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1. With the operator form of the Transport Equations

$$L\psi = MS\phi + Mq_e$$
$$\phi = D\psi$$

and given the following discretizations:

- 3 groups
- $P_2$  (number of moments is  $(N+1)^2$ )
- $S_2$  (number of angles is N(N+2), with the N being from  $S_N$  rather than  $P_N$
- Diamond difference

(a) Indicate the dimensions of each matrix in Equation 1, using real numbers for what we did generically in class.

The granularity of discretization can be used to define the size of the operators:

$$\alpha = G \times n \times c \times u$$

and

$$\beta = G \times N \times c \times u$$

Where G is the number of energy groups, N is the number of moments, n is the number of angular unknowns, c is the number of cells, and u is the number of unknowns per cell, determined by spatial discretization. Equation 1 can be presented in terms of operator size as follows:

$$(\alpha \times \alpha)(\alpha \times 1) = (\alpha \times \beta)(\beta \times \beta)(\beta \times 1) + (\alpha \times \beta)(\beta \times 1)$$

In our case, we have G = 3,  $N = (2 + 1)^2 = 9$ , n = 2(2 + 2) = 8, c = 4x4x4 = 64, and u = 1 (the flux).

```
In [1]:
        G=3
        N=(2+1)**2
        n=(2+2)*2
        c = 4 * 4 * 4
        ນ=1
        a = G*n*c*u
        b = G*N*c*u
        print('the dimensions of L are '+str(a)+' x '+str(a))
        print('the dimensions of psi are '+str(a)+' x 1')
        print('the dimensions of M are '+str(a)+' x '+str(b))
        print('the dimensions of S are '+str(b)+' x '+str(b))
        print('the dimensions of phi are '+str(b)+' x 1')
        print('the dimensions of qe are '+str(b)+' x 1')
        the dimensions of L are 1536 x 1536
        the dimensions of psi are 1536 \times 1
        the dimensions of M are 1536 x 1728
        the dimensions of S are 1728 x 1728
        the dimensions of phi are 1728 x 1
```

(b) Write out the matrices  $[M]_{gg}$ , S, and  $[S]_{21}$  as well as the vectors  $\psi$ ,  $[\psi]_1$ , and  $[\phi]_1$  to make sure you know what values match with what.

the dimensions of qe are 1728 x 1

 $[M_{gg}]$  is one of the submatrices on the diagonal of M. There are G  $[M_{gg}]$  submatrics in M. The number of rows in  $[M_{gg}]$  is equal to the number of angular unknowns; the number of columns is equal to the number of moments.

of moments. 
$$[\boldsymbol{M}]_{gg} = \begin{bmatrix} Y_{00}^{e}(\hat{\Omega}_{1}) & Y_{10}^{e}(\hat{\Omega}_{1}) & Y_{11}^{e}(\hat{\Omega}_{1}) & Y_{21}^{e}(\hat{\Omega}_{1}) & Y_{21}^{e}(\hat{\Omega}_{1}) & Y_{22}^{e}(\hat{\Omega}_{1}) \\ Y_{00}^{e}(\hat{\Omega}_{2}) & Y_{10}^{e}(\hat{\Omega}_{2}) & Y_{11}^{e}(\hat{\Omega}_{2}) & Y_{20}^{e}(\hat{\Omega}_{2}) & Y_{21}^{e}(\hat{\Omega}_{2}) & Y_{21}^{e}(\hat{\Omega}_{2}) & Y_{22}^{e}(\hat{\Omega}_{2}) \\ Y_{00}^{e}(\hat{\Omega}_{3}) & Y_{10}^{e}(\hat{\Omega}_{3}) & Y_{11}^{e}(\hat{\Omega}_{3}) & Y_{11}^{e}(\hat{\Omega}_{3}) & Y_{20}^{e}(\hat{\Omega}_{3}) & Y_{21}^{e}(\hat{\Omega}_{3}) & Y_{21}^{e}(\hat{\Omega}_{3}) & Y_{22}^{e}(\hat{\Omega}_{3}) \\ Y_{00}^{e}(\hat{\Omega}_{4}) & Y_{10}^{e}(\hat{\Omega}_{4}) & Y_{11}^{e}(\hat{\Omega}_{4}) & Y_{20}^{e}(\hat{\Omega}_{3}) & Y_{21}^{e}(\hat{\Omega}_{3}) & Y_{21}^{e}(\hat{\Omega}_{3}) & Y_{22}^{e}(\hat{\Omega}_{3}) \\ Y_{00}^{e}(\hat{\Omega}_{5}) & Y_{10}^{e}(\hat{\Omega}_{5}) & Y_{11}^{e}(\hat{\Omega}_{4}) & Y_{20}^{e}(\hat{\Omega}_{4}) & Y_{21}^{e}(\hat{\Omega}_{4}) & Y_{22}^{e}(\hat{\Omega}_{4}) \\ Y_{00}^{e}(\hat{\Omega}_{5}) & Y_{10}^{e}(\hat{\Omega}_{5}) & Y_{11}^{e}(\hat{\Omega}_{5}) & Y_{20}^{e}(\hat{\Omega}_{5}) & Y_{21}^{e}(\hat{\Omega}_{5}) & Y_{22}^{e}(\hat{\Omega}_{5}) \\ Y_{00}^{e}(\hat{\Omega}_{6}) & Y_{10}^{e}(\hat{\Omega}_{6}) & Y_{11}^{e}(\hat{\Omega}_{6}) & Y_{20}^{e}(\hat{\Omega}_{5}) & Y_{21}^{e}(\hat{\Omega}_{5}) & Y_{21}^{e}(\hat{\Omega}_{5}) & Y_{22}^{e}(\hat{\Omega}_{5}) \\ Y_{00}^{e}(\hat{\Omega}_{7}) & Y_{10}^{e}(\hat{\Omega}_{6}) & Y_{11}^{e}(\hat{\Omega}_{7}) & Y_{20}^{e}(\hat{\Omega}_{6}) & Y_{21}^{e}(\hat{\Omega}_{6}) & Y_{22}^{e}(\hat{\Omega}_{6}) \\ Y_{00}^{e}(\hat{\Omega}_{7}) & Y_{10}^{e}(\hat{\Omega}_{7}) & Y_{11}^{e}(\hat{\Omega}_{7}) & Y_{20}^{e}(\hat{\Omega}_{7}) & Y_{21}^{e}(\hat{\Omega}_{7}) & Y_{21}^{e}(\hat{\Omega}_{7}) & Y_{22}^{e}(\hat{\Omega}_{7}) \\ Y_{00}^{e}(\hat{\Omega}_{8}) & Y_{10}^{e}(\hat{\Omega}_{8}) & Y_{11}^{e}(\hat{\Omega}_{8}) & Y_{11}^{e}(\hat{\Omega}_{8}) & Y_{20}^{e}(\hat{\Omega}_{8}) & Y_{21}^{e}(\hat{\Omega}_{8}) & Y_{21}^{e}(\hat{\Omega}_{8}) & Y_{22}^{e}(\hat{\Omega}_{8}) \\ Y_{00}^{e}(\hat{\Omega}_{8}) & Y_{10}^{e}(\hat{\Omega}_{8}) & Y_{11}^{e}(\hat{\Omega}_{8}) & Y_{11}^{e}(\hat{\Omega}_{8}) & Y_{20}^{e}(\hat{\Omega}_{8}) & Y_{21}^{e}(\hat{\Omega}_{8}) & Y_{21}^{e}(\hat{\Omega}_{8}) & Y_{22}^{e}(\hat{\Omega}_{8}) \\ Y_{00}^{e}(\hat{\Omega}_{8}) & Y_{10}^{e}(\hat{\Omega}_{8}) & Y_{11}^{e}(\hat{\Omega}_{8}) & Y_{11}^{e}(\hat{\Omega}_{8}) & Y_{20}^{e}(\hat{\Omega}_{8}) & Y_{21}^{e}(\hat{\Omega}_{8}) & Y_{21}^{e}(\hat{\Omega}_{8}) & Y_{22}^{e}(\hat{\Omega}_{8}) & Y_{22}^{e}(\hat{\Omega}_{8}) \\ Y_{00}^{e}(\hat{\Omega}_{8}) & Y_{10}^{e}(\hat{\Omega}_{8}) & Y_{11}^{e}(\hat{\Omega$$

S is the scattering matrix and consists of many submatrices. There are G rows and G columns in S; each entry is a matrix  $[S]_{gg}$ 

$$S = \begin{bmatrix} [S]_{11} & [S]_{12} & [S]_{13} \\ [S]_{21} & [S]_{22} & [S]_{23} \\ [S]_{31} & [S]_{22} & [S]_{33} \end{bmatrix}$$
$$[S]_{21} = \begin{bmatrix} \Sigma_{s0}^{21} & 0 & 0 \\ 0 & \Sigma_{s1}^{21} & 0 \\ 0 & 0 & \Sigma_{s2}^{21} \end{bmatrix}$$

The vectors  $\psi$ ,  $[\psi]_1$ , and  $[\phi]_1$  are the flux values, group 1 flux values, and group 1 flux moments, respectively. Technically,  $\psi$  includes  $[\psi]_1$ .

$$\psi = \begin{pmatrix} [\psi]_1 & [\psi]_2 & [\psi]_3 \end{pmatrix}^T$$

$$[\psi]_1 = \begin{pmatrix} \psi_1^1 & \psi_2^1 & \psi_3^1 & \psi_4^1 & \psi_5^1 & \psi_6^1 & \psi_7^1 & \psi_8^1 \end{pmatrix}^T$$

$$[\phi]_1 = \begin{pmatrix} \phi_{00}^1 & \phi_{10}^1 & \phi_{11}^1 & v_{11}^1 & \phi_{20}^1 & \phi_{21}^1 & v_{21}^1 & \phi_{22}^1 & v_{22}^1 \end{pmatrix}^T$$

In  $[\phi]_1$ ,  $\phi$  marks the even moments and v marks the odd moments.

## (c) Write what the ${\it D}\,$ matrix would be.

 $m{D}$  is the discrete-to-moment operator;  $m{M}$  is  $\alpha \times \alpha$  and  $m{W}$  is a diagonal matrix made up of  $n \times n$  diagonal matrices of quadrature weights. The diagonal matrices in  $m{W}$  line up with those in  $m{M}$  such that

$$D = M^{T}W = \sum_{a=1}^{n} Y_{lm}^{elo} w_{a}$$

$$D = \begin{bmatrix} [D]_{11} & 0 & 0 \\ 0 & [D]_{22} & 0 \\ 0 & 0 & [D]_{33} \end{bmatrix}$$

Because M is diagonal, this is analogous to saying that for each submatrix  $[M]_{gg}$  in M,

$$[D]_{gg} = [M]_{gg}^T [W]_{gg} = \sum_{a=1}^n Y_{lm}^{e/o} w_a$$

The result is another matrix with submatrices on the diagonal. Now, each submatrix on the diagonal  $[\boldsymbol{D}]_{gg}$  has dimensions  $(N \times n) \times (n \times n) = N \times n$ , so the overall matrix  $\boldsymbol{D}$  has dimension  $\beta \times \alpha$ .

$$\mathbf{D} = \begin{bmatrix} \Sigma_{a=1}^{n} Y_{lm}^{e/o} w_{a} & 0 & 0 \\ 0 & \Sigma_{a=1}^{n} Y_{lm}^{e/o} w_{a} & 0 \\ 0 & 0 & \Sigma_{a=1}^{n} Y_{lm}^{e/o} w_{a} \end{bmatrix}$$

## (d) Why don't we form an $\boldsymbol{L}$ matrix?

The L matrix is very sparse and would be expensive in memory. We can handle the inversion of L by performing the numerical 'sweeps' through space and angle.

(e) Combine Equations (1) and (2) to get a system that looks like Ax = b, writing out the steps.

We can combine the equations given above to get the following.

$$L\psi = MSD\psi + Mq_e$$

If  $L\psi$  is subtracted from both sides,  $\psi$  can be factored from the first two terms on the right hand side.

$$0.0 = MSD\psi - L\psi + Mq_e$$
  
$$0.0 = [MSD - L]\psi + Mq_e$$

Rearranging into the form Ax = b yields:

$$[L - MSD] \psi = Mq_e$$

2. Implement a Jacobi multigroup solver for the 1D, steady state transport equations with isotropic scattering and an isotropic external source. Use the weighted diamond difference solver you wrote for the previous homework to solve the within group equations (if you are unsure if yours worked let me know) (note: you functionally should have written source iteration). Use the following values and three energy groups:

- $x_0 = 0.0, x_1 = 2.0, h = 0.1$
- $\alpha = 0.5$
- $\mu_a = \pm [0.2, 0.5, 0.7]$
- $\Sigma_{t1} = 0.5, \Sigma_{t2} = 0.8, \Sigma_{t3} = 1.0$
- $\Sigma_s^{gg'}$  values in Table 1
- $q_{e1} = 1.5, q_{e2} = 0.0, q_{e3} = 0.2$
- left boundary condition is 0.5 incoming in group 1, zero otherwise

Plot the resulting scalar flux in each energy group as a function of x. Use a convergence tolerance for the multigroup iteration and the scattering iteration of at least  $1 \times 10^{-4}$ .

```
In [3]: %matplotlib inline import matplotlib.pyplot as plt import numpy as np
```

```
In [4]: %%javascript
    IPython.OutputArea.auto_scroll_threshold = 9999;
```

This function solves for the flux over the spatial mesh using WDD. This function is called repeatedly in the space-angle iterations to resolve the source in each group within each outer iteration.

```
In [5]: import numpy as np
       # Function that solves for the flux over the spatial mesh, given input
       def wdd(cells, h, alpha, sigma t, sourceVector, incomingFlux, mu):
           ########################
           # SUPPORTING FUNCTIONS FOR THE MAIN WDD FUNCTION
       ----#
           def center flux(incomingFlux, source, xs, alpha, h, mu):
           # returns the cell-centered flux from a single mesh cell
               if(mu > 0):
                  cellCenteredFlux = (source+(2*abs(mu)*(incomingFlux)/(1+al
       pha)/h))\
                                    /(xs+(2*abs(mu)/(1+alpha)/h))
               if(mu < 0):
                  cellCenteredFlux = (source+(2*abs(mu)*(incomingFlux)/(1-al
       pha)/h))\
                                    /(xs+(2*abs(mu)/(1-alpha)/h))
              return(cellCenteredFlux)
       ____#
           def outgoing flux(incomingFlux, cellCenteredFlux, source, xs, alph
       a, h, mu):
              # returns the outgoing flux from a single mesh cell
                  outgoingFlux = 2*cellCenteredFlux/(1+alpha)-(1-alpha)*inco
       mingFlux/(1+alpha)
              if(mu < 0):
                  outgoingFlux = 2*cellCenteredFlux/(1-alpha)-(1+alpha)*inco
       mingFlux/(1-alpha)
              return(outgoingFlux)
           #####################
           # MAIN WDD FUNCTION: returns a single iteration for flux in both d
       irections given mu
           # note that source is an array over all cells
           def wdd_iter(cells, h, sigma_t, source, angle, inwardflux):
              #sweep to the left
              angle = abs(angle)
              lFlux = np.zeros(len(cells))
              hFlux = inwardflux # incoming flux at the left bound
               for i in range(0, len(lFlux)):
                  lFlux[i] = center flux(hFlux, source[i], sigma t, alpha, h
       , angle)
                  hFlux = outgoing flux(hFlux, lFlux[i], source[i], sigma t,
       alpha, h, angle)
```

I just tossed this here - this function creates the mesh based on specifications of 1D space. It returns the cell centers.

```
In [6]: def mesh(xmin, xmax, h):
    # determine cell-center x values
    nCells = int((xmax-xmin)/h)
    cellCenters = np.zeros(nCells)
    for i in range(0, nCells):
        cellCenters[i] = round((i+1)*h-(h/2.0), 4)
    return(cellCenters)
```

Function to perform quadrature integration

```
In [7]: def quad_int(fluxes, wts):
    # returns sum_a=1^N(psi_a*w_a)
    for i in range(0, len(fluxes)):
        fluxes[i]=wts[i]*fluxes[i]
    return(np.sum(fluxes, axis=0))
```

This function guesses the scattering source. Based on the previous flux result it produces sources in the specified group that can be used to start the inner space-angle iterations.

```
In [81]:
       def quess s source(sigma s, muVector, mgflux, egroup):
           ###############################
           # returns a guess scattering source in each mesh cell for the inpu
       t energy group
           #########################
           # select xs and source based on energy group of interest
           sigma s = sigma s[egroup,:]
           num e grps=len(sigma s)
           #----
       ----#
           s source = [0]*num_e_grps
           # calculate source contribution from each energy group
           for i in range(0, num_e_grps):
              #print('egroup = '+str(i))
              #print(mqflux[i])
              s source[i] = (sigma s[i]/2.0)*mgflux[i]
           # to account for scattering contributions from all energies, just
       sum in each cell
           return(np.sum(s source, axis=0))
```

This function performs the within-group space-angle iterations (similar to what was in HW4, but I had to tweak it quite a bit to get it to fit these circumstances).

```
def within_group_iteration(cells, h, alpha, sigma t, sigma s, muVector
In [82]:
        , mgfluxVals, egroup, \
                            sourceGuess, ext source, qs tol=1e-5):
           ###############################
           # returns the spatial flux for the specified energy group
           #########################
           # cells is a vector of x values for position of the center of cell
           # h is the cell spacing
           # alpha is the weight
           # sigma t is a vector of total xs at each energy
           # sigma s is an array of scattering xs g'->g
           # muVector is a vector of the absolute values of mu (negatives are
        implied)
           # mgflux is a dictionary of the multigroup flux values from the pr
        evious energy
              iteration (if the first iteration, mgflux is just zeros)
           ########################
       #
            def scattering sources(xs s, fluxes, wts):
       #
                # returns the scattering source in each mesh cell
       #
                \# qs = (Sigma s/4pi)*2pi+sum a=1^N(psi a*w a)
       #
                fluxes = quad int(fluxes, wts)
        #
                return((xs s/2.0)*fluxes)
```

```
#-----
   # determine the weights; these sum to 2.0 and are equal for all an
gles
   weights = np.ones(2*len(muVector))/len(muVector)
   #-----
____#
   # select xs and source based on energy group of interest; note tha
t here the xs s
   # is a single value, because we are only solving for in-group scat
tering
   #sigma_s = sigma_s[egroup,egroup]
   #sigma t = sigma t[egroup]
   #ext source = externalSource[egroup]
   s source new = sourceGuess
   #-----
----#
   # pre allocate flux object
   flux = {}
   for mu in muVector:
      flux[mu]=[]
      flux[-mu]=[np.zeros(len(cells))]
   if(egroup == 0):
      leftboundflux = 0.5
   else:
       leftboundflux = 0.0
   #-----
 ----#
   error = 1.0 # arbitrary
   counter = 0 # iteration counter
   while(error > qs tol):
      counter = counter+1
      #print('inner counter = '+str(counter))
      s source old = s source new
      source = ext source+s source old
      #print(np.average(source))
      # over all angles...
       for mu in muVector:
          # calculate the flux with the new source; update in multig
roup
          flux[mu], flux[-mu]=wdd(cells, h, alpha, sigma t, source,
leftboundflux, mu)
       # update the source to get an even newer source
      newflux = quad_int(flux.values(), weights)
      mgfluxVals[egroup]=newflux
      s source new = guess s source(sigma s, muVector, mgfluxVals, e
group)
      # s source new = scattering sources(sigma s, flux.values(), we
ights)
      # calculate error over the space
      error = np.linalg.norm(s source new - s source old)
   # flux = quad int(flux.values(), weights)
   # print('within group '+str(egroup)+' convergence in '+str(counter
```

```
)+' iterations.')
   return(newflux)
```

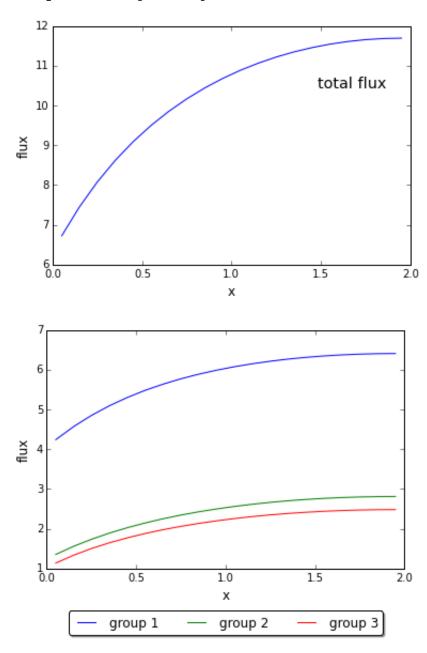
This function performs outer iterations over energy groups. The iterations are Jacobi in nature even though I never form any of the matrices. Jacobi iteration involves using the k iteration on the scattering side of the TE (RHS in our derivation) to find the k+1 iteration on the transport side of the TE (the LHS in our derivation). In this function, the a guess for the source is computed based on the old flux, starting with k=0, and then the flux is found in the within-group space-angle iterations, where k=1.

```
def outer group jacobi(xmin, xmax, h, alpha, sigma t, sigma s, muVecto
In [83]:
         r, \
                               externalSource, tol=1e-5):
            ----#
            cells = mesh(xmin, xmax, h)
          ____#
            mgflux = {}
            for i in range(0, len(sigma t)):
                mgflux[i]=np.zeros(len(cells))
            def check convergence(newSourceGuesses, oldSourceGuesses, toleranc
         e):
                # there should be the same number of source vectors as there a
         re energy groups
                conv=[False]*len(newSourceGuesses)
                for i in range(0, len(newSourceGuesses)):
                    # if convergence hasn't been reached, no further checks sh
         ould be done
                    # print(newSourceGuesses)
                    # print(oldSourceGuesses)
                    #print(np.linalq.norm(newSourceGuesses[i]-oldSourceGuesses
         [i]))
                    if(np.linalg.norm(newSourceGuesses[i]-oldSourceGuesses[i])
         < tolerance):
                        conv[i]=True
                if(sum(conv)==len(newSourceGuesses)):
                    return(True)
                else:
                    return(False)
           ----#
              old source = []
         #
              for i in range(0, len(sigma t)):
                  old source.append()
            #-----
               ----#
            tempflux = {}
            for i in range(0, len(sigma t)):
                tempflux[i]=[]
```

```
counter = 0
   convergence = False
   while(convergence == False):
      counter = counter+1
      #print('outer counter = '+str(counter))
      #-----
----#
      # for each energy group, generate the initial source guesses
      old source = []
      for i in range(0, len(sigma t)):
         old source.append([])
         old source[i]=guess s source(sigma s, muVector, mgflux, i)
      #-----
----#
      # for each energy group, calculate the flux based on the sourc
e quess
      for i in range(0, len(sigma t)):
         # compute the LHS (spatial transport, k+1 iterate)
         tempflux[i] = within_group_iteration(cells, h, alpha, sigm
a t[i], sigma s, \
                                     muVector, mgflux, i, ol
d source[i], \
                                    externalSource[i])
      #-----
      # update source and flux and check for convergence (RHS, kth i
terate)
      nextSourceGuess = []
      for i in range(0, len(sigma_t)):
         nextSourceGuess.append([])
         nextSourceGuess[i]=guess s source(sigma s, muVector, tempf
lux, i)
         mgflux[i]=tempflux[i]
      #-----
----#
      # update fluxes
      #print('oldsource')
      #print(old source)
      #print('newsource')
      #print(nextSourceGuess)
      convergence = check convergence(nextSourceGuess, old source, t
ol)
      old source = nextSourceGuess
   #-----
----#
   print('outer convergence reached in '+str(counter)+' iteration(s).
')
   return(cells, mqflux)
```

```
In [84]:
         # initialize values
         alpha = 0.5
         xmin, xmax, h = 0.0, 2.0, 0.1
         muVals = np.array([0.2, 0.5, 0.7]) # plus/minus is implied
         sigma t = np.array([0.5, 0.8, 1.0])
         sigma_s = np.array([[0.1, 0.0, 0.0], [0.3, 0.1, 0.1], [0.1, 0.3, 0.3]])
         qe = np.array([1.5, 0.0, 0.2])
In [85]: pts, flux = outer group jacobi(xmin, xmax, h, alpha, sigma t, sigma s,
         muVals, qe)
         outer convergence reached in 6 iteration(s).
In [96]: plt.figure()
         plt.plot(pts, np.sum(flux.values(), axis=0))
         plt.xlabel('x', size = 'large')
         plt.ylabel('flux', size = 'large')
         plt.figtext(0.7, 0.7, 'total flux', size = 'x-large')
         plt.figure()
         plt.plot(pts, flux[0], label='group 1')
         plt.plot(pts, flux[1], label='group 2')
         plt.plot(pts, flux[2], label='group 3')
         plt.xlabel('x', size = 'large')
         plt.ylabel('flux', size = 'large')
         plt.legend(loc='upper center', bbox to anchor=(0.5, -0.15), fancybox=T
         rue, shadow=True, ncol=5)
         # FANCY BOX!
```

Out[96]: <matplotlib.legend.Legend at 0x10d59b1d0>



This looks like an appropriate flux shape; the scattering

In [ ]:			
---------	--	--	--