## Visual Odometry Pipeline

## Sandbox

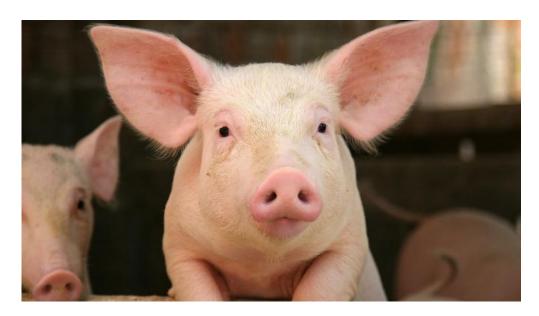
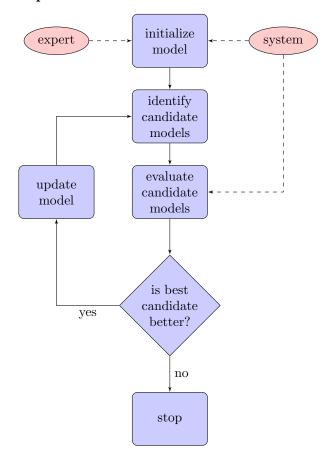


Figure 1: Pig image

## Pipeline overview



 ${\bf Monocular\ initialization}$   ${\bf Continuous\ Operation}$