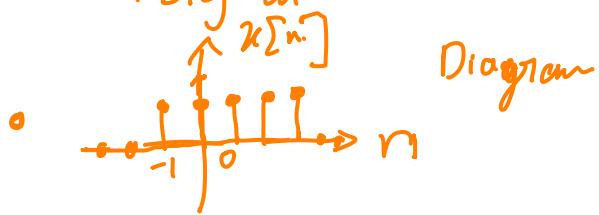


Review: Signal



- $x[n] = \begin{cases} u[n+1], & n < 4 \\ 0, & \text{else} \end{cases}$ formula

$$\bullet x[n] = [1, 1, 1, 1, 1] \quad \text{vector}$$

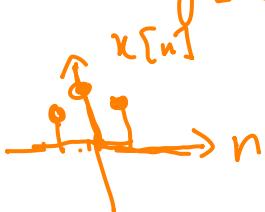
\Rightarrow Represent Signal

- disc-time
(time is point)
- cont-time
(time is continuous)

\Rightarrow Signal Classification

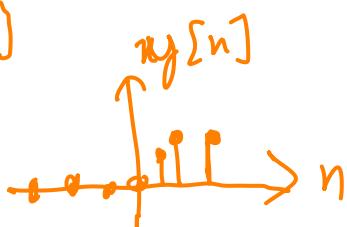
Time Shift

$$y[n] = x[n - n_0]$$



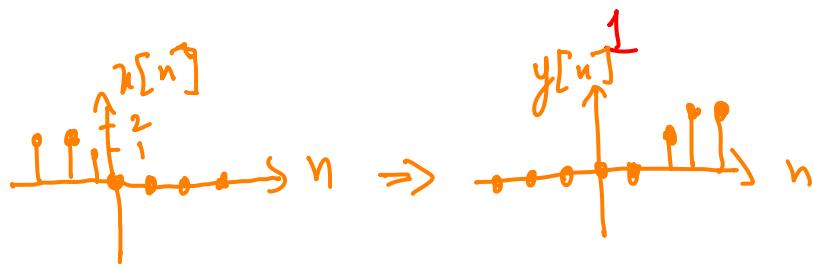
Time Reverse:

$$x[n] \quad y[n] = x[-n]$$



• Combine Time Reverse + time Shift

$$y[n] = x[-n + \underline{n_0}]$$



$$\begin{bmatrix} 2, 2, 1, 0 \\ \downarrow \end{bmatrix} \quad \begin{bmatrix} 0, 0, 1, 2, 2 \\ \uparrow \end{bmatrix}$$

$\hookrightarrow y[n] = x[-n+1]$

$$x[0] = 0 \rightarrow (-n+1) = 0 \Rightarrow n = 1 \Rightarrow y[1] = 0$$

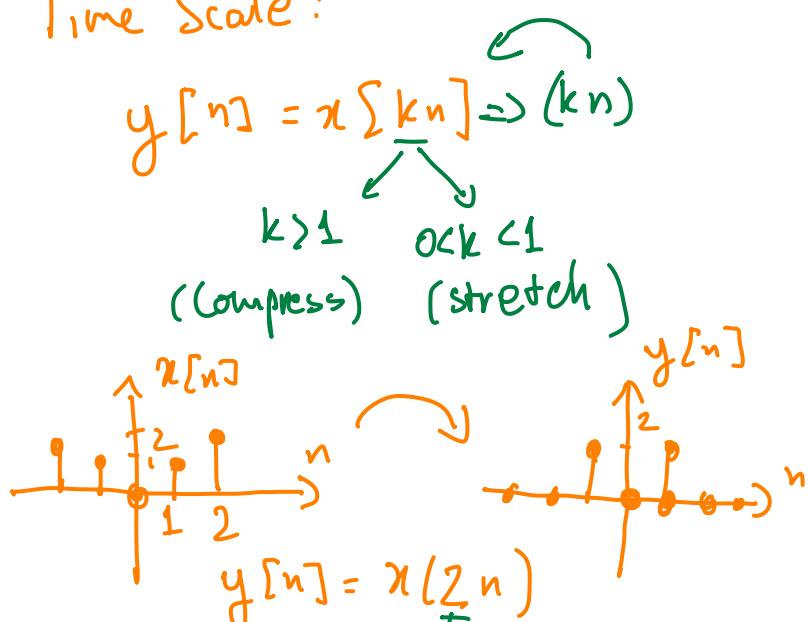
$$x[-1] = 1 \longrightarrow n = 2 \Rightarrow y[2] = 1$$

$$x[-2] = 2 \longrightarrow n = 3 \Rightarrow y[3] = 2$$

$$x[-3] = 3 \longrightarrow n = 4 \Rightarrow y[4] = 2$$

• Time Scale :

$$y[n] = x[\underline{kn}] \xrightarrow{k > 1} \text{(compress)} \quad \xrightarrow{0 < k < 1} \text{(stretch)}$$



$$y[1] = x[2] = 2$$

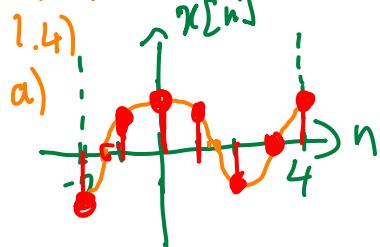
$$y[2] = x[4] = 0$$

$$y[-1] = x[-2] = 2$$

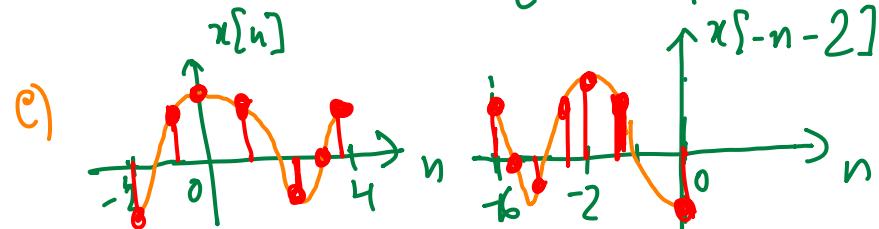
$$y[3] = x[6] = 0$$

\Rightarrow Signal Transform.

Exercise:



$$x[n-3] = 0, \text{ when } \begin{cases} n < 1 \\ n > 7 \end{cases}$$

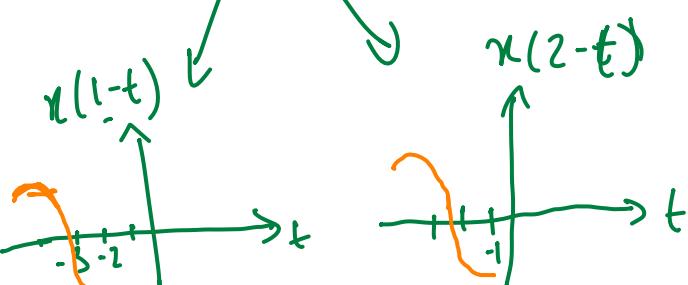
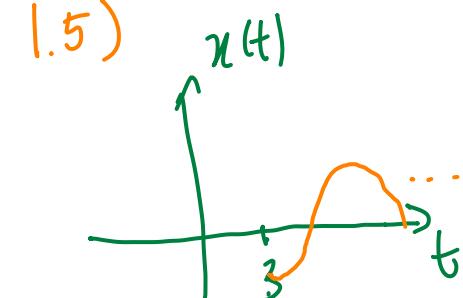


$$x[-n-2] = 0, \text{ when } \begin{cases} n < -6 \\ n > 0 \end{cases}$$

$$\hookrightarrow x[-n-2] = 0, \text{ when } \begin{cases} -n-2 < -2 \\ -n-2 > 4 \end{cases}$$

$$\hookrightarrow \begin{cases} n > 0 \\ n < -6 \end{cases}$$

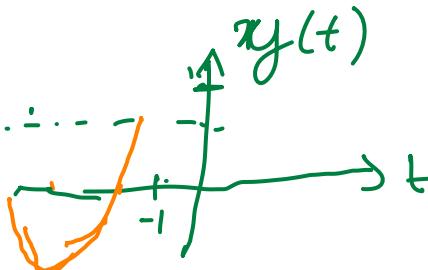
1.5)



$$x(t) = 0, t < 3$$

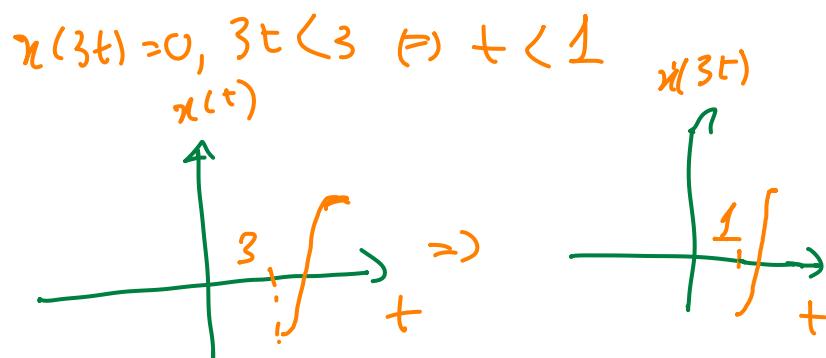
$$\left. \begin{array}{l} x(1-t) = 0, t > -1 \\ x(2-t) = 0, t > -2 \end{array} \right\} \Rightarrow y(t) = 0, t > -1$$

$$\begin{aligned}
 y(t) &= \cos(1-t) + \cos(2-t) \\
 &= 2 \cos\left(\frac{1-t+2-t}{2}\right) \cos\left(\frac{1-t-2+t}{2}\right) \\
 &= 2 \cos\left(\frac{3-2t}{2}\right) \cos\left(-\frac{1}{2}\right) \\
 &= \underbrace{2 \cos\left(-\frac{1}{2}\right)}_A \cos\left(-t + \frac{3}{2}\right) \\
 &\quad t \leq -1
 \end{aligned}$$



d) $x(3t)$

$$x(t)=0, t < 3$$

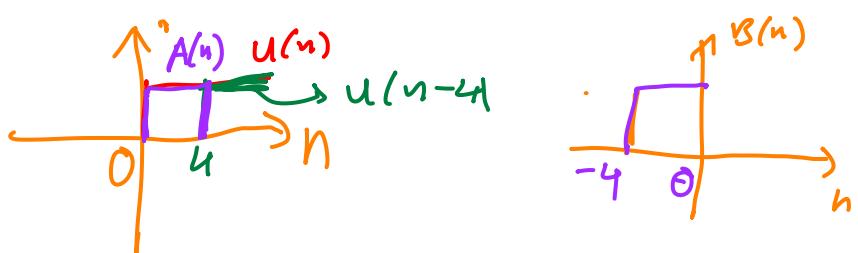


1.7)

a) $\sum_v(x(t)) = \frac{x(t) + x(-t)}{2}$

$$\begin{aligned}
 \sum_v(x(t)) &= \frac{x_1(n) + x_1(-n)}{2} \\
 &= \underbrace{u(n) - u(n-4)}_{A(n)} + \underbrace{u(-n) - u(-n-4)}_{B(n)}
 \end{aligned}$$

$$A(n) = 1, 0 < n \leq 4 \Rightarrow A(n) = 0 \begin{cases} n < 0 \\ n \geq 4 \end{cases}$$



$$B(n) = 0 \Leftrightarrow \begin{cases} n > 0 \\ n \leq -4 \end{cases}$$

$$y(n) = \frac{A(n) + B(n)}{2} = 0 \Leftrightarrow \begin{cases} n \leq -4 \\ n \geq 4 \end{cases}$$

Review : System



- Relation between $y(t)$ vs $x(t)$

Combination
of Signal transform

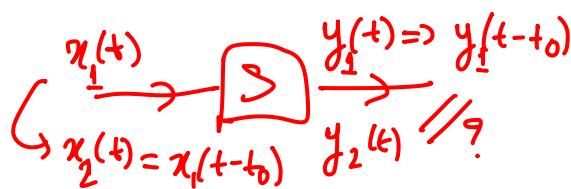
- 4 properties

Causality

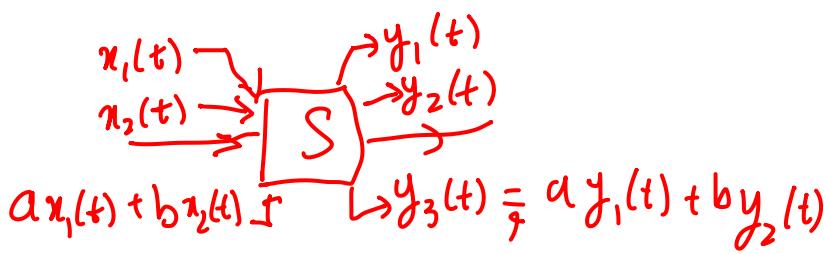
Stability

if $|x(+)| < N \forall t$
then $\exists M$ that
 $|y(+)| < M \forall t$

Time Invariance



Linearity

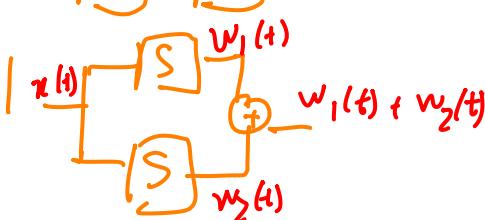


- Interconnection

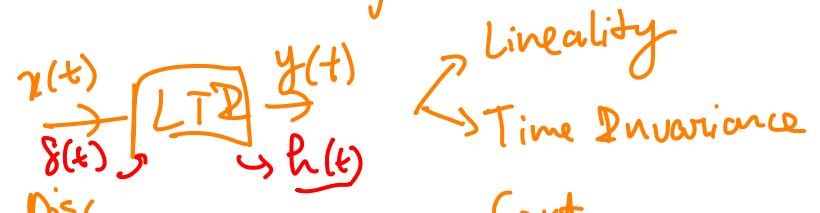
Series



parallel



Review: LTI System



Linearity

Time Invariance

Disc

- $\delta[n] = \begin{cases} 1, & n=0 \\ 0, & \text{else} \end{cases}$

Impulse

- $y[n] = x[n] * h[n]$
- $= \sum_{k=-\infty}^{+\infty} x[k] h[n-k]$

Conv

$$\int_{-\infty}^{+\infty} \delta(t) = 1$$

- $h[n] = 0 \forall n < 0$

↳ Causal

- $h(t) = 0 \forall t < 0$

↳ Causal

- $\sum_{n=-\infty}^{+\infty} |h[n]| < \infty$

↳ Stable

- $\int_{-\infty}^{+\infty} |h(t)| dt < +\infty$

↳ Stable

Convolution Properties:

- Commutative

$$x(t) * h(t) = h(t) * x(t)$$

- Distributive

$$x(t) * (h_1(t) + h_2(t)) = x(t) * h_1(t) + x(t) * h_2(t)$$

- Associative

$$x(t) * (h_1(t) * h_2(t)) = (x(t) * h_1(t)) * h_2(t)$$

Computation Convolution:

- Compute convolution formula directly

- Use 5 steps below:

• S1: Fix input Signal

• S2: Flip impulse Resp Signal

• S3: Align original of Fixed Signal vs Flip Signal

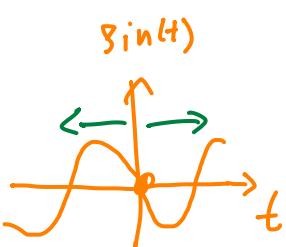
- S4: Element wise multiply 2 signals and Sum them.
- S5 : Assign value to $y[0]$
then Shift ~~Flip~~ Signal.

Exercise: 1.17, 2.1

1.17)

- $y(t) = n(\sin(t))$

↳ not causal



$$t = -\frac{\pi}{2} \Rightarrow \sin(-\frac{\pi}{2}) = -1$$

$$= -1.57$$

$$y(-1.57) = n(-1)$$

$$\circ y_1(t) = x_1(\sin(t))$$

$$y_2(t) = x_2(\sin(t))$$

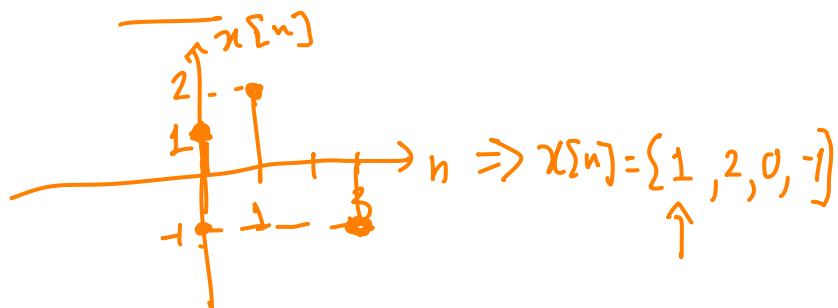
$$x_3(t) = a x_1(t) + b x_2(t)$$

$$\begin{aligned} \hookrightarrow y_3(t) &= x_3(\sin(t)) = a y_1(t) + b y_2(t) \\ &= a x_1(\sin(t)) + b x_2(\sin(t)) \\ &= a y_1(t) + b y_2(t) \end{aligned}$$

\Rightarrow System is linear.

2.1)

$$x[n] = \delta[n] + 2\delta[n-1] - \delta[n-3]$$



$$h[n] = 2\delta[n+1] + 2\delta[n-1] \Rightarrow h[n] = [2, 0, 2]$$

$$y[n] = x[n] * h[n]$$

-----.

$$h'[n] = h[-n] = [2, 0, 2]$$

$$y[0] = [1, 2, 0, -1] = 4 \\ [2, 0, 2]$$

$$y[-1] = [1, 2, 0, -1] = 2 \\ [2, 0, 2]$$

$$y[1] = [1, 2, 0, -1] = 2 \\ [2, 0, 2]$$

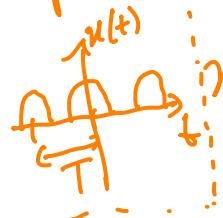
$$y[2] = [1, 2, 0, -1] = 2 \\ [0, 2, 0, 2]$$

⋮ ↑

$$y[n] = [2, 4, 2, 2, 0, -2]$$

Review: Fourier Series

- periodic signal:



$$x(t) = x(t + T)$$

period value

Disc

Cont

$$\begin{array}{c|c} e^{jn\frac{\pi}{T}} = j \sin(n) + \cos(n) & e^{jt} = j \sin(t) + \cos(t) \\ \text{integer} & \text{Real} \end{array}$$

- Synthesis

$$x[n] = \sum_{k=-N}^N a_k e^{j k \omega_0 n} \quad ; \quad x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{j k \omega_0 t} \quad \frac{2\pi}{T}$$

- Analysis

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-j k \omega_0 n} \quad ; \quad a_k = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-j k \omega_0 t} dt$$

$$\bullet \sin(\varphi) = \frac{e^{j\varphi} - e^{-j\varphi}}{2j} \quad \cos(\varphi) = \frac{e^{j\varphi} + e^{-j\varphi}}{2}$$

- Properties:

- Linear: $x(t) \xrightarrow{\text{FS}} a_k$
 $y(t) \xrightarrow{\text{FS}} b_k$

$$A x(t) + B y(t) \xrightarrow{\text{FS}} A a_k + B b_k$$

- Time Rev:

$$x(-t) \xrightarrow{\text{FS}} a_{-k}$$

- Multiply:

$$x(t) * y(t) \xrightarrow{\text{FS}} \sum_{l=-\infty}^{+\infty} a_l b_{k-l}$$

