## **Extract Ceiling**

ISL

안재원



MOET

Ceiling

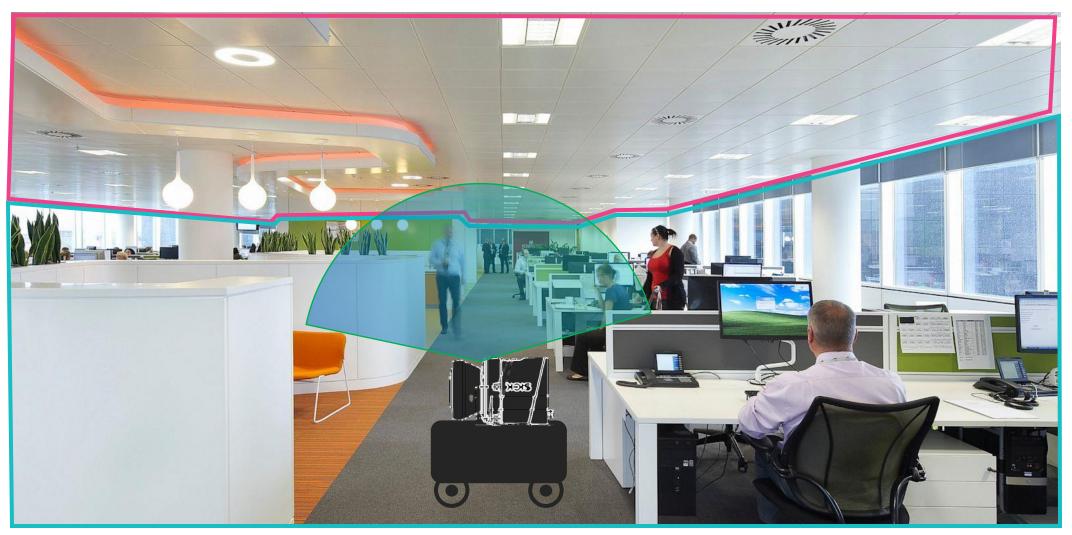
Extract Ceiling based on Geometry

Extract Ceiling based on Segmentation

Result

### Ceiling

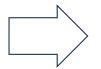
Intro





Intro

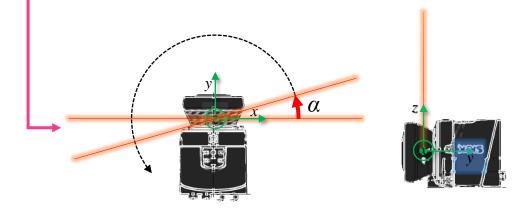
각 Point Cloud의 (x,y,z) 정보 획득

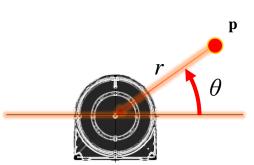


높이 정보를 이용해 천장 후보 선정



천장 후보 정보를 이용해 천장 검출





 $P_{\text{spherical coordinate system}}(r, \theta, \phi) => P_{\text{rectangular coordinate system}}(r \sin \theta \cos \phi, r \sin \theta \sin \phi, r \cos \theta)$ 



Intro

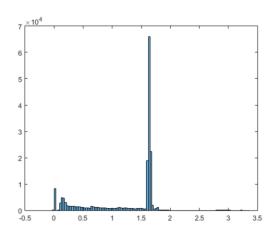
각 Point Cloud의 (x,y,z) 정보 획득

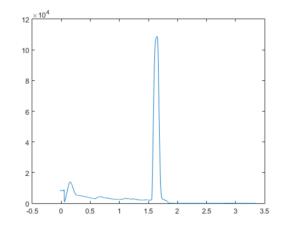


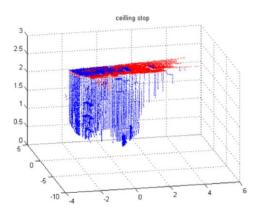
높이 정보를 이용해 천장 후보 선정

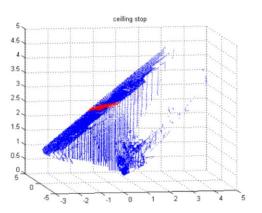


천장 후보 정보를 이용해 천장 검출

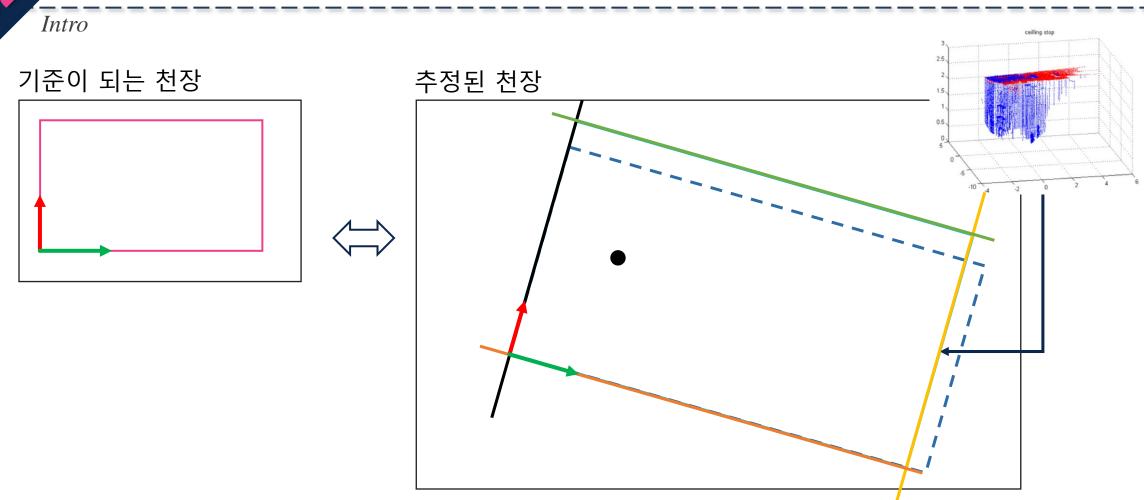








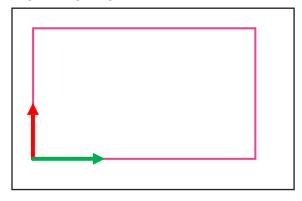




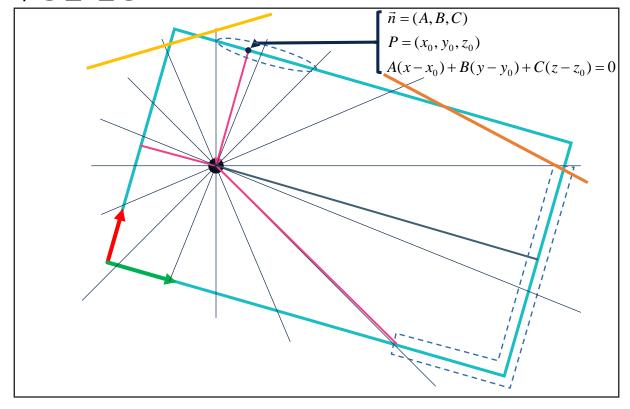


Intro

#### 기준이 되는 천장



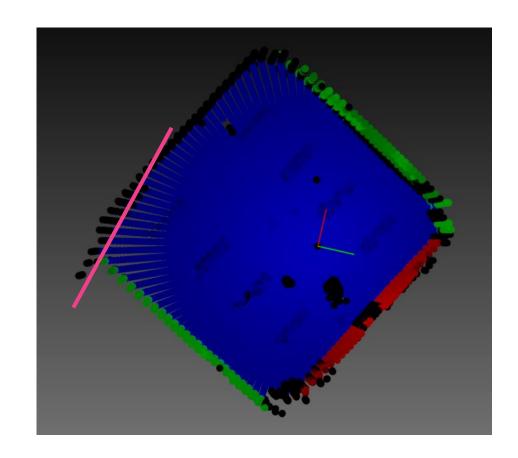
### 추정된 천장

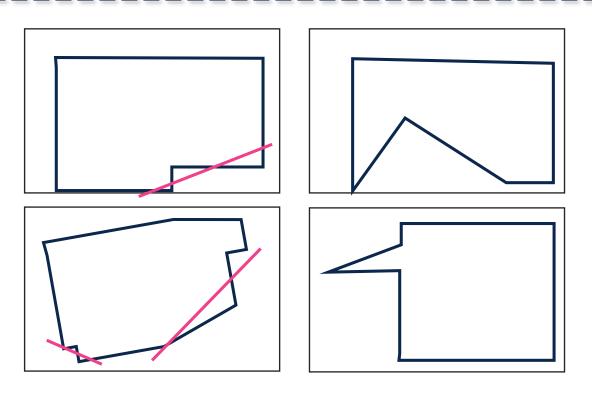


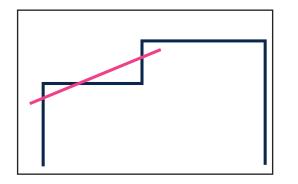
# 02

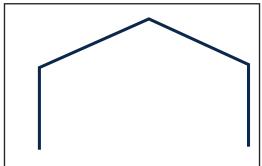
### Extract Ceiling based on Geometry

Problem



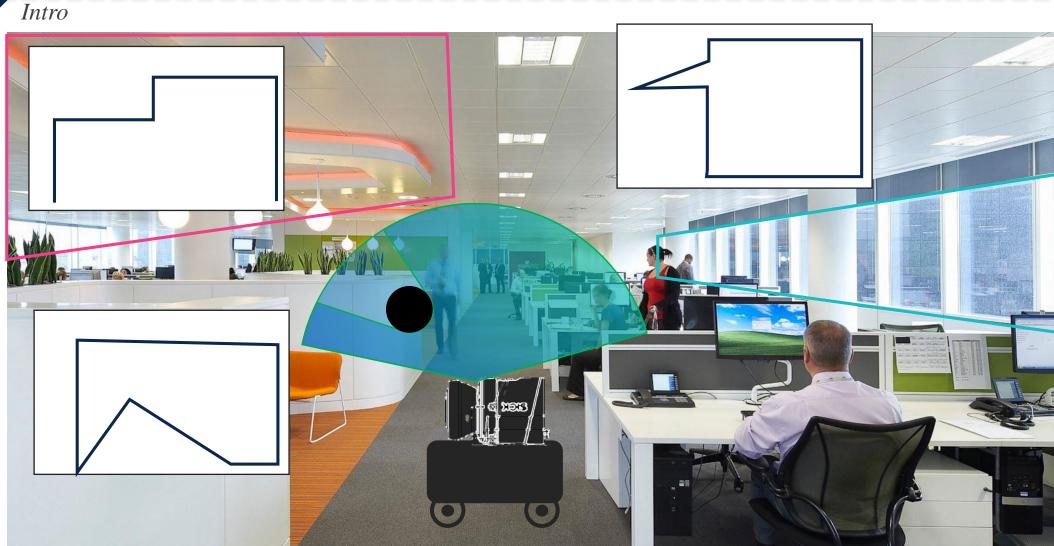






# 0

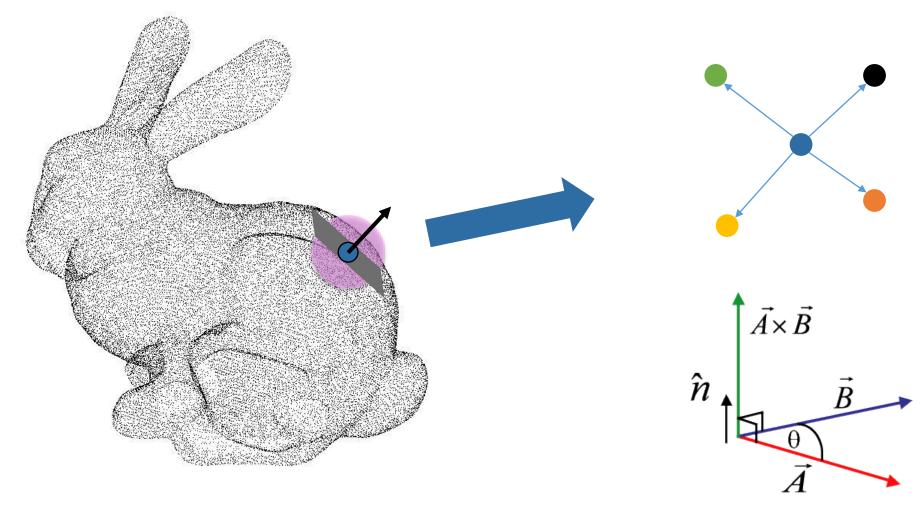
### Extract Ceiling based on Geometry





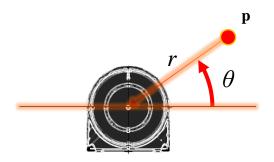
#### Intro

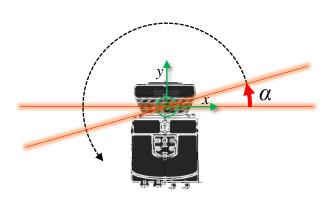
X Moosmann, Frank, Oliver Pink, and Christoph Stiller. "Segmentation of 3D lidar data in non-flat urban environments using a local convexity criterion." *Intelligent Vehicles Symposium, 2009 IEEE.* IEEE, 2009.

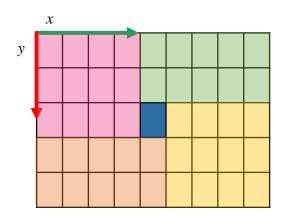


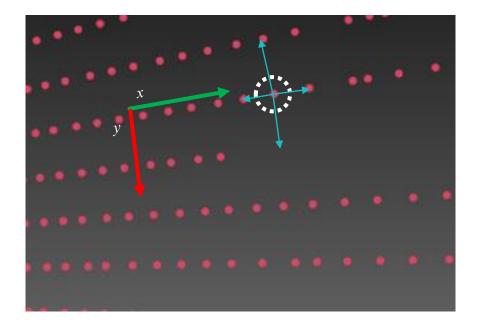


Get normal



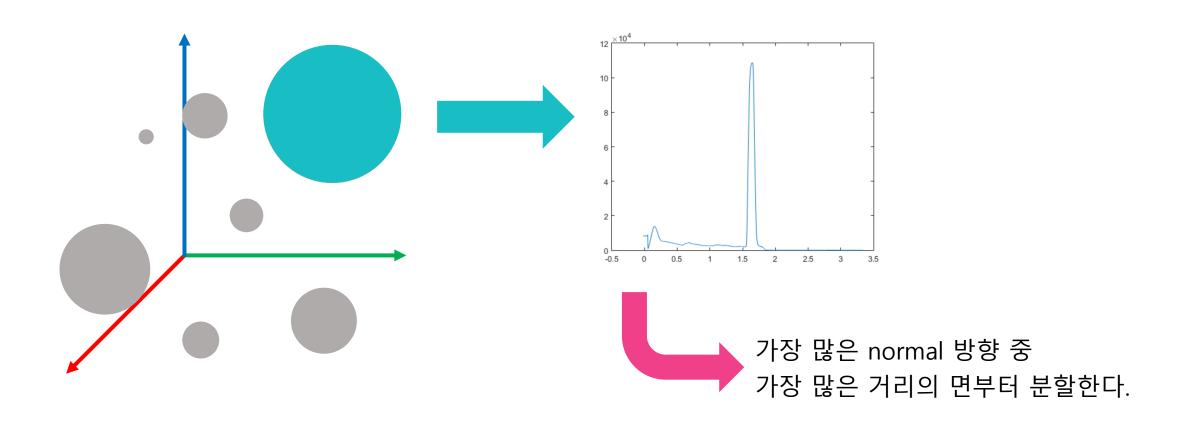






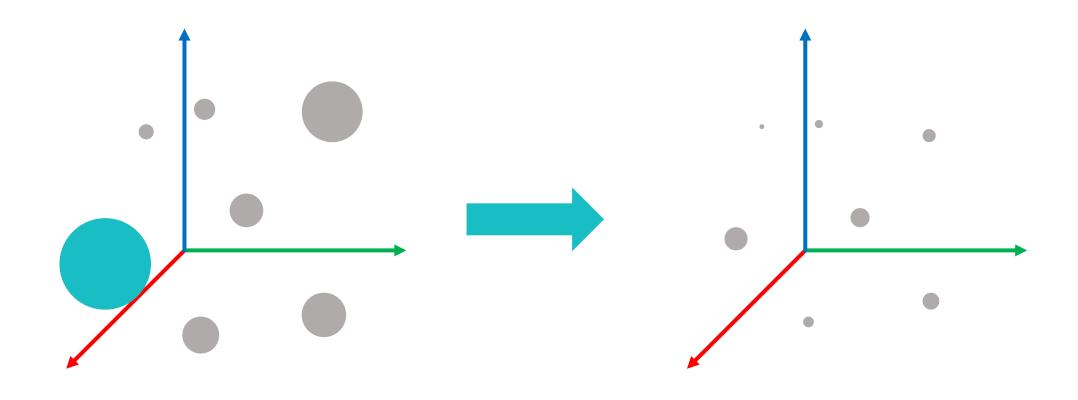


Segmentation

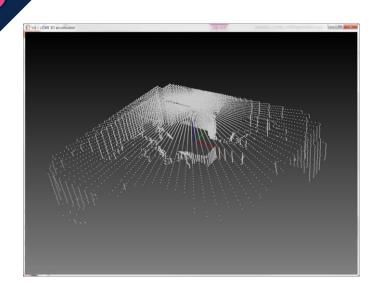




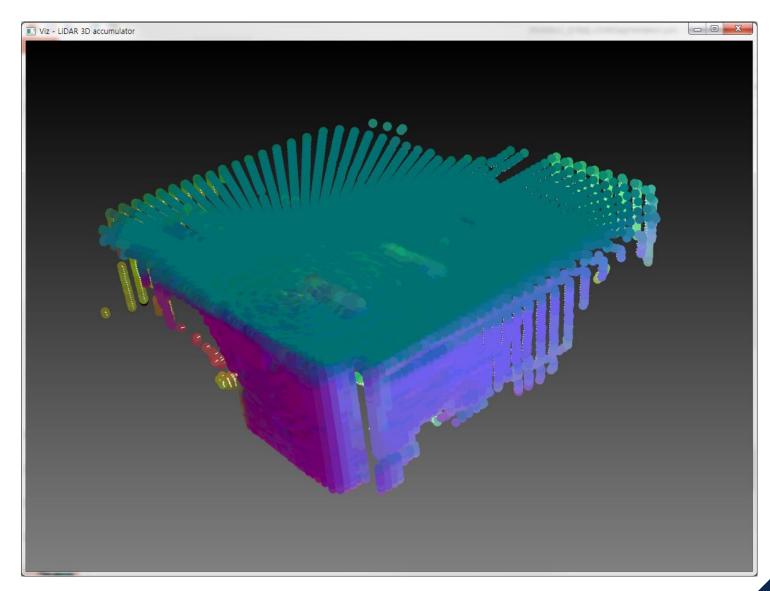
Segmentation



### Result

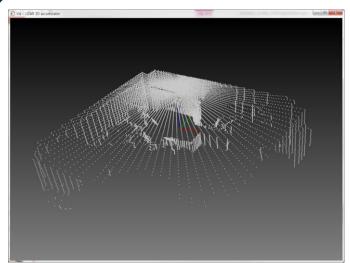


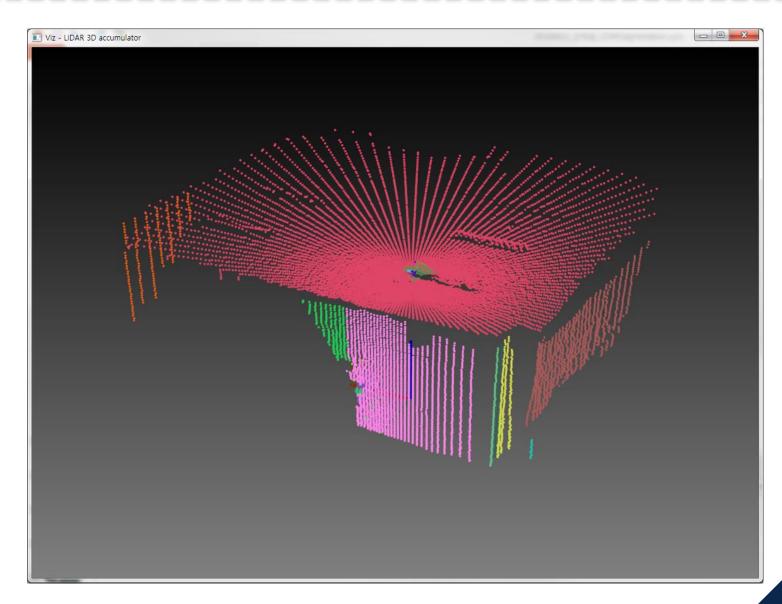




### Result







# Q&A

