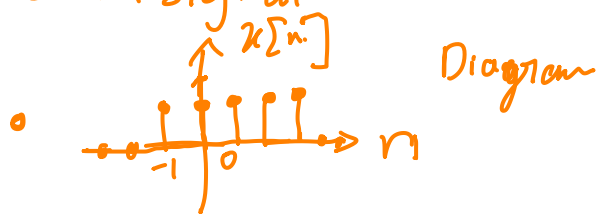


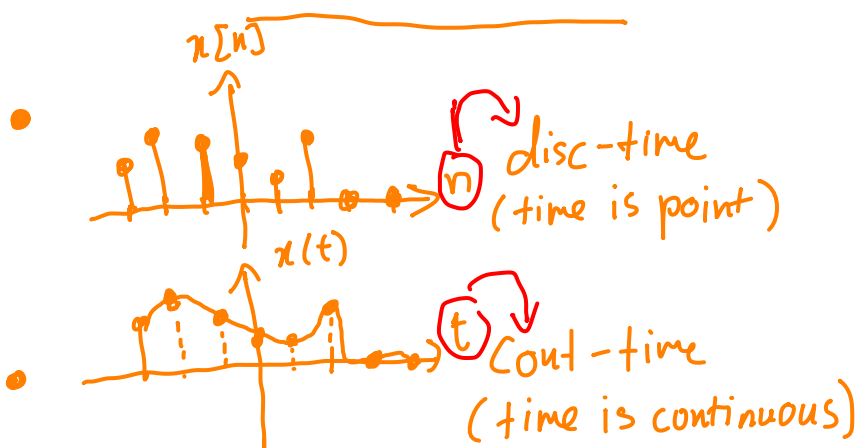
Review: Signal



- $x[n] = \begin{cases} u[n+1], & n < 4 \\ 0, & \text{else} \end{cases}$ formula

- $x[n] = [1, 1, 1, 1, 1]$ vector

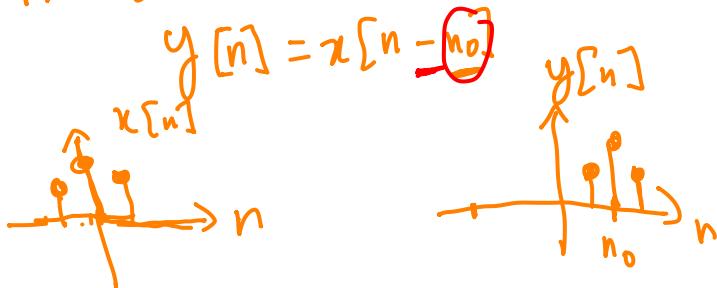
\Rightarrow Represent Signal



\Rightarrow Signal Classification

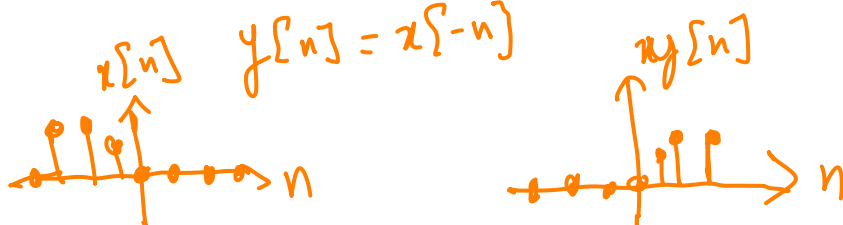
Time Shift

$$y[n] = x[n - n_0]$$



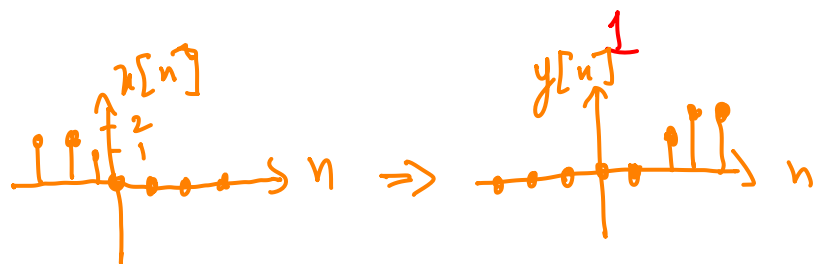
Time Reverse:

$$y[n] = x[-n]$$



- Combine Time Reverse + time Shift

$$y[n] = x[-n + \underline{n_0}]$$



$$[2, 2, 1, 0] \quad [0, 0, 1, 2, 2]$$

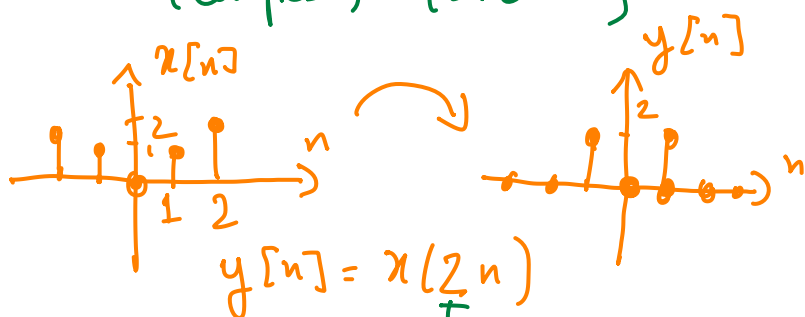
$$\hookrightarrow y[n] = x[-n+1]$$

$$\begin{aligned} x[0] &= 0 \quad \xrightarrow{(-n+1)=0 \Rightarrow n=1} y[1] = 0 \\ x[-1] &= 1 \quad \xrightarrow{\quad \quad \quad n=2} y[2] = 1 \\ x[-2] &= 2 \quad \xrightarrow{\quad \quad \quad n=3} y[3] = 2 \\ x[-3] &= 3 \quad \xrightarrow{\quad \quad \quad n=4} y[4] = 2 \end{aligned}$$

- Time Scale:

$$y[n] = x[kn] \Rightarrow (kn)$$

$k > 1$ (compress)
 $0 < k < 1$ (stretch)



$$y[1] = x[2] = 2 \quad \xrightarrow{k=2}$$

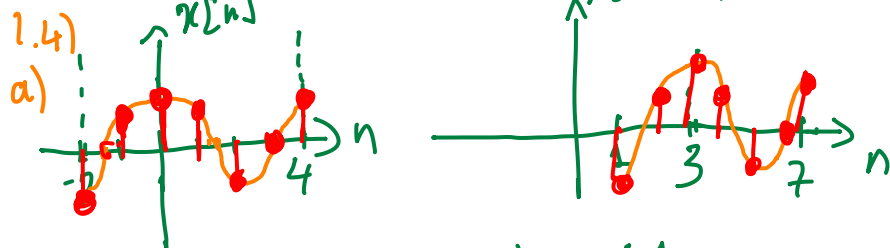
$$y[2] = x[4] = 0$$

$$y[-1] = x[-2] = 2$$

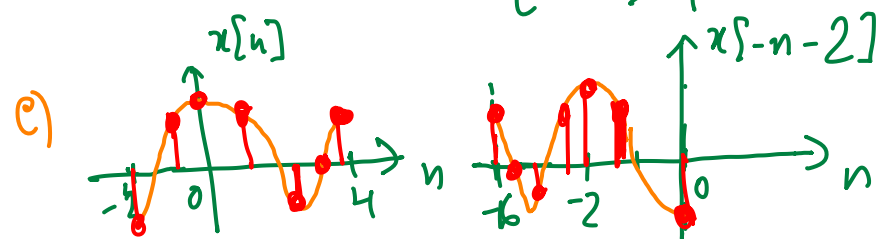
$$y[-2] = x[-4] = 0$$

\Rightarrow Signal Transform.

Exercise:



$$x[n-3] = 0, \text{ when } \begin{cases} n < 1 \\ n > 7 \end{cases}$$

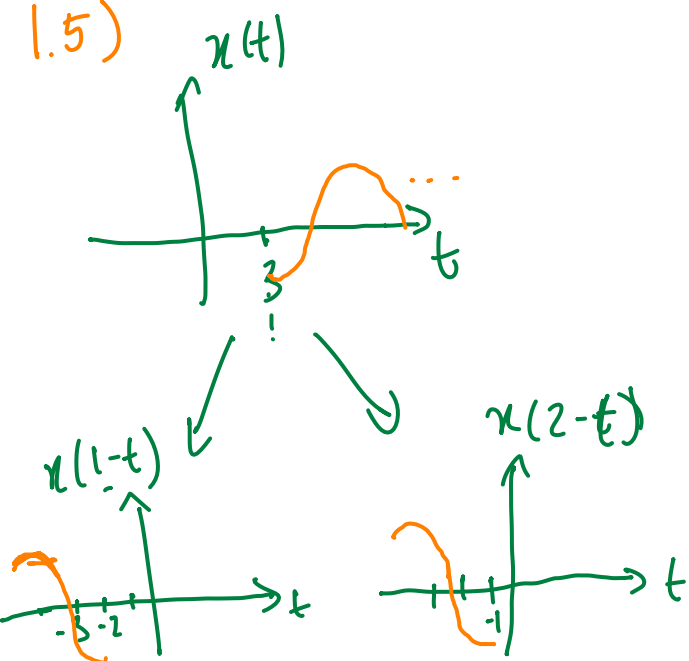


$$x[-n-2] = 0, \text{ when } \begin{cases} n < -6 \\ n > 0 \end{cases}$$

$$\Rightarrow x[-n-2] = 0, \text{ when } \begin{cases} -n-2 < -2 \\ -n-2 > 4 \end{cases}$$

$$\Rightarrow \begin{cases} n > 0 \\ n < -6 \end{cases}$$

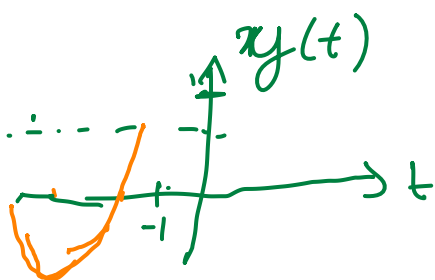
1.5)



$$x(t) = 0, t < 3$$

$$\begin{cases} x(1-t) = 0, t > -2 \\ x(2-t) = 0, t > -1 \end{cases} \Rightarrow y(t) = 0, \underline{t > -1}$$

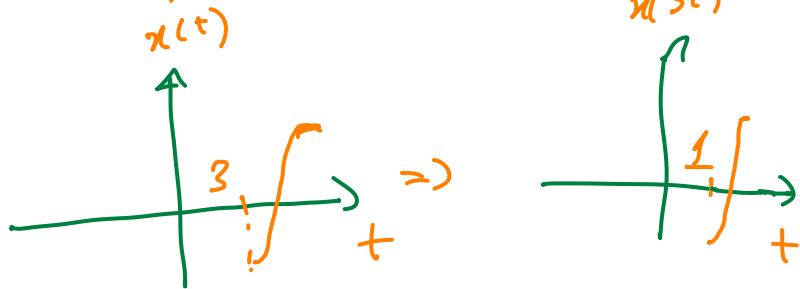
$$\begin{aligned}
 y(t) &= \cos(1-t) + \cos(2-t) \\
 &= 2 \cos\left(\frac{1-t+2-t}{2}\right) \cos\left(\frac{1-t-2+t}{2}\right) \\
 &= 2 \cos\left(\frac{3-2t}{2}\right) \cos\left(-\frac{1}{2}\right) \\
 &= \underbrace{2 \cos\left(-\frac{1}{2}\right)}_A \underbrace{\cos\left(-t + \frac{3}{2}\right)}_{t \leq -1}
 \end{aligned}$$



d) $x(3t)$

$$x(t) = 0, t < 3$$

$$x(3t) = 0, 3t < 3 \Leftrightarrow t < 1$$

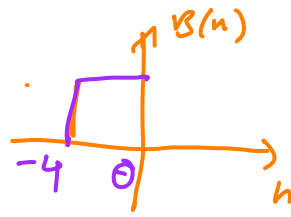
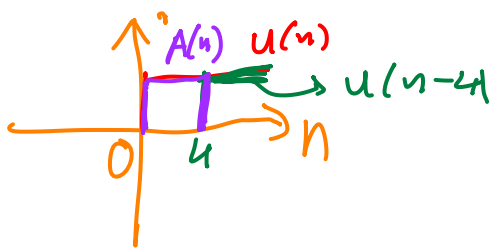


1.7)

$$a) \sum_v(x(t)) = \frac{x(t) + x(-t)}{2}$$

$$\begin{aligned}
 \sum_v(x(t)) &= \frac{x_1(n) + x_1(-n)}{2} \\
 &= \underbrace{u(n) - u(n-4)}_{A(n)} + \underbrace{u(-n) - u(-n-4)}_{B(n)}
 \end{aligned}$$

$$A(n) = 1, 0 < n < 4 \Leftrightarrow A(n) = 0 \begin{cases} n < 0 \\ n \geq 4 \end{cases}$$



$$B(n) = 0, (\Leftrightarrow) \begin{cases} n > 0 \\ n \leq -4 \end{cases}$$

$$y(n) = \frac{A(n) + B(n)}{2} = 0 \Leftrightarrow \begin{cases} n \leq -4 \\ n > 4 \end{cases}$$

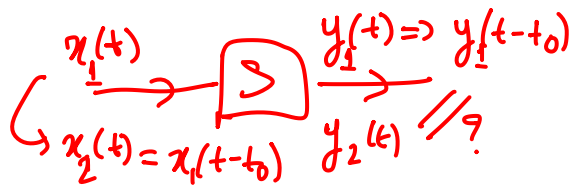
Review : System



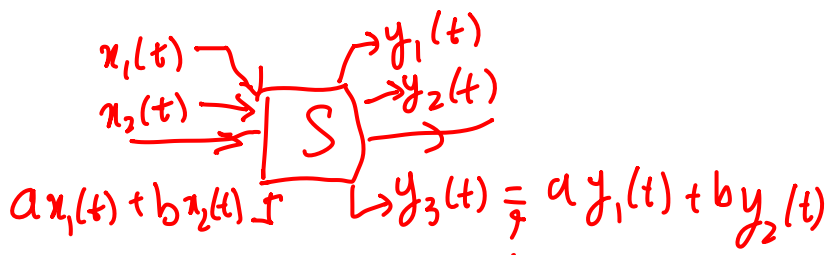
- Relation between $y(t)$ vs $x(t)$

Combination of Signal transform

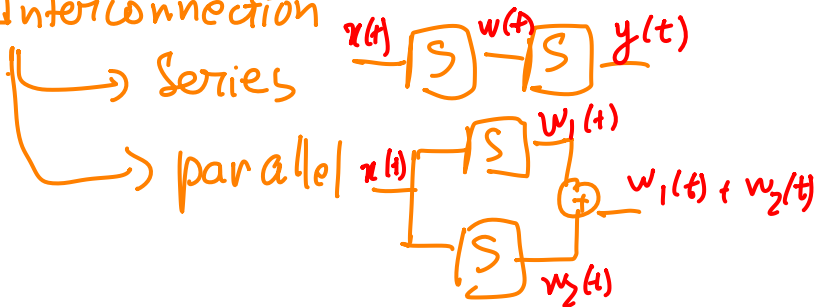
- 4 properties
 - Causality
 - Stability
if $|x(t)| < N \forall t$
then $\exists M$ that
 $|y(t)| < M \forall t$
 - Time Invariance



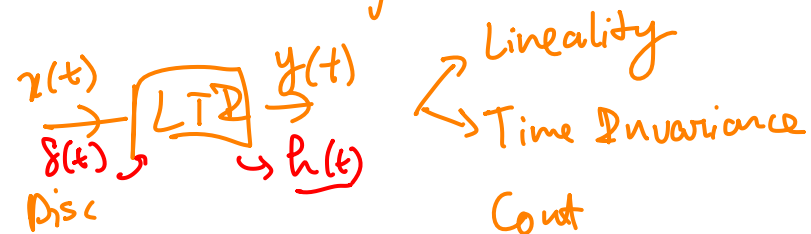
Linearity



- Interconnection



Review: LTI System



Discrete

$$\delta[n] = \begin{cases} 1, & n=0 \\ 0, & \text{else} \end{cases}$$

Impulse

$$y[n] = x[n] * h[n] \\ = \sum_{k=-\infty}^{+\infty} x[k] h[n-k]$$

$$h[n] = 0 \quad \forall n < 0$$

↳ Causal

$$\sum_{n=-\infty}^{+\infty} |h[n]| < +\infty$$

↳ Stable

Continuous

$$\int_{-\infty}^{+\infty} \delta(t) dt = 1$$

$$y(t) = \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$$

$$h(t) = 0 \quad \forall t < 0$$

↳ Causal

$$\int_{-\infty}^{+\infty} |h(t)| dt < +\infty$$

↳ Stable

Convolution Properties:

- Commutative

$$x(t) * h(t) = h(t) * x(t)$$

- Distributive

$$x(t) * (h_1(t) + h_2(t)) = x(t) * h_1(t) + x(t) * h_2(t)$$

- Associative

$$x(t) * (h_1(t) * h_2(t)) = (x(t) * h_1(t)) * h_2(t)$$

Computation Convolution:

- Compute convolution formula directly

- Use 5 steps below:

• S1: Fix input signal

• S2: Flip impulse Resp signal

• S3: Align original of Fixed signal vs Flip signal

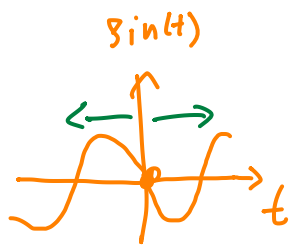
- S4: Element wise multiply 2 signals and Sum them.
- S5: Assign value to $y[0]$ then Shift Flip Signal.

Exercise: 1.17, 2.1

1.17)

- $y(t) = x(\sin(t))$

↳ not casual



$$t = -\frac{\pi}{2} \Rightarrow \sin(-\frac{\pi}{2}) = \underline{\underline{-1}}$$

$$= -1.57$$

$$y(-1.57) = x(-1)$$

- $y_1(t) = x_1(\sin(t))$

$$y_2(t) = x_2(\sin(t))$$

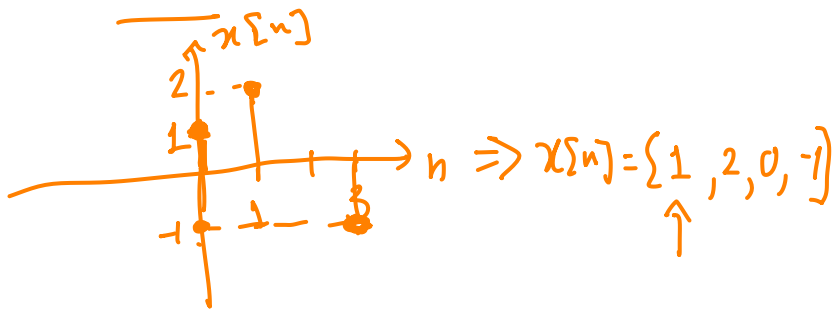
$$x_3(t) = ax_1(t) + bx_2(t)$$

$$\begin{aligned} \hookrightarrow y_3(t) &= x_3(\sin(t)) \stackrel{?}{=} ay_1(t) + by_2(t) \\ &= ax_1(\sin(t)) + bx_2(\sin(t)) \\ &= ay_1(t) + by_2(t) \end{aligned}$$

\Rightarrow System is linear.

2.1)

$$x[n] = \delta[n] + 2\delta[n-1] - \delta[n-3]$$



$$h[n] = 2\delta[n+1] + 2\delta[n-1] \Rightarrow h[n] = [2, 0, 2]$$

$$y[n] = x[n] * h[n]$$

$$h'[n] = h[-n] = [2, 0, 2]$$

$$y[0] = [1, 2, 0, -1] = 4$$

$[2, 0, 2]$
 \uparrow

$$y[-1] = [1, 2, 0, -1] = 2$$

$[2, 0, 2]$
 \uparrow

$$y[1] = [1, 2, 0, -1] = 2$$

$[2, 0, 2]$
 \uparrow

$$y[2] = [1, 2, 0, -1] = 2$$

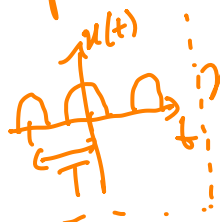
$[0, 2, 0, 2]$
 \uparrow
 \vdots

$$y[n] = [2, 4, 2, 2, 0, -2]$$

\uparrow

Review: Fourier Series

- periodic signal:



$$x(t) = x(t + \underbrace{T}_{\text{period value}})$$

Disc

Cont

- $e^{jn} = j \sin(n) + \cos(n)$
 \downarrow
integer

- $e^{jt} = j \sin(t) + \cos(t)$
 \downarrow
Real

- Synthesis

- Synthesis:

$$x[n] = \sum_{\langle n \rangle} a_k e^{jk\omega_0 n}$$

\downarrow
 $\frac{2\pi}{N}$

$$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t}$$

\downarrow
 $\frac{2\pi}{T}$

- Analysis

$$a_k = \frac{1}{N} \sum_{\langle n \rangle} x[n] e^{-jk\omega_0 n}$$

- Analysis:

$$a_k = \frac{1}{T} \int_T x(t) e^{-jk\omega_0 t} dt$$

- $\sin(\varphi) = \frac{e^{j\varphi} - e^{-j\varphi}}{2j}$ $\cos(\varphi) = \frac{e^{j\varphi} + e^{-j\varphi}}{2}$

- Properties:

- Linear: $x(t) \xrightarrow{FS} a_k$
 $y(t) \xrightarrow{FS} b_k$

$$A x(t) + B y(t) \xrightarrow{FS} A a_k + B b_k$$

- Time Rev:

$$x(-t) \xrightarrow{FS} a_{-k}$$

- Multiply:

$$x(t) * y(t) \xrightarrow{FS} \sum_{l=-\infty}^{\infty} a_l b_{k-l}$$

