

exercise2

June 10, 2020

```
[1]: import numpy as np
import pandas as pd
import matplotlib.pyplot as plt

from copy import deepcopy
from sklearn.linear_model import LinearRegression

from sympy.solvers import solve
from sympy import *

%matplotlib inline
```

1 MA(q) processes

$$y_t = \alpha_0 \eta_t + \alpha_1 \eta_{t-1} + \dots + \alpha_q \eta_{t-q}$$

$$y_t = \left(\sum_{i=0}^q \alpha_i B^i \right) \eta_t$$

where: * η is a White Gaussian Noise * $\langle \eta_t \rangle = 0$ * $\langle \eta^2 \rangle = 1$ * B - backshift operator ($B^0 = 1$)

1.1 a)

Find the order and fit the parameters: $\beta_i (i = 1, \dots, p)$, α_0 using the 2-step linear regression method. In order to find p and the best fit use the “AIC” and “BIC” criteria. Use $m = 5$ to estimate the realized noise in 1-st step and remember about normalizing it such that the variance is 1, in 2-nd step use this data to fit regression of $y(t)$ against the (shifted) noise variables.

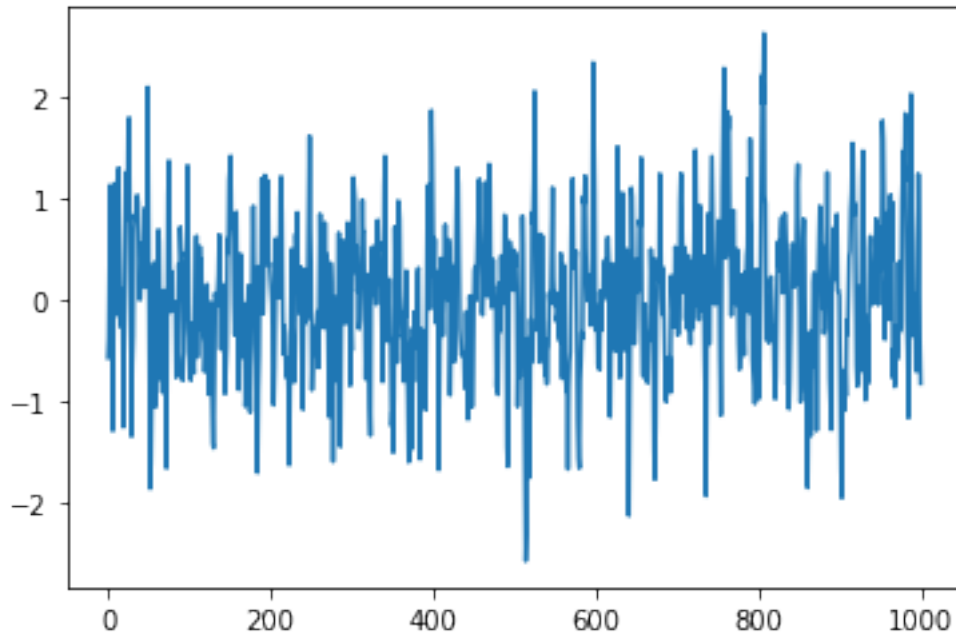
```
[2]: data = []

with open("MAdata.txt", "r") as f:
    for line in f:
        data.append(float(line))

data = np.array(data)
```

```
plt.plot(data)
```

```
[2]: [<matplotlib.lines.Line2D at 0x7fc6e8074790>]
```



1.1.1 Two step regression: step 1

```
[3]: def dividing_data_into_subseries_II(data, k=2):
```

```
    X = []
```

```
    Y = []
```

```
    for i in range(len(data)-k):
```

```
        tmp = []
```

```
        for j in range(k):
```

```
            tmp.append(data[j+i])
```

```
        X.append(tmp)
```

```
        Y.append(data[k+i] )
```

```
    return np.array(X), np.array(Y)
```

```
[4]: X,Y = dividing_data_into_subseries_II(data, k=5)
```

```
reg = LinearRegression(fit_intercept = False).fit(X, Y)
```

```
prediction = reg.predict(X)
```

```
print("fitted coefficients  beta_(t-4)...beta_(t-1): {}".format(reg.coef_))
```

```

eps = Y - reg.predict(X)
eps = eps/eps.std()

print("\nmean= {:.2f}\t std = {:.2f}".format( eps.mean(), eps.std()))

```

```

fitted coefficients  beta_(t-4)...beta_(t-1): [-0.11996622  0.36024784
-0.37833758 -0.08663265  0.80459043]

```

```

mean= 0.013197    std = 1.000000

```

```

[5]: YY = np.vstack((Y,eps)).transpose()
      np.hstack((YY, X))
      df = pd.DataFrame(np.hstack((X,YY)), columns = ['y(t5)', 'y(t4)', 'y(t3)', 'y(t2)', 'y(t1)', 'y(t)', 'eps'])

      df['eps+1'] = df['eps'].shift(1)
      df['eps+2'] = df['eps'].shift(2)
      df['eps+3'] = df['eps'].shift(3)
      df['eps+4'] = df['eps'].shift(4)
      df['eps+5'] = df['eps'].shift(5)

      df.dropna(inplace = True)
      df

```

```

[5]:
      y(t5)    y(t4)    y(t3)    y(t2)    y(t1)    y(t)    eps  \
5   -0.192600 -1.299081 -0.226935  0.065571  1.144725  0.265750 -0.563038
6   -1.299081 -0.226935  0.065571  1.144725  0.265750 -0.153007 -0.614121
7   -0.226935  0.065571  1.144725  0.265750 -0.153007  0.284510  1.575092
8    0.065571  1.144725  0.265750 -0.153007  0.284510  1.295828  1.452625
9    1.144725  0.265750 -0.153007  0.284510  1.295828  0.755126 -0.540861
..      ...      ...      ...      ...      ...      ...
991 -0.363077  0.036522  0.048544 -0.697383 -0.713475  0.160522  1.231984
992  0.036522  0.048544 -0.697383 -0.713475  0.160522  1.239079  1.494245
993  0.048544 -0.697383 -0.713475  0.160522  1.239079  0.618735 -0.730864
994 -0.697383 -0.713475  0.160522  1.239079  0.618735 -0.401085 -1.080186
995 -0.713475  0.160522  1.239079  0.618735 -0.401085 -0.831914 -0.252345

      eps+1    eps+2    eps+3    eps+4    eps+5
5    1.353333  0.103533  1.123592 -1.602866 -0.475611
6   -0.563038  1.353333  0.103533  1.123592 -1.602866
7   -0.614121 -0.563038  1.353333  0.103533  1.123592
8    1.575092 -0.614121 -0.563038  1.353333  0.103533
9    1.452625  1.575092 -0.614121 -0.563038  1.353333
..      ...      ...      ...      ...      ...
991  0.122370 -1.847775  0.172484  0.156206 -0.317439
992  1.231984  0.122370 -1.847775  0.172484  0.156206

```

```

993  1.494245  1.231984  0.122370 -1.847775  0.172484
994 -0.730864  1.494245  1.231984  0.122370 -1.847775
995 -1.080186 -0.730864  1.494245  1.231984  0.122370

```

[991 rows x 12 columns]

1.1.2 Two step regression: step 2

```

[6]: def get_AIC_BIC(df, x_cols):

    k=len(x_cols)
    Y = np.array(df['y(t)'])
    X = np.array(df[x_cols])

    reg = LinearRegression(fit_intercept = False).fit(X, Y)
    prediction = reg.predict(X)
    N = len(X)

    alpha = np.sqrt(((Y-prediction)**2).mean())
    AIC = N*np.log(((Y-prediction)**2).mean()) + 2*k
    BIC = N*np.log(((Y-prediction)**2).mean()) + np.log(N)*k

    print("\n\nk = {:}, alpha = {:}\t AIC = {:}\t BIC = {:}\n".format(k,alpha,
→AIC, BIC))
    print("intercept = {:}\t reg.coef_ = {:}".format(reg.intercept_, reg.coef_)
→)

    return [k, alpha, AIC, BIC]

```

```

[7]: tab = []

tab.append(get_AIC_BIC(df, ['eps+1'] ))
tab.append(get_AIC_BIC(df, ['eps+1', 'eps+2'] ))
tab.append(get_AIC_BIC(df, ['eps+1', 'eps+2', 'eps+3'] ))
tab.append(get_AIC_BIC(df, ['eps+1', 'eps+2', 'eps+3', 'eps+4'] ))
tab.append(get_AIC_BIC(df, ['eps+1', 'eps+2', 'eps+3', 'eps+4', 'eps+5'] ))

```

```

k = 1, alpha = 0.5983398034602126          AIC = -1015.948170249943          BIC =
-1011.049455715613

```

```

intercept = 0.0  reg.coef_ = [0.40763142]

```

```

k = 2, alpha = 0.5112762579620876          AIC = -1325.6152114266736          BIC =

```

```
-1315.8177823580136
```

```
intercept = 0.0 reg.coef_ = [0.41227231 0.31086954]
```

```
k = 3, alpha = 0.510873738399572          AIC = -1325.1762226617864      BIC =  
-1310.4800790587965
```

```
intercept = 0.0 reg.coef_ = [ 0.41314462  0.3105654  -0.02029883]
```

```
k = 4, alpha = 0.5108607704161228          AIC = -1323.2265342505132      BIC =  
-1303.6316761131932
```

```
intercept = 0.0 reg.coef_ = [ 0.41330546  0.31040558 -0.02024874  0.00364592]
```

```
k = 5, alpha = 0.5098490840077213          AIC = -1325.1554923366602      BIC =  
-1300.6619196650104
```

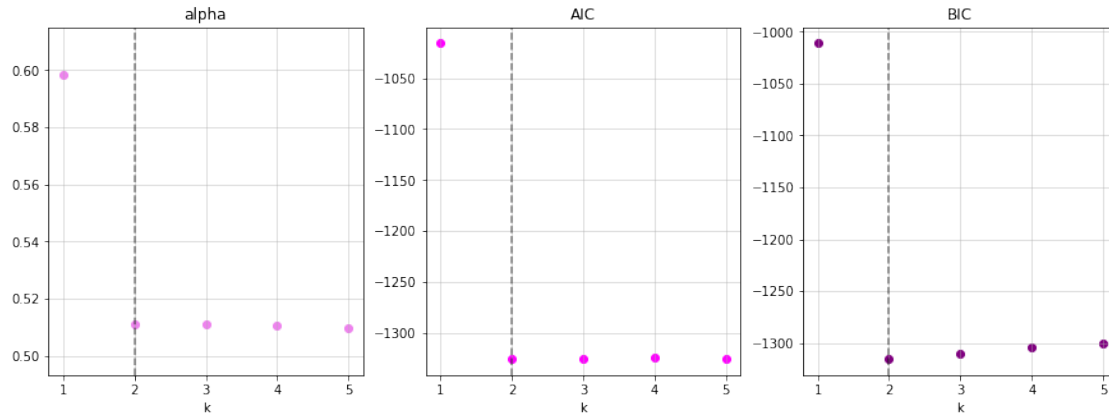
```
intercept = 0.0 reg.coef_ = [ 0.41343387  0.3117848  -0.02167565  0.00412761  
0.03220715]
```

```
[8]: k_tab, alpha_tab, AIC_tab, BIC_tab = np.array(tab).transpose()

fig, axs = plt.subplots(nrows=1, ncols=3, figsize = (15,5))
for ax in axs:
    ax.set_xlabel('k')
    ax.grid(True, alpha = 0.5)
    ax.axvline(x = 2, linestyle='dashed', color = 'black', alpha = 0.5)

axs[0].set_title('alpha')
axs[1].set_title('AIC')
axs[2].set_title('BIC')
axs[0].scatter(k_tab, alpha_tab, color = 'violet')
axs[1].scatter(k_tab, AIC_tab, color = 'fuchsia')
axs[2].scatter(k_tab, BIC_tab, color = 'purple')
```

```
[8]: <matplotlib.collections.PathCollection at 0x7fc6e7689490>
```



According to the 2-step regression method, $q=2$ is the order of $MA(q)$ process with the coefficients: * $\beta_1 = 0.4112644$ (coefficient at $\text{eps}+1$) * $\beta_2 = 0.3131448$ (coefficient at $\text{eps}+2$) * $\alpha_0 = 0.5112762$

```
[9]: q=2
Y = np.array(df['y(t)'])
X = np.array(df[['eps+1', 'eps+2']])

reg = LinearRegression(fit_intercept = False).fit(X, Y)
prediction = reg.predict(X)
N = len(Y)

alpha_0 = np.sqrt(((Y-prediction)**2).mean())
AIC = N*np.log(((Y-prediction)**2).mean()) + 2*q
BIC = N*np.log(((Y-prediction)**2).mean()) + np.log(N)*q

print("\n\nq = {:}, alpha = {:}\t AIC = {:}\t BIC = {:}\n".format(q,alpha_0,
    ↪AIC, BIC))
print("reg.coef_ = {:}\tintercept = {:}".format(reg.coef_, reg.intercept_))
```

```
q = 2, alpha = 0.5112762579620876      AIC = -1325.6152114266736      BIC =
-1315.8177823580136
```

```
reg.coef_ = [0.41227231 0.31086954]      intercept = 0.0
```

2 b)

Compute the sample autocorrelation function (SACF), $\rho(t)$ and the sample partial autocorrelation function (SPACF), $\phi(t)$ and plot them for $t = 1, \dots, 10$. Based on the plot of SPACF check the orderp

(on the plot include Gaussian $N(0, (T-t)^{-1})$ bands for 95% confidence level to check when SPACF becomes statistically zero).

```
[10]: def dividing_data_into_subseries(data, k=2, k_max=11):
    data_k = []
    for i in range(len(data)-k_max):
        tmp = [ ]
        for j in range(k):
            tmp.append(data[j+i])
        tmp.append(data[k+i])
        data_k.append(tmp)
    return np.array(data_k).T
```

```
[11]: def get_autocorrelation_coeff(data, delta):

    data_k = dividing_data_into_subseries(data, k=delta)
    denominator = (data**2).mean()
    nominator = (data_k[0]*data_k[-1]).mean()

    return nominator/denominator
```

```
[12]: def get_autocorrelation(p,data):

    autocorrelation_tab = [ ]

    for delta in range(1,p+1):
        autocorrelation = get_autocorrelation_coeff(data, delta)
        autocorrelation_tab.append(autocorrelation)

    return autocorrelation_tab
```

2.0.1 sample autocorrelation function (SACF)

```
[13]: p=10
p_tab = list(range(1,p+1))
autocorrelation_tab = get_autocorrelation(p,data)

for delta_t, corr in zip(p_tab, autocorrelation_tab):
    print(u'\u0394t = {:.}\t \u03C1(\u0394t)={:.2f}'.format(delta_t,corr ))

N = 490
confidence_level = 1.96/np.sqrt(N)

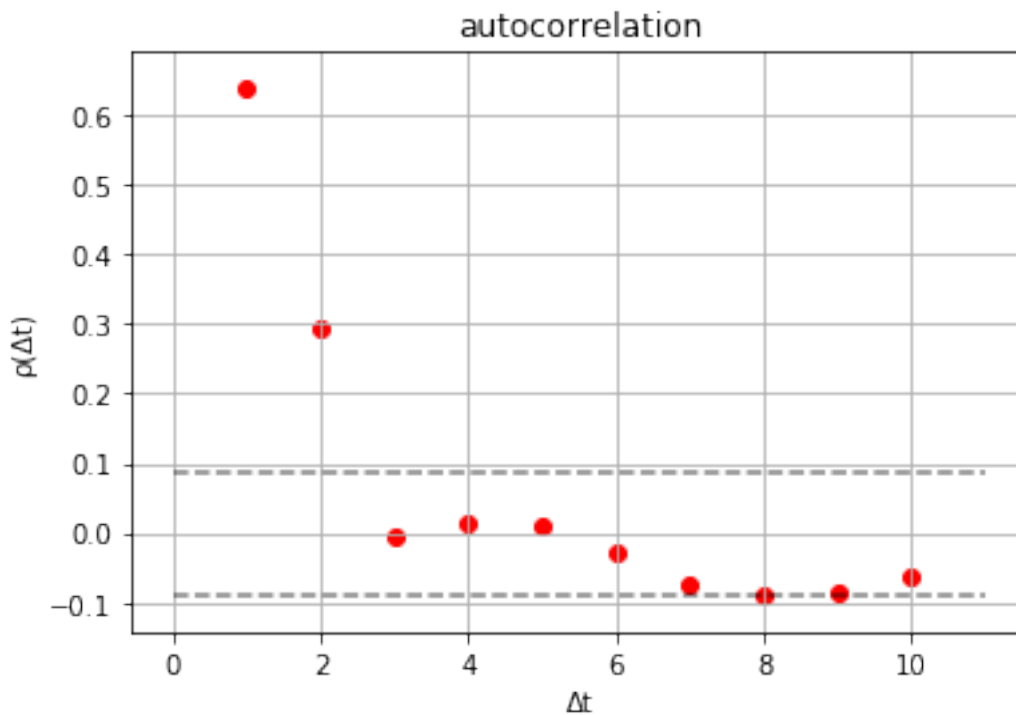
plt.title('autocorrelation')
```

```
plt.scatter(p_tab, autocorrelation_tab, color = 'red')
plt.ylabel(u'\u03C1(\u0394t)')
plt.xlabel(u'\u0394t')
plt.grid()

plt.hlines(y = confidence_level, xmin=0, xmax = p+1, linestyle='dashed', color='black', alpha = 0.5)
plt.hlines(y = -confidence_level, xmin=0, xmax = p+1, linestyle='dashed', color='black', alpha = 0.5)
```

```
 $\Delta t = 1$     ( $\Delta t$ )=0.639600
 $\Delta t = 2$     ( $\Delta t$ )=0.294154
 $\Delta t = 3$     ( $\Delta t$ )=-0.003510
 $\Delta t = 4$     ( $\Delta t$ )=0.014596
 $\Delta t = 5$     ( $\Delta t$ )=0.010283
 $\Delta t = 6$     ( $\Delta t$ )=-0.027150
 $\Delta t = 7$     ( $\Delta t$ )=-0.075388
 $\Delta t = 8$     ( $\Delta t$ )=-0.090840
 $\Delta t = 9$     ( $\Delta t$ )=-0.086528
 $\Delta t = 10$    ( $\Delta t$ )=-0.062394
```

[13]: <matplotlib.collections.LineCollection at 0x7fc6e7654e90>



2.0.2 Partial autocorrelation function (PACF)

```
[14]: def get_partial_autocorrelation(p, data):

    autocorrelation_tab = get_autocorrelation(p,data)

    M = np.identity(p)*0.5
    for i in range(p):
        for j in range(i+1, p):
            M[i][j] = autocorrelation_tab[j-i-1]

    A = np.matrix(M.T + M)
    A_inv = np.linalg.inv(A)

    psi_vec = np.array(np.dot(A_inv,autocorrelation_tab))[0]

    return psi_vec[-1]

[15]: p=10
p_tab = list(range(1,p+1))
partial_corr_tab_tab = []

for k in range(1,p+1):
    partial_corr_tab_tab.append(get_partial_autocorrelation(k,data))

for delta_t, p_corr in zip(p_tab, partial_corr_tab_tab):
    print(u'\u0394t = {:}\t \u03A6(\u0394t)={:2f}'.format(delta_t, p_corr ))

plt.title('partial autocorrelation')
plt.scatter(p_tab, partial_corr_tab_tab, color = 'red')
plt.ylabel(u'\u03A6(\u0394t)')
plt.xlabel(u'\u0394t')
plt.grid()
plt.hlines(y = confidence_level, xmin=0, xmax = p+1, linestyle='dashed', color='black', alpha = 0.5)
plt.hlines(y = -confidence_level, xmin=0, xmax = p+1, linestyle='dashed', color = 'black', alpha = 0.5)
```

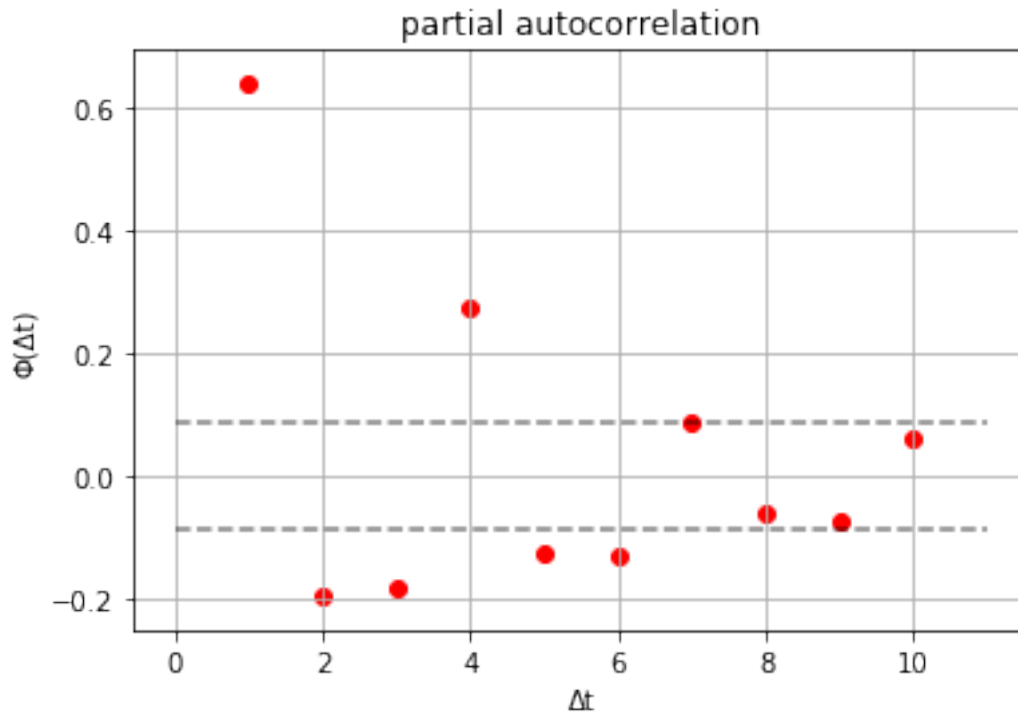
```
 $\Delta t = 1$      $\Phi(\Delta t)=0.639600$ 
 $\Delta t = 2$      $\Phi(\Delta t)=-0.194504$ 
 $\Delta t = 3$      $\Phi(\Delta t)=-0.182638$ 
 $\Delta t = 4$      $\Phi(\Delta t)=0.273179$ 
 $\Delta t = 5$      $\Phi(\Delta t)=-0.125215$ 
 $\Delta t = 6$      $\Phi(\Delta t)=-0.128887$ 
 $\Delta t = 7$      $\Phi(\Delta t)=0.086820$ 
```

```

 $\Delta t = 8$      $\Phi(\Delta t) = -0.060005$ 
 $\Delta t = 9$      $\Phi(\Delta t) = -0.071853$ 
 $\Delta t = 10$     $\Phi(\Delta t) = 0.060464$ 

```

[15]: <matplotlib.collections.LineCollection at 0x7fc6e75f7f50>



The autocorrelation drops abruptly to 0 (with confidence level 95%) after $q = 2$, therefore we may assume that the order of MA(q) process is 2.

3 c

For the order q established in (b) fit the parameters: $\beta_i (i = 1, \dots, q)$ and α_0 using the Yule-Walkermethod (in the matrix form).

```

[16]: def dividing_data_into_subseries(data, k=2):
        data_k = []
        for i in range(len(data)-k):
            tmp = [ ]
            for j in range(k):
                tmp.append(data[j+i])
            tmp.append(data[k+i])
            data_k.append(tmp)
        return np.array(data_k).T

```

```
[17]: data_1 = dividing_data_into_subseries(data, k=1)
      data_2 = dividing_data_into_subseries(data, k=2)
      data_3 = dividing_data_into_subseries(data, k=3)
```

We are looking for the autocorrelation function $ACF \equiv \rho_{\Delta t}$

$$\langle y_t y_{t-\Delta t} \rangle = \langle y_t^2 \rangle \rho_{\Delta t}$$

$$y_t = \sum_{i=0}^g \alpha_i \eta_{t-i}$$

$$y_{t-\Delta t} = \sum_{j=0}^g \alpha_j \eta_{t-\Delta t-j}$$

$$\langle y_t y_{t-\Delta t} \rangle = \sum_{i=0}^g \sum_{j=0}^g \langle \eta_{t-i} \eta_{t-\Delta t-j} \rangle = \sum_{i=\Delta t}^g \alpha_i \alpha_{i-\Delta t}$$

```
[18]: cov0 = (data**2).mean()
      cov1 = (data_1[0]*data_1[-1]).mean()
      cov2 = (data_2[0]*data_2[-1]).mean()
      cov3 = (data_3[0]*data_3[-1]).mean()

      print("cov0 = {:.2f} \t cov1 = {:.2f} \t cov2 = {:.2f} \t cov3 = {:.2f} ".
            ↪format(cov0, cov1, cov2, cov3))
```

```
cov0 = 0.524192          cov1 = 0.333107          cov2 = 0.150836          cov3 =
-0.003968
```

3.0.1 Yule Walker Equations:

- MA(1):

$$\langle y_t y_t \rangle = \alpha_0^2 + \alpha_1^2$$

$$\langle y_t y_{t-1} \rangle = \alpha_0 \cdot \alpha_1$$

- MA(2):

$$\langle y_t y_t \rangle = \alpha_0^2 + \alpha_1^2 + \alpha_2^2$$

$$\langle y_t y_{t-1} \rangle = \alpha_0 \alpha_1 + \alpha_1 \alpha_2$$

$$\langle y_t y_{t-2} \rangle = \alpha_0 \alpha_2$$

```
[19]: alpha0, alpha1, alpha2 = symbols('alpha0 alpha1 alpha2', real=True)
      x = symbols('x')
```

```
[20]: ## q=1

f1 = cov0-alpha0**2-alpha1**2
f2 = cov1-alpha0*alpha1

sol_q1 = solve( [f1,f2], set = True)
sol_q1 = sol_q1[1]
sol_q1
```

```
[20]: set()
```

```
[21]: ## q=2

f1=cov0-alpha0**2-alpha1**2-alpha2**2
f2=cov1-alpha0*alpha1-alpha1*alpha2
f3=cov2-alpha0*alpha2

sol_q2 = solve( [f1,f2,f3], set = True)
sol_q2 = sol_q2[1]
sol_q2
```

```
[21]: {(-0.521048424658716, -0.410972423453576, -0.289485433038988),
      (-0.289485433038988, -0.410972423453576, -0.521048424658716),
      (0.289485433038988, 0.410972423453576, 0.521048424658716),
      (0.521048424658716, 0.410972423453576, 0.289485433038988)}
```

3.0.2 Invertibility condition: checking the roots of the polynomial:

$$\sum a_i z^i = 0$$

If we take only a_i 's such that the roots $|z| < 1$, we are left with:

```
[22]: X = [1,x,x**2]

for coeffs in list(sol_q2):
    roots = solve(sum(list(map(lambda x,y: x*y, X, coeffs))))
    print("\ncoeffs:\t", coeffs)
    print("roots:\t", roots)
```

```
coeffs: (0.521048424658716, 0.410972423453576, 0.289485433038988)
roots:  [-0.709832648812809 - 1.13844192863999*I, -0.709832648812809 +
1.13844192863999*I]
```

```
coeffs: (-0.521048424658716, -0.410972423453576, -0.289485433038988)
roots:  [-0.709832648812809 - 1.13844192863999*I, -0.709832648812809 +
1.13844192863999*I]
```

```

coeffs: (0.289485433038988, 0.410972423453576, 0.521048424658716)
roots:  [-0.394370661155689 - 0.632498514735841*I, -0.394370661155689 +
0.632498514735841*I]

```

```

coeffs: (-0.289485433038988, -0.410972423453576, -0.521048424658716)
roots:  [-0.394370661155689 - 0.632498514735841*I, -0.394370661155689 +
0.632498514735841*I]

```

for $q = 2$ we have two possible sets of coefficients α_i :

- $\alpha_0 = 0.52105, \alpha_1 = 0.41097, \alpha_2 = 0.28949$
- $\alpha_0 = -0.52105, \alpha_1 = -0.41097, \alpha_2 = -0.28949$

4 d)

Using the data and the fit of point (a) and/or (c) compute the empirical noise

$$\hat{\eta}(t) = \frac{y_t - \hat{y}_t}{\alpha_0}$$

and check if it has standard Gaussian $N(0,1)$ distribution (use e.g. Kolmogorov-Smirnov test).

[23]: *## Based on results in a:*

```

coeff_a = np.array([ 0.41126442, 0.31314482])  ## a1, a2
alpha_0a = 0.5113506601881491

## Based on results in c:
coeff_c = np.array([0.410972423453576, 0.289485433038988])  ## a1, a2
alpha_0c = 0.521048424658716

```

[24]: `df.drop(['y(t5)', 'y(t4)', 'y(t3)', 'eps+3', 'eps+4', 'eps+5'], inplace = True, ↪axis = 1)`
`df.head()`

```

[24]:      y(t2)    y(t1)    y(t)    eps    eps+1    eps+2
5  0.065571  1.144725  0.265750 -0.563038  1.353333  0.103533
6  1.144725  0.265750 -0.153007 -0.614121 -0.563038  1.353333
7  0.265750 -0.153007  0.284510  1.575092 -0.614121 -0.563038
8 -0.153007  0.284510  1.295828  1.452625  1.575092 -0.614121
9  0.284510  1.295828  0.755126 -0.540861  1.452625  1.575092

```

[25]: `q=2`
`Y = np.array(df['y(t)'])`
`X = np.array(df[['eps+1', 'eps+2']])`
`N = len(Y)`

```
reg = LinearRegression(fit_intercept = False).fit(X, Y)
df['prediction'] = reg.predict(X)

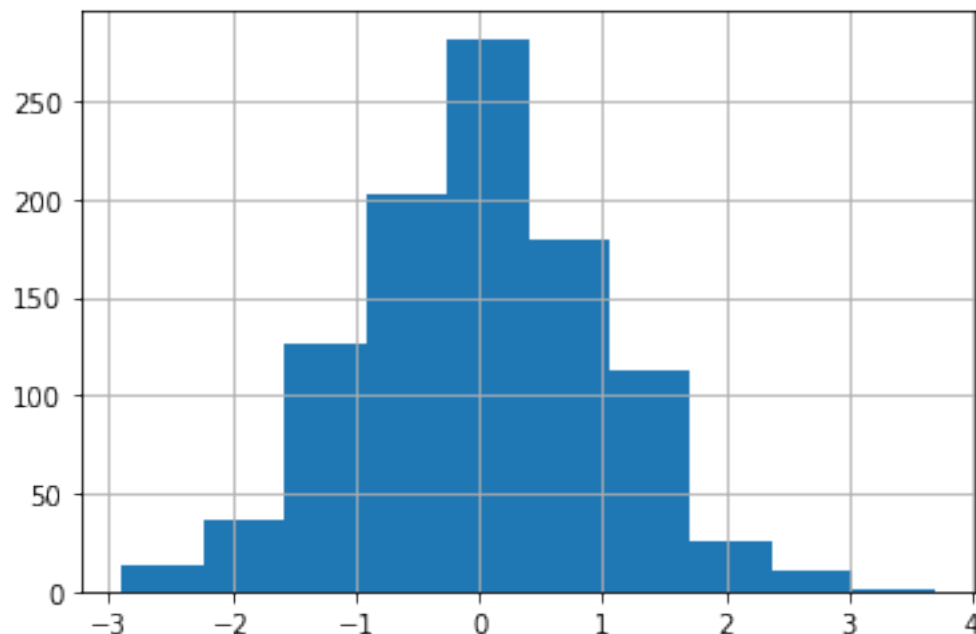
alpha_0 = np.sqrt(((Y-df['prediction'] )**2).mean())
df['empirical_noise'] = (Y - prediction)/alpha_0

print("reg.coef_ = {:}\t alpha_0 = {:}".format(reg.coef_, alpha_0) )
```

```
reg.coef_ = [0.41227231 0.31086954]      alpha_0 = 0.5112762579620874
```

```
[26]: df['empirical_noise'].hist()
```

```
[26]: <matplotlib.axes._subplots.AxesSubplot at 0x7fc6e74af890>
```



```
[27]: df['empirical_noise'].std()
```

```
[27]: 1.0004284202360652
```

```
[28]: from scipy.stats import norm, kstest
```

```
D_N, p_value = kstest(df['empirical_noise'], 'norm', args=(0,1))

print("data: test statistic: D_N = {:}, p-value = {:}".format(D_N, p_value) )
```

```
data: test statistic: D_N = 0.025872930770524993, p-value = 0.520767196660961
```

5 e)

Using the fit of point (a) and/or (c) simulate $N = 100$ future(forecast) paths for $t = T + 1, T + 2, \dots, T + 10$. Using the generated forecast paths estimate the mean value $\langle y(t) \rangle$ and the standard deviation $\sigma(y(t))$ of $y(t)$ for each future $t = T + 1, T + 2, T + 10$ and plot them as the continuation of the sample data series (plot of mean with error bars of standard deviation).

We may predict only 2 next steps for MA(2) process

```
[31]: def data_generator(alpha1, alpha2, alpha_0, past_data, T=2):

    for i in range(len(past_data), T + len(past_data)):
        noise = np.random.normal(0,1)
        new = alpha_0*noise + alpha1*past_data[i-1] + alpha2*past_data[i-2]
        past_data= np.append(past_data,new)

    return past_data
```

```
[32]: alpha1, alpha2 = [ 0.41126442, 0.31314482]
alpha_0 = 0.5113506601881491

past_data = data[-2:]
n = 100
data_gen = []

for i in range(n):
    data_gen.append(data_generator(alpha1, alpha2, alpha_0, past_data))
```

```
[34]: cols=[ 't-1', 't', 't+1', 't+2']

df_gen = pd.DataFrame(data_gen, columns = cols)
df_gen
```

```
[34]:      t-1      t      t+1      t+2
0  -0.401085 -0.831914  0.043877 -0.374000
1  -0.401085 -0.831914 -1.344821 -1.238094
2  -0.401085 -0.831914 -0.257514 -0.943468
3  -0.401085 -0.831914 -0.456999 -1.223775
4  -0.401085 -0.831914 -0.704910 -0.630838
..      ...      ...      ...      ...
95 -0.401085 -0.831914  0.018417  0.314068
96 -0.401085 -0.831914  0.190134  0.092740
97 -0.401085 -0.831914 -0.861085 -0.987868
98 -0.401085 -0.831914 -0.380093 -0.194630
99 -0.401085 -0.831914  0.676589  0.068266
```

[100 rows x 4 columns]

```
[36]: fig, ax = plt.subplots(figsize = (12,10))

ax.set_ylabel('y_t')
ax.set_title(' N=100 future paths for t={T+1,T+2}', fontsize = 15)
ax.grid(color = 'gray', alpha = 0.5)

for i in range(n):
    ax.plot(df_gen.loc[i])
```

