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Teoría del Control  
Transformada de Laplace

Electrónica y Comp.  
29/08/23

$$f(t) = A \cos(\omega t)$$

$$F(s) = \mathcal{L}\{A \cos(\omega t)\} = \int_0^{\infty} e^{-st} A \cos(\omega t) dt$$

$$F(s) = A \int_0^{\infty} \cos(\omega t) e^{-st} dt \Rightarrow \mathcal{L}\{\cos(\omega t)\} \Rightarrow$$

$$F(s) = A \cdot \frac{s}{s^2 + \omega^2} \int_0^{\infty} e^{-st} dt$$

$$\frac{s}{s^2 + \omega^2}$$

$$F(s) = A \cdot \frac{\cancel{s}}{s^2 + \omega^2} \cdot \frac{1}{\cancel{s}}$$

$$F(s) = \frac{A}{s^2 + \omega^2}$$

$$\int_0^{\infty} e^{-st} dt = \frac{1}{s}$$

Entonces:

$$\mathcal{L}\{A \cos(\omega t)\} = \frac{A}{s^2 + \omega^2}$$