

MILIND

Software Developer

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📅 20.10.1998 🇮🇳 Indian in http://www.linkedin.com/in/milind-514b62151
🔗 https://github.com/Milind-cod3-base



ABOUT

Passionate about crafting scalable and efficient software solutions by leveraging modern development methodologies.

EDUCATION

Artificial Intelligence for Smart Sensors and Actuators (Master of Engineering)

Deggendorf Institute of Technology

📅 03.2022 - 03.2025 📍 93413 Cham

Mechanical Engineering (Bachelor of Technology)

Vellore Institute of Technology

📅 07.2016 - 06.2020 📍 Vellore, Tamil Nadu, India

EXPERIENCE

Qt Application Developer

Persystems

📅 01.10.2024 - 28.02.2025 📍 Franz-Mayer-Straße 1, 93053 Regensburg

- Developing Virtual Testbench, a Simulation Windows Application for industrial and automotive electric components, using C++ and the Qt Framework. Virtual TestBench is a lightweight alternative to MATLAB / Simulink.
- Implemented Licence check service in the Virtual Testbench.

Qt Application Working Student

Persystems

📅 01.07.2024 - 01.10.2024 📍 Franz-Mayer-Straße 1, 93053 Regensburg

- Created a visual nodes system where users can drag, drop, and connect various simulation electronic components with their interfaces to run the simulation using the Qt Nodes library.
- Utilizing Qt Creator as the Integrated Development Environment (IDE) for development.
- Iteratively optimising the UI and UX for better User Flow using MVC architecture.

Master Thesis in ADAS Virtual Validation

AVL Software and Functions GmbH

📅 01.11.2023 - 01.05.2024 📍 Im Gewerbepark B29 93059 Regensburg

- Engineered a co-simulation platform for AV ADAS verification and enhanced AVL's FMU Generation Utility to FMI 3.0 with C++ for integration with Carla and esmini, adhering to ASAM standards.

Working Student

AVL Software and Functions GmbH

📅 15.02.2023 - 31.10.2023 📍 Im Gewerbepark B29 93059 Regensburg

- Worked in ADAS Digitalization, focusing on engineering environments, including demonstrating SOA (Service-Oriented Architecture) with Adaptive AUTOSAR for automobiles.
- Analyzed middleware technologies like ROS 2 and Adaptive AUTOSAR, and developed C++ applications and tools for Adaptive Application deployment using Azure DevOps.
- Optimized RT Linux OS via Yocto for real-time automotive systems, ensuring efficiency across ECUs.

SKILLS

C / C++	●●●●●●
Linux / Unix Systems	●●●●●●
Qt Framework / QML	●●●●●●
Sensor Fusion	●●●●●●
Python	●●●●●●
ROS / ROS2	●●●●●●
CMake / Make	●●●●●●
SQL / PostgreSQL	●●●●●●
Object Oriented Programming	●●●●●●
CI / CD	●●●●●●
Software Test / V Model	●●●●●●
Docker / Kubernetes	●●●●●●
Azure DevOps	●●●●●●
Git	●●●●●●

PROJECT

- 🚗 **Autonomous Driving with Turtlebot3**
📅 12.2022
Developed various key ROS Nodes in C++ and Python for a Turtlebot3 autonomous driving project, leveraging ROS (Noetic) and Gazebo for a virtual testing environment via Sensor Fusion. Established and managed a CI/CD pipeline for software testing and validation against key performance indicators (KPIs). Utilized MySQL for efficient data storage, query optimization, and analysis, aiding in the improvement of autonomous driving features.

HOBBIES

- Video Games
- Cycling
- Classic and Hard Rock

LANGUAGES

English	●●●●●●
German	●●●●●●
Hindi	●●●●●●