

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Homework

Systems

TRAN Hoang Tung
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September 19, 2025

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Homework

1 Lesson Objectives

2 An Introduction to Systems

3 Systems' Properties

4 Homework

Lesson Objectives

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Homework

At the end of this lesson, you should be able to

Lesson Objectives

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Homework

At the end of this lesson, you should be able to

- 1** recognize basic system types and system interconnections

Lesson Objectives

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Homework

At the end of this lesson, you should be able to

- 1** recognize basic system types and system interconnections
- 2** determine (and justify) properties of a system:
 - Causality
 - Stability
 - Time Invariance
 - Linearity

Lesson Objectives

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Homework

At the end of this lesson, you should be able to

- 1** recognize basic system types and system interconnections
- 2** determine (and justify) properties of a system:
 - Causality
 - Stability
 - Time Invariance
 - Linearity
- 3** have some feelings about LTI systems

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

System Types
Interconnections

Systems'
Properties

Homework

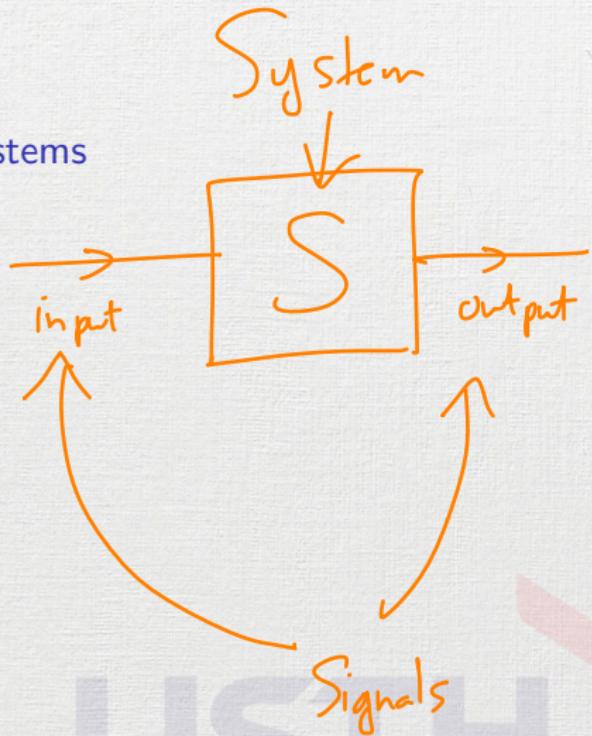
1 Lesson Objectives

2 An Introduction to Systems

- System Types
- Interconnections

3 Systems' Properties

4 Homework



System Types

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Systems

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Objectives

An Intro-
duction to
Systems

System Types
Interconnections

Systems'
Properties

Homework

■ Single-variable vs. Multiple-variable systems

- 1 SISO (single-input single-output) systems
- 2 SIMO (single-input multiple-output) systems
- 3 MISO (multiple-input single-output) systems
- 4 MIMO (multiple-input multiple-output) systems

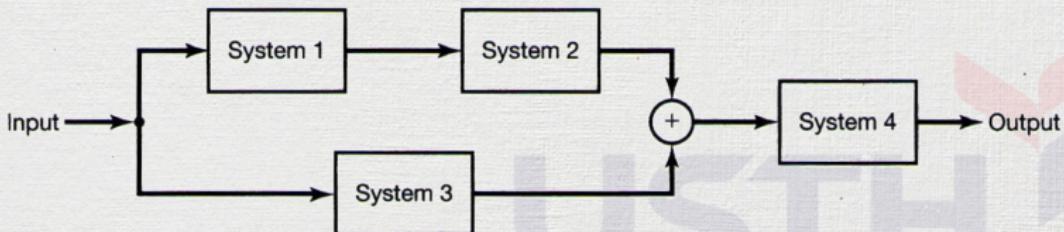
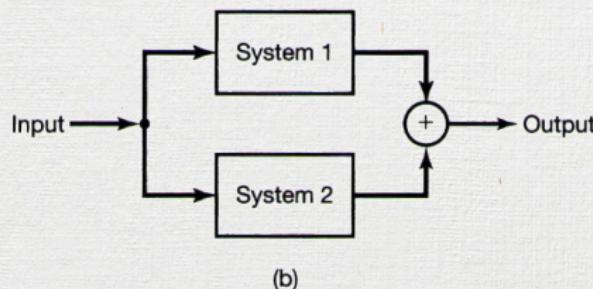
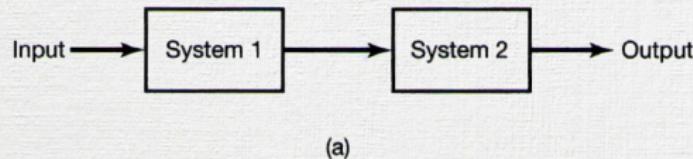


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SystemsTRAN
Hoang Tung

Objectives

An Intro-
duction to
SystemsSystem Types
InterconnectionsSystems'
Properties

Homework



Feedback

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Systems

TRAN
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Objectives

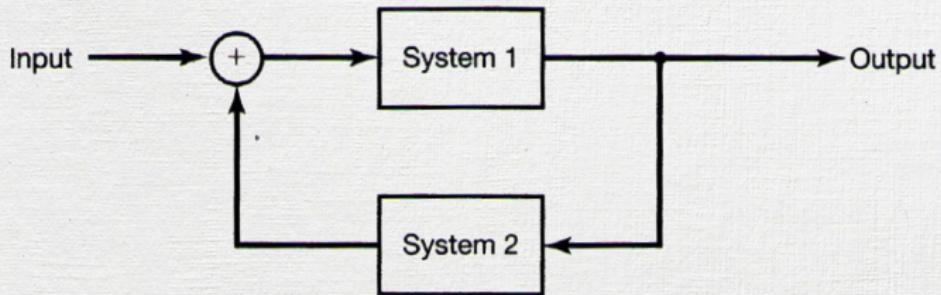
An Intro-
duction to
Systems

System Types

Interconnections

Systems'
Properties

Homework



Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance
Linearity

Homework

1 Lesson Objectives

2 An Introduction to Systems

3 Systems' Properties

- Causality
- Stability
- Time Invariance
- Linearity

□ Memoryless

4 Homework

□ . , - -

Causality



Causal Systems

Output signal depends only on the present and/or past values of the input signal.



$y_{(0)}$ depends on $x_{(\lambda)}$ $\lambda \leq 0$

$y_{(0)}$ doesn't depend on $x_{(1)}$

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability

Time Invariance
Linearity

Homework

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality

Stability

Time Invariance

Linearity

Homework

Causal Systems

Output signal depends only on the present and/or past values of the input signal.

Examples

- $y(t) = x(t)\sin(t)$

Signals &
SystemsTRAN
Hoang Tung

Objectives

An Intro-
duction to
SystemsSystems'
PropertiesCausality
Stability
Time Invariance
Linearity

Homework

Causal Systems

Output signal depends only on the present and/or past values of the input signal.

Examples

- ~~$y(t) = x(t) \sin(t)$~~

- $y[n] = x[-n]$



$$y[1] = x[-1]$$

$$y[0] = x[0]$$

$$y[-1] = x[1]$$

non causal

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Objectives

An Intro-
duction to
SystemsSystems'
PropertiesCausality
Stability
Time Invariance
Linearity

Homework

Causal Systems

Output signal depends only on the present and/or past values of the input signal.

Examples

- $y(t) = x(t)\sin(t)$
- $y[n] = x[-n]$
- $y[n] = x[n] - x[n - 1]$

Causal or not ?

$$\text{At } n_0 \quad y[n_0] = x[n_0] - x[n_0 - 1]$$

now now past

$$\exists M : |x(t)| \leq M \quad \forall t$$

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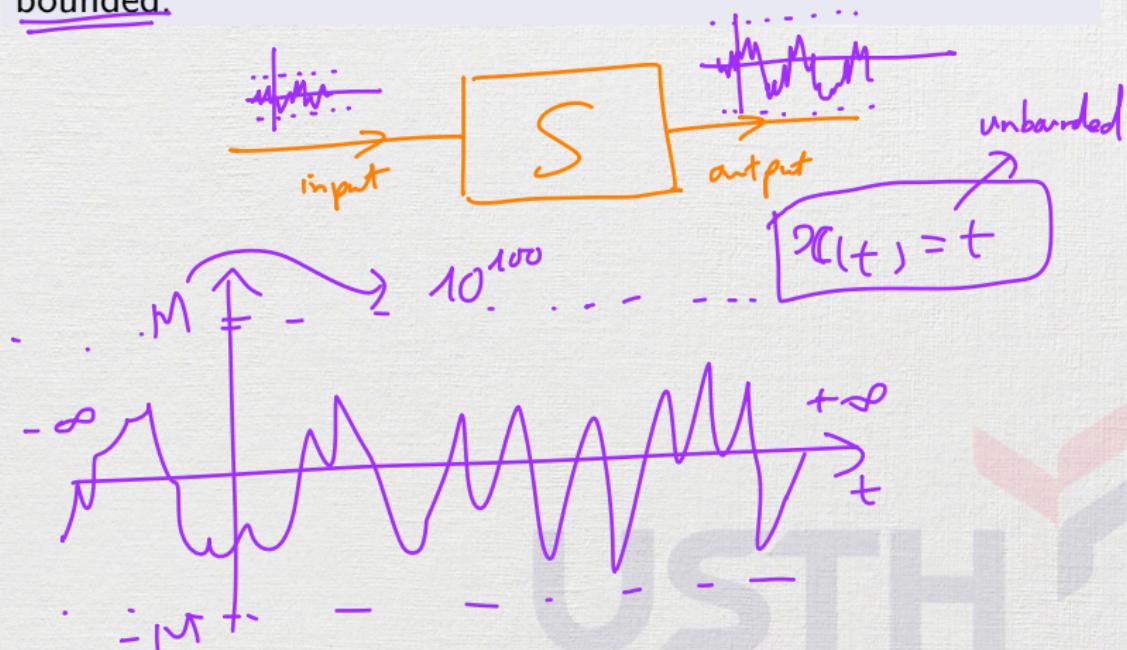
Objectives

An Intro-
duction to
SystemsSystems'
PropertiesCausality
Stability
Time Invariance
Linearity

Homework

Stable Systems

The output signal is bounded whenever the input signal is bounded.



Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality

Stability

Time Invariance

Linearity

Homework

Stable Systems

The output signal is bounded whenever the input signal is bounded.

Examples

- $y(t) = tx(t)$

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality

Stability

Time Invariance

Linearity

Homework

Stable Systems

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Examples

- $y(t) = tx(t)$
- $y[n] = x[-n]$

Stability

S_1 is not stable!

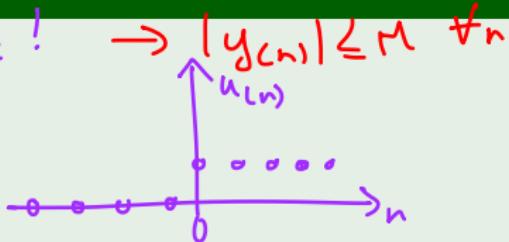
Stable Systems

The output signal is bounded whenever the input signal is bounded.

$$\exists M \quad |x(n)| \leq M \forall n \Rightarrow |y(-n)| \leq M \forall n$$

Examples

- S_1 ■ $y(t) = tx(t)$ \rightarrow unstable ! $\rightarrow |y(n)| \leq M \forall n$
- S_2 ■ $y[n] = x[-n]$ \rightarrow stable
- S_3 ■ None!



$$y[n] = \sum_{k=-\infty}^n u[k]$$

where $u[n]$ is the unit step

discrete

$$u(n) = \begin{cases} 1 & \text{if } n \geq 0 \\ 0 & \text{else} \end{cases}$$

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance

Linearity

Homework

Time-Invariant Systems

The input-output relation does not depend on the time origin,
i.e. the systems are fixed over time.

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability

Time Invariance

Linearity

Homework

Time-Invariant Systems

The input-output relation does not depend on the time origin,
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Examples

- $y(t) = \sin[x(t)]$

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance

Linearity

Homework

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- $y(t) = \sin[x(t)]$
- $y[n] = nx[n]$

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability

Time Invariance

Linearity

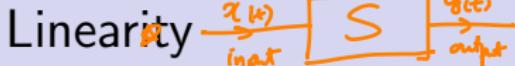
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Time-Invariant Systems

The input-output relation does not depend on the time origin,
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- $y[n] = x[-n]$

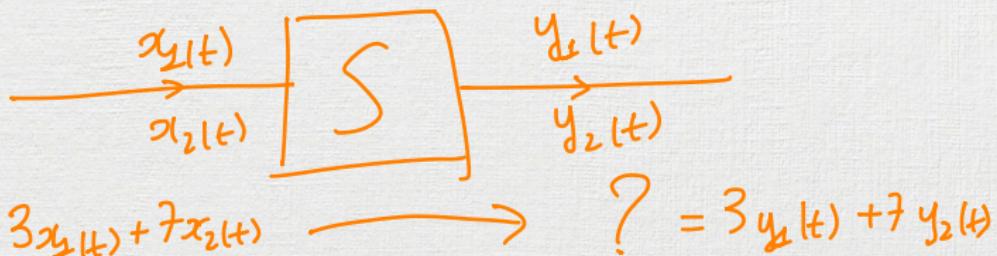


$y(t)$ is the response of S to $x(t)$

A diagram illustrating the weighted sum of inputs. Two signals, $x_1(t)$ and $x_2(t)$, are shown with arrows pointing towards a central point. From this point, two arrows labeled "weight" point to the inputs. The equation $3x_1(t) + 7x_2(t) \rightarrow z_S(t)$ is written below, where $z_S(t)$ is labeled as the "weighted sum".

Linear Systems

If an input consists of the weighted sum of several signals, then the output is the weighted sum of the responses of the system to each of those signals.



$$3x_1(t) + 7x_2(t) \rightarrow ? = 3y_1(t) + 7y_2(t)$$

↓
LINEAR !!!!!

Signals &
Systems

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Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance

Linearity

Homework

Linear Systems

If an input consists of the **weighted sum** of several signals, then the output is the **weighted sum** of the responses of the system to each of those signals.

In math language

Given a system in which:

- $y_1(t)$ is the response to an input $x_1(t)$
- $y_2(t)$ is the response to an input $x_2(t)$

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance
Linearity

Homework

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Then the system is linear if:

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance
Linearity

Homework

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Given a system in which:

- $y_1(t)$ is the response to an input $x_1(t)$
- $y_2(t)$ is the response to an input $x_2(t)$

Then the system is linear if:

- The response to $x_1(t) + x_2(t)$ is $y_1(t) + y_2(t)$
Additivity

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance
Linearity

Homework

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Given a system in which:

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- $y_2(t)$ is the response to an input $x_2(t)$

Then the system is linear if:

- The response to $x_1(t) + x_2(t)$ is $y_1(t) + y_2(t)$
Additivity
- The response to $ax_1(t)$ is $ay_1(t)$, where a is a constant
Scaling

Signals &
Systems

TRAN
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Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance
Linearity

Homework

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Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance
Linearity

Homework

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- $y[n] = x[-n]$

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance

Linearity

Homework

Examples

- $y(t) = tx(t)$
- $y[n] = x[-n]$
- $y[n] = 2x[n] + 5$

Summary

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance
Linearity

Homework

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Summary

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance
Linearity

Homework

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Stable Systems

The output signal is bounded whenever the input signal is bounded (BIBO).

Summary

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance
Linearity

Homework

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Summary

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Causality
Stability
Time Invariance
Linearity

Homework

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Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Homework

1 Lesson Objectives

2 An Introduction to Systems

3 Systems' Properties

4 Homework

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Homework

Systems' Exercises

1.15, 1.17, 1.18, 1.27, 1.28, 1.31, 1.42

Signals &
Systems

TRAN
Hoang Tung

Objectives

An Intro-
duction to
Systems

Systems'
Properties

Homework

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1.15, 1.17, 1.18, 1.27, 1.28, 1.31, 1.42

A Gentle Remind

Exam problems will not be different from homework!!