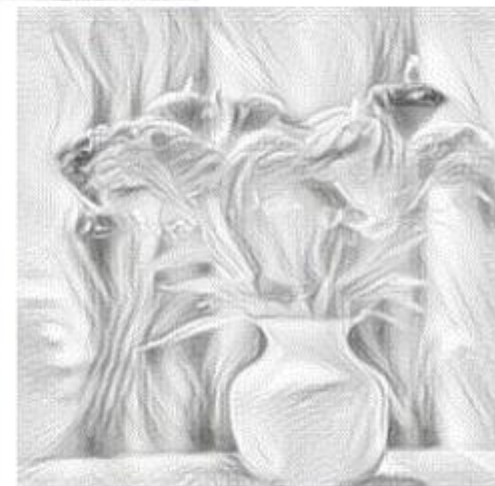




## Example 3: Style Transfer

- My lecture at ML@MATF Seminary:
  - <http://machinelearning.math.rs/Cugurovic-Style.pdf>

Style  
*Sketch*





## Example 3: Style Transfer

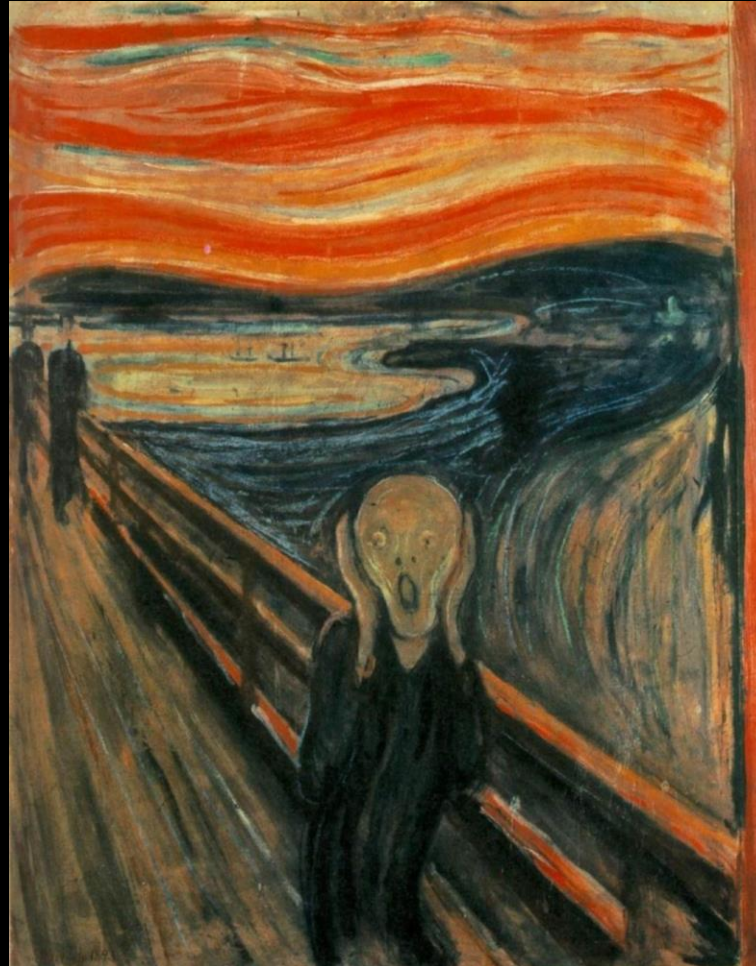
- *The Starry Night*, 1889
- Oil on canvas
- By the Dutch post-impressionist painter Vincent van Gogh
- The Stanford campus photo





## Example 3: Style Transfer

- *The Scream*, 1893
- A composition created by Norwegian Expressionist artist
- Edvard Munch
- Tübingen, Germany





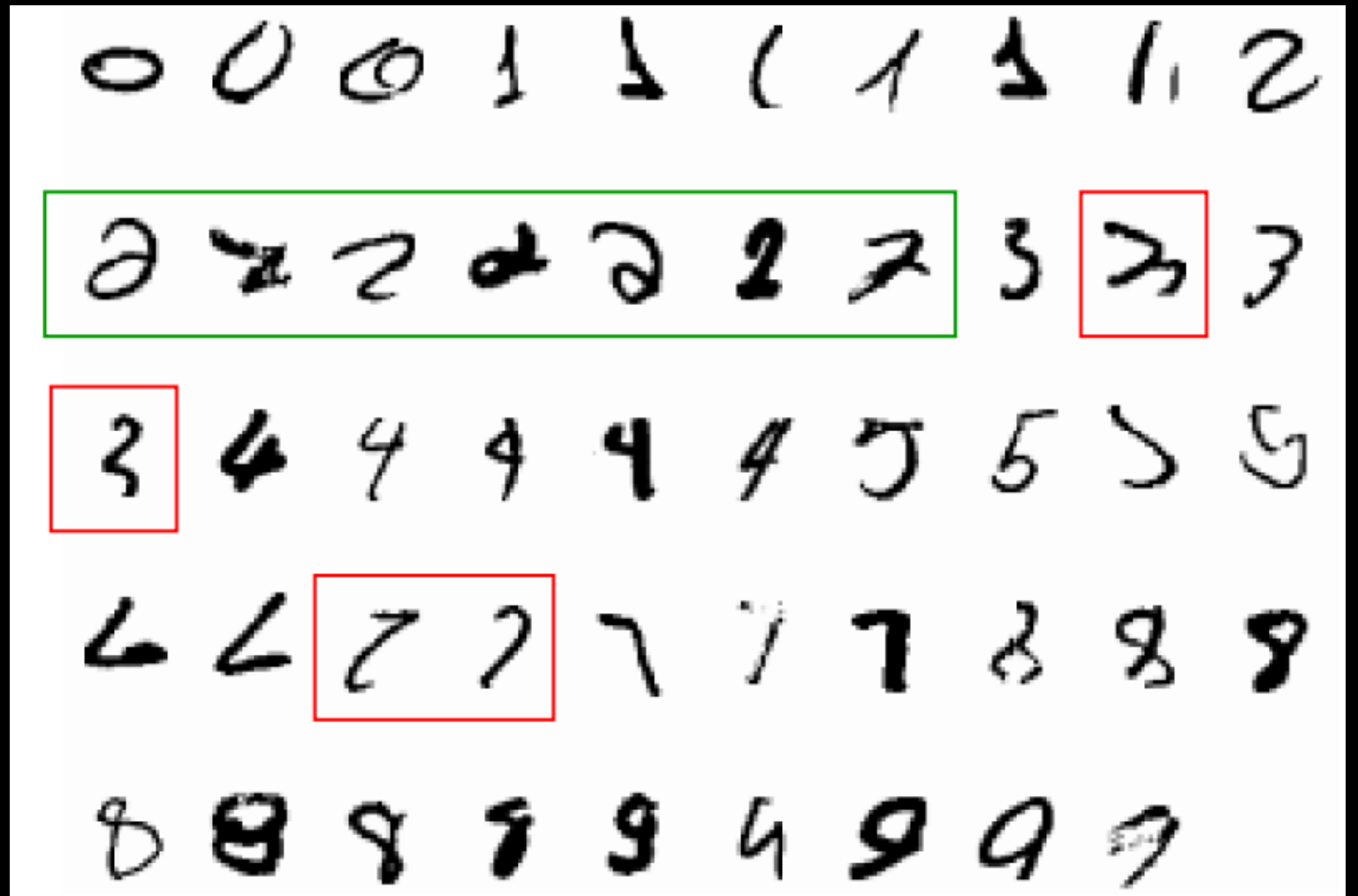
## Example 3: Style Transfer

- Combine them
- The style of Picasso's 1907 self-portrait onto Brad Pitt, etc.



## Example 4: Handwriting Recognition

- It is very hard to say what makes a 2
- There were “manual” methods for recognizing handwritten characters before
- ML (DNN) a few orders of magnitude better



# Example 4: Handwriting Recognition

- We currently working on it
- Try to further improve deep CNN



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## Learning the Way We Write: A Lightweight Automatic Adaptation of Neural Classifier of Handwritten Text to Individual Users

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Abstract



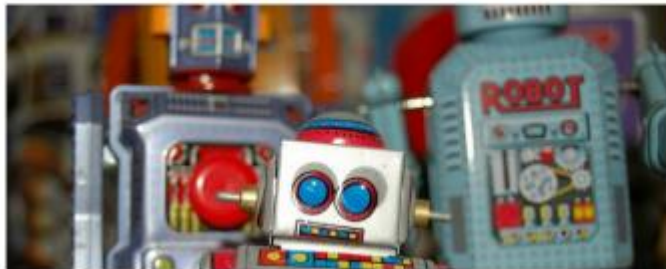
# NN basics

# NN == DL

- Can see it everywhere
- The idea of mimicking the human brain

## Deep Learning's Role in the Age of Robots

BY JULIAN GREEN, JETPAC 05.02.14 2:56 PM



BUSINESS NEWS

## Is Google Cornering the Market on Deep Learning?

A cutting-edge corner of science is being wooed by Silicon Valley, to the dismay of some academics.

By Antonio Regalado on January 26, 2014



How much are a dozen deep-learning researchers worth? Apparently, more than \$400 million.

This week, Google reportedly paid the acquire [DeepMind Technologies](#), a sta

## BloombergBusinessweek Technology

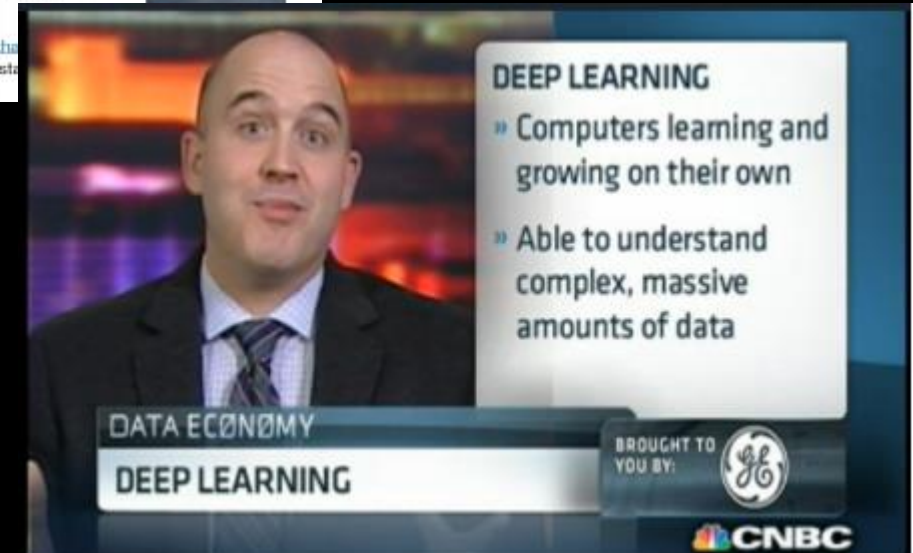
Acquisitions

## The Race to Buy the Human Brains Behind Deep Learning Machines

By Ashlee Vance | January 27, 2014

intelligence projects. "DeepMind is bona fide in terms of its research capabilities and depth," says Peter Lee, who heads Microsoft Research.

According to Lee, Microsoft, Facebook (FB), and Google find themselves in a battle for deep learning talent. Microsoft has gone from four full-time deep learning experts to 70 in the past three years. "We would have more if the talent was there to



# Neural Networks - First Look

- Most popular and most appropriate machine learning methods
- Five main types:
  - Feed Forward neural network (basic)
  - Convolutional neural network (images)
  - Recurrent neural network (memory)
  - Recursive neural network (tree)
  - Graph neural network (graph)
- As we said before:
  - Medical diagnostic
  - Image recognition and Object detection
  - Autonomous driving
  - NLP (Natural Language Processing)
  - Go, FlappyBird ...
- The reason for their re-popularity (computational power – GPU!)

# Before we dive in...

- Biological motivation and connection
  - Neuron - the basic computational unit of the brain
  - Around 86 billion neurons can be found in the human nervous system
  - They are connected with approximately  $10^{14} - 10^{15}$  synapses
  - Human 'training process' - a couple of years :) (AlphaGo 40 days right now)
- Mathematical strength
  - Universal approximation theorem:

Let  $\phi(\cdot)$  be a nonconstant, bounded, and monotonically-increasing continuous function. Let  $I_m$  denote the  $m$ -dimensional unit hypercube  $[0, 1]^m$ . The space of continuous functions on  $I_m$  is denoted by  $C(I_m)$ . Then, given any  $\epsilon > 0$  and any function  $f \in C(I_m)$ , there exists an integer  $N$ , real constants  $v_i, b_i$  and real vectors  $w_i \in \mathbb{R}^m$ , where  $i = 1, 2, \dots, N$ , such that we may define:

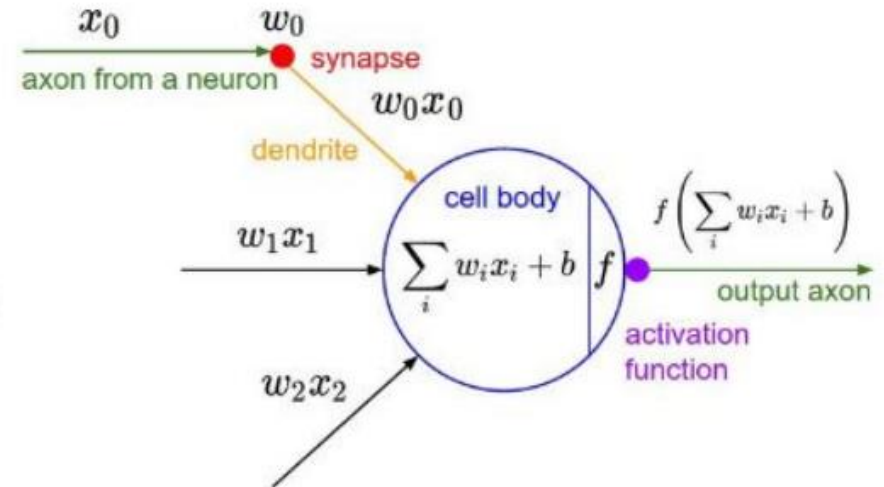
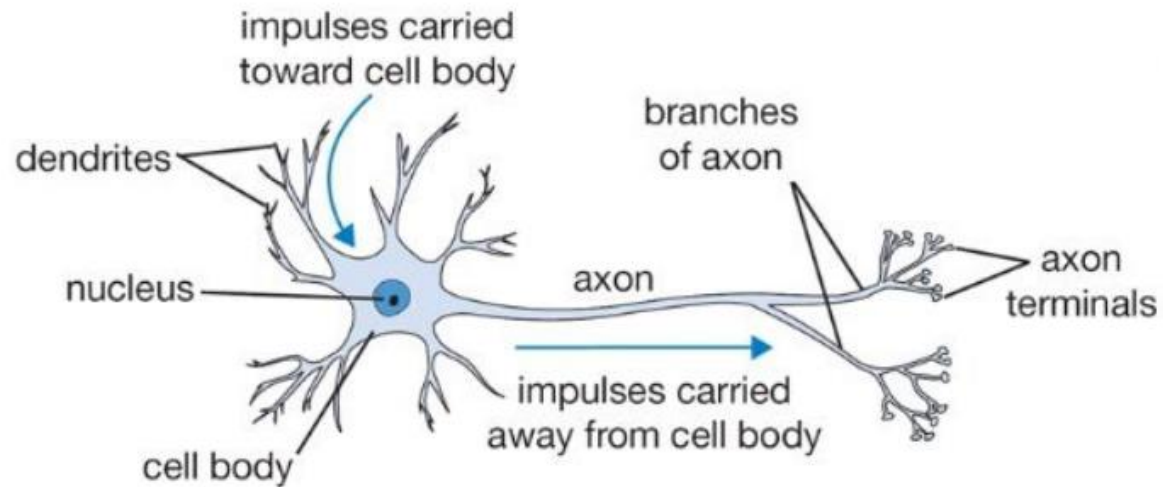
$$F(x) = \sum_{i=1}^N v_i \phi(w_i^T x + b_i)$$

as an approximate realization of the function  $f$ , where  $f$  is independent of  $\phi$ ;  
That is  $|F(x) - f(x)| < \epsilon$ , for all  $x \in I_m$ .



# Main parts of Feed Forward Neural Network

- Neuron:



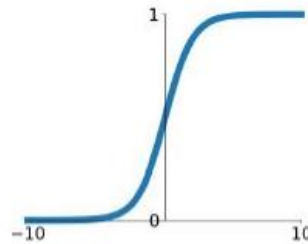
biological neuron (left) and a common mathematical model (right)

# Main parts of Feed Forward Neural Network

- Activation function:

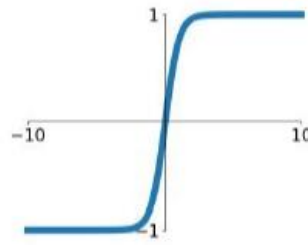
**Sigmoid**

$$\sigma(x) = \frac{1}{1+e^{-x}}$$



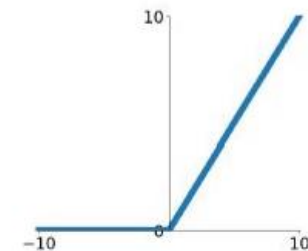
**tanh**

$$\tanh(x)$$



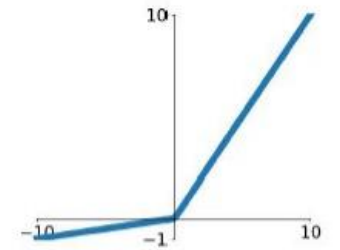
**ReLU**

$$\max(0, x)$$



**Leaky ReLU**

$$\max(0.1x, x)$$

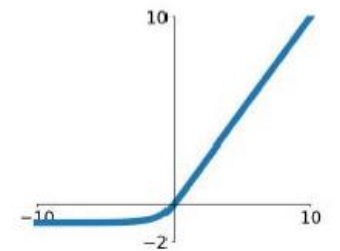


**Maxout**

$$\max(w_1^T x + b_1, w_2^T x + b_2)$$

**ELU**

$$\begin{cases} x & x \geq 0 \\ \alpha(e^x - 1) & x < 0 \end{cases}$$



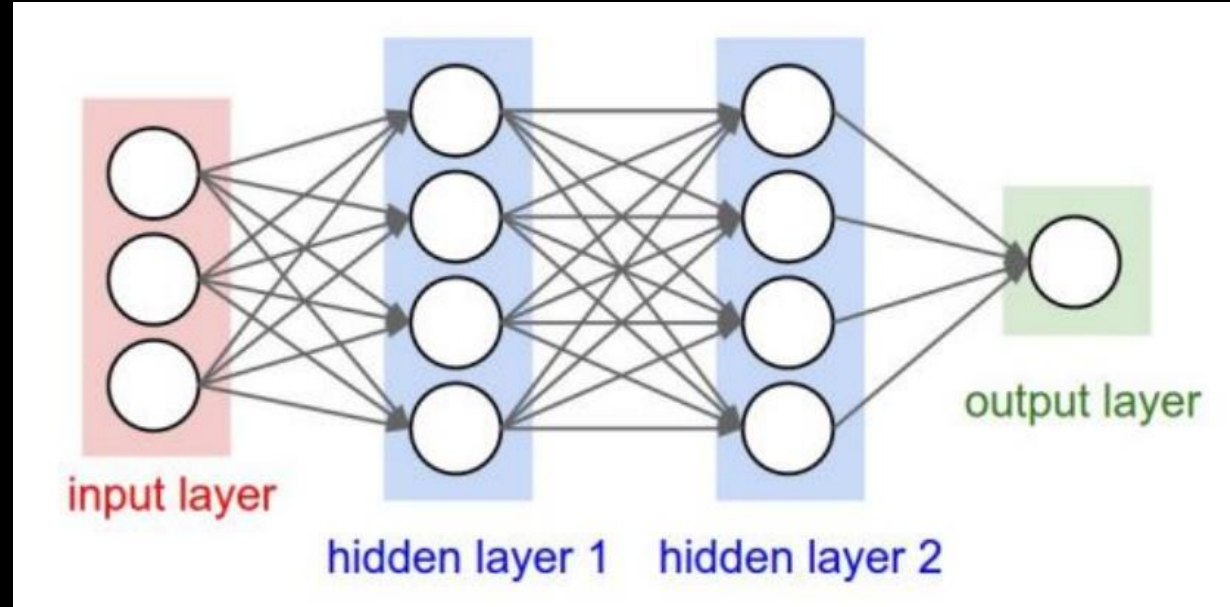
# Main parts of Feed Forward Neural Network

- Neurons (with its activation functions) are stored in layers
- **Input layer** - No computation is done here within this layer, they just pass the information to the next layer
- **Hidden layers** - they perform computations and then transfer the weights (signals or information) from the input layer to the following layer (another hidden layer or to the output layer)
- **Output layer** - Here we finally use an activation function that maps to the desired output format (e.g. Softmax for classification):

$$\text{softmax}((x_1, \dots, x_C)) = \left( \frac{e^{x_1}}{\sum_{i=1}^C e^{x_i}}, \dots, \frac{e^{x_C}}{\sum_{i=1}^C e^{x_i}} \right)$$

# Main parts of Feed Forward Neural Network

- Fully image:
  - (FC NN)

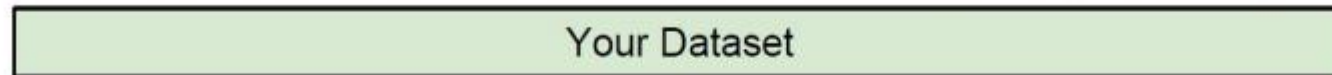




# Dataset split (coding scenario)

**Idea #1:** Choose hyperparameters that work best on the data

**BAD:**  $K = 1$  always works perfectly on training data



**Idea #2:** Split data into **train** and **test**, choose hyperparameters that work best on test data

**BAD:** No idea how algorithm will perform on new data



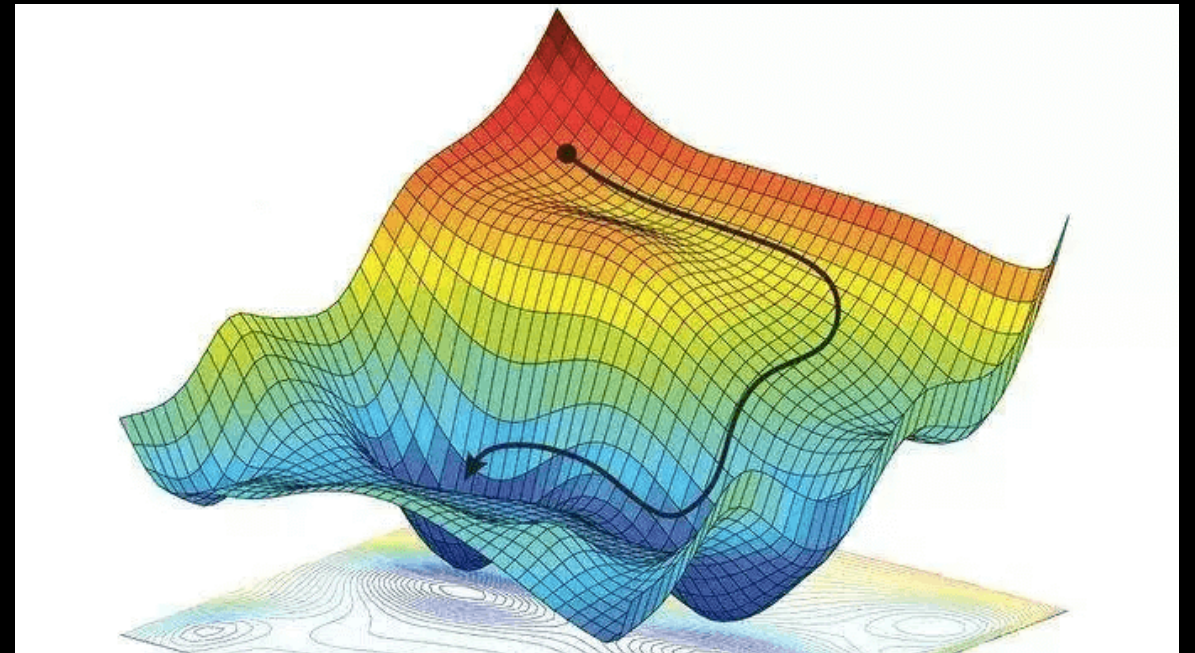
**Idea #3:** Split data into **train**, **val**, and **test**; choose hyperparameters on val and evaluate on test

**Better!**



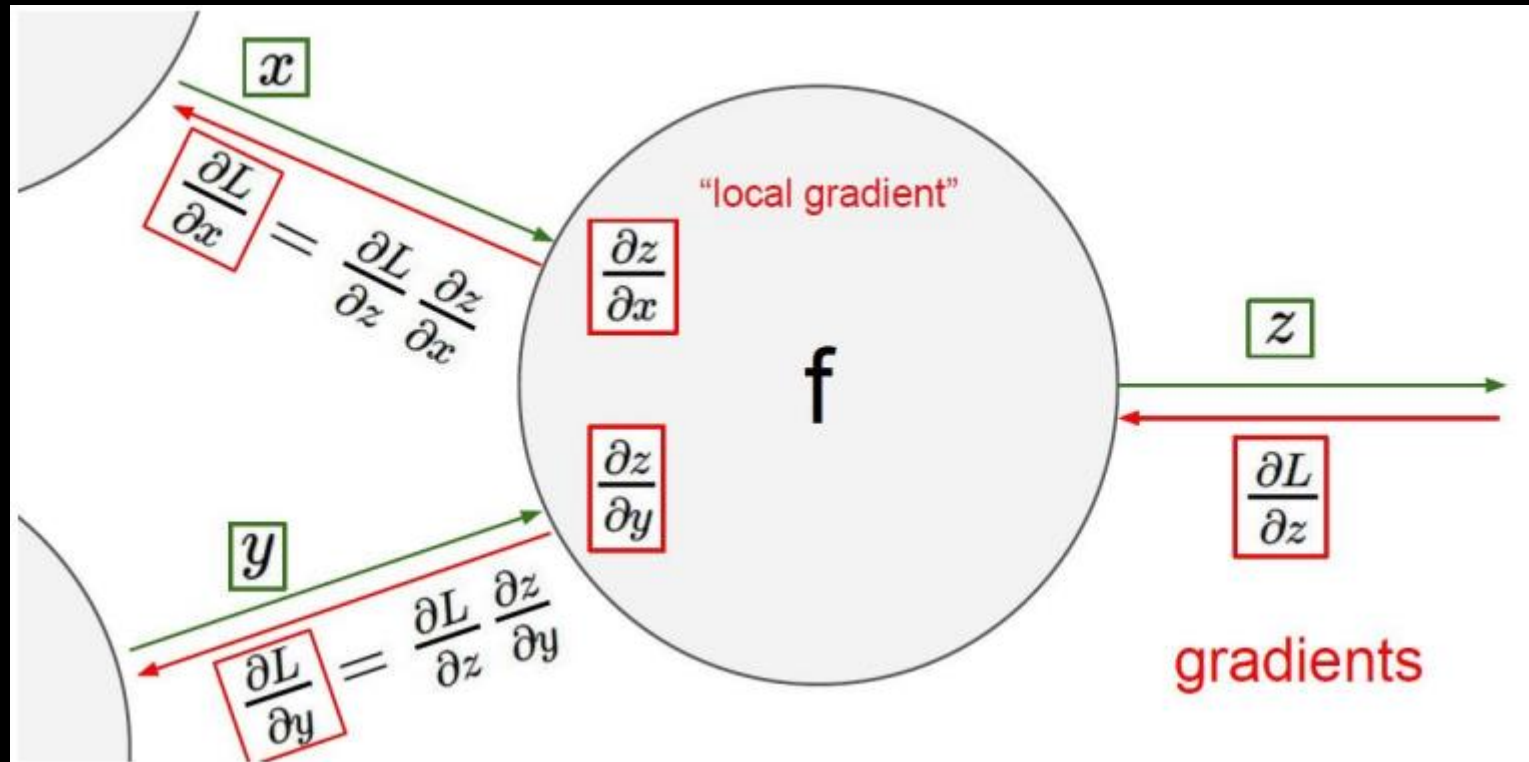
# Gradient descent

- Find the minimum of a function
- Iteratively search for a minimum
- Rolling down the hill
- The direction of the fastest descends



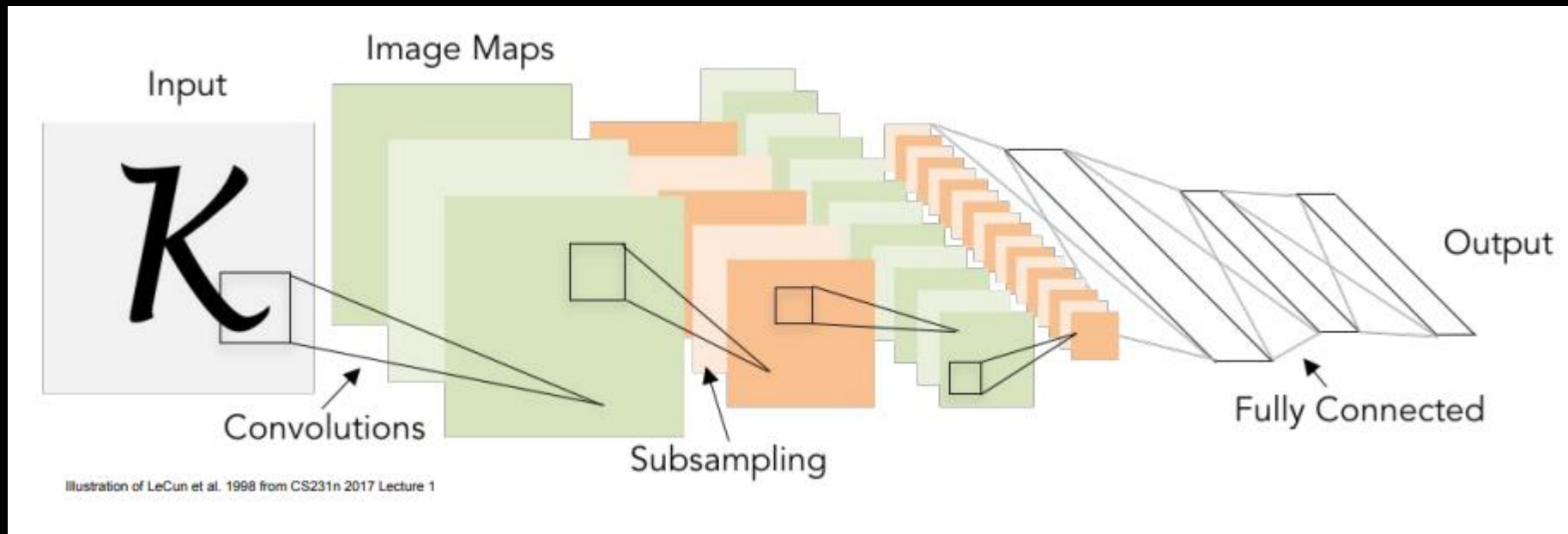
# Backpropagation

- Global optimization problem
- Fine tune weights



# CNN

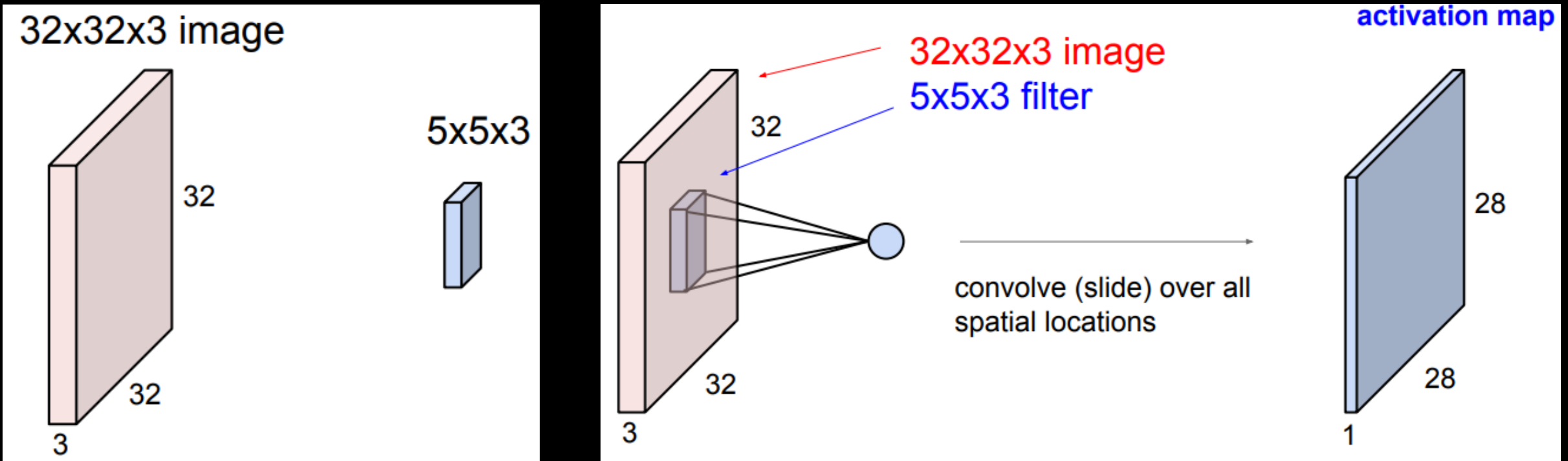
- Extensively use in Computer Vision tasks
- Raw signals (voice, images, ...)
- ConvNets stack CONV, POOL, FC layers



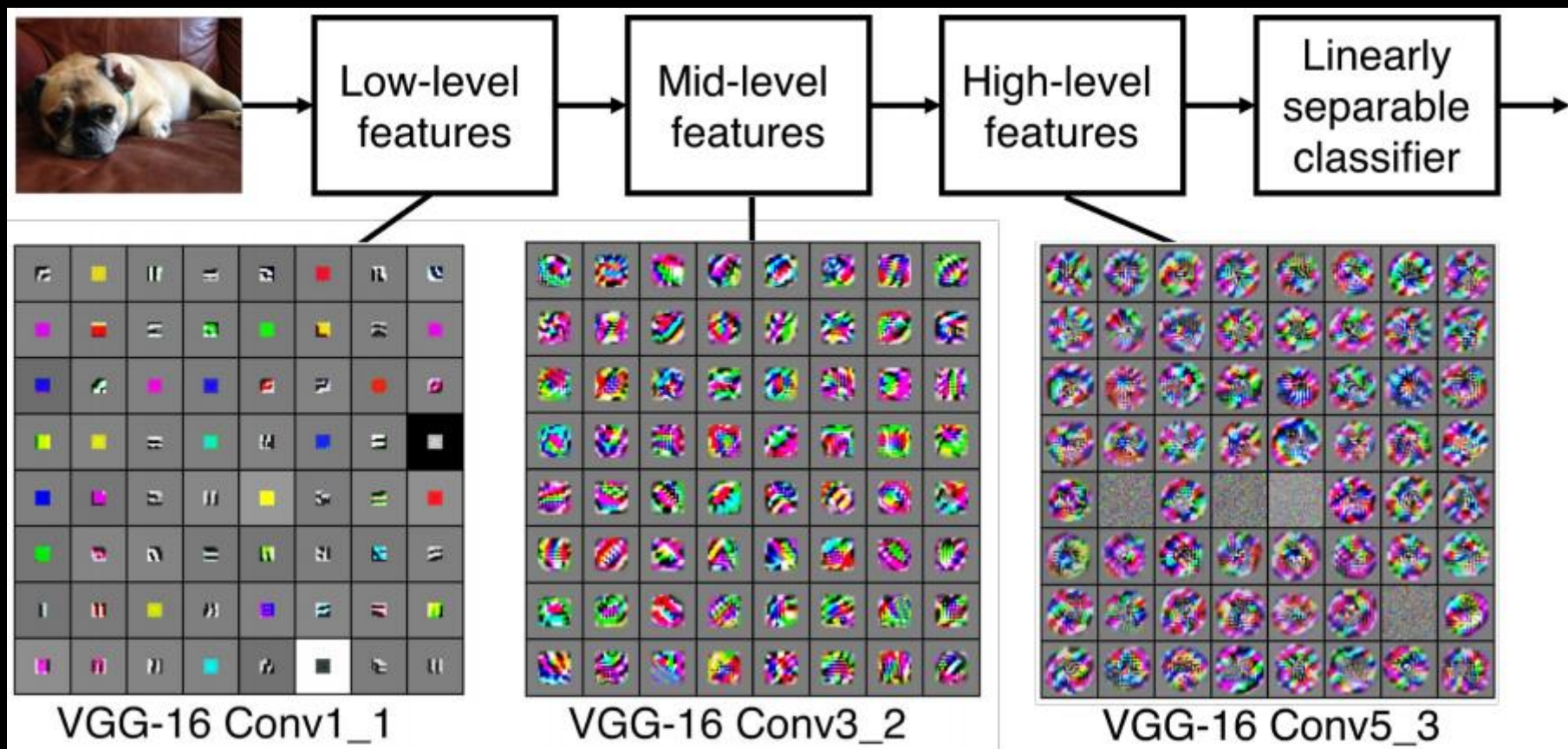


# Convolution layers

- **Convolve** the filter with the image
- “slide over the image spatially, computing dot products”

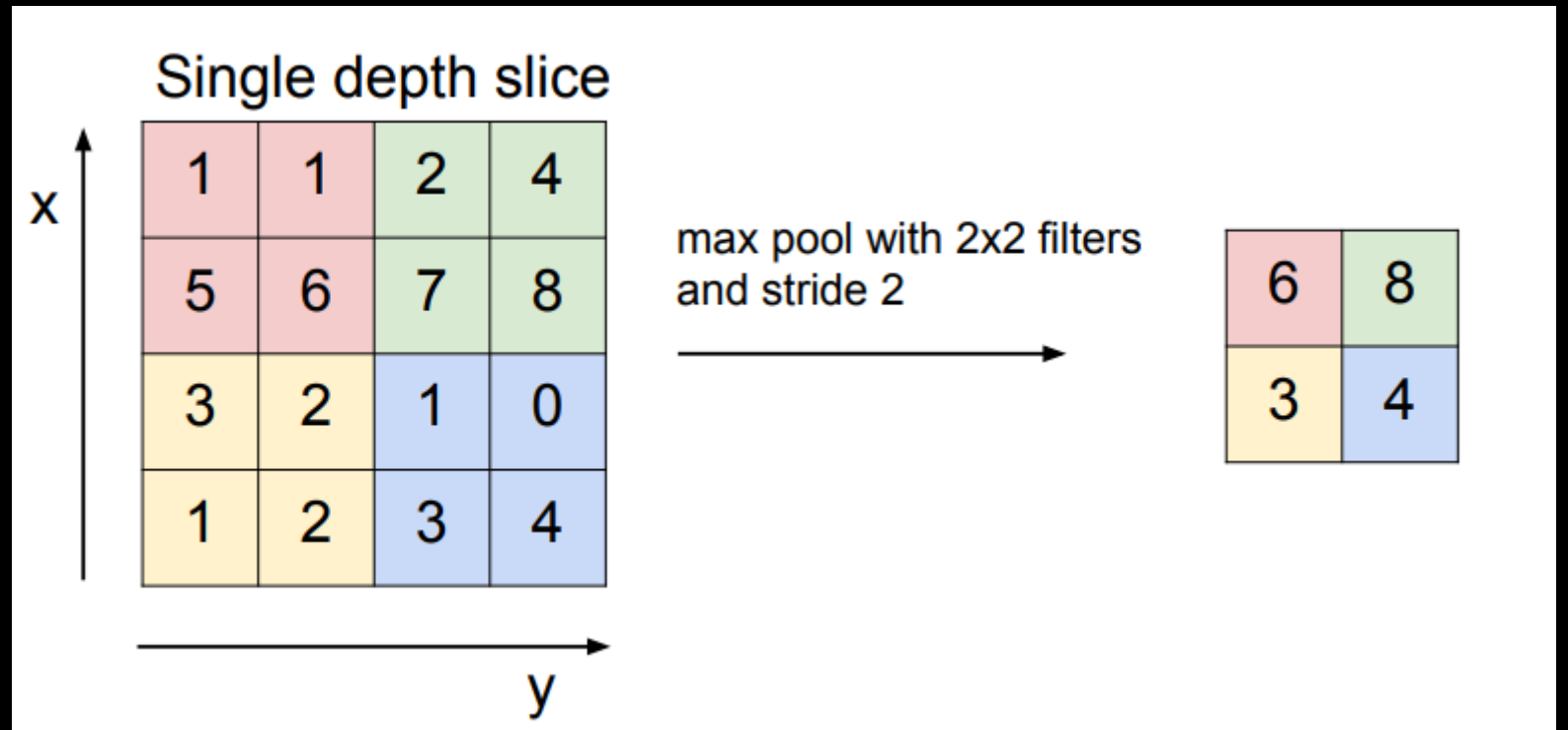


# Convolution layers



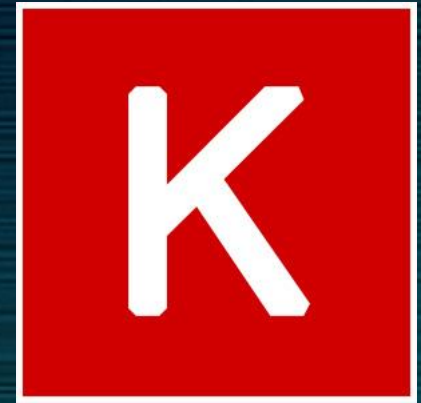
# Pooling layers

- Max Pooling, Average Pooling, etc.
- Makes the representations smaller and more manageable



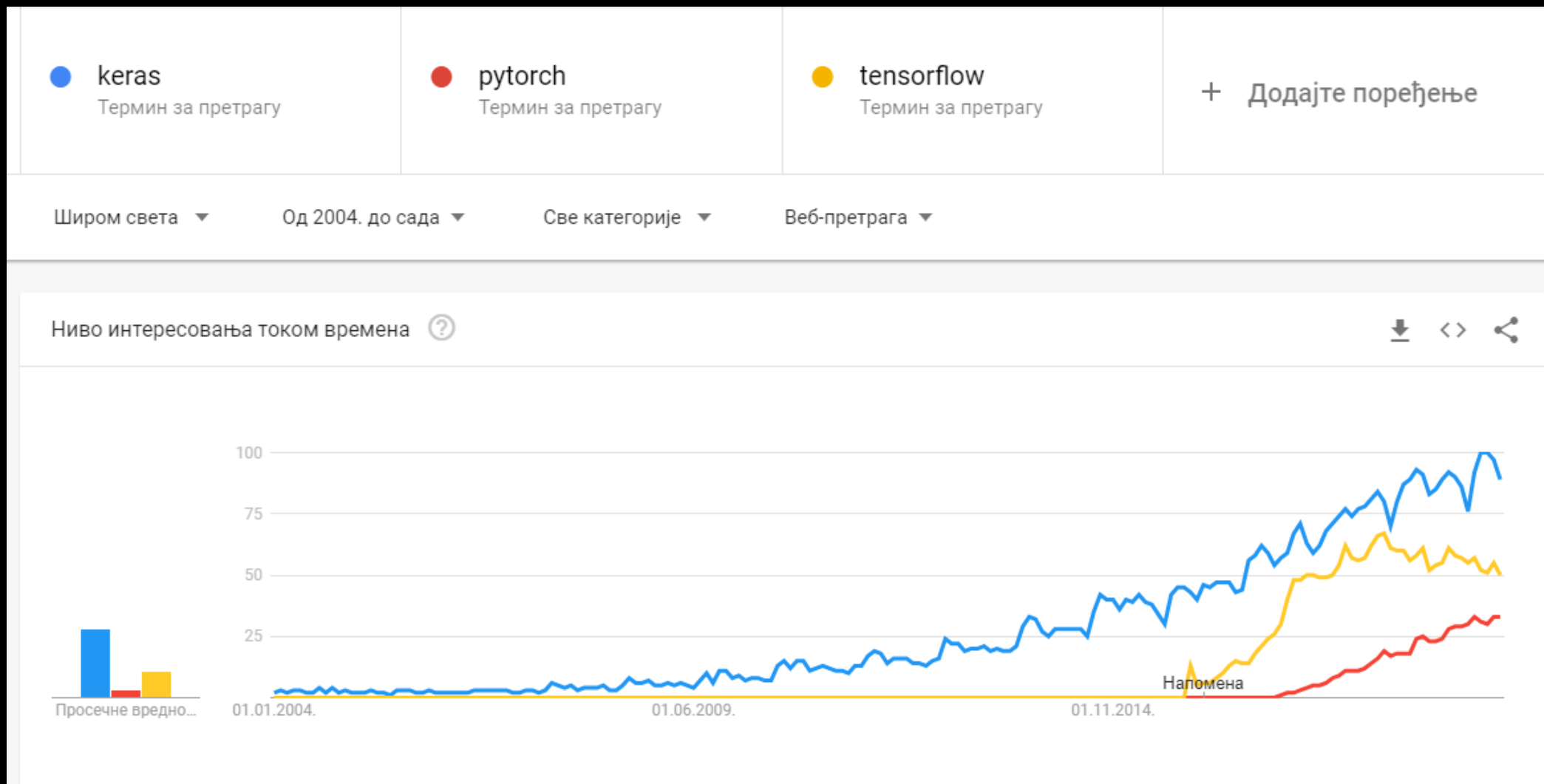
# Keras Library

[keras.io](https://keras.io)

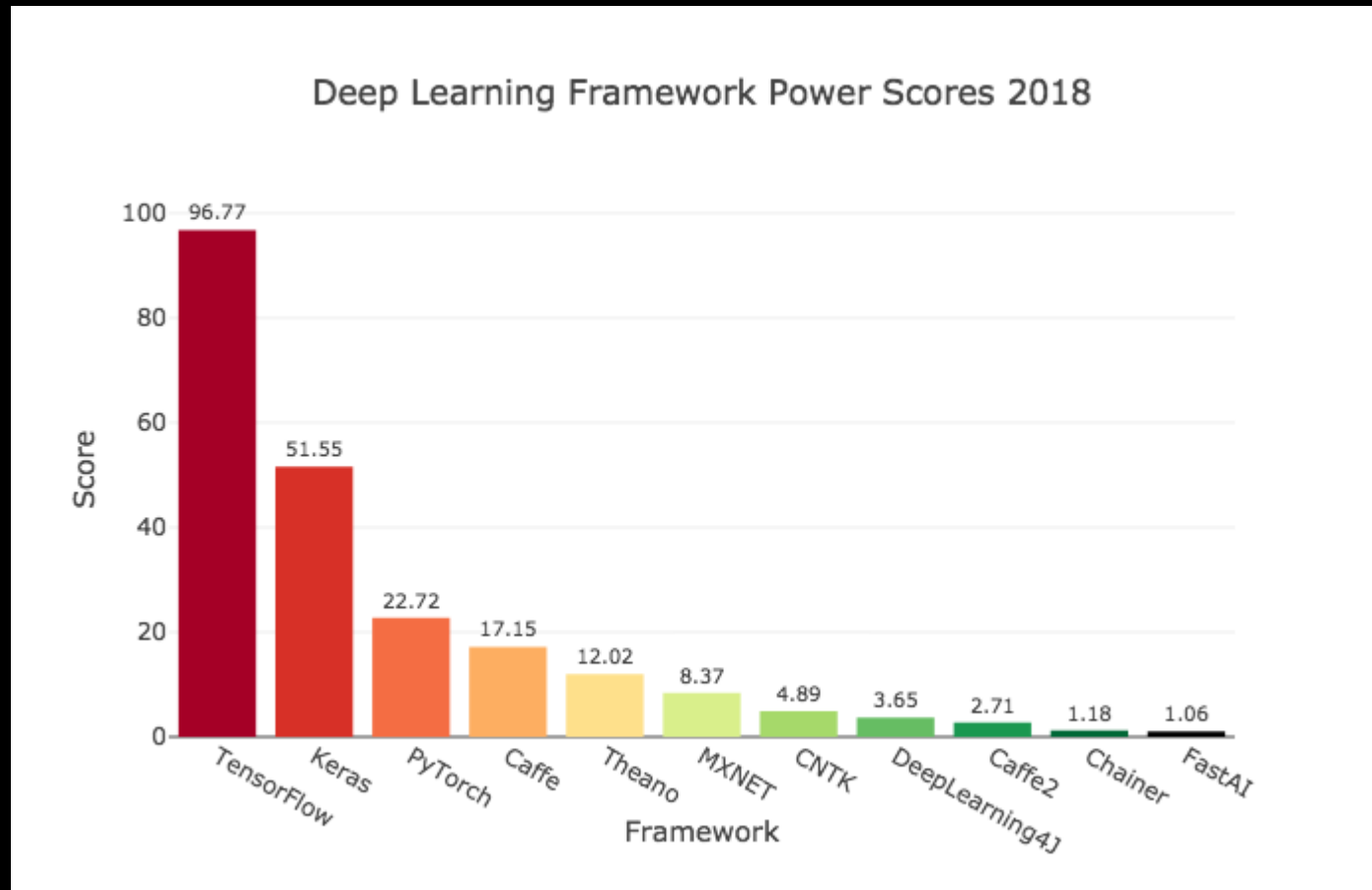




# Keras (κέρας)



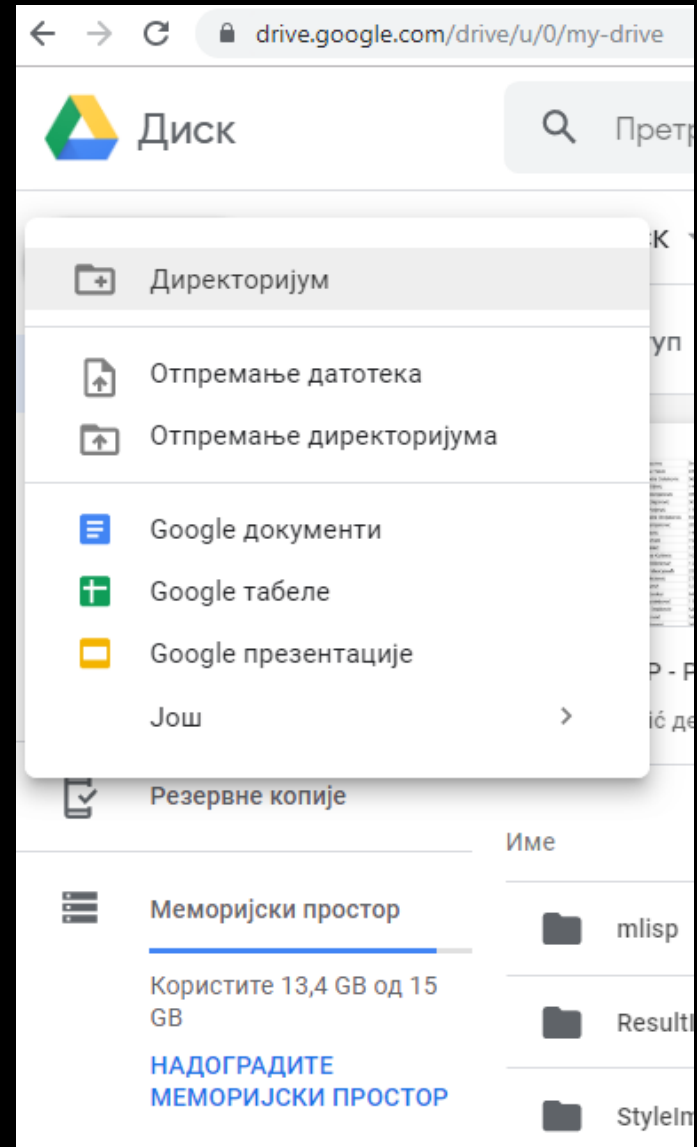
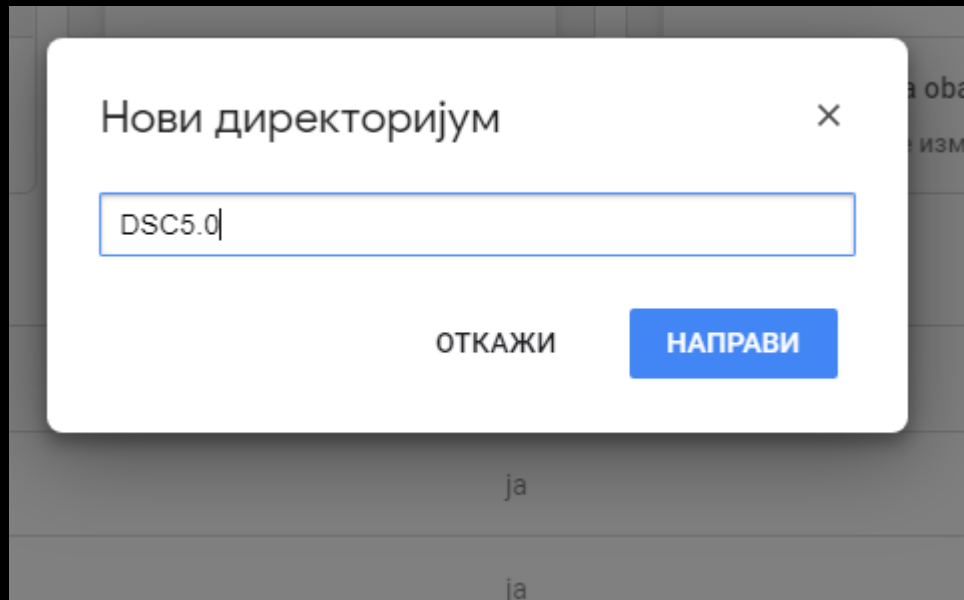
# Without cheating



- Why Keras?
  - powerful
  - easy-to-use
  - open source

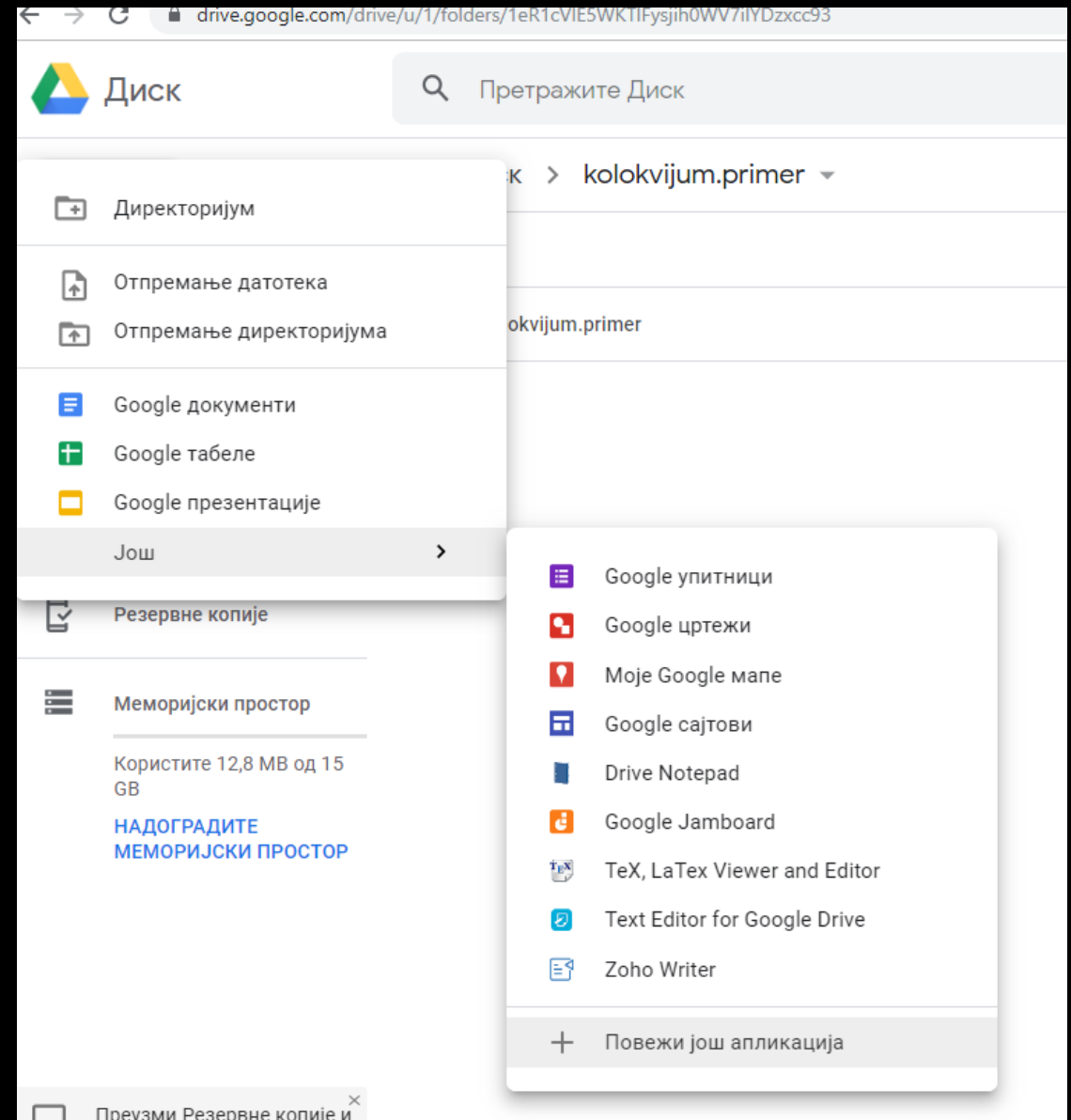
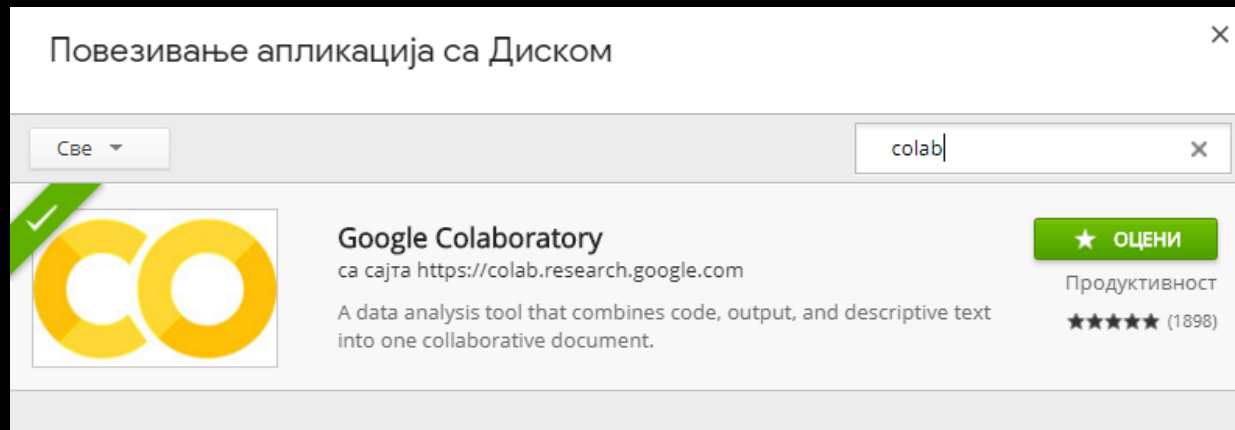
# Condensing time

- Go to [drive.google.com/](https://drive.google.com/)
- Create new folder



# Coding time

- Connect with Google Colab
- Go to: [colab.research.google.com/](https://colab.research.google.com/)
- Enjoy coding!



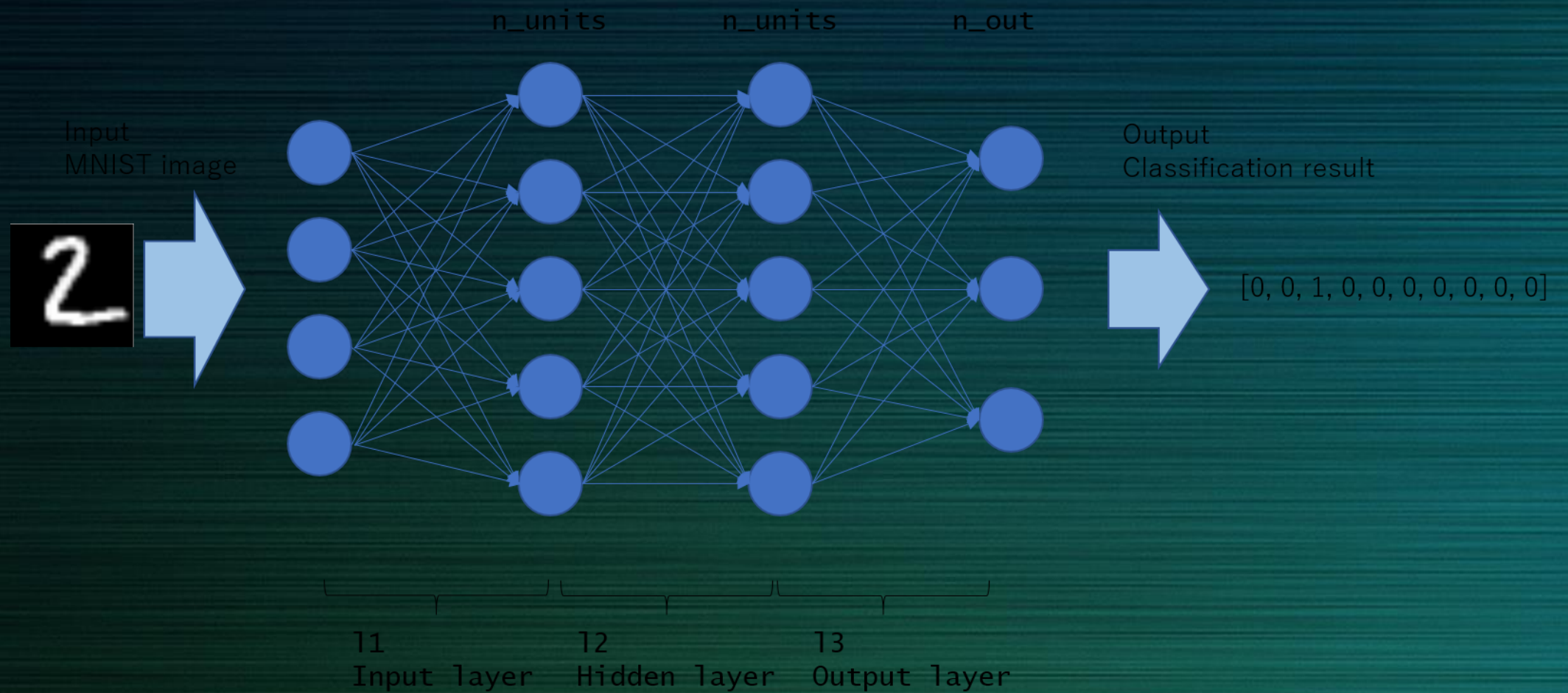




## Example 1

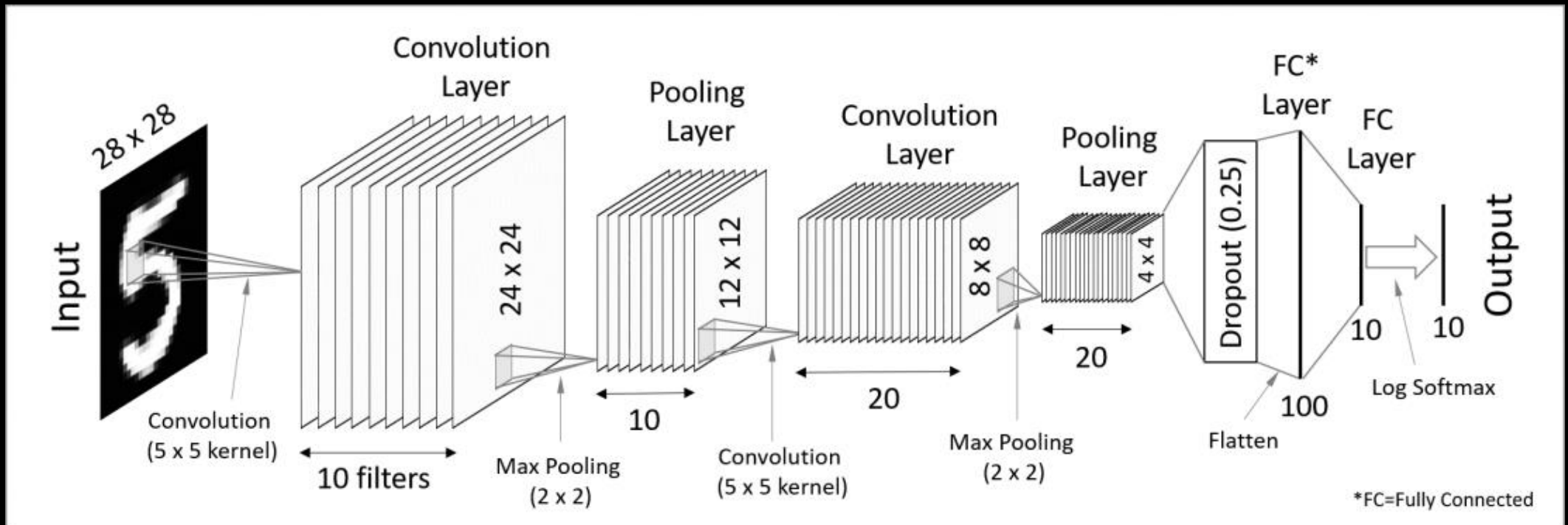
- Pima Indians onset of diabetes dataset
- Predict diabetes

## Example 2



## Example 3

- Ex2\_MNIST\_CNN.ipynb
- Trains a simple ConvNet on the MNIST dataset.
- Gets to 99.25% test accuracy after 12 epochs





# Thank you

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- [github.com/MilanCugur](https://github.com/MilanCugur)