Ignacio Andrade Salazar Teoria del Control Circuito Rc de Segundo Orden 11/10/2023 Vo (t) Vi(t) VR, (t) = R, i, (t) VRZ(t)= Bziz(t) $i_1(t) = i_2(t) = C_1 \frac{dvC_1(t)}{dt}$ $i_2(t) = C_2 \frac{dvC_2(t)}{dt}$ i, (t) = c2 dvcz(t) + c, dvc, (t) VR,(t) = R, (Cz dvCz(t) + C, (RzCz d²VCz(t) + dvCz(t) Vi(t) = VR, (t)+ VR2(t)+ VC2(t) vi(t) = R, C, R2C2 d2 V(z(t) + (R,C+R,C2+RzCz) dv(z(t) + V(z(t)

$$Q_{2} = R_{1}C_{1}R_{2}C_{2}$$

$$Vi = Q_{2} \frac{d^{2}Vc_{2}(t)}{dt^{2}} + Q_{1} \frac{dvC_{2}(t)}{dt} + VC_{2}(t)$$

$$Vi(s) = Q_{2} \left[s^{2}V(c_{2}(s)) + Q_{1} s Vc_{2}(s) + Vc_{2}(s) \right]$$

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$$Vi(s) = \left(q_{2} s^{2} + Q_{1} s + 1 \right) V_{0}(s) \left[V_{0}(s) - Vc_{2}(s) \right]$$

$$Vo(s) = Q_{2} \left[s^{2} + Q_{1} s + 1 \right]$$

$$Vo(s) = Q_{2} \left[r_{1}C_{1}R_{2}C_{2} \right] s^{2} + \left(r_{1}C_{1} + r_{1}C_{2} + r_{2}C_{2} \right) s + 1$$

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