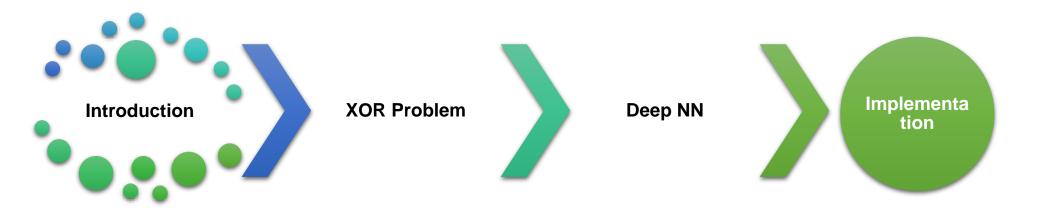
27 Mar 2017

Basic of DL: XOR and DNN

ISL lab Seminar

Han-Sol Kang

Contents

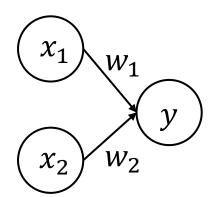


★ Perceptron

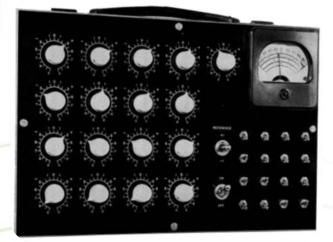


Frank Rosenblatt(1957)

Frank Rosenblatt, ~1957: Perceptron



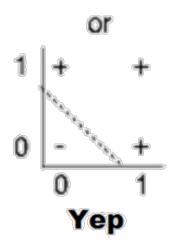
Widrow and Hoff, ~1960: Adaline/Madaline

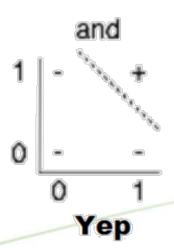


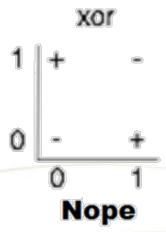
★ Perceptron

The Navy revealed the embryo of an electronic computer today that it expects will be able to walk, talk, see, write, reproduce itself an be conscious of its existence.

The New York Times July 08, 1958







★ Perceptron



Perceptrons (1969) by Marvin Minsky, founder of the MIT AI Lab

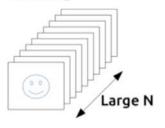
- We need to use MLP, multilayer perceptrons (multilayer neural nets)
- No one on earth had found a viable way to train MLPs good enough to learn such simple functions.

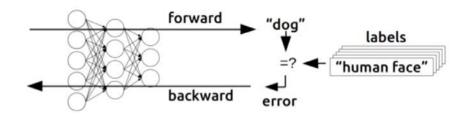
"No one on earth had found a viable way to train"

★ Backpropagation

1974, 1982 by Paul Werbos, 1986 by Hinton

Training







Terminator 2 (1991)

JOHN: Can you learn? So you can be... you know. More human. Not such a dork all the time.

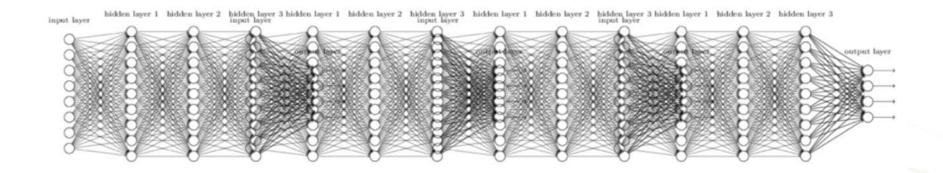
TERMINATOR: My CPU is a neural-net processor... a learning computer. But **Skynet** presets the switch to "read-only" when we are sent out alone.

We'll learn how to set the neural net

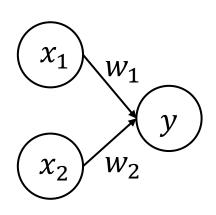


* A BIG problem

- Backpropagation just did not work well for normal neural nets with many layers
- Other rising machine learning algorithms: SVM, RandomForest, etc.
- 1995 "Comparison of Learning Algorithms For Handwritten Digit Recognition" by LeCun et al. found that this new approach worked better

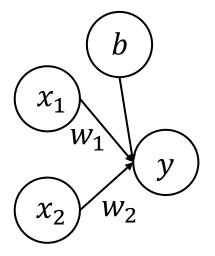


AND, OR, XOR using NN



$$y = \begin{cases} 0 & (w_1 x_1 + w_2 x_2 \le \theta) \\ 1 & (w_1 x_1 + w_2 x_2 > \theta) \end{cases}$$

$$y = \begin{cases} 0 & (b + w_1 x_1 + w_2 x_2 \le 0) \\ 1 & (b + w_1 x_1 + w_2 x_2 > 0) \end{cases}$$



x1	x2	y
0	0	0
1	0	0
0	1	0
1	1	1

x1	x2	у
0	0	0
1	0	1
0	1	1
1	1	1

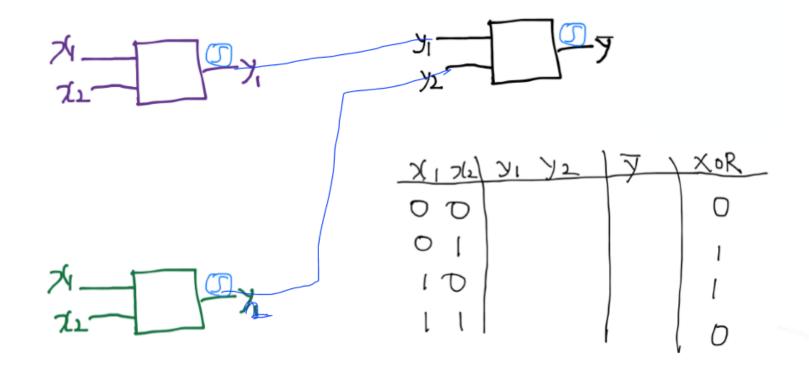
x1	x2	у
0	0	1
1	0	1
0	1	1
1	1	0

$$(w_1, w_2, \theta) = (0.5, 0.5, 0.7)$$
 $(w_1, w_2, \theta) = (0.5, 0.5, 0.2)$ $(w_1, w_2, \theta) = (-0.5, -0.5, -0.7)$

$$(w_1, w_2, \theta) = (0.5, 0.5, 0.2)$$

$$(w_1, w_2, \theta) = (-0.5, -0.5, -0.7)$$

* AND, OR, XOR using NN



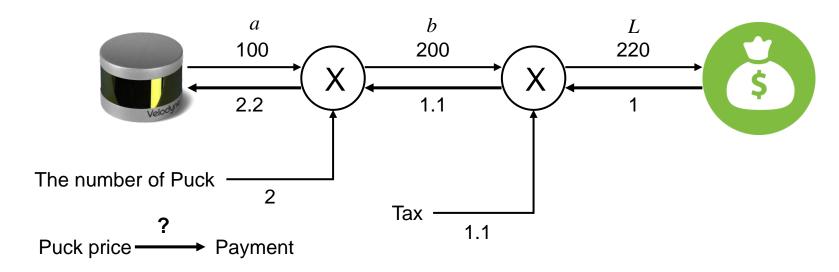
"No one on earth had found a viable way to train"

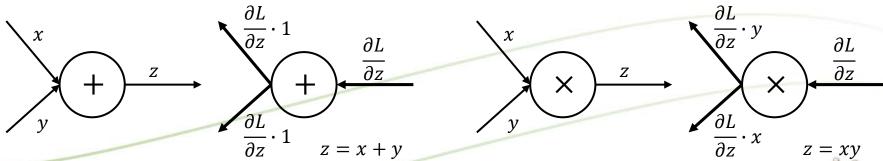
Image System Laborator

XOR Problem

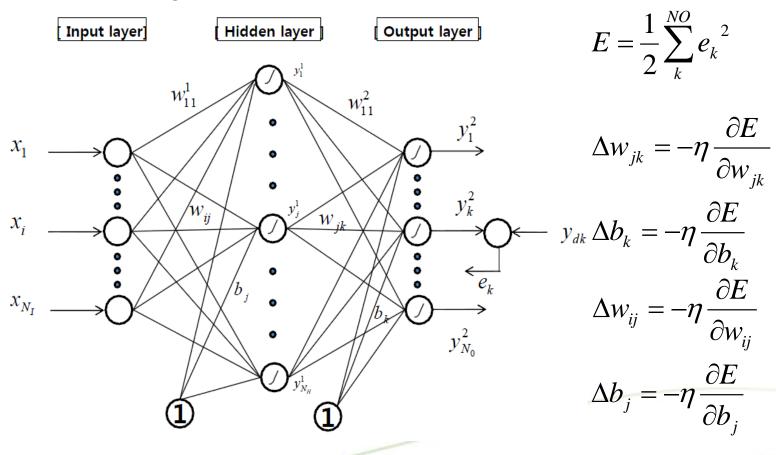
★ Backpropagation

Kurt bought two pucks, one for 100. Get the payment amount. However, consumption tax is charged at 10%.





★ Backpropagation



Backpropagation

$$\frac{\partial E}{\partial b_{j}} = \frac{\partial E}{\partial e_{k}} \frac{\partial e_{k}}{\partial b_{k}} \qquad \qquad \frac{\partial E}{\partial e_{k}} = \eta e_{k} f'(s_{k})$$

$$= e_{k} \frac{\partial e_{k}}{\partial b_{k}} \qquad \qquad \frac{\partial E}{\partial e_{k}} = \frac{1}{2} \frac{\partial e_{k}^{2}}{\partial e_{k}} = e_{k}$$

$$= e_{k} \frac{\partial e_{k}}{\partial y_{k}} \frac{\partial y_{k}}{\partial b_{k}}$$

$$= -e_{k} \frac{\partial y_{k}}{\partial s_{k}} \frac{\partial s_{k}}{\partial b_{k}}$$

$$= -e_{k} \frac{\partial y_{k}}{\partial s_{k}} \frac{\partial s_{k}}{\partial b_{k}}$$

$$= -e_{k} f'(s_{k}) \frac{\partial s_{k}}{\partial b_{k}}$$

$$= -e_{k} f'(s_{k}) y_{j}$$

$$\Rightarrow \frac{\partial S_{k}}{\partial s_{k}} = \frac{\partial f(s_{k})}{\partial s_{k}} = f'(s_{k})$$

$$\Rightarrow \frac{\partial S_{k}}{\partial s_{k}} = \frac{\partial f(s_{k})}{\partial s_{k}} = 1$$

★ Backpropagation

$$\frac{\partial E}{\partial w_{ij}} = \frac{\partial E}{\partial e_{k}} \frac{\partial e_{k}}{\partial w_{ij}}$$

$$= e_{k} \frac{\partial e_{k}}{\partial v_{i}}$$

$$= e_{k} \frac{\partial e_{k}}{\partial v_{i}} \frac{\partial v_{k}}{\partial w_{ij}}$$

$$= -e_{k} \frac{\partial v_{k}}{\partial v_{i}} \frac{\partial v_{k}}{\partial w_{ij}}$$

$$= -e_{k} \frac{\partial v_{k}}{\partial v_{i}} \frac{\partial v_{i}}{\partial w_{ij}}$$

$$= -e_{k} \frac{\partial v_{k}}{\partial v_{i}} \frac{\partial v_{i}}{\partial w_{ij}}$$

$$= -e_{k} \frac{\partial v_{k}}{\partial v_{i}} \frac{\partial v_{i}}{\partial w_{ij}}$$

$$= -e_{k} \frac{\sum_{k=1}^{N_{0}} \frac{\partial v_{k}}{\partial v_{j}} \frac{\partial v_{k}}{\partial w_{ij}}$$

$$= -e_{k} \sum_{k=1}^{N_{0}} f'(s_{k}) \frac{\partial s_{k}}{\partial w_{ij}}$$

$$= -e_{k} \sum_{k=1}^{N_{0}} f'(s_{k}) \frac{\partial s_{k}}{\partial v_{i}} \frac{\partial v_{j}}{\partial w_{ij}}$$

$$= -e_{k} \sum_{k=1}^{N_{0}} f'(s_{k}) w_{jk} \frac{\partial v_{j}}{\partial v_{ij}}$$

$$= -e_{k} \sum_{k=1}^{N_{0}} f'(s_{k}) w_{jk} \frac{\partial v_{j}}{\partial v_{ij}}$$

$$= -e_{k} \sum_{k=1}^{N_{0}} f'(s_{k}) w_{jk} \frac{\partial v_{j}}{\partial v_{ij}}$$

$$= -e_{k} \sum_{k=1}^{N_{0}} f'(s_{k}) w_{jk} f'(s_{j}) \frac{\partial s_{j}}{\partial w_{ij}}$$

$$= -e_{k} \sum_{k=1}^{N_{0}} f'(s_{k}) w_{jk} f'(s_{j}) \frac{\partial s_{j}}{\partial w_{ij}}$$

$$= -e_{k} \sum_{k=1}^{N_{0}} f'(s_{k}) w_{jk} f'(s_{j}) x_{i}$$

$$\frac{\partial v_{j}}{\partial v_{j}} = \frac{\partial v_{j}}{\partial v_{j}} \sum_{i=1}^{N_{0}} w_{j} x_{i} + b_{j} = x_{i}$$

★ Backpropagation

$$\frac{\partial E}{\partial b_{j}} = \frac{\partial E}{\partial e_{k}} \frac{\partial e_{k}}{\partial b_{j}}$$

$$= e_{k} \frac{\partial e_{k}}{\partial b_{j}}$$

$$= e_{k} \frac{\partial e_{k}}{\partial v_{k}} \frac{\partial v_{k}}{\partial v_{j}}$$

$$= -e_{k} \frac{\partial v_{k}}{\partial v_{j}} \frac{\partial v_{j}}{\partial v_{j}}$$

$$= -e_{k} \frac{\partial v_{k}}{\partial v_{j}} \frac{\partial v_{j}}{\partial v_{j}}$$

$$= -e_{k} \frac{\partial v_{k}}{\partial v_{j}} \frac{\partial v_{j}}{\partial v_{j}}$$

$$= -e_{k} \frac{\sum_{k=1}^{No} \frac{\partial v_{k}}{\partial v_{k}} \frac{\partial v_{j}}{\partial v_{j}}$$

$$= -e_{k} \frac{\sum_{k=1}^{No} \frac{\partial v_{k}}{\partial v_{k}} \frac{\partial v_{j}}{\partial v_{j}}$$

$$= -e_{k} \frac{\sum_{k=1}^{No} \frac{\partial v_{k}}{\partial v_{k}} \frac{\partial v_{j}}{\partial v_{j}}$$

$$= -e_{k} \frac{\sum_{k=1}^{No} f'(s_{k}) \frac{\partial s_{k}}{\partial v_{j}}}{\frac{\partial v_{j}}{\partial v_{j}} \frac{\partial v_{j}}{\partial v_{j}}}$$

$$= -e_{k} \frac{\sum_{k=1}^{No} f'(s_{k}) w_{jk} \frac{\partial v_{j}}{\partial v_{j}}}{\frac{\partial v_{j}}{\partial v_{j}} \frac{\partial v_{j}}{\partial v_{j}}}$$

$$= -e_{k} \frac{\sum_{k=1}^{No} f'(s_{k}) w_{jk} \frac{\partial v_{j}}{\partial v_{j}}}{\frac{\partial v_{j}}{\partial v_{j}}}$$

$$= -e_{k} \frac{\sum_{k=1}^{No} f'(s_{k}) w_{jk} \frac{\partial v_{j}}{\partial v_{j}}}{\frac{\partial v_{j}}{\partial v_{j}}}$$

$$= -e_{k} \frac{\sum_{k=1}^{No} f'(s_{k}) w_{jk} \frac{\partial v_{j}}{\partial v_{j}}}{\frac{\partial v_{j}}{\partial v_{j}}}$$

$$= -e_{k} \frac{\sum_{k=1}^{No} f'(s_{k}) w_{jk} f'(s_{j}) \frac{\partial s_{j}}{\partial v_{j}}}{\frac{\partial v_{j}}{\partial v_{j}}}$$

$$= -e_{k} \frac{\sum_{k=1}^{No} f'(s_{k}) w_{jk} f'(s_{j}) \frac{\partial s_{j}}{\partial v_{j}}}$$

$$= -e_{k} \frac{\partial v_{j}}{\partial v_{j}} f'(s_{k}) w_{jk} f'(s_{j}) \frac{\partial s_{j}}{\partial v_{j}}$$

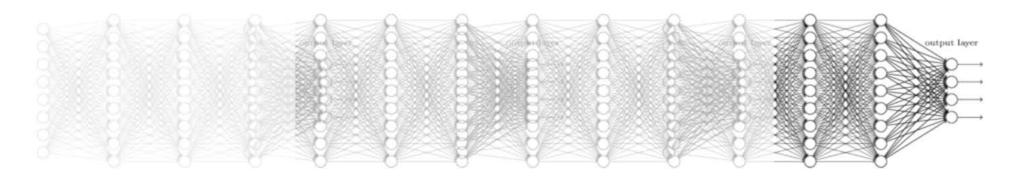
$$= -e_{k} \frac{\partial v_{j}}{\partial v_{j}} f'(s_{k}) w_{jk} f'(s_{j}) \frac{\partial s_{j}}{\partial v_{j}}$$

$$= -e_{k} \frac{\partial v_{j}}{\partial v_{j}} f'(s_{k}) w_{jk} f'(s_{j}) \frac{\partial s_{j}}{\partial v_{j}}$$

$$= -e_{k} \frac{\partial v_{j}}{\partial v_{j}} f'(s_{k}) w_{jk} f'(s_{j}) \frac{\partial v_{j}}{\partial v_{j}}$$

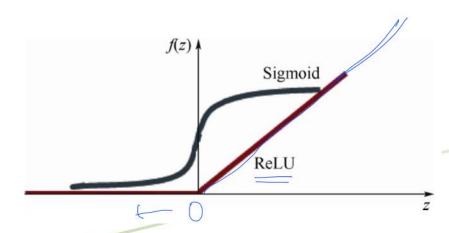
$$= -e_{k} \frac{\partial v_{j}}{\partial v_{j}} f'(s_{k}) w_{jk} f'(s_{j}) \frac{\partial v_{j}}{\partial v_{j}}$$

★ Vanishing Gradient



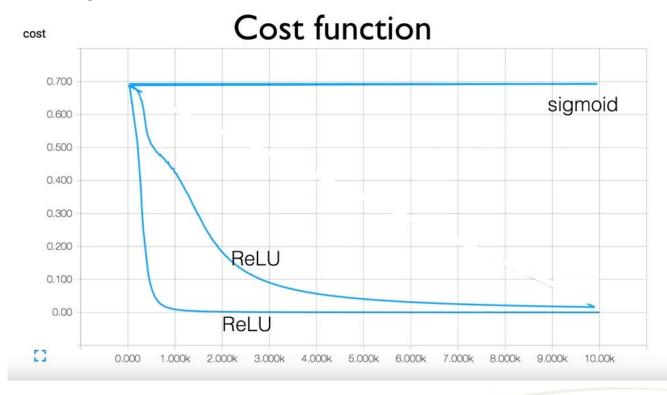
"We used the wrong type of non-linearity"

Geoffrey Hinton



ReLU(Rectified Linear Unit)

★ Initialize weights



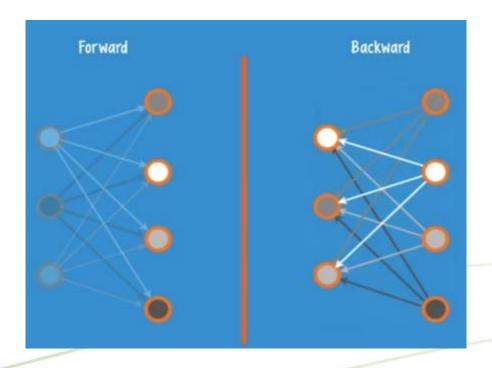
"We initialized the weights in a stupid way"

Geoffrey Hinton

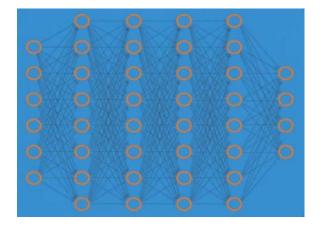
★ Initialize weights

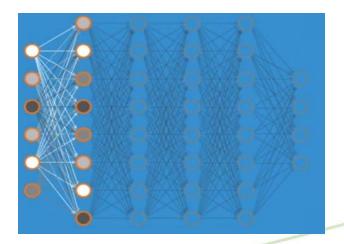
Hinton et al. (2006) "A Fast Learning Algorithm for Deep Belief Nets"

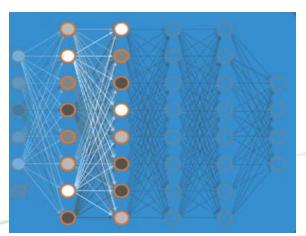
- Restricted Boltzmann Machine (RBM)

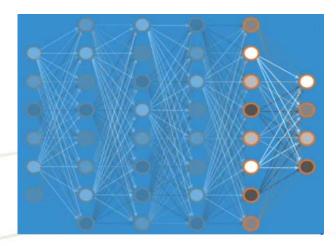


★ Initialize weights









- Initialize weights(Xavier/He initialization)
 - Makes sure the weights are 'just right', not too small, not too big
 - Using number of input (fan_in) and output (fan_out)

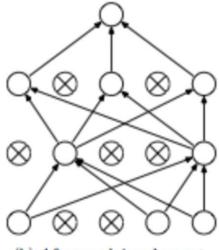
Xavier

W = np.random.randn(fan_in, fan_out)/np.sqrt(fan_in)

He

W = np.random.randn(fan_in, fan_out)/np.sqrt(fan_in/2)

★ Dropout



(b) After applying dropout.



Implementation

from tensorflow.examples.tutorials.mnist import input_data

import tensorflow as tf

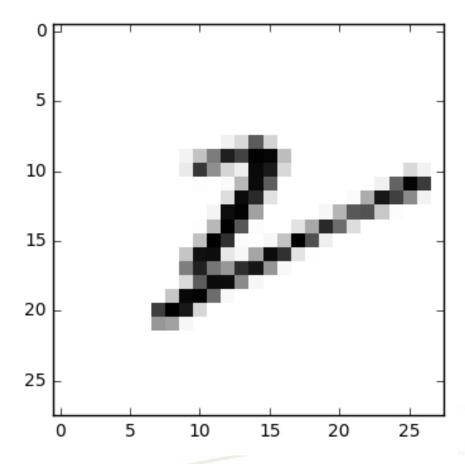
import matplotlib.pyplot as plt

```
mnist = input_data.read_data_sets("MNIST_data/", one_hot=True)
# parameters
learning_rate = 0.001
training_epochs = 15
batch size = 100
# input place holders
X = tf.placeholder(tf.float32, [None, 784])
Y = tf.placeholder(tf.float32, [None, 10])
# weights & bias for nn layers
W = tf. Variable(tf.random normal([784, 10]))
b = tf. Variable(tf.random normal([10]))
hypothesis = tf.matmul(X, W) + b
# define cost/loss & optimizer
cost =
tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(logits=h
ypothesis, labels=Y))
optimizer =
tf.train.AdamOptimizer(learning rate=learning rate).minimize(cost)
# initialize
sess = tf.Session()
sess.run(tf.global_variables_initializer())
```

```
# train mv model
for epoch in range(training_epochs):
  avg_cost = 0
  total_batch = int(mnist.train.num_examples / batch_size)
  for i in range(total batch):
     batch_xs, batch_ys = mnist.train.next_batch(batch_size)
     feed_dict = {X: batch_xs, Y: batch_ys}
     c, _ = sess.run([cost, optimizer], feed_dict=feed_dict)
     avg cost += c / total batch
  print('Epoch:', '%04d' % (epoch + 1), 'cost =', '{:.9f}'.format(avg_cost))
print('Learning Finished!')
# Test model and check accuracy
correct_prediction = tf.equal(tf.argmax(hypothesis, 1), tf.argmax(Y, 1))
accuracy = tf.reduce mean(tf.cast(correct prediction, tf.float32))
print('Accuracy:', sess.run(accuracy, feed_dict={
    X: mnist.test.images, Y: mnist.test.labels}))
# Get one and predict
r = random.randint(0, mnist.test.num_examples - 1)
print("Label: ", sess.run(tf.argmax(mnist.test.labels[r:r + 1], 1)))
print("Prediction: ", sess.run(tf.argmax(hypothesis, 1), feed_dict={X:
mnist.test.images[r:r + 1]}))
plt.imshow(mnist.test.images[r:r + 1].reshape(28, 28), cmap='Greys',
interpolation='nearest')
plt.show()
```

Implementation

```
('Epoch:', '0001', 'cost =', '5.916487252')
('Epoch:', '0002', 'cost =', '1.863573338')
('Epoch:'.
           '0003',
                    'cost ='
           '0004'. 'cost =',
                              '0.894605613')
('Epoch:'.
           '0005'. 'cost ='.
                              '0.753347107')
('Epoch:'.
           '0006', 'cost =', '0.665160576')
('Epoch:'.
           '0007'.
                    'cost =',
                              '0.604045915')
           '0008'.
('Epoch:'.
                    'cost =',
                              '0.558101759')
           '0009'.
                   'cost ='. '0.523281238')
('Epoch:'.
           '0010', 'cost =',
                              '0.495043325')
('Epoch:'.
           '0011'.
                   'cost ='
                              'O. 471873087' )
           '0012',
                    'cost ='
           '0013', 'cost =', '0,435230404')
('Epoch:', '0014', 'cost =', '0.420703621')
('Epoch:', '0015', 'cost =', '0.407859434')
Learning Finished!
('Accuracy:', 0.90359998)
('Label: ', array([2]))
('Prediction: ', array([1]))
```



import tensorflow as tf import random

Implementation

```
from tensorflow.examples.tutorials.mnist import input_data
tf.set_random_seed(777) # reproducibility
mnist = input_data.read_data_sets("MNIST_data/", one_hot=True)
# parameters
learning_rate = 0.001
training_epochs = 15
batch size = 100
# input place holders
X = tf.placeholder(tf.float32, [None, 784])
Y = tf.placeholder(tf.float32, [None, 10])
# weights & bias for nn layers
W1 = tf.Variable(tf.random_normal([784, 256]))
b1 = tf.Variable(tf.random_normal([256]))
L1 = tf.nn.relu(tf.matmul(X, W1) + b1)
W2 = tf.Variable(tf.random normal([256, 256]))
b2 = tf.Variable(tf.random_normal([256]))
L2 = tf.nn.relu(tf.matmul(L1, W2) + b2)
W3 = tf.Variable(tf.random_normal([256, 10]))
b3 = tf.Variable(tf.random_normal([10]))
hypothesis = tf.matmul(L2, W3) + b3
# define cost/loss & optimizer
cost = tf.reduce_mean(tf.nn.softmax_cross_entropy_with_logits(
  logits=hypothesis, labels=Y))
optimizer =
tf.train.AdamOptimizer(learning_rate=learning_rate).minimize(cost)
```

```
# initialize
sess = tf.Session()
sess.run(tf.global variables initializer())
# train my model
for epoch in range(training_epochs):
  avg cost = 0
  total_batch = int(mnist.train.num_examples / batch_size)
  for i in range(total_batch):
     batch_xs, batch_ys = mnist.train.next_batch(batch_size)
     feed_dict = {X: batch_xs, Y: batch_ys}
    c, = sess.run([cost, optimizer], feed dict=feed dict)
    avg cost += c / total batch
  print('Epoch:', '%04d' % (epoch + 1), 'cost =', '{:.9f}'.format(avg_cost))
print('Learning Finished!')
# Test model and check accuracy
correct_prediction = tf.equal(tf.argmax(hypothesis, 1), tf.argmax(Y, 1))
accuracy = tf.reduce_mean(tf.cast(correct_prediction, tf.float32))
print('Accuracy:', sess.run(accuracy, feed_dict={
   X: mnist.test.images, Y: mnist.test.labels}))
# Get one and predict
r = random.randint(0, mnist.test.num_examples - 1)
print("Label: ", sess.run(tf.argmax(mnist.test.labels[r:r + 1], 1)))
print("Prediction: ", sess.run(tf.argmax(hypothesis, 1), feed_dict={X:
mnist.test.images[r:r + 1]}))
```

Implementation

Softmax

```
('Epoch:', '0001', 'cost =', '5.916487252')
('Epoch:', '0002', 'cost =', '1.863573338')
('Epoch:', '0003', 'cost =', '1.162345760')
('Epoch:', '0004', 'cost =', '0.894605613')
('Epoch:', '0005', 'cost =', '0.753347107')
('Epoch:', '0006', 'cost =', '0.665160576')
('Epoch:', '0007', 'cost =', '0.604045915')
('Epoch:', '0008', 'cost =', '0.558101759')
('Epoch:', '0009', 'cost =', '0.523281238')
('Epoch:', '0010', 'cost =', '0.495043325')
('Epoch:', '0011', 'cost =', '0.471873087')
('Epoch:', '0012', 'cost =', '0.452187982')
('Epoch:', '0013', 'cost =', '0.435230404')
('Epoch:', '0014', 'cost =', '0.420703621')
('Epoch:', '0015', 'cost =', '0.407859434')
Learning Finished!
```

('Accuracy:',0.90359998)

NN

```
('Epoch:', '0001', 'cost =', '164.116649972')
('Epoch:', '0002', 'cost =', '41.866736450')
('Epoch:', '0003', 'cost =', '26.609068727')
('Epoch:', '0004', 'cost =', '18.717741623')
('Epoch:', '0005', 'cost =', '13.838593242')
('Epoch:', '0006', 'cost =', '10.368780142')
('Epoch:', '0007', 'cost =', '7.660989459')
('Epoch:', '0008', 'cost =', '5.893673751')
('Epoch:', '0009', 'cost =', '4.475466314')
('Epoch:', '0010', 'cost =', '3.376285574')
('Epoch:', '0011', 'cost =', '2.614971533')
('Epoch:', '0012', 'cost =', '1.986375339')
('Epoch:', '0013', 'cost =', '1.538742549')
('Epoch:', '0014', 'cost =', '1.246197118')
('Epoch:', '0015', 'cost =', '0.954491639')
Learning Finished!
('Accuracy:', 0.95029998)
```

import tensorflow as tf import random import matplotlib.pyplot as plt

Implementation

```
from tensorflow.examples.tutorials.mnist import input_data
tf.set random seed(777) # reproducibility
mnist = input_data.read_data_sets("MNIST_data/", one_hot=True)
# parameters
learning_rate = 0.001
training_epochs = 15
batch size = 100
# input place holders
X = tf.placeholder(tf.float32, [None, 784])
Y = tf.placeholder(tf.float32, [None, 10])
# dropout (keep_prob) rate 0.7 on training, but should be 1 for testing
keep prob = tf.placeholder(tf.float32)
W1 = tf.get_variable("W1", shape=[784,
512],initializer=tf.contrib.layers.xavier_initializer())
b1 = tf.Variable(tf.random_normal([512]))
L1 = tf.nn.relu(tf.matmul(X, W1) + b1)
L1 = tf.nn.dropout(L1, keep prob=keep prob)
W2 = tf.get\_variable("W2", shape=[512,
512],initializer=tf.contrib.layers.xavier_initializer())
b2 = tf.Variable(tf.random normal([512]))
L2 = tf.nn.relu(tf.matmul(L1, W2) + b2)
L2 = tf.nn.dropout(L2, keep_prob=keep_prob)
```

```
W3 = tf.get variable("W3", shape=[512,
512],initializer=tf.contrib.layers.xavier initializer())
b3 = tf.Variable(tf.random normal([512]))
L3 = tf.nn.relu(tf.matmul(L2, W3) + b3)
L3 = tf.nn.dropout(L3, keep prob=keep prob)
W4 = tf.get variable("W4", shape=[512,
512],initializer=tf.contrib.layers.xavier initializer())
b4 = tf.Variable(tf.random_normal([512]))
L4 = tf.nn.relu(tf.matmul(L3, W4) + b4)
L4 = tf.nn.dropout(L4, keep prob=keep prob)
W5 = tf.get_variable("W5", shape=[512,
10],initializer=tf.contrib.layers.xavier_initializer())
b5 = tf.Variable(tf.random_normal([10]))
hypothesis = tf.matmul(L4, W5) + b5
cost = tf.reduce mean(tf.nn.softmax cross entropy with logits(
  logits=hypothesis, labels=Y))
optimizer =
tf.train.AdamOptimizer(learning rate=learning rate).minimize(cost)
```

Implementation

NN

```
('Epoch:', '0001', 'cost =', '164.116649972')
('Epoch:', '0002', 'cost =', '41.866736450')
('Epoch:', '0003', 'cost =', '26.609068727')
('Epoch:', '0004', 'cost =', '18.717741623')
('Epoch:', '0005', 'cost =', '13.838593242')
('Epoch:', '0006', 'cost =', '10.368780142')
('Epoch:', '0007', 'cost =', '7.660989459')
('Epoch:', '0008', 'cost =', '5.893673751')
('Epoch:', '0009', 'cost =', '4.475466314')
('Epoch:', '0010', 'cost =', '3.376285574')
('Epoch:', '0011', 'cost =', '2.614971533')
('Epoch:', '0012', 'cost =', '1.986375339')
('Epoch:', '0013', 'cost =', '1.538742549')
('Epoch:', '0014', 'cost =', '1.246197118')
('Epoch:', '0015', 'cost =', '0.954491639')
Learning Finished!
```

('Accuracy:', 0.95029998)

NN(Xavier, Dropout)

```
('Epoch:', '0001', 'cost =', '0.475521204')
('Epoch:', '0002', 'cost =', '0.174723941')
('Epoch:', '0003', 'cost =', '0.132422534')
('Epoch:', '0004', 'cost =', '0.110649394')
('Epoch:', '0005', 'cost =', '0.094175926')
('Epoch:', '0006', 'cost =', '0.082326408')
('Epoch:', '0007', 'cost =', '0.078204827')
('Epoch:', '0008', 'cost =', '0.067890784')
('Epoch:', '0009', 'cost =', '0.065861956')
('Epoch:', '0010', 'cost =', '0.059872363')
('Epoch:', '0011', 'cost =', '0.056675084')
('Epoch:', '0012', 'cost =', '0.053590286')
('Epoch:', '0013', 'cost =', '0.049909270')
('Epoch:', '0014', 'cost =', '0.049200659')
('Epoch:', '0015', 'cost =', '0.048159967')
Learning Finished!
```

('Accuracy:', 0.98250002)

Appendix

★ Sung Hun Kim & Deep Learning from Scratch





모두를 위한 머신러닝/딥러닝 강의

모두를 위한 머신러닝과 딥러닝의 강의

알파고와 이세돌의 경기를 보면서 이제 머신 러닝이 인간이 잘 한다고 여겨진 직관과 의사 결정능력에서도 충분한 데이타가 있으면 어느정도 또는 우리보다 더 잘할수도 있다는 생각을 많이 하게 되었습니다. Andrew Ng 교수님이 말씀하신것 처럼 이런 시대에 머신 러닝을 잘 이해하고 잘 다물수 있다면 그야말로 "Super Power"를 가지게 되는 것이 아닌가 생각합니다.

더 많은 분들이 머신 러닝과 딥러닝에 대해 더 이해하고 본인들의 문제를 이 멋진 도구를 이용해서 ᅏ수 있게 하기위해 비디오 강의를 준비하였습니다. 더 나아가 이론에만 그치지 않고 최근 구글이 공개한 머신러닝을 위한 오픈소스인 TensorFlow를 이용해서 이론을 구현해 볼수 있도록 하였습니다.

수학이나 컴퓨터 공학적인 지식이 없이도 쉽게 볼수 있도록 만들려고 노력하였습니다.



시즌 RL - Deep Reinforcement Learning

비디오 리스트 (일주일에 한강좌씩 천천이 업데이트 예정입니다.)

- Lecture 1: 수업의 개요 비디오 🔾 강의 슬라이드 📆
- Lecture 2: OpenAI GYM 게임해보기 비디오 강의 슬라이드 [™]
 Lab 2: OpenAI GYM 게임해보기 실습 비디오 실습슬라이드 [™]
- Lecture 3: Dummy Q-learning (table) 비디오 강의 슬라이드 ™
 Lab 3: Dummy Q-learning (table) 비디오 실습슬라이드 ™
- Lecture 4: Q-learning exploit&exploration and discounted reward 비디오 강의 슬라이드 ™
 Lab 4: Q-learning exploit&exploration and discounted reward 비디오 실습슬라이드 ™

