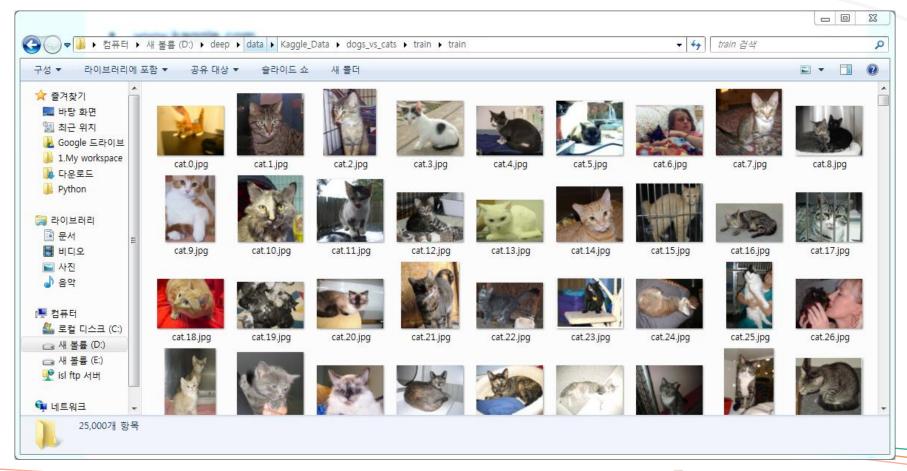
전현호



Contents



- 각각 12,500장의 학습 데이터 (총 25,000장)
- 12,500장의 테스트 데이터



```
In [1]: import cv2
        import numpy as no
         import os
        from random import shuffle
        from tadm import tadm
In [2]: TRAIN_DIR = 'D:/deep/data/Kaggle_Data/dogs_vs_cats/train/train'
        TEST_DIR = 'D:/deep/data/Kaggle_Data/dogs_vs_cats/test/test'
        IMG SIZE = 50
        LR = 1e-3
        MODEL NAME = 'dogsvscats-{}-{}.model'.format(LR. '5cony')
In [3]: def label_img(img):
            word_label = img.split('.')[-3]
            if word label = 'cat': return [1.0]
            elif word_label = 'dog': return [0,1]
        def create_train_data():
In [4]:
            training_data = []
            for img in tadm(os.listdir(TRAIN_DIR)):
                label = label_img(img)
                path = os.path.join(TRAIN_DIR,img)
                img = cv2.imread(path,cv2.IMREAD_GRAYSCALE)
                img = cv2.resize(img, (IMG_SIZE,IMG_SIZE))
                training_data.append([np.array(img),np.array(label)])
            shuffle(training_data)
            np.save('train_data.npy', training_data)
            return training_data
```

```
In [5]: def process_test_data():
    testing_data = []
    for img in tqdm(os.listdir(TEST_DIR)):
        path = os.path.join(TEST_DIR,img)
        img_num = img.split('.')[0]
        img = cv2.imread(path,cv2.IMREAD_GRAYSCALE)
        img = cv2.resize(img, (IMG_SIZE,IMG_SIZE))
        testing_data.append([np.array(img), img_num])

        shuffle(testing_data)
        np.save('test_data.npy', testing_data)
        return testing_data

In [6]: #train_data = create_train_data()
        # If you have already created the dataset:
        train_data = np.load('train_data.npy')
```

```
In [7]: import tflearn
        from tflearn, layers, conv import conv 2d, max pool 2d
        from tflearn, layers, core import input_data, dropout, fully_connected
        from tflearn, layers, estimator import regression
        import tensorflow as tf
        tf.reset_default_graph()
        convnet = input_data(shape=[None, IMG_SIZE, IMG_SIZE, 1], name='input')
        convnet = conv_2d(convnet, 32, 5, activation='relu')
        convnet = max pool_2d(convnet, 5)
        convnet = conv_2d(convnet, 64, 5, activation='relu')
        convnet = max pool 2d(convnet, 5)
        convnet = conv 2d(convnet, 128, 5, activation='relu')
        convnet = max pool 2d(convnet, 5)
        convnet = conv_2d(convnet, 64, 5, activation='relu')
        convnet = max pool 2d(convnet, 5)
        convnet = conv_2d(convnet, 32, 5, activation='relu')
        convnet = max pool 2d(convnet, 5)
        convnet = fully_connected(convnet, 1024, activation='relu')
        convnet = dropout(convnet, 0.8)
        convnet = fully_connected(convnet, 2, activation='softmax')
        convnet = regression(convnet, optimizer='adam', learning_rate=LR, loss='categorical_crossentropy', name='targets')
        model = tflearn.DNN(convnet, tensorboard dir='log')
```

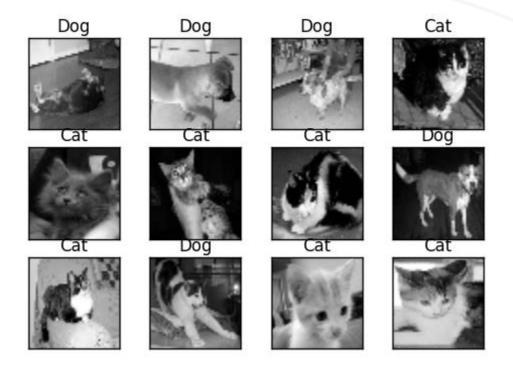
■ 비교

```
import tflearn
from tflearn.layers.conv import conv_2d, max_pool_2d
from tflearn.layers.core import input_data, dropout, fully_connected
from tflearn.layers.estimator import regression
import tensorflow as tf
tf.reset_default_graph()
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                                                                      TF-learn
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```

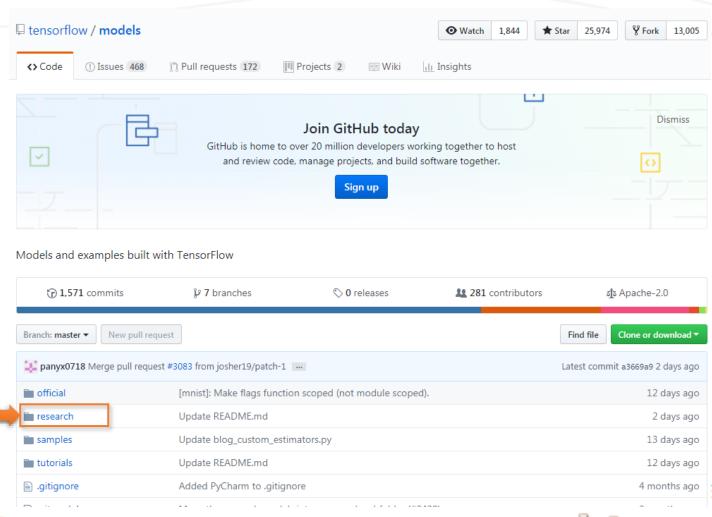
```
import tensorflow as tf
from tensorflow.examples.tutorials.mnist import input_data
mnist = input_data.read_data_sets("/tmp/data/", one_hot = True)
n nodes hl1 = 500
n nodes h12 = 500
n_nodes_h13 = 500
                                                Tensorflow
n classes = 10
batch_size = 100
                                                3 hidden layer
x = tf.placeholder('float', [None, 784])
y = tf.placeholder('float')
hidden_1_layer = {'weights':tf.Variable(tf.random_normal([784, n_nodes_hl1])),
                      'biases':tf.Variable(tf.random_normal([n_nodes_hl1]))}
hidden 2 layer = {'weights':tf.Variable(tf.random normal([n nodes hl1, n nodes hl2])).
                      'biases':tf.Variable(tf.random_normal([n_nodes_hl2]))}
hidden_3_layer = {'weights':tf.Variable(tf.random_normal([n_nodes_hl2, n_nodes_hl3])),
                      'biases':tf.Variable(tf.random_normal([n_nodes_hl3]))}
output_layer = {'weights':tf.Variable(tf.random_normal([n_nodes_hl3, n_classes])),
                    'biases':tf.Variable(tf.random_normal([n_classes])).}
11 = tf.add(tf.matmul(x,hidden_1_layer['weights']), hidden_1_layer['biases'])
I1 = tf.nn.relu(I1)
12 = tf.add(tf.matmul(11,hidden_2_laver['weights']), hidden_2_laver['biases'])
12 = tf.nn.relu(12)
13 = tf.add(tf.matmul(12,hidden_3_layer['weights']), hidden_3_layer['biases'])
13 = tf.nn.relu(13)
output = tf.matmul(|3,output_layer['weights']) + output_layer['biases']
prediction = output
cost = tf.reduce_mean( tf.nn.softmax_cross_entropy_with_logits(prediction,y) )
optimizer = tf.train.AdamOptimizer().minimize(cost)
hm = pochs = 10
                                                      +Session ~~~
sess = tf.Session()
sess.run(tf.global_variables_initializer())
```

```
In [8]: if os.path.exists('{}.meta'.format(MODEL_NAME)):
              model.load(MODEL_NAME)
              print('model loaded!')
          model loaded!
 In [9]: | train = train_data[:-500]
          test = train_data[-500:]
In [10]: print(train.shape)
                                                                                                      Validation set 생성
          X = np.array([i[0] for i in train]).reshape(-1,IMG_SIZE,IMG_SIZE,1)
          Y = [i[1] \text{ for } i \text{ in train}]
          test_x = np.array([i[0] for i in test]).reshape(-1,IMG_SIZE,IMG_SIZE,1)
          test v = [i[1] \text{ for } i \text{ in test}]
          (24500, 2)
In [11]: | model.fit({'input': X}, {'targets': Y}, n_epoch=30, validation_set=({'input': test_x}, {'targets': test_y}),
              snapshot_step=500, show_metric=True, run_id=MODEL_NAME)
          #tensorboard --logdir=fooid:\deep\log
          Training Step: 11489 | total loss: 0.07476 | time: 6.873s
          | Adam | epoch: 030 | loss: 0.07476 - acc: 0.9727 -- iter: 24448/24500
          Training Step: 11490 | total loss: 0.07033 | time: 7.907s
          | Adam | epoch: 030 | loss: 0.07033 - acc: 0.9738 | val_loss: 1.51778 - val_acc: 0.7540 -- iter: 24500/24500
In [12]:
         model.save(MODEL_NAME)
          INFO:tensorflow:D:#deep#dogsyscats-0.001-5cony-basic-video.model is not in all_model_checkpoint_paths. Manually adding it.
```

```
In [13]: import matplotlib.pyplot as plt
         #if you dont have this file yet
         #test_data = process_test_data()
         #if you already have it
         test_data = np.load('test_data.npy')
         fig = plt.figure()
         for num, data, in enumerate(test_data[:12]):
             # cat : [1,0]
             # dog : [0,1]
             img_num = data[1]
             img_data = data[0]
             y = fig.add_subplot(3, 4, num+1)
             orig = img_data
             data = img_data.reshape(IMG_SIZE, IMG_SIZE, 1)
             model_out = model.predict([data])[0]
             if np.argmax(model_out) == 1: str_label = 'Dog'
             else: str_label = 'Cat'
             y.imshow(orig, cmap = 'gray')
             plt.title(str_label)
             y.axes.get_xaxis().set_visible(False)
             y.axes.get_yaxis().set_visible(False)
         plt.show()
```



Tensorflow object detection API (https://github.com/tensorflow/models)



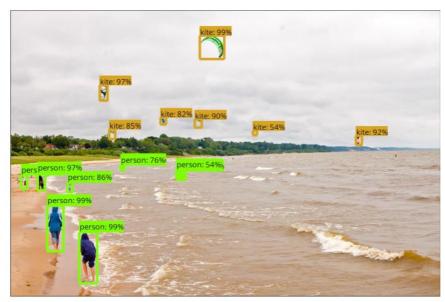
Tensorflow object detection API (https://github.com/tensorflow/models)

ranch: master ▼ models / research /		Create new file Find file Histor	
		Latest commit 32d1954 2 days ag	
adv_imagenet_models	Update README.md in adv_imagenet_models.	13 days ag	
adversarial_crypto	A few more formatting fixes.	2 months ag	
adversarial_text	Replace deprecated get_or_create_global_step	2 months ag	
attention_ocr	Fix xrange import	a month ag	
audioset	Fixing wrong path	3 months ag	
autoencoder	Move the research models into a research subfolder (#2430)	3 months ag	
cognitive_mapping_and_planning	Move the research models into a research subfolder (#2430)	3 months ag	
compression	Group imports properly	a month ag	
■ delf	Adding troubleshooting information for DELF code	2 months ag	
differential_privacy	Move the research models into a research subfolder (#2430)	3 months ag	
domain_adaptation	Move the research models into a research subfolder (#2430)	3 months ag	
fivo	Fixing README typo in research/fivo	a month ag	
gan	Merge branch 'master' into master	a month ag	
im2txt	Fix broken links in the models repo (#2445)	3 months ag	
inception	Make the redirect to slim notice more prominent	12 days ag	
learned_optimizer	Move the research models into a research subfolder (#2430)	3 months ag	
learning_to_remember_rare_events	Replace deprecated get_or_create_global_step	2 months ag	
Ifads	Move the research models into a research subfolder (#2430)	3 months ag	
■ lm_1b	Move the research models into a research subfolder (#2430)	3 months ag	
namignizer	Move the research models into a research subfolder (#2430)	3 months ag	
neural_gpu	Move the research models into a research subfolder (#2430)	3 months ag	
neural_programmer	Move the research models into a research subfolder (#2430)	3 months ag	
next_frame_prediction	Move the research models into a research subfolder (#2430)	3 months ag	

Tensorflow object detection API (https://github.com/tensorflow/models)

Tensorflow Object Detection API

Creating accurate machine learning models capable of localizing and identifying multiple objects in a single image remains a core challenge in computer vision. The TensorFlow Object Detection API is an open source framework built on top of TensorFlow that makes it easy to construct, train and deploy object detection models. At Google we've certainly found this codebase to be useful for our computer vision needs, and we hope that you will as well.

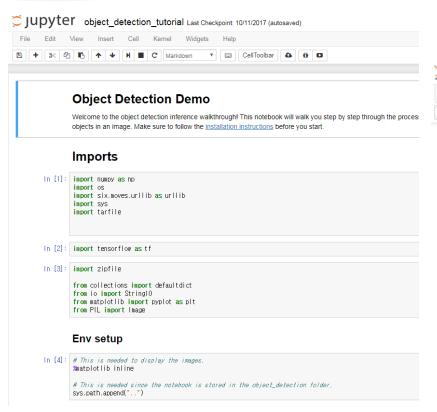


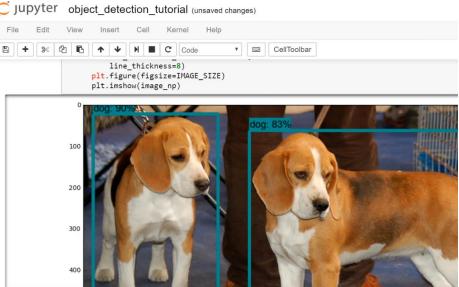
Contributions to the codebase are welcome and we would love to hear back from you if you find this API useful. Finally if you use the Tensorflow Object Detection API for a research publication, please consider citing:

"Speed/accuracy trade-offs for modern convolutional object detectors." Huang J, Rathod V, Sun C, Zhu M, Korattikara A, Fathi A, Fischer I, Wojna Z, Song Y, Guadarrama S, Murphy K, CVPR 2017



Tensorflow object detection API (https://github.com/tensorflow/models)





Adapting to video

```
In [1]:
        import numby as no
        import os
        import six.moves.urllib as urllib
        import sys
        import tarfile
        import tensorflow as tf
In [2]:
        import zipfile
        from collections import defaultdict
        from io import StringlO
        from matplotlib import pyplot as plt
        from PIL import Image
In [3]:
        import cv2
        cap = cv2.VideoCapture(0)
```

Env setup

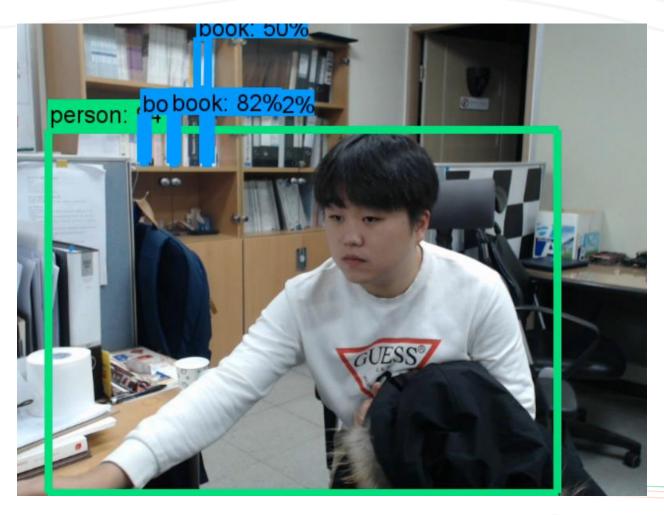
In [4]:



Adapting to video

```
In [14]: with detection_graph.as_default():
          with tf.Session(graph=detection_graph) as sess:
            # Definite input and output Tensors for detection_graph
            image tensor = detection graph.get tensor by name('image tensor:0')
            # Each box represents a part of the image where a particular object was detected.
            detection_boxes = detection_graph.get_tensor_by_name('detection_boxes:0')
            # Each score represent how level of confidence for each of the objects,
            # Score is shown on the result image, together with the class label,
            detection_scores = detection_graph.get_tensor_by_name('detection_scores:0')
            detection_classes = detection_graph.get_tensor_by_name('detection_classes:0')
            num detections = detection graph.get tensor by name('num detections:0')
             for image path in TEST IMAGE PATHS:
              image = Image.open(image_path)
                                                                                                              While True:
              # the array based representation of the image
              # result image with boxes and labels on it.
                                                                                                                       ret, image np = cp.read()
              image np = load image into numpy array(image)
              # expand dimensions since the model expects images to have shape: [1, None, None, 3]
              image_np_expanded = np.expand_dims(image_np, axis=0)
              # Actual detection.
              (boxes, scores, classes, num) = sess.run(
                  [detection_boxes, detection_scores, detection_classes, num_detections],
                  feed dict={image tensor: image np expanded})
              # Visualization of the results of a detection,
              vis_util.visualize_boxes_and_labels_on_image_array(
                  image_np.
                                                                          cv2.imshow('object detection', cv2.resize(image np, (800,600)))
                  np.saueeze(boxes).
                  np.squeeze(classes).astype(np.int32).
                                                                          if cv2.waitKey(25) & 0xFF == ord('q'):
                  np.squeeze(scores).
                  category_index.
                                                                                   cv2.destroyAllWindows()
                  use normalized coordinates=True.
                  line thickness=8)
                                                                                   break
              plt.figure(figsize=IMAGE_SIZE)
              plt.imshow(image_np)
```

Adapting to video



#