

# Visual Odometry Pipeline

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## Sandbox



Figure 1: Cute pig image

## Symbols, Nomenclature

## Introduction

VO, sequential, monocular, markov assumption

## Implementation

### Framework

Coordinate Frames

Pipeline overview

Flow chart

Options and parameters

parameter handling, GUI

### Initialization

Continuous Operation

## Results

### Overall performance

Real time ness, comparison to groundtruth, compare different datasets Impact of features

## Discussion

What have we learned, what worked?

Possible future work, improvements (loop closure, ...)

## Conclusion