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Summary

Each team fixed each part and set up the details. A broom team had started to make a broom part and a platform team just finished the detail things. Chapter 3 of the paper had been written down.

What C.C completed this week:
- Went to Menards to buy equipment and tools
- Made broom prototype with wood
- Installed ROS2 Foxy on Ubuntu 20.0.5 [1]
- Searched how to add Lidar and ROS2 [2]
- Downloaded Ubuntu 20.04.5 on Raspberry Pi 4b
- Designed robot platform and planned a meeting with Professor Eric
- Started to write chapter 3 of the paper
- Connected several Raspberry Pis 4b using publisher and subscriber on ROS2 [1]
- Finished ROS2 beginner tutorial [3]
- Prepared for midterm presentation, set presentation flow, and made PPT material

Things to do by next week
- The platform team is going to make the first floor of the robot platform.
- The broom team will keep making the broom part.
- The network team is going to keep studying ROS 2.
- All team members will prepare for midterm presentations.

Problems or challenges:
- Several trials and errors from installing ROS2 Foxy on Ubuntu 20.04.5
- Connection between Raspberry pi and laptop did not work.

References

[1] "ROS 2 Documentation: Foxy." ROS.org. http://docs.ros.org/en/foxy/Installation/Ubuntu-Install-Debians.html (accessed Oct. 17, 2022).

[2] Articulated Robotics. How do we add LIDAR to a ROS robot?. (Jun. 2, 2022), Accessed: Oct. 19, 2022. [Online Video]. Available: https://docs.ros.org/en/foxy/Installation/Ubuntu-Install-Debians.html

[3] "ROS 2 Documentation: Foxy." ROS.org. http://docs.ros.org/en/foxy/Tutorials/Beginner-CLI-Tools.html (accessed Oct. 21, 2022).