

Image Stitching#3

ISL

안재원

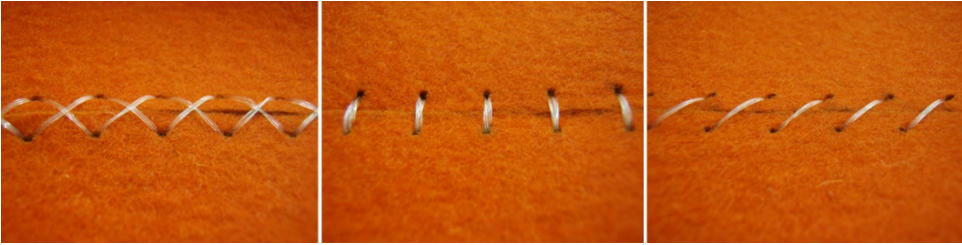
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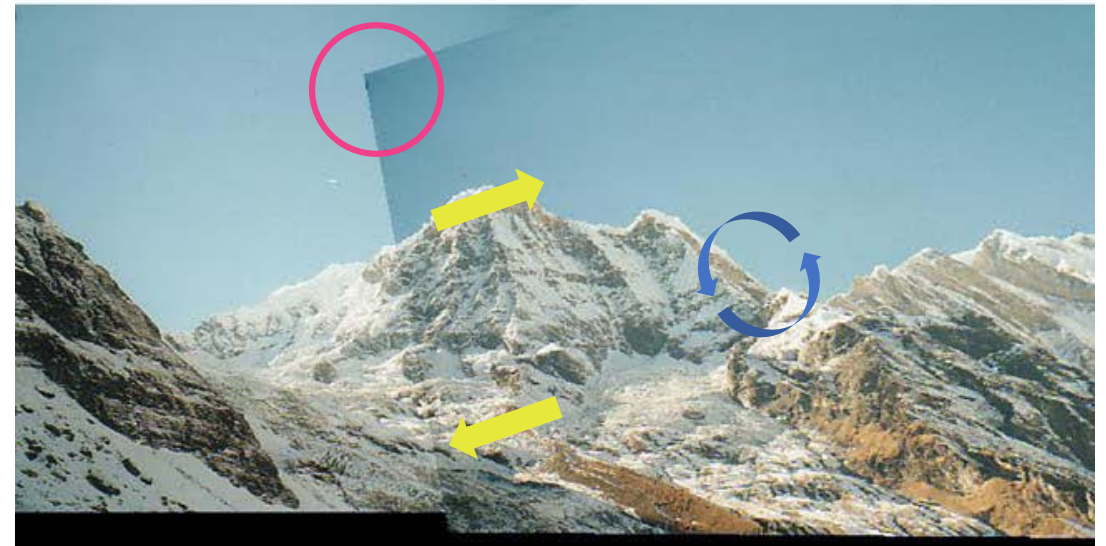
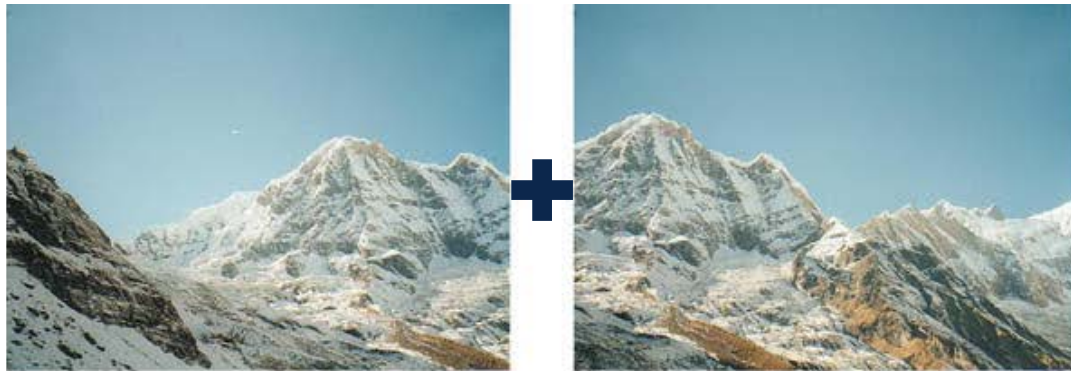
Stitching

Intro

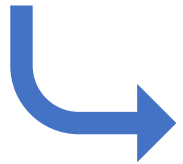
- Stitch : 바느질(방식)



- Image stitching : 여러 사진을 합쳐 고해상도(파노라마) 이미지를 생성하는 기법



- 이동 및 회전에 맞춰 영상 병합. ○ (blue)
- 형태적 왜곡 문제에 맞춰 영상 병합. ○ (yellow)
- 각 영상의 특성 차이가 없도록 영상 병합. ○ (pink)



매칭 기반의 영상 병합



Stitching

Stitching 의 3 단계 구성



Alpha blending



After labeling

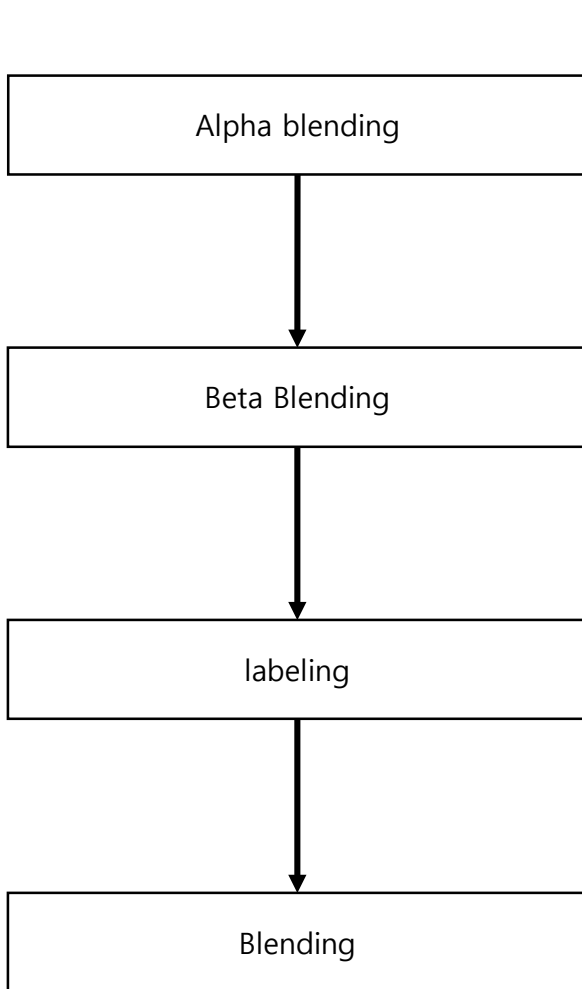


Blending

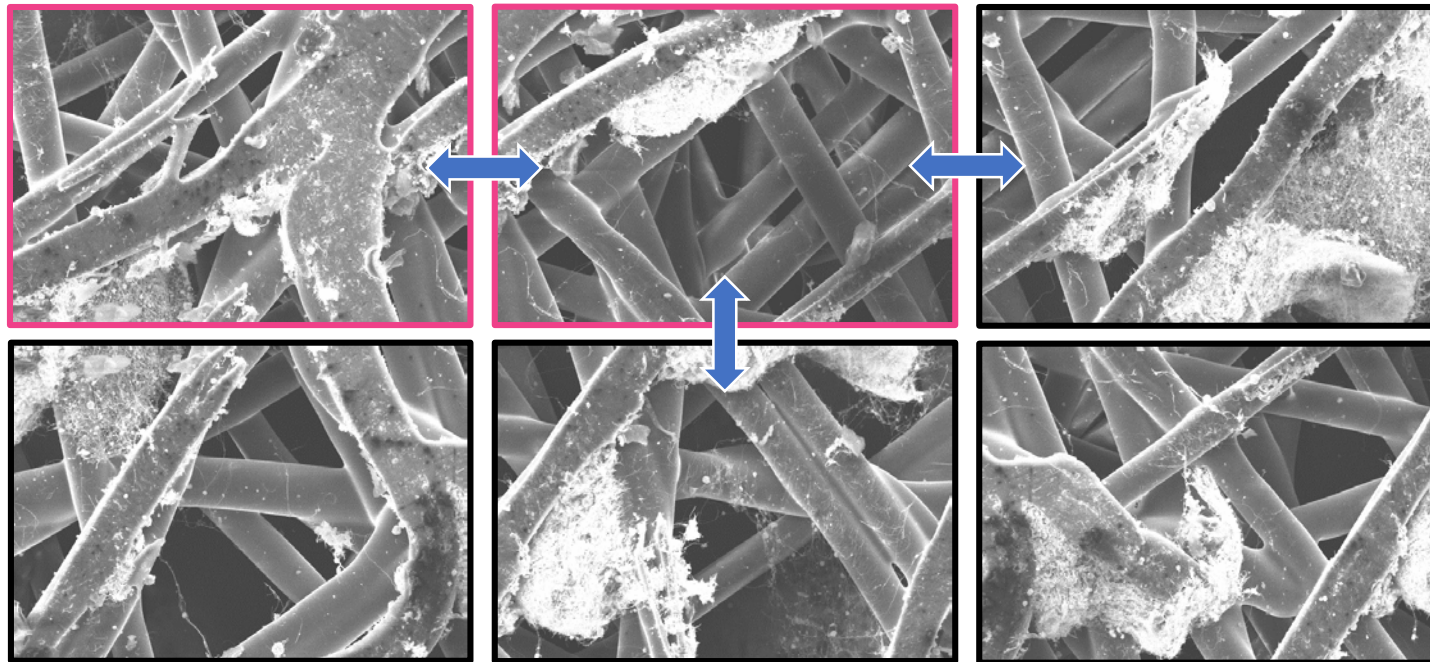


Stitching

Stitching의 4 단계 구성



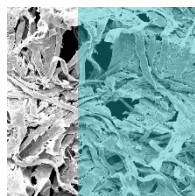
- Stitching을 위한 모든 방향의 움직임 정보(Motion vector) 수집.



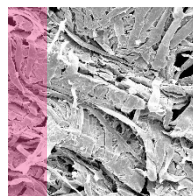
- MFVed NCC(Multiple Feature Value weightED Normalized Cross Correlation)

$$wNCC(x, y) = \frac{1}{N} \sum_{(\alpha, \beta) \in \Omega} \frac{(S(\alpha, \beta) - \bar{S})(t(\alpha, \beta) - \bar{t})}{\sigma_S \sigma_t} (1 + Sobel(t(\alpha, \beta)) + Harris(t(\alpha, \beta)))$$

$$\times \bar{f} = E[f(\alpha, \beta) | (\alpha, \beta) \in \Omega]$$



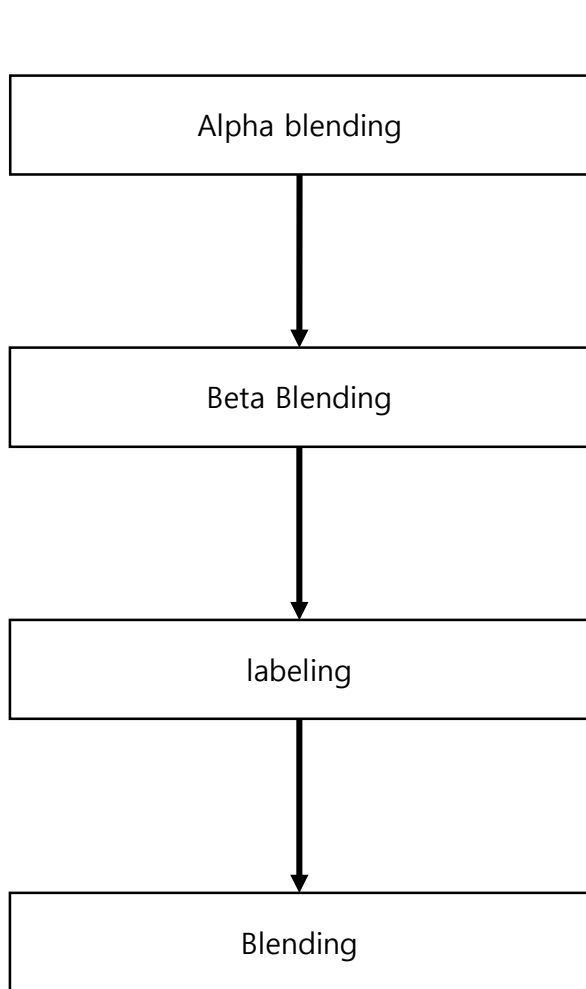
Search area



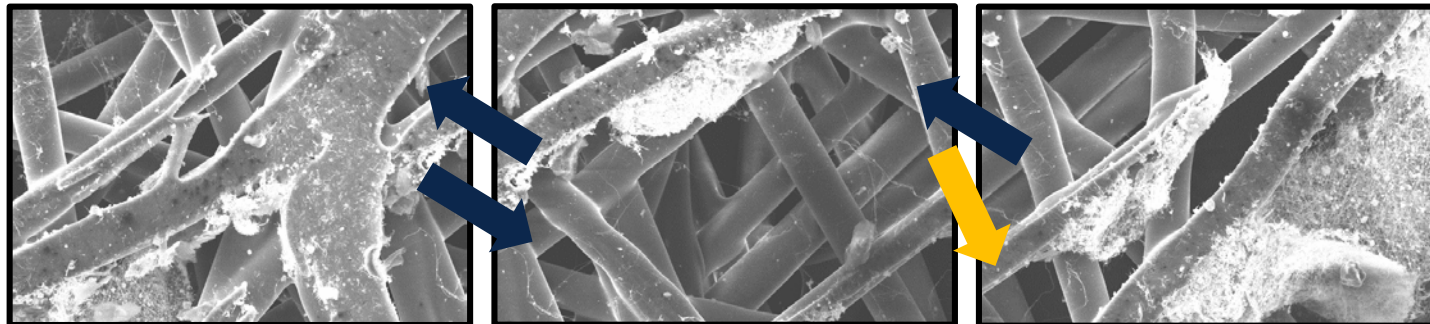
Template

Stitching

Stitching의 4 단계 구성

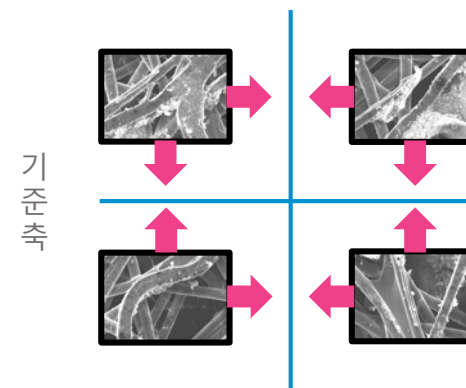


- Alpha blending에서 구한 움직임 정보 필터링.



- Vector median filter를 기반으로 기준 움직임 선정, 기준 움직임에 충실한 정보를 바탕으로 기준축 생성 및 스티칭

$$v_{vm} = \operatorname{argmin}_{v \in V} \sum_{u \in U} \|v - u\|$$

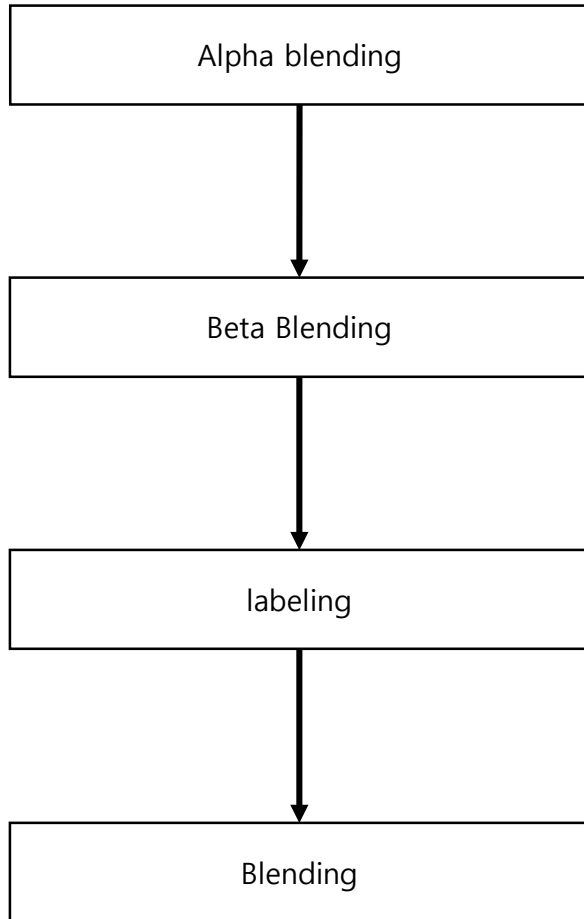


- 부적합한 움직임 정보는 NCC value map을 이용해 새로운 움직임 선정
- NCC value map

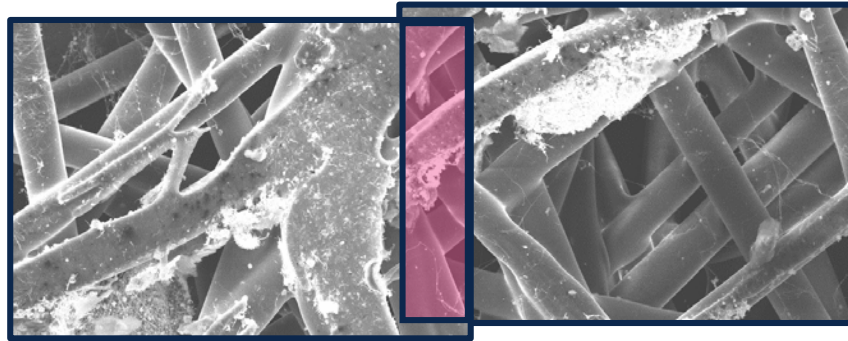


Stitching

Stitching의 4 단계 구성



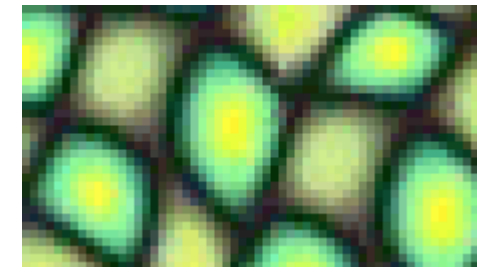
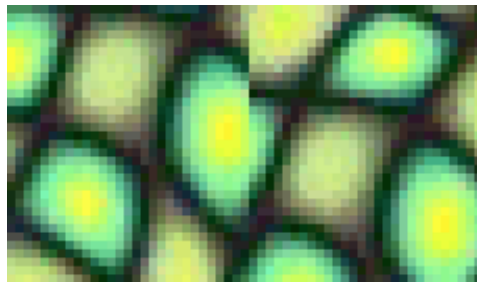
- 자연스러운 연결을 위해 영상의 경계를 가변적으로 선정
- 영상이 겹쳐진 영역에서 동작하며, 겹쳐진 영상 간의 차이가 최소가 되는 경계를 따라 영상을 이어 붙인다.



- Labeling boundary

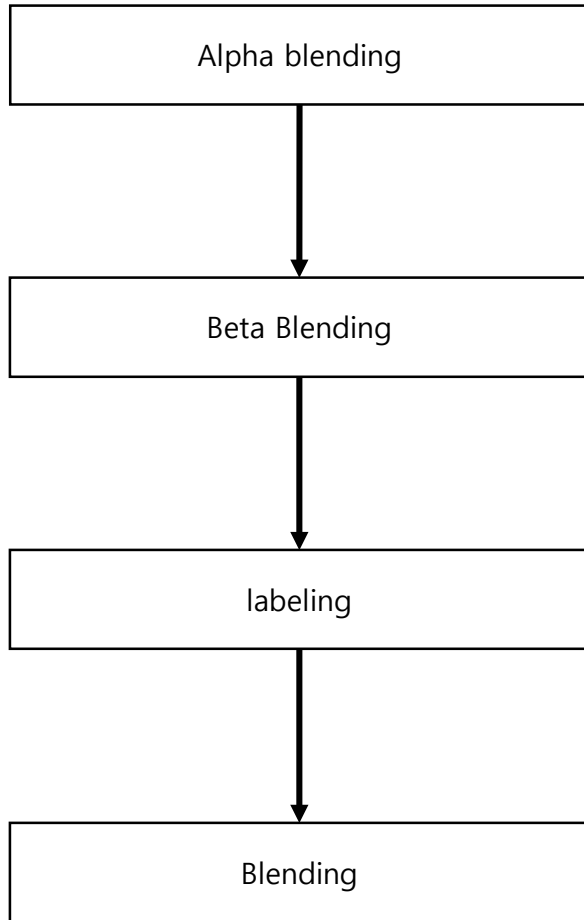
s1	s2	s3	s1	s2	s3	s1	s2	s3
5	4	1	5	4	1	5	4	1
2	5	0	2	5	0	2	5	0
1	1	7	1	1	7	1	1	7
6	0	1	6	0	1	6	0	1
0	0	0	0	0	0	0	0	0
e1	e2	e3	e1	e2	e3	e1	e2	e3
= 5			= 2			= 2		

- Labeling의 효과

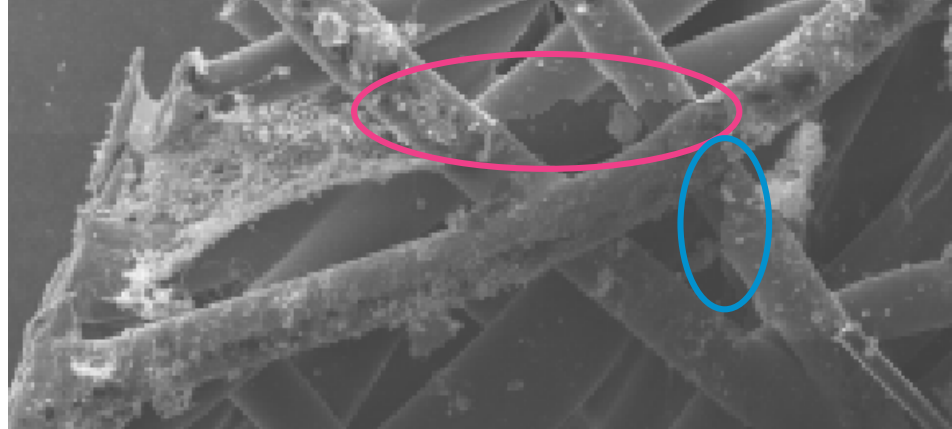


Stitching

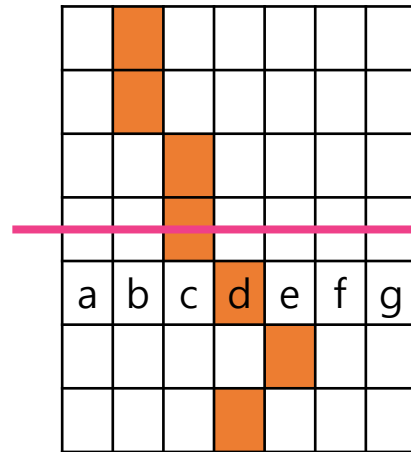
Stitching의 4 단계 구성



- 인접한 영상 간의 촬영 상태 차이에 따라 발생하는 어색함을 줄이는 과정.

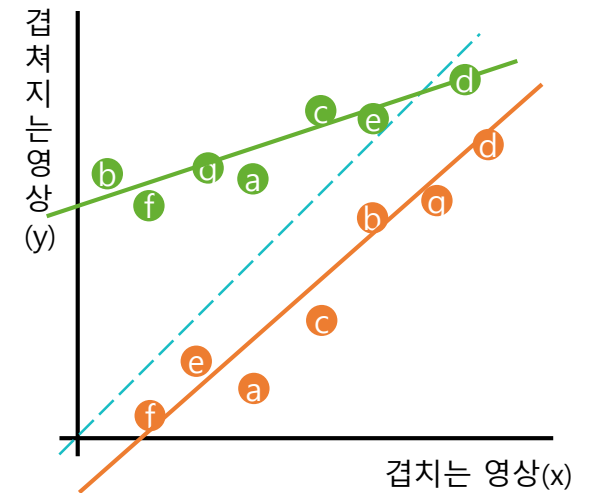


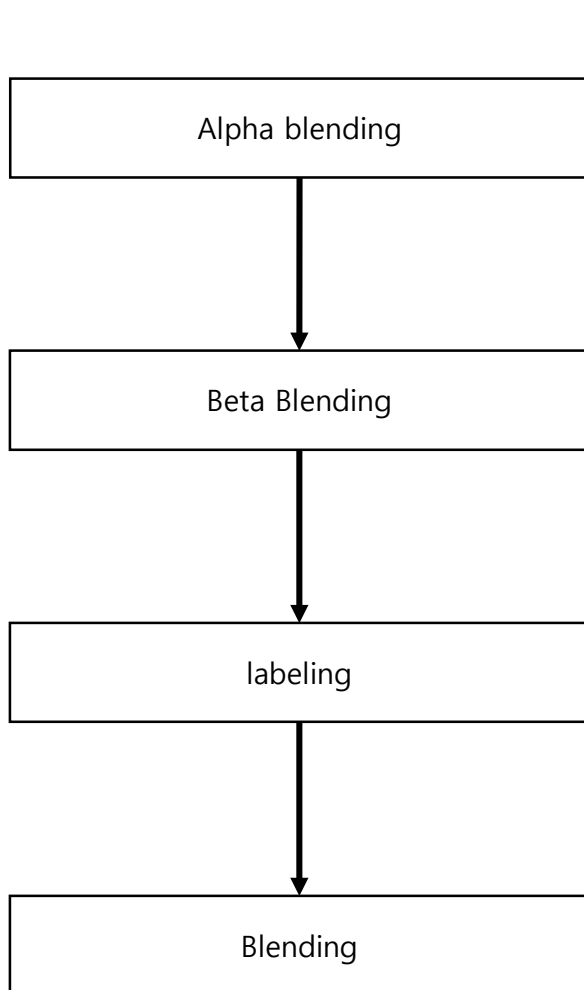
- 겹쳐진 영역의 경향성 변화를 이용해 어색함을 줄인다.



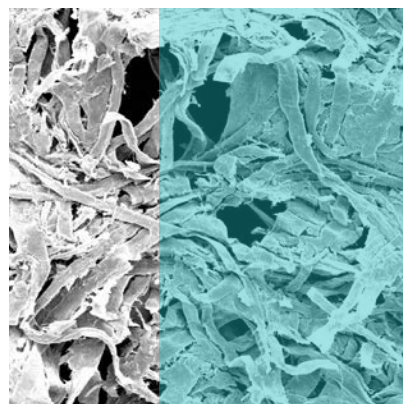
영상 쌍의 연결 방향

Labeling boundary

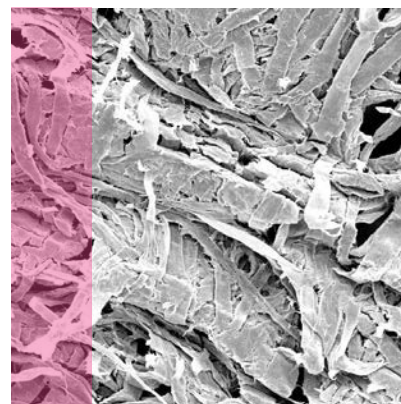




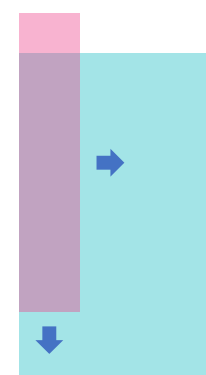
- 모든 위치에서 영상 쌍을 비교하기 때문에 많은 연산 시간을 필요로 한다.



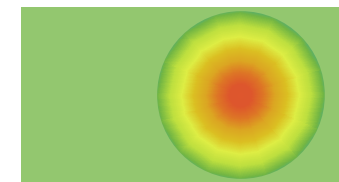
Search area



Template



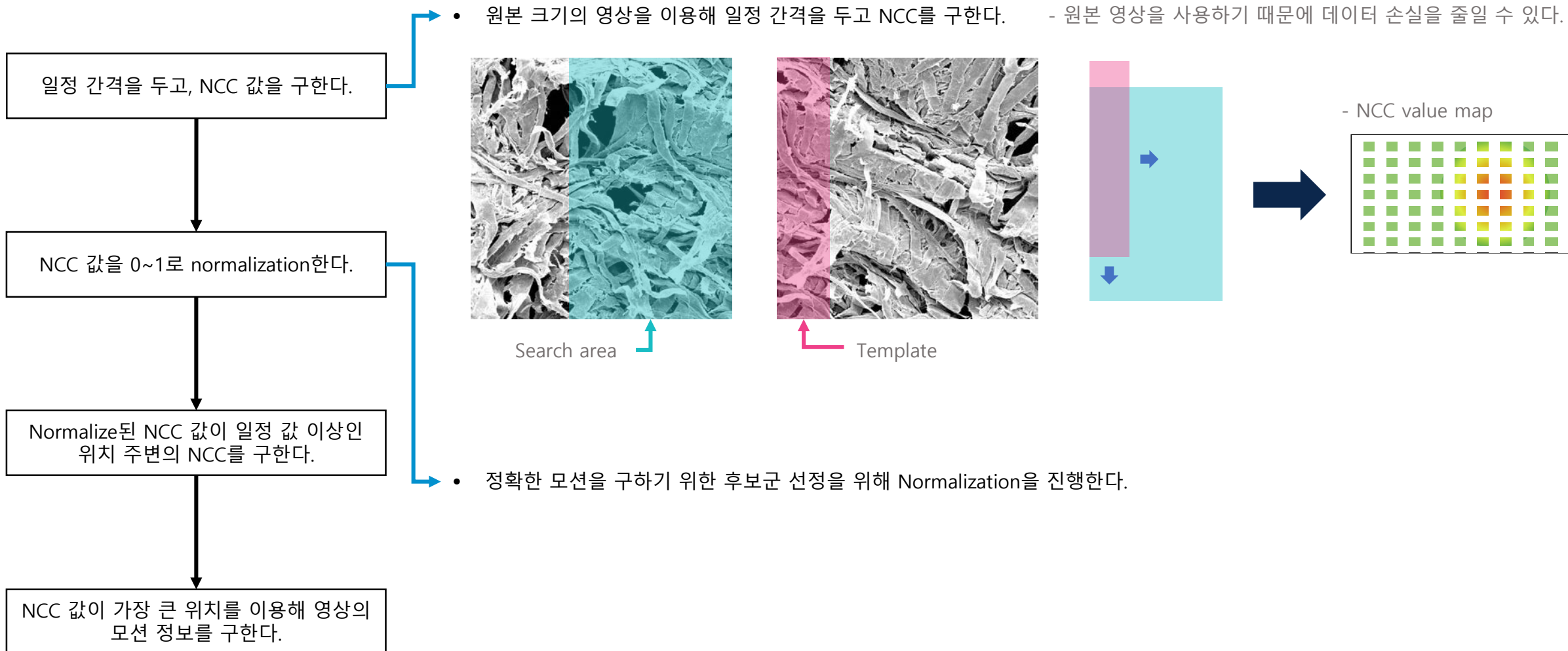
- NCC value map

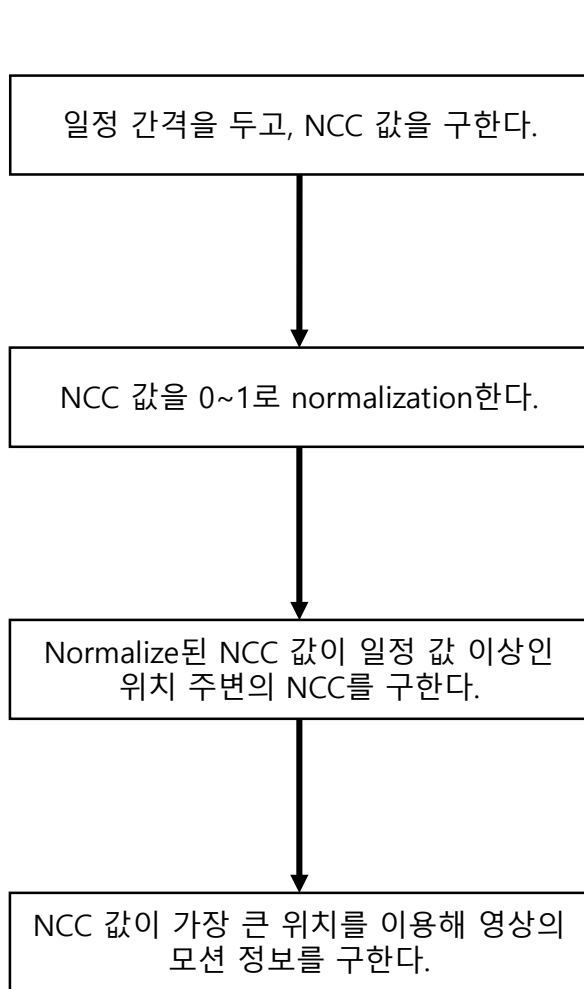


- Alpha blending 단계에서 630x433 영상 25(5x5)장 기준 약 100초 정도 소비
 - Overlap : 10%
 - Overlap error rate : 10%
 - 병렬처리 연산(OpenMP 등 미사용)
- Alpha blending 단계에서 600x600 영상 9(3x3)장 기준 약 420초 정도 소비
 - Overlap : 20%
 - Overlap error rate : 20%
 - 병렬처리 연산(OpenMP 등 미사용)

해결방안

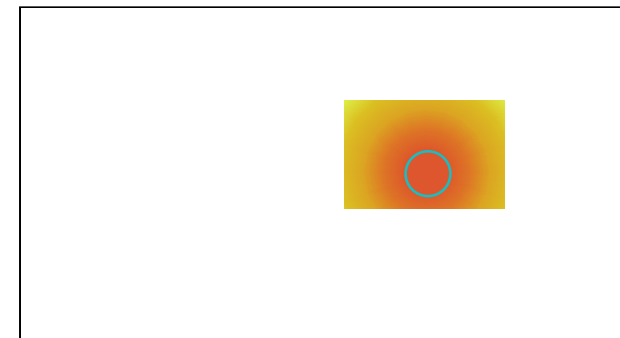
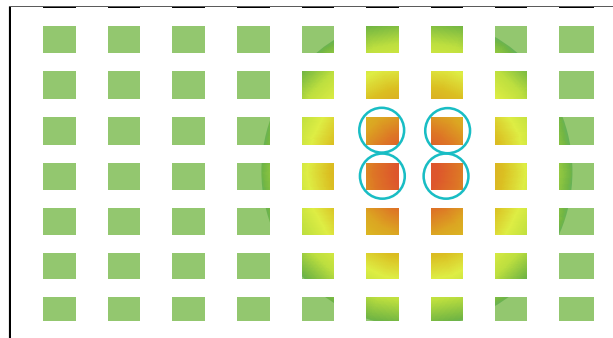
Interval search





- 선정된 위치 주변 영역에서 NCC 값을 구한다.

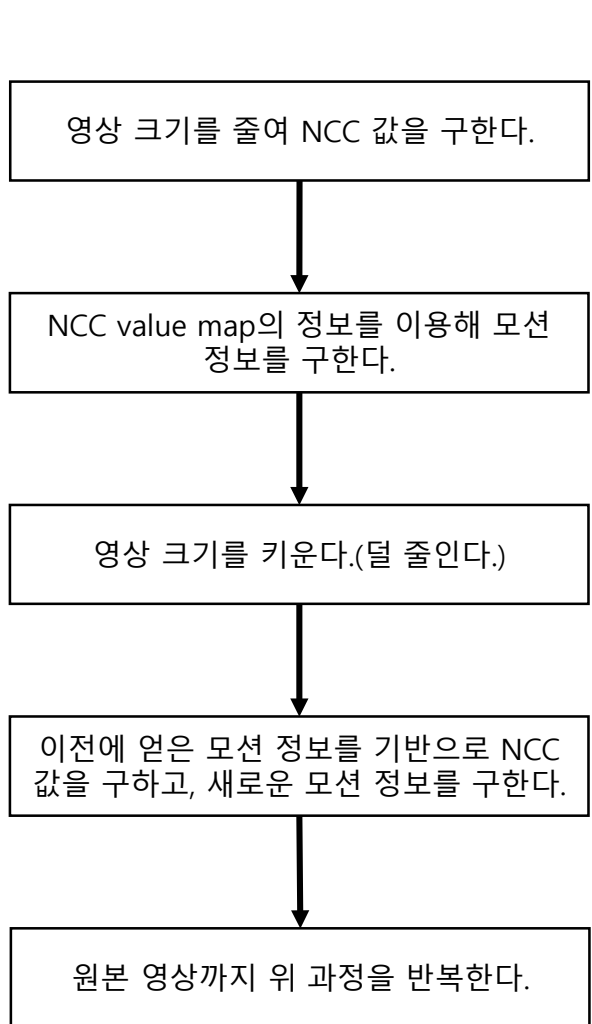
- NCC value map



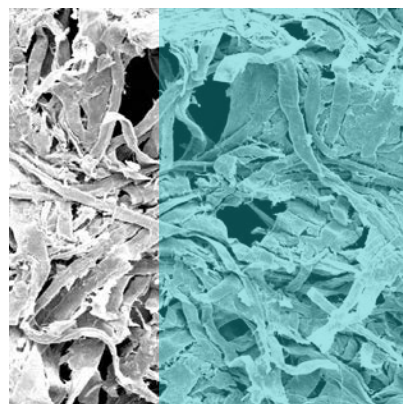
- 새로운 NCC value map에서 최종적인 모션 정보를 선정한다.

해결방안

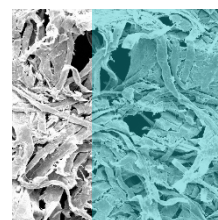
Hierarchical search



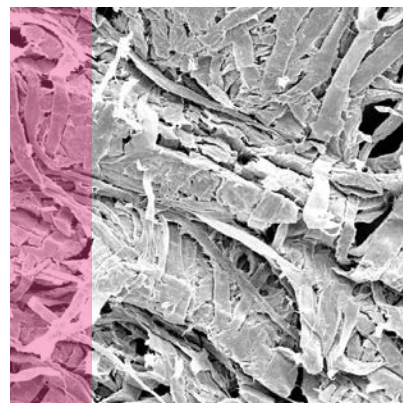
- 영상 크기를 줄여 NCC 값을 구하고, 모션 정보를 추정한다.



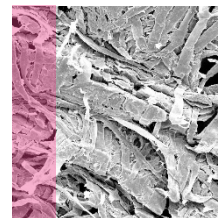
Search area



Search area

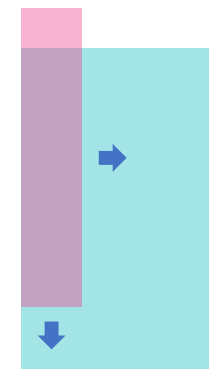


Template

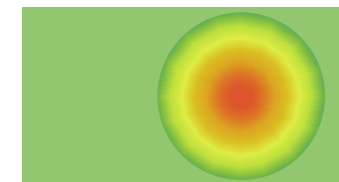


Template

- 영상의 크기를 줄이기 때문에 데이터 손실이 생길 수 있다.



- NCC value map

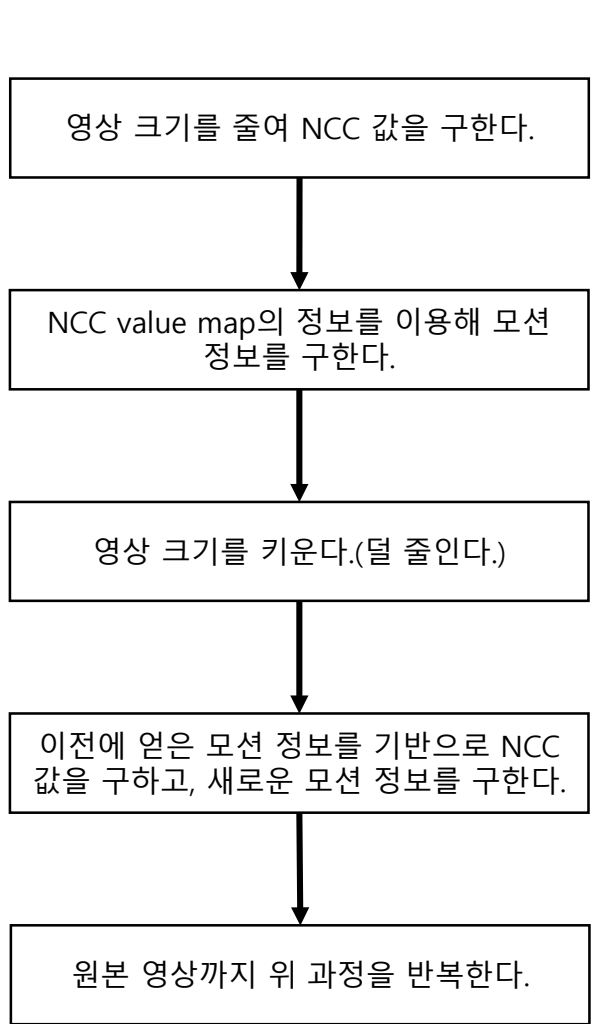


- NCC value map

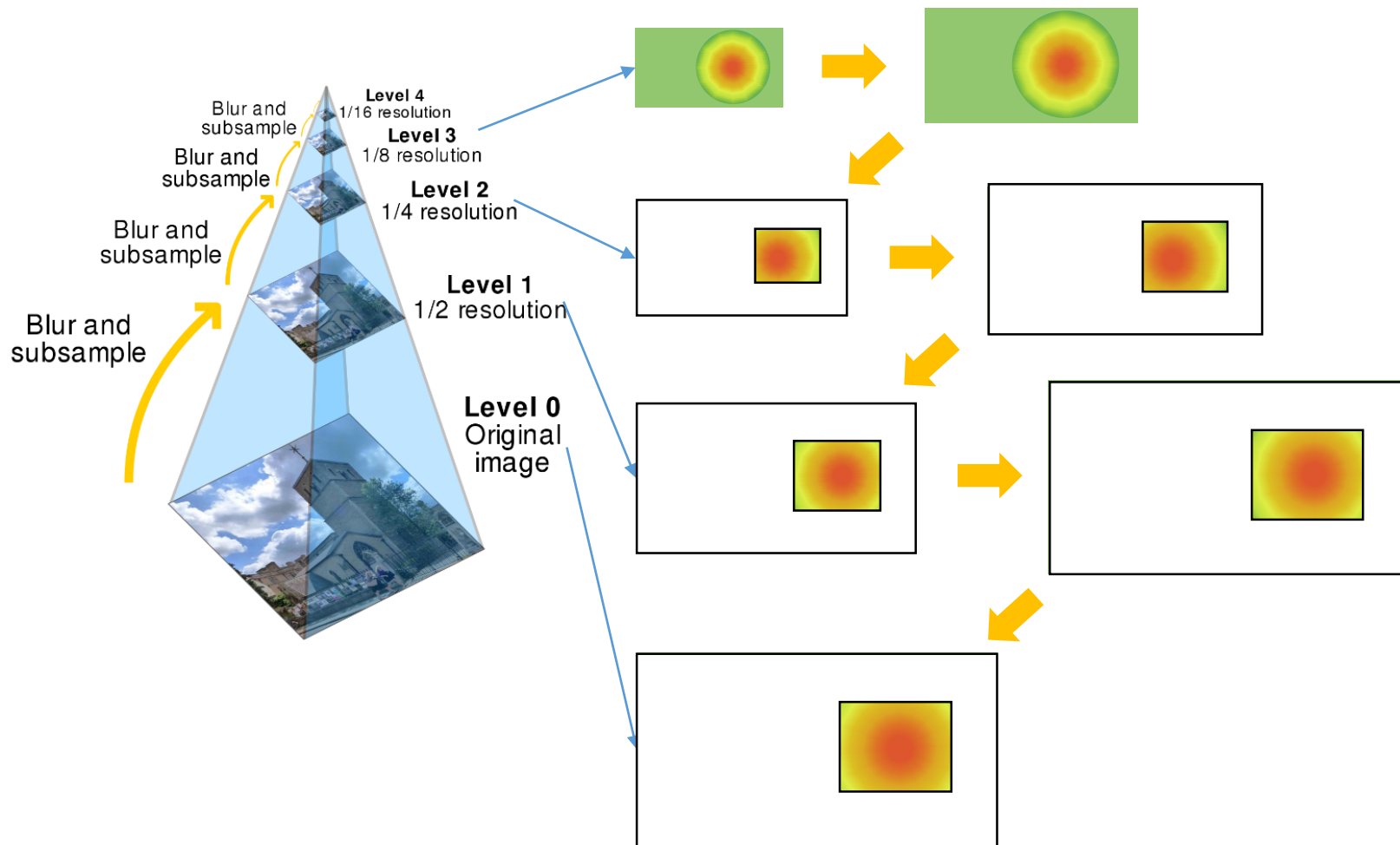


해결방안

Hierarchical search



- 영상 크기를 바꿔 가며 NCC 값을 구하고, 모션 정보를 추정한다.
- 이전 단계의 NCC map을 기반으로 다음 단계의 탐색 위치 선정.



Result

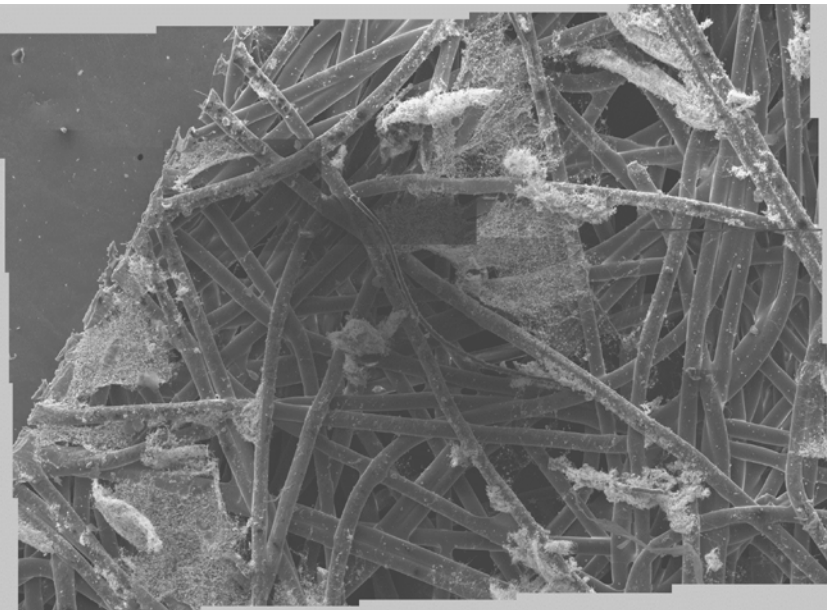
시간 비교

- Case #1 : 630x433 영상 25(5x5)장
 - Overlap : 10%
 - Overlap error rate : 10%
 - 병렬처리 연산(OpenMP 등 미사용)

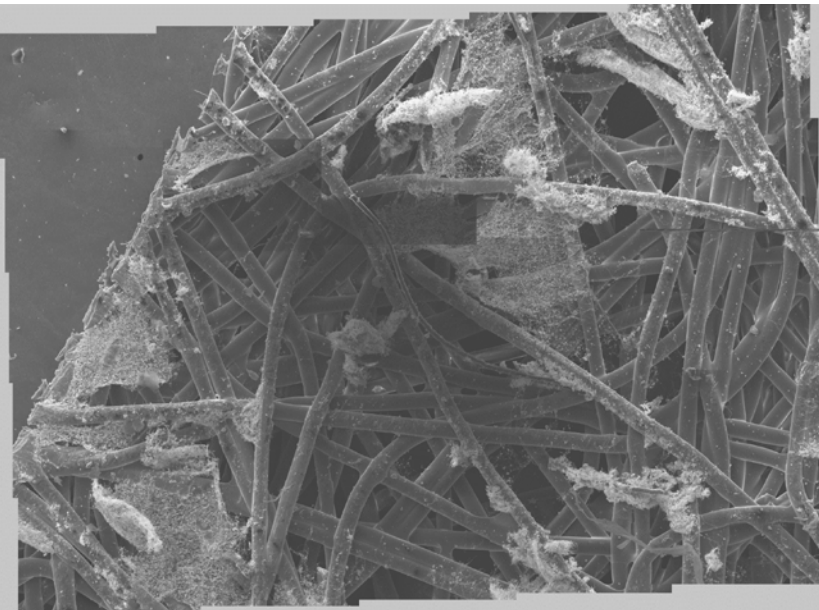
- ◆ 기존 방법 : 약 100초
- ◆ Interval search : 약 40초
 - Interval : 10%
 - Threshold : 70%
- ◆ Hierarchical search : 약 1.5초
 - 최소 크기 : 25%
 - 스텝 수 : 4
 - Threshold : 70%

- Case #2 : 600x600 영상 9(3x3)장
 - Overlap : 20%
 - Overlap error rate : 20%
 - 병렬처리 연산(OpenMP 등 미사용)

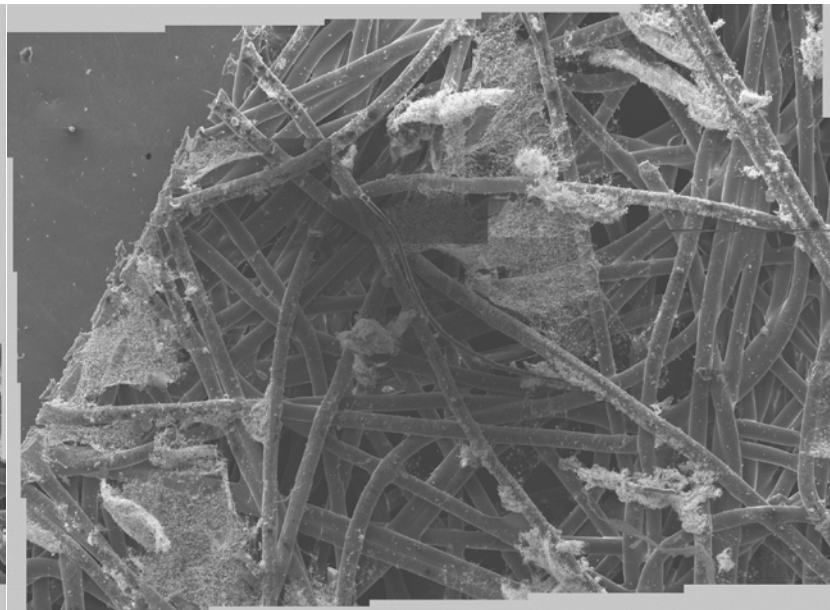
- ◆ 기존 방법 : 약 420초
- ◆ Interval search : 약 160초
 - Interval : 10%
 - Threshold : 70%
- ◆ Hierarchical search : 약 3.5초
 - 최소 크기 : 25%
 - 스텝 수 : 4
 - Threshold : 70%



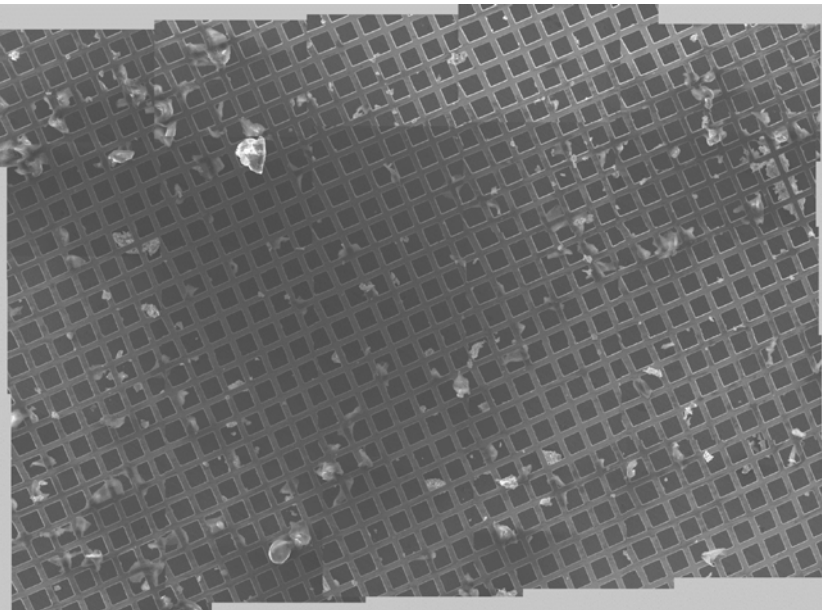
- Original



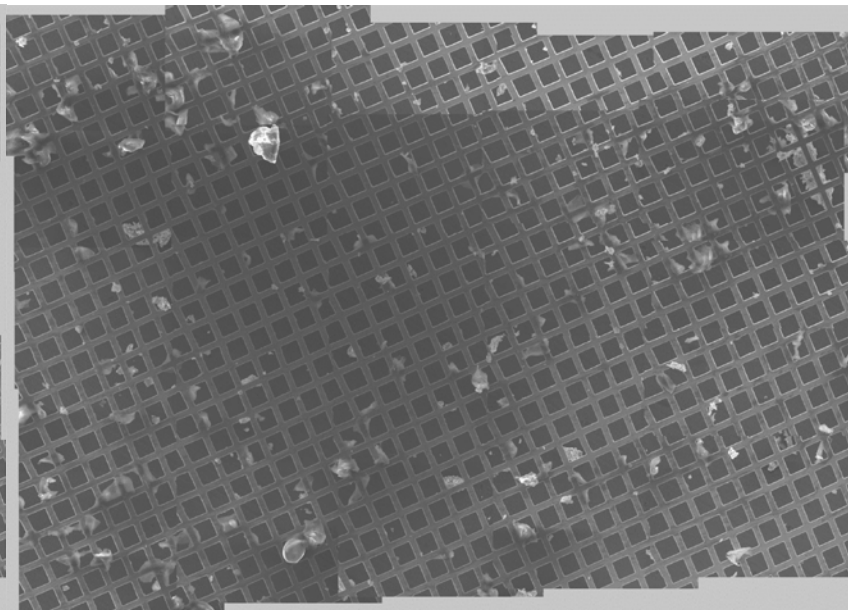
- Interval



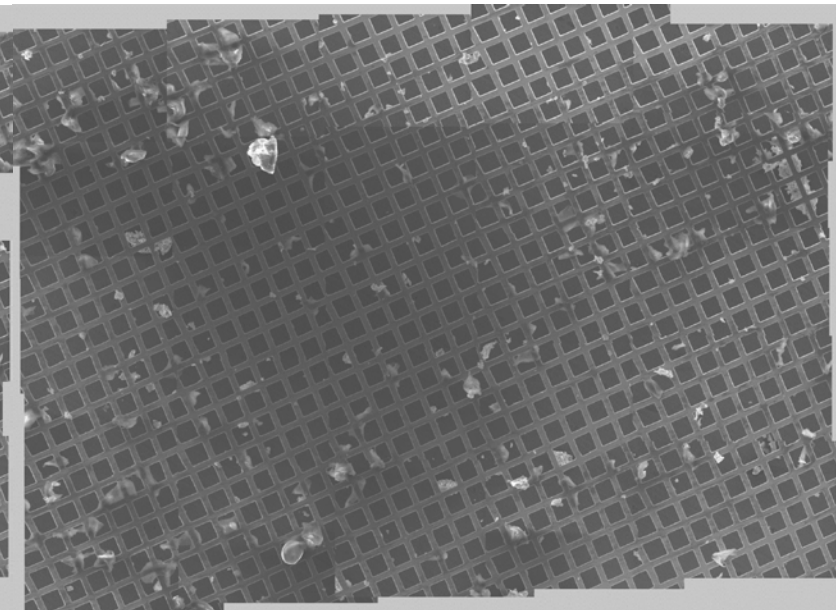
- Hierarchical



- Original

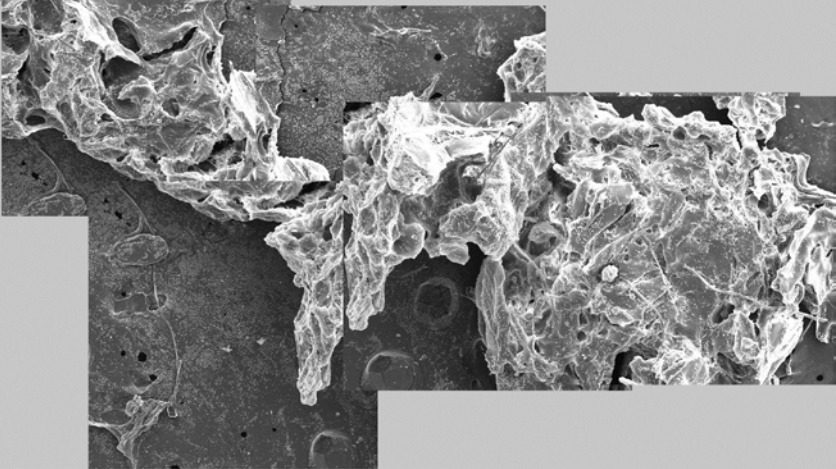
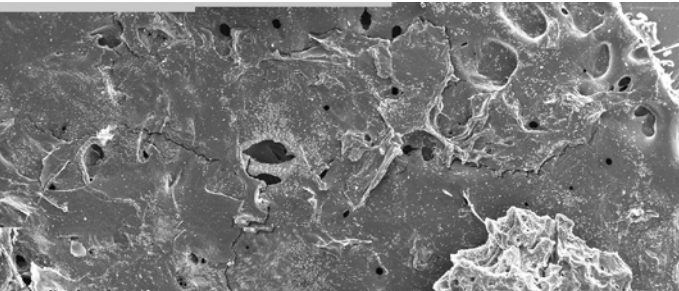


- Interval

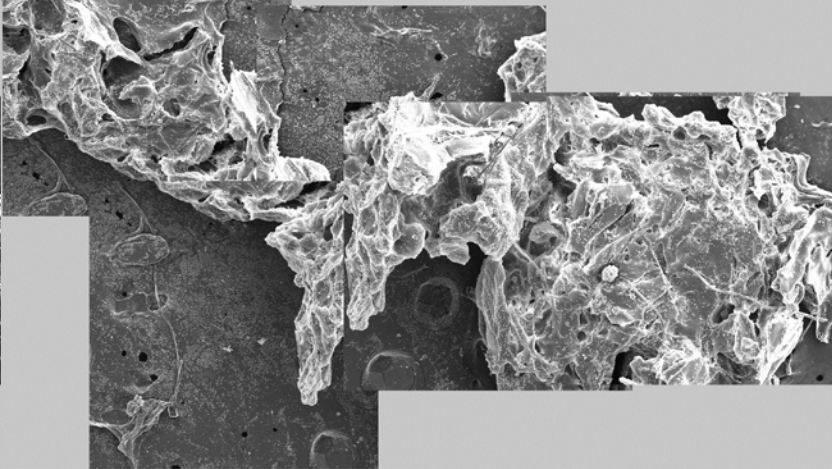
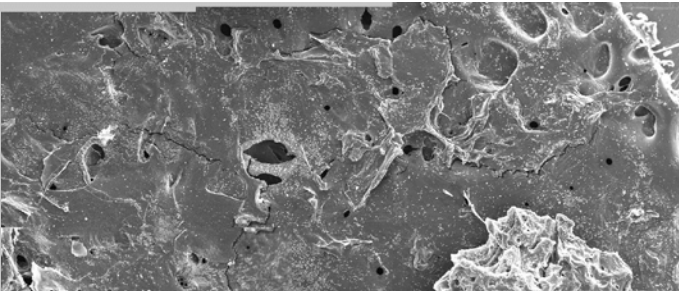


- Hierarchical

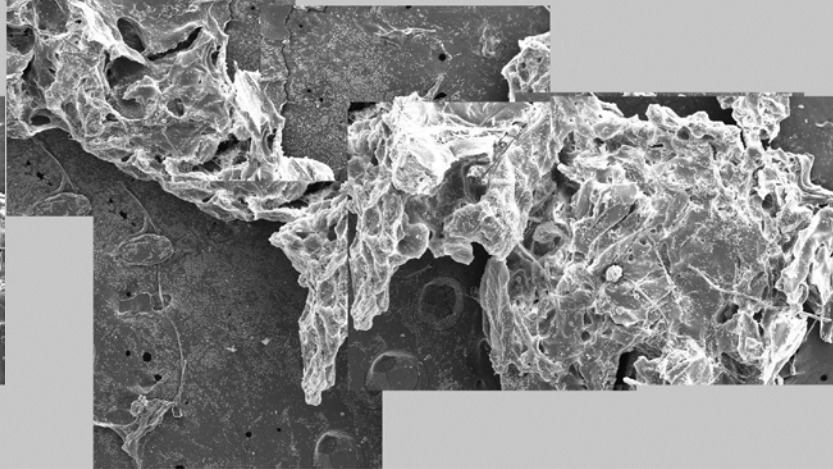
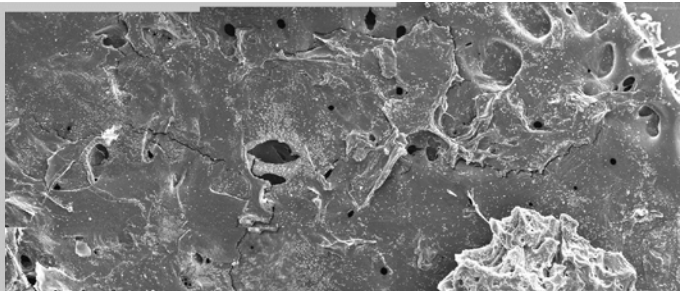
Result



- Original



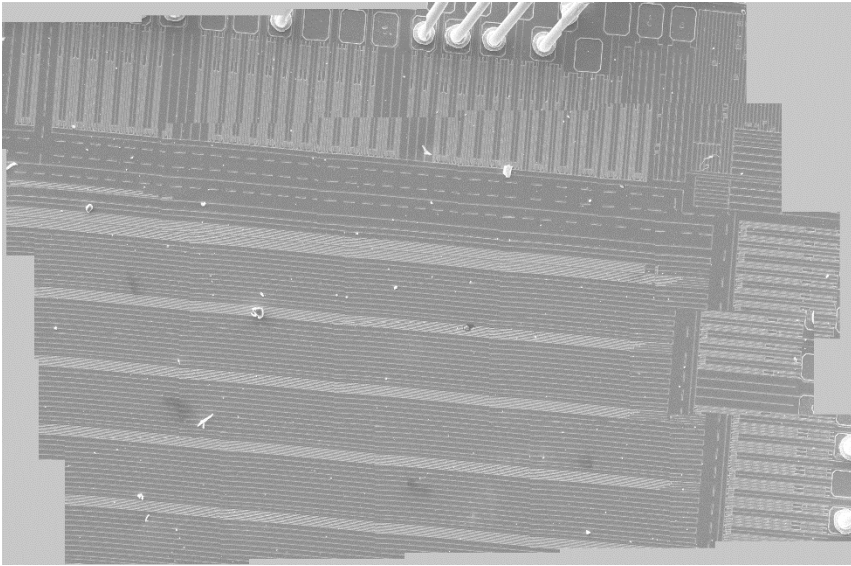
- Interval



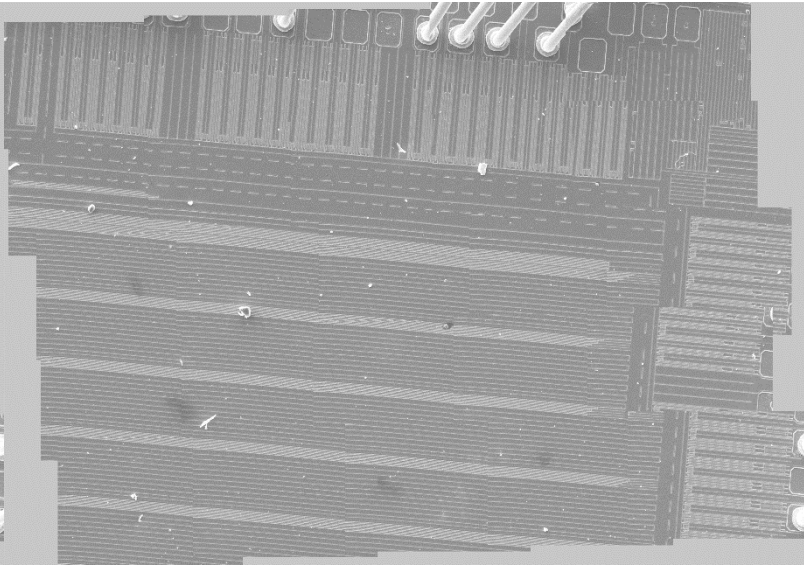
- Hierarchical

Result

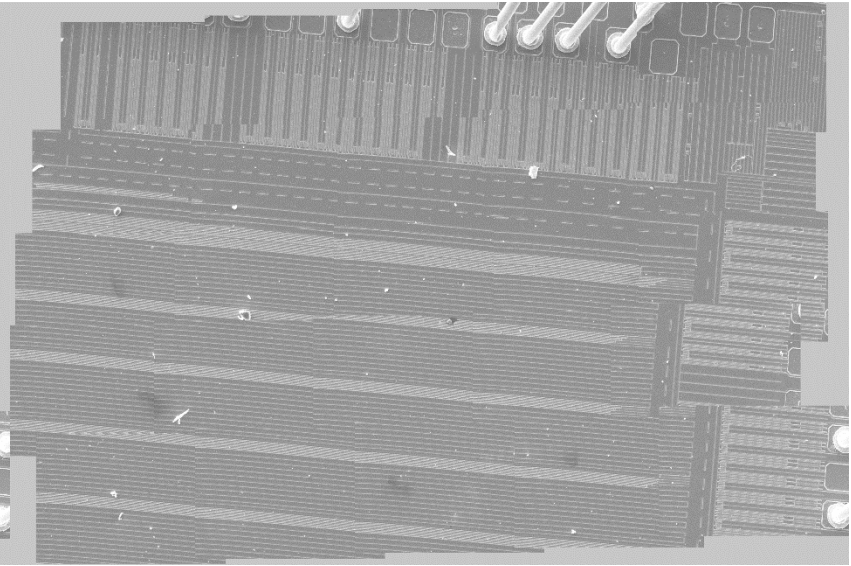
결과 비교



- Original



- Interval
- 약 100 초 걸림



- Hierarchical
- 약 2.5초 걸림

Q & A
