# Mina Henein



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https://github.com/MinaHenein

https://minahenein.github.io/

https://scholar.google.com.eg/citations?user=PUBFzCAAAAAJ&hl=en

in https://www.linkedin.com/in/mina-henein-41660a53/

### **EDUCATION**

2016 - Today PhD candidate in Robotics, The Australian National University

The Australian Centre of Excellence for Robotic Vision

2013 - 2015 European Masters on Advanced Robotics, Ecole Centrale de Nantes

Università degli studi di Genova

Degrees Awarded: Masters in Automation, and Robotics.

Masters in Information Science.

2007 - 2012 Bachelor of Science, The German University in Cairo

**Mechatronics Engineering** 

**Graduation Grade: Excellent with honours** 

2007 College De La Salle, International French school in Cairo

Ranked 4th nation-wide

## **RESEARCH**

03/2016 - Today PhD candidate in Robotics Engineering, ANU

Australian National University Supervisors: Dr. Viorela IIa, Prof. Robert Mahony and Prof. Hongdong Li. Simultaneous Localisation and Mapping in dynamic environments.

02/2015 - 08/2015 Masters Thesis, Autonomous Systems Lab, ETH Zürich

Supervisors: Dr. Péter Fankhauser, Prof. Marco Hutter and Prof. Roland Siegwart.

Kinematic Planning for Challenging Maneuvers with a Legged Robot.

04/2014 - 07/2014 Semester Project (Masters), Italian Institute of Technology, Genoa

Dynamic Legged System Lab.

Supervisors: Prof. Roy Feather

Supervisors: Prof. Roy Featherstone and Prof. Claudio Semini.

Skippy: the high-jumping hopper.

## **EMPLOYMENT**

06/2019 - Today EduTech Australia

Director of EduTech Australia Innovators Academy ACT.

2016, 2017, 2018 Tutor, The Australian National University

Courses: Robotics ENGN4627/6627, Control Systems ENGN3223/6223.

Robotic Vision Summer School, Kioloa, Australia

07/2012 - 07/2013 Supply Network Operations Associate Manager, Procter & Gamble, Egypt

Near-East Demand Manager for Gillette and Duracell.

09/2011 Intern, Schlumberger Petroleum Services, Egypt

Summer internship in the Wire Line Sector.

08/2010 Mercedes Benz, Egypt

Summer internship in the Quality Control Department.

2013 - 2019 Private Tutor

Mathematics, and MATLAB Programming.

#### **AWARDS AND SCHOLARSHIPS**

2018	Research to Impact, Canberra Innovation Network.
2018	Research Top-Up Scholarship, Australian Centre of Excellence for Robotic Vision.
2016	HDR Merit Scholarship, The Australian National University.
2016	International Student PhD Scholarship, The Australian National University.
2013	EMARo Excellence Consortium Scholarhsip.
2012	Honours List, Bachelor of Science, German University in Cairo, Egypt.
2007	German University in Cairo Excellence Award Scholarship.
2007	Prime-Minister, Minister of Education, Minister of Social Solidarity, Minister of
	Communication Honouring.
2007	German Chancellor Angela Merkel Honouring.
2007	National Top Ranked Students, 4 <sup>th</sup> place nation-wide over 800,000 students, Egypt.
2000	"Le Kangourou des Maths" competition, 3 <sup>rd</sup> place, France.

## **PUBLICATIONS**

M. Henein, J. Zhang, R. Mahony and V. Ila (2020).
 Dynamic SLAM: The Need For Speed.

IEEE International Conference on Robotics and Automation (ICRA), 2020. (under review)

- J. Zhang, M. Henein, R. Mahony and V. IIa (2020).
   Robust Ego and Object 6-DoF Motion Tracking for Autonomous Driving Applications.
   IEEE International Conference on Robotics and Automation (ICRA), 2020. (under review)
- M. Henein, G. Kennedy, R. Mahony and V. Ila (2018).

**Exploiting Rigid Body Motion for SLAM in Dynamic Environments.** 

IEEE International Conference on Robotics and Automation (ICRA), 2018. Workshop paper. Multi-modal Robot Perception: Perception, Inference and Learning for Joint Semantic, Geometric and Physical Understanding.

- M. Henein, G. Kennedy, R. Mahony and V. Ila (2018).
   Simultaneous localization and mapping with dynamic rigid objects.
   Submitted as an arXiv paper.
- M. Henein, M. Abello, V. Ila and R. Mahony (2017).
   Exploring The Effect of Meta-Structural Information on the Global Consistency of SLAM.
   IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2017.

## **LANGUAGES**

- Arabic: native language,
- English: proficient user,
- French: proficient user,
- Italian: limited working proficiency,
- German: elementary proficiency, and
- Spanish: elementary proficiency.

03/2019 PTE Overall Score: 90. 03/2018 IELTS Band score: 8.

05/2008 DELF B2.

## **REFERENCES**

Available upon request.