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Atliko:

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1. C++ arba Ruby(L1)

1.1. Darbo užduotis

Some school children discovered that by getting on a weighing machine in couples, and then exchanging places—one at a time—they could get the correct weight of a whole party on the payment of but one cent. They found that in couples they weighed (in pounds): 129, 125, 124, 123, 122, 121, 120, 118, 116 and 114. What was the weight of each one of the five little girls if taken separately?

It proves that they must have been clever scholars or they never would have been able to work out the correct answer to such an interesting puzzle question, which is liable to confuse older heads than theirs.



Guess the weights of the girls

Given a list of 10 integers, representing the weights of each couple formed from a group of 5 people, determine the weights of each person.

Input

Input starts with a positive integer T , that denotes the number of test cases. Each test case is described by 10 integers W_1, W_2, \dots, W_{10} in a single line.

$T \leq 3000$; $100 \leq W_1 \leq W_2 \leq \dots \leq W_{10} \leq 400$

Output

For each test case, print the case number, followed by the 5 weights asked, separated by spaces. Print these numbers in ascending order.

Sample Input

```
3
114 116 118 120 121 122 123 124 125 129
110 111 114 115 118 118 119 122 123 126
180 190 190 196 196 206 216 216 226 232
```

Sample Output

```
Case 1: 56 58 60 64 65
Case 2: 53 57 58 61 65
Case 3: 90 90 100 106 126
```

1.2. Programos tekstas

```
#include <iostream>
#include <fstream>
#include <string>
#include <chrono>

using namespace std;
using namespace std::chrono;

class AllWeight{
public:
```

```

int getWeight(int i)
{
    return weights[i];
}

void set(int i, int data)
{
    weights[i] = data;
}

void sort()
{
    int temp;

    for(int i=0; i<(10-1); i++)
    {
        for(int j=0; j<(10-i-1); j++)
        {
            if(weights[j]>weights[j+1])
            {
                temp = weights[j];
                weights[j] = weights[j+1];
                weights[j+1] = temp;
            }
        }
    }
}

```

private:

```

int weights[10];

```

```

};

```

```

class FinalWeight{
public:

```

```

    int getWeight(int i)
    {
        return weights[i];
    }

```

```

    void set(int i, int data)
    {
        weights[i] = data;
    }

```

```

    void sort()
    {
        int temp;

        for(int i=0; i<(5-1); i++)

```

```

        {
            for(int j=0; j<(5-i-1); j++)
            {
                if(weights[j]>weights[j+1])
                {
                    temp = weights[j];
                    weights[j] = weights[j+1];
                    weights[j+1] = temp;
                }
            }
        }
    }

    void printData()
    {
        for(int i = 0; i < 5; i++)
        {
            cout << weights[i] << " ";
        }
    }

private:
    int weights[5];
};

int main()
{
    int n;
    ifstream fin;
    fstream fout;

    fin.open("data.txt");
    auto chronoStart = chrono::system_clock::now();
    fin >> n;
    AllWeight foo[n];

    int tempValue;
    for(int i = 0; i < n; i++)
    {
        for (int j = 0; j < 10; j++)
        {
            fin >> tempValue;
            foo[i].set(j, tempValue);
        }
    }

    int bendras_sv[n] {0, 0, 0};

    for(int i = 0; i < n; i++)
    {

```

```

        for(int j = 0; j < 10; j++)
        {
            bendras_sv[i] += foo[i].getWeight(j);
        }
        bendras_sv[i] = bendras_sv[i]/4; //rastas tikras svoris
    }

    for(int i = 0; i < n; i++)
    {
        foo[i].sort();
    }

    int aa[n]; //sunkiausia pora
    int bb[n]; //lengviausia pora
    int ab[n]; //antra pagal sunkuma pora
    int ba[n]; //antra pagal lengvuma pora

    for (int i = 0; i < n; i++) //Masyvas yra isrikiuotas todel galime naudoti tikslius skaicius
    {
        aa[i] = foo[i].getWeight(9);
        bb[i] = foo[i].getWeight(0);
        ab[i] = foo[i].getWeight(8);
        ba[i] = foo[i].getWeight(1);
    }

    FinalWeight svoriai[n];

    for(int i = 0; i < n; i++)
    {
        svoriai[i].set(0, bendras_sv[i] - aa[i] - bb[i]);
        svoriai[i].set(1, ba[i] - svoriai[i].getWeight(0));
        svoriai[i].set(2, bb[i] - svoriai[i].getWeight(1));
        svoriai[i].set(3, ab[i] - svoriai[i].getWeight(0));
        svoriai[i].set(4, aa[i] - svoriai[i].getWeight(3));
    }

    for(int i = 0; i < n; i++)
    {
        svoriai[i].sort();
    }

    fout.open("results.txt");

    for(int i = 0; i < n; i++)
    {
        fout << "Case " << i + 1 << ": ";
        for(int j = 0; j < 5; j++)
        {
            fout << svoriai[i].getWeight(j) << " ";
        }
        fout << endl;
    }

```

```

}

//Ends the clock
auto chronoEnd = chrono::system_clock::now();
auto elapsed = std::chrono::duration_cast<std::chrono::microseconds>(chronoEnd -
chronoStart);
//Writes time taken
cout << "Program Finished" << endl;
cout << "Time Elapsed in microseconds: " << elapsed.count() << endl;

fin.close(); fout.close();
return 0;
}

```

1.3. Pradiniai duomenys ir rezultatai

„data.txt“

```

≡ data.txt
1    3
2    114 116 118 120 121 122 123 124 125 129
3    110 111 114 115 118 118 119 122 123 126
4    180 190 190 196 196 206 216 216 226 232

```

„results.txt“

```

≡ results.txt
1    Case 1: 56 58 60 64 65
2    Case 2: 53 57 58 61 65
3    Case 3: 90 90 100 106 126
4

```

2. Scala (L2)

2.1. Boto kodas

```

import scalatron.botwar.botPlugin._

object ControlFunction
{
    import util.Random
    val rnd = new Random()

    def forMaster(bot: Bot) {
        //Analyzes grid
        val (enemiesInVision, myOwnSlavesInVision, directionValue, nearestEnemyMaster, nearestEnemySlave,
nearestBeast) = analyzeViewAsMaster(bot.view)

        //Inputs
        val dontFireAggressiveMissileUntil = bot.inputAsIntOrElse("dontFireAggressiveMissileUntil", -1)
        val dontFireDefensiveMissileUntil = bot.inputAsIntOrElse("dontFireDefensiveMissileUntil", -1)
    }
}

```

```

val lastDirection = bot.inputAsIntOrElse("lastDirection", 0)

// Determine movement direction
directionValue(lastDirection) += 10 // try to break ties by favoring the last direction
val bestDirection45 = directionValue.zipWithIndex.maxBy(_._1)._2
val direction = XY.fromDirection45(bestDirection45)
bot.move(direction)
bot.set("lastDirection" -> bestDirection45)

// fire attack missile?
if(dontFireAggressiveMissileUntil < bot.time && bot.energy > 100) {
    nearestEnemyMaster match {
        case None => // no-on nearby
        case Some(relPos) => // a master is nearby
            val unitDelta = relPos.signum
            val remainder = relPos - unitDelta // we place slave nearer target, so subtract that from overall delta
            bot.spawn(unitDelta, "mood" -> "Aggressive", "target" -> remainder)
            bot.set("dontFireAggressiveMissileUntil" -> (bot.time + relPos.stepCount + 1))
    }
}
else
// fire defensive missile?
if(dontFireDefensiveMissileUntil < bot.time && bot.energy > 100) {
    nearestEnemySlave match {
        case None => // no-on nearby
        case Some(relPos) => // an enemy slave is nearby
            if(relPos.stepCount < 8) {
                // this one's getting too close!
                val unitDelta = relPos.signum
                val remainder = relPos - unitDelta // we place slave nearer target, so subtract that from overall
                bot.spawn(unitDelta, "mood" -> "Defensive", "target" -> remainder)
                bot.set("dontFireDefensiveMissileUntil" -> (bot.time + relPos.stepCount + 1))
            }
    }
}

// Make a slave to defend against beasts?
if(enemiesInVision >= 3 && bot.energy >= 100 && myOwnSlavesInVision < 5) {
    nearestBeast match {
        case None => // no-on nearby
        case Some(relPos) => // a beast is nearby
            if(relPos.stepCount < 5) {
                // A breast is close, make a slave
                val chance1 = rnd.nextInt(3)
                var chance2 = rnd.nextInt(3)-1
                val chance3 = rnd.nextInt(3)-1
                if(chance2 == 0 && chance3 == 0){
                    chance2 = 1
                }
                chance1 match {
                    case 0 =>
                        bot.spawn(XY(chance2,chance3), "mood" -> "Mine")
                    case 1 =>
                        bot.spawn(XY(chance2,chance3), "mood" -> "Bomb")
                    case 2 =>
                        bot.spawn(XY(chance2,chance3), "mood" -> "Bait")
                    case default =>
                        throw new IllegalStateException("Error: " + default)
                }
            }
    }
}

```



```

        }
        bot.say("Made a new slave")
    }
}

// Logs
bot.log("Owned slaves on screen - " + myOwnSlavesInVision.toString)
bot.log("Number of enemies on screen - " + enemiesInVision.toString)
}

def forSlave(bot: MiniBot) {
    bot.inputOrElse("mood", "Lurking") match {
        case "Bomb" => reactAsBomb(bot)
        case "Mine" => reactAsMine(bot)
        case "Bait" => reactAsBait(bot)
        case "Aggressive" => reactAsAggressiveMissile(bot)
        case "Defensive" => reactAsDefensiveMissile(bot)
        case s: String => bot.log("Error: " + s)
    }
}

def reactAsBait(bot: MiniBot) {
    val dx = rnd.nextInt(3)-1
    val dy = rnd.nextInt(3)-1
    bot.move(XY(dx,dy))
}

def reactAsBomb(bot: MiniBot) {
    bot.explode(4)
}

def reactAsMine(bot: MiniBot) {
    bot.view.offsetToNearest('b') match {
        case Some(delta: XY) =>
            if(delta.length <= 2) {
                bot.explode(4)
            }
    }
}

def reactAsAggressiveMissile(bot: MiniBot) {
    bot.view.offsetToNearest('m') match {
        case Some(delta: XY) =>
            // another master is visible at the given relative position (i.e. position delta)

            // close enough to blow it up?
            if(delta.length <= 2) {
                // yes -- blow it up!
                bot.explode(4)

            } else {
                // no -- move closer!
                bot.move(delta.signum)
                bot.set("rx" -> delta.x, "ry" -> delta.y)
            }
        case None =>
            // no target visible -- follow our targeting strategy
            val target = bot.inputAsXYOrElse("target", XY.Zero)
    }
}

```

```

    // did we arrive at the target?
    if(target.isNonZero) {
        // no -- keep going
        val unitDelta = target.signum // e.g. CellPos(-8,6) => CellPos(-1,1)
        bot.move(unitDelta)

        // compute the remaining delta and encode it into a new 'target' property
        val remainder = target - unitDelta // e.g. = CellPos(-7,5)
        bot.set("target" -> remainder)
    } else {
        // yes -- but we did not detonate yet, and are not pursuing anything?!? => switch purpose
        bot.set("mood" -> "Lurking", "target" -> "")
        bot.say("Lurking")
    }
}

def reactAsDefensiveMissile(bot: MiniBot) {
    bot.view.offsetToNearest('s') match {
        case Some(delta: XY) =>
            // another slave is visible at the given relative position (i.e. position delta)
            // move closer!
            bot.move(delta.signum)
            bot.set("rx" -> delta.x, "ry" -> delta.y)

        case None =>
            // no target visible -- follow our targeting strategy
            val target = bot.inputAsXYOrElse("target", XY.Zero)

            // did we arrive at the target?
            if(target.isNonZero) {
                // no -- keep going
                val unitDelta = target.signum // e.g. CellPos(-8,6) => CellPos(-1,1)
                bot.move(unitDelta)

                // compute the remaining delta and encode it into a new 'target' property
                val remainder = target - unitDelta // e.g. = CellPos(-7,5)
                bot.set("target" -> remainder)
            } else {
                // yes -- but we did not annihilate yet, and are not pursuing anything?!? => switch purpose
                bot.set("mood" -> "Lurking", "target" -> "")
                bot.say("Lurking")
            }
    }
}

/** Analyze the view, building a map of attractiveness for the 45-degree directions and
 * recording other relevant data, such as the nearest elements of various kinds.
 */
def analyzeViewAsMaster(view: View) = {
    //Enemies in vision
    var enemiesInVision = 0;
    var myOwnSlavesInVision = 0;
    //Directional values
    val directionValue = Array.ofDim[Double](8)
    //Nearest dangers

```

```

var nearestEnemyMaster: Option[XY] = None
var nearestEnemySlave: Option[XY] = None
var nearestBeast: Option[XY] = None

//Take all cells
val cells = view.cells
val cellCount = cells.length

for(i <- 0 until cellCount) {
  val currentCellRelPos = view.relPosFromIndex(i)
  if(currentCellRelPos.isNonZero) {
    val stepDistance = currentCellRelPos.stepCount
    val value: Double = cells(i) match {
      case 'm' => // another master: not dangerous, but an obstacle
        nearestEnemyMaster = Some(currentCellRelPos)
        enemiesInVision = 1
        if(stepDistance < 7) -2500 else 0
      case 's' => // another slave: potentially dangerous?
        nearestEnemySlave = Some(currentCellRelPos)
        enemiesInVision += 1
        -1000 / stepDistance
      case 'S' => // out own slave
        myOwnSlavesInVision += 1
        10.0
      case 'B' => // good beast: valuable, but runs away
        if(stepDistance == 1) 600
        else if(stepDistance == 2) 300
        else (150 - stepDistance * 15).max(10)

      case 'P' => // good plant: less valuable, but does not run
        if(stepDistance == 1) 500
        else if(stepDistance == 2) 300
        else (150 - stepDistance * 10).max(10)

      case 'b' => // bad beast: dangerous, but only if very close
        nearestBeast = Some(currentCellRelPos)
        enemiesInVision += 1
        if(stepDistance < 5) -600 / stepDistance else -200 / stepDistance

      case 'p' => // bad plant: bad, but only if I step on it
        if(stepDistance < 3) -1000 else 0

      case 'W' => // wall: harmless, just don't walk into it
        if(stepDistance < 4) -1000 else 0

      case _ => 0.0
    }
    val direction45 = currentCellRelPos.toDirection45
    directionValue(direction45) += value
  }
}

//BFS path finding algorithm
import java.util.ArrayDeque
if (cells.contains('B') || cells.contains('P')) {
  //Make an array to store distance
  val distanceArray = Array.ofDim[Double](cellCount)
  for (i <- 0 until cellCount) {
    cells(i) match {
      case 'P' =>

```

```

        //Saves the distance to a plant
        val cellRelPos = view.relPosFromIndex(i)
        if (cellRelPos.isNonZero) {
            val stepDistance = cellRelPos.stepCount
            distanceArray(i) += stepDistance
        }
        //Saves the distance to a beast
        case 'B' =>
            val cellRelPos = view.relPosFromIndex(i)
            if (cellRelPos.isNonZero) {
                val stepDistance = cellRelPos.stepCount
                distanceArray(i) += stepDistance
            }
        case default =>
    }
}
//Find the destination
val destination = view.relPosFromIndex(distanceArray.indexOf(distanceArray.filter(_ != 0).min))
//Directions
val dirVector = Vector(XY.Up, XY.RightUp, XY.Right, XY.DownRight, XY.Down, XY.LeftDown,
XY.Left, XY.UpLeft)
//an empty queue to store a list of positions that represent the path to reach the destination
val aq = new ArrayDeque[List[XY]]()
//a list of positions as the shortest path
var path: Option[List[XY]] = None
//current position of the agent
var visited = Set[XY](XY.Zero)
//adds the starting position
aq.add(List(XY.Zero))
// looping the queue while its not empty and the path variable is still 'None'
while (!aq.isEmpty && path.isEmpty) {
    val steps@(point :: _) = aq.pop()
    //Check all possible directions
    for (dir <- dirVector) {
        //Gets the new location
        val dirTarget = point + dir
        val cell = view.cellAtRelPos(dirTarget)
        //If nothing is blocking the way
        if (cell != 'W' && cell != 'm' && cell != 's' && cell != 'b' && cell != 'p' && !visited(dirTarget))
        {
            //Add it to the queue or the path if the destination is reached
            if (dirTarget == destination)
            {
                path = Some(dirTarget :: steps)
            }
            else
            {
                visited += dirTarget
                aq.add(dirTarget :: steps)
            }
        }
    }
}
if(path.get.size < 5){
    directionValue(path.get(path.get.size - 2).toDirection45) += 10000
}
else if(path.get.size < 8){
    directionValue(path.get(path.get.size - 2).toDirection45) += 5000
}
}

```

```

        else{
            directionValue(path.get(path.get.size - 2).toDirection45) += 2500
        }
    }
    (enemiesInVision, myOwnSlavesInVision, directionValue, nearestEnemyMaster, nearestEnemySlave,
nearestBeast)
    }
}

// -----
// Framework
// -----

class ControlFunctionFactory {
    def create = (input: String) => {
        val (opcode, params) = CommandParser(input)
        opcode match {
            case "React" =>
                val bot = new BotImpl(params)
                if( bot.generation == 0 ) {
                    ControlFunction.forMaster(bot)
                } else {
                    ControlFunction.forSlave(bot)
                }
                bot.toString
            case _ => "" // OK
        }
    }
}

// -----

trait Bot {
    // inputs
    def inputOrElse(key: String, fallback: String): String
    def inputAsIntOrElse(key: String, fallback: Int): Int
    def inputAsXYOrElse(keyPrefix: String, fallback: XY): XY
    def view: View
    def energy: Int
    def time: Int
    def generation: Int

    // outputs
    def move(delta: XY) : Bot
    def say(text: String) : Bot
    def status(text: String) : Bot
    def spawn(offset: XY, params: (String,Any)*) : Bot
    def set(params: (String,Any)*) : Bot
    def log(text: String) : Bot
}

trait MiniBot extends Bot {
    // inputs
    def offsetToMaster: XY

    // outputs

```

```

def explode(blastRadius: Int) : Bot
}

case class BotImpl(inputParams: Map[String, String]) extends MiniBot {
  // input
  def inputOrElse(key: String, fallback: String) = inputParams.getOrElse(key, fallback)
  def inputAsIntOrElse(key: String, fallback: Int) = inputParams.get(key).map(_.toInt).getOrElse(fallback)
  def inputAsXYOrElse(key: String, fallback: XY) = inputParams.get(key).map(s => XY(s)).getOrElse(fallback)

  val view = View(inputParams("view"))
  val energy = inputParams("energy").toInt
  val time = inputParams("time").toInt
  val generation = inputParams("generation").toInt
  def offsetToMaster = inputAsXYOrElse("master", XY.Zero)

  // output

  private var stateParams = Map.empty[String, Any] // holds "Set()" commands
  private var commands = "" // holds all other commands
  private var debugOutput = "" // holds all "Log()" output

  /** Appends a new command to the command string; returns 'this' for fluent API. */
  private def append(s: String) : Bot = { commands += (if(commands.isEmpty) s else "|" + s); this }

  /** Renders commands and stateParams into a control function return string. */
  override def toString = {
    var result = commands
    if(!stateParams.isEmpty) {
      if(!result.isEmpty) result += "|"
      result += stateParams.map(e => e._1 + "=" + e._2).mkString("Set(", ", ", ")")
    }
    if(!debugOutput.isEmpty) {
      if(!result.isEmpty) result += "|"
      result += "Log(text=" + debugOutput + ")"
    }
    result
  }

  def log(text: String) = { debugOutput += text + "\n"; this }
  def move(direction: XY) = append("Move(direction=" + direction + ")")
  def say(text: String) = append("Say(text=" + text + ")")
  def status(text: String) = append("Status(text=" + text + ")")
  def explode(blastRadius: Int) = append("Explode(size=" + blastRadius + ")")
  def spawn(offset: XY, params: (String, Any)*) =
    append("Spawn(direction=" + offset +
      (if(params.isEmpty) "" else ", " + params.map(e => e._1 + "=" + e._2).mkString(", ")) +
      ")")
  def set(params: (String, Any)*) = { stateParams ++= params; this }
  def set(keyPrefix: String, xy: XY) = { stateParams ++= List(keyPrefix+"x" -> xy.x, keyPrefix+"y" -> xy.y);
this }
}

// -----

```

```

/** Utility methods for parsing strings containing a single command of the format
 * "Command(key=value,key=value,...)"
 */
object CommandParser {
  /** "Command(.." => ("Command", Map( ("key" -> "value"), ("key" -> "value"), ..)) */
  def apply(command: String): (String, Map[String, String]) = {
    /** "key=value" => ("key","value") */
    def splitParameterIntoKeyValue(param: String): (String, String) = {
      val segments = param.split('=')
      (segments(0), if(segments.length>=2) segments(1) else "")
    }

    val segments = command.split('(')
    if( segments.length != 2 )
      throw new IllegalStateException("invalid command: " + command)
    val opcode = segments(0)
    val params = segments(1).dropRight(1).split(',')
    val keyValuePairs = params.map(splitParameterIntoKeyValue).toMap
    (opcode, keyValuePairs)
  }
}

// -----

/** Utility class for managing 2D cell coordinates.
 * The coordinate (0,0) corresponds to the top-left corner of the arena on screen.
 * The direction (1,-1) points right and up.
 */
case class XY(x: Int, y: Int) {
  override def toString = x + ":" + y

  def isNonZero = x != 0 || y != 0
  def isZero = x == 0 && y == 0
  def isNonNegative = x >= 0 && y >= 0

  def updateX(newX: Int) = XY(newX, y)
  def updateY(newY: Int) = XY(x, newY)

  def addToX(dx: Int) = XY(x + dx, y)
  def addToY(dy: Int) = XY(x, y + dy)

  def +(pos: XY) = XY(x + pos.x, y + pos.y)
  def -(pos: XY) = XY(x - pos.x, y - pos.y)
  def *(factor: Double) = XY((x * factor).intValue, (y * factor).intValue)

  def distanceTo(pos: XY): Double = (this - pos).length // Phythagorean
  def length: Double = math.sqrt(x * x + y * y) // Phythagorean

  def stepsTo(pos: XY): Int = (this - pos).stepCount // steps to reach pos: max delta X or Y
  def stepCount: Int = x.abs.max(y.abs) // steps from (0,0) to get here: max X or Y

  def signum = XY(x.signum, y.signum)

  def negate = XY(-x, -y)
  def negateX = XY(-x, y)
  def negateY = XY(x, -y)
}

```

```

/** Returns the direction index with 'Right' being index 0, then clockwise in 45 degree steps. */
def toDirection45: Int = {
  val unit = signum
  unit.x match {
    case -1 =>
      unit.y match {
        case -1 =>
          if(x < y * 3) Direction45.Left
          else if(y < x * 3) Direction45.Up
          else Direction45.UpLeft
        case 0 =>
          Direction45.Left
        case 1 =>
          if(-x > y * 3) Direction45.Left
          else if(y > -x * 3) Direction45.Down
          else Direction45.LeftDown
      }
    case 0 =>
      unit.y match {
        case 1 => Direction45.Down
        case 0 => throw new IllegalArgumentException("cannot compute direction index for (0,0)")
        case -1 => Direction45.Up
      }
    case 1 =>
      unit.y match {
        case -1 =>
          if(x > -y * 3) Direction45.Right
          else if(-y > x * 3) Direction45.Up
          else Direction45.RightUp
        case 0 =>
          Direction45.Right
        case 1 =>
          if(x > y * 3) Direction45.Right
          else if(y > x * 3) Direction45.Down
          else Direction45.DownRight
      }
  }
}

def rotateCounterClockwise45 = XY.fromDirection45((signum.toDirection45 + 1) % 8)
def rotateCounterClockwise90 = XY.fromDirection45((signum.toDirection45 + 2) % 8)
def rotateClockwise45 = XY.fromDirection45((signum.toDirection45 + 7) % 8)
def rotateClockwise90 = XY.fromDirection45((signum.toDirection45 + 6) % 8)

def wrap(boardSize: XY) = {
  val fixedX = if(x < 0) boardSize.x + x else if(x >= boardSize.x) x - boardSize.x else x
  val fixedY = if(y < 0) boardSize.y + y else if(y >= boardSize.y) y - boardSize.y else y
  if(fixedX != x || fixedY != y) XY(fixedX, fixedY) else this
}

object XY {
  /** Parse an XY value from XY.toString format, e.g. "2:3". */
  def apply(s: String) : XY = { val a = s.split(':'); XY(a(0).toInt,a(1).toInt) }

  val Zero = XY(0, 0)
  val One = XY(1, 1)
}

```



```

val Right    = XY( 1, 0)
val RightUp  = XY( 1, -1)
val Up       = XY( 0, -1)
val UpLeft   = XY(-1, -1)
val Left     = XY(-1, 0)
val LeftDown = XY(-1, 1)
val Down     = XY( 0, 1)
val DownRight = XY( 1, 1)

def fromDirection45(index: Int): XY = index match {
  case Direction45.Right => Right
  case Direction45.RightUp => RightUp
  case Direction45.Up => Up
  case Direction45.UpLeft => UpLeft
  case Direction45.Left => Left
  case Direction45.LeftDown => LeftDown
  case Direction45.Down => Down
  case Direction45.DownRight => DownRight
}

def fromDirection90(index: Int): XY = index match {
  case Direction90.Right => Right
  case Direction90.Up => Up
  case Direction90.Left => Left
  case Direction90.Down => Down
}

def apply(array: Array[Int]): XY = XY(array(0), array(1))
}

object Direction45 {
  val Right = 0
  val RightUp = 1
  val Up = 2
  val UpLeft = 3
  val Left = 4
  val LeftDown = 5
  val Down = 6
  val DownRight = 7
}

object Direction90 {
  val Right = 0
  val Up = 1
  val Left = 2
  val Down = 3
}

// -----

case class View(cells: String) {
  val size = math.sqrt(cells.length).toInt
  val center = XY(size / 2, size / 2)

```

```

def apply(relPos: XY) = cellAtRelPos(relPos)

def indexFromAbsPos(absPos: XY) = absPos.x + absPos.y * size
def absPosFromIndex(index: Int) = XY(index % size, index / size)
def absPosFromRelPos(relPos: XY) = relPos + center
def cellAtAbsPos(absPos: XY) = cells.charAt(indexFromAbsPos(absPos))

def indexFromRelPos(relPos: XY) = indexFromAbsPos(absPosFromRelPos(relPos))
def relPosFromAbsPos(absPos: XY) = absPos - center
def relPosFromIndex(index: Int) = relPosFromAbsPos(absPosFromIndex(index))
def cellAtRelPos(relPos: XY) = cells.charAt(indexFromRelPos(relPos))

def offsetToNearest(c: Char) = {
  val matchingXY = cells.view.zipWithIndex.filter(_._1 == c)
  if( matchingXY.isEmpty )
    None
  else {
    val nearest = matchingXY.map(p => relPosFromIndex(p._2)).minBy(_._length)
    Some(nearest)
  }
}

```

2.2. Išvada

Naudotas BFS kelio radimo algoritmo botas yra greitesnis už scalatron kūrėjo sukurta botą.

3. Haskell (Lab2)

3.1. Užduotis

Tri-du is a card game inspired in the popular game of Truco. The game uses a normal deck of 52 cards, with 13 cards of each suit, but suits are ignored. What is used is the value of the cards, considered as integers between 1 to 13.

In the game, each player gets three cards. The rules are simple:

- A Three of a Kind (three cards of the same value) wins over a Pair (two cards of the same value).
- A Three of a Kind formed by cards of a larger value wins over a Three of a Kind formed by cards of a smaller value.
- A Pair formed by cards of a larger value wins over a Pair formed by cards of a smaller value.

Note that the game may not have a winner in many situations; in those cases, the cards are returned to the deck, which is re-shuffled and a new game starts.

A player received already two of the three cards, and knows their values. Your task is to write a program to determine the value of the third card that maximizes the probability of that player winning the game.

Input

The input contains several test cases. In each test case, the input consists of a single line, which contains two integers A ($1 \leq A \leq 13$) and B ($1 \leq B \leq 13$) that indicates the value of the two first received cards.

Output

For each test case in the input, your program must produce a single line, containing exactly one integer, representing the value of the card that maximizes the probability of the player winning the game.

Sample Input

```
10 7
2 2
```

Sample Output

```
10
2
```

3.2. Programos kodas

```
import System.IO

maxCard :: Int -> Int -> Int
maxCard a b
  | a == b = a
  | otherwise = max a b

main :: IO ()
main = do
  contents <- getContents
  let cases = lines contents
  let results = map (\line -> let [a, b] = map read (words line) in maxCard a b) cases
```

3.3. Rezultatai

„input.txt“

```
≡ input.txt
1    10 7
2    2 2
3    3 3
4    10 1
5    11 4
6    4 13
```

Output terminale

```
PS C:\Users\milda\OneDrive\Stalinis kompiuteris\Haskell> Get-Content .\input.txt | .\TriDu
10
2
3
10
11
13
PS C:\Users\milda\OneDrive\Stalinis kompiuteris\Haskell> █
```