

Trees





Outline

- Tree concept
- General tree
- Types of trees
- Binary tree: representation, operation
- Binary tree traversal
- Binary search tree
- BST- The data structure and implementation
- Threaded binary trees.
- Search Trees
 - AVL tree, Multiway Search Tree, B Tree, B+ Tree, and Trie,
- Applications/Case study of trees.
- Summary





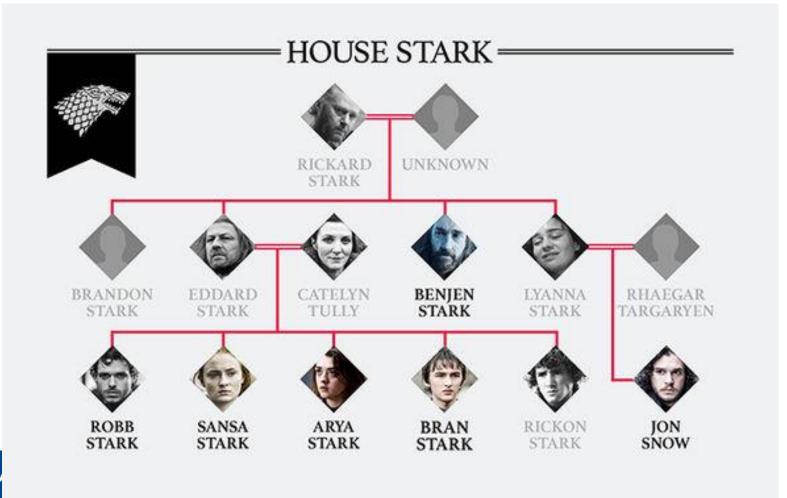
Tree

- linear data structures strings, arrays, lists, stacks and queues
- Non-linear data structure tree.
- Mainly used to represent data containing a hierarchical relationship between elements, for example, records, family trees and table of contents.
 - E.g. a parent-child relationship





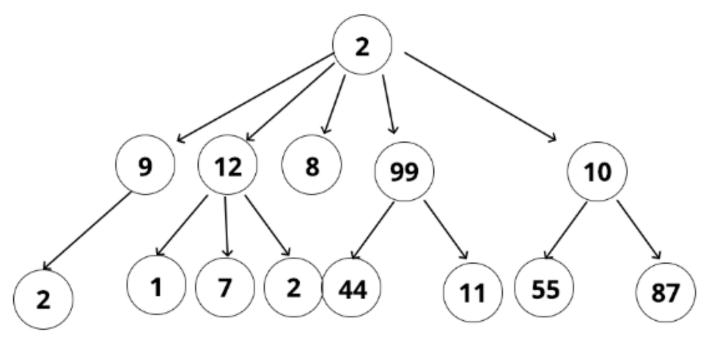
A family tree







TRES





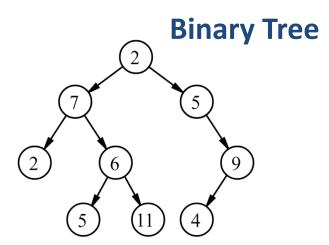


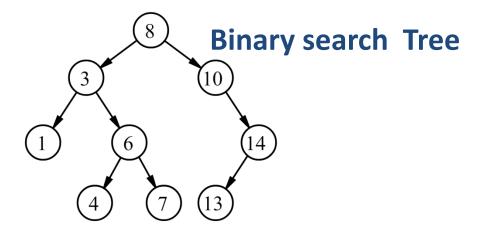
Types of trees

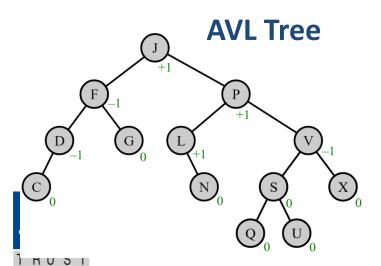
- General tree
- Binary tree
- Binary search tree
- Threaded binary tree
- AVL Tree
- B tree
- B+ Tree
- Trie
- Heap
- Red black tree
- Splay tree



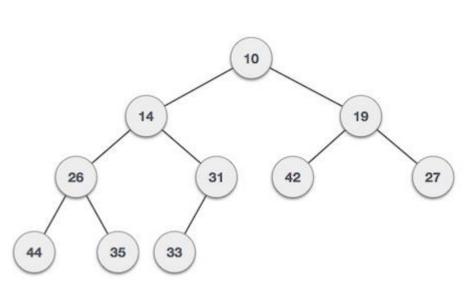






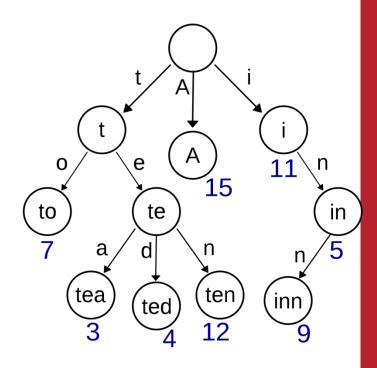






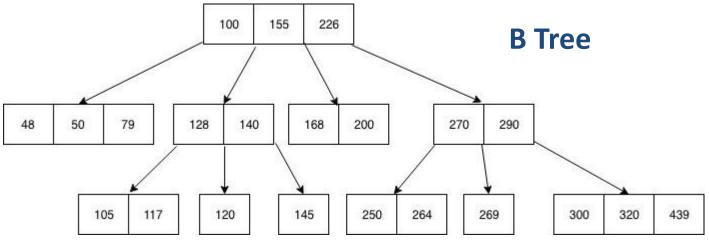


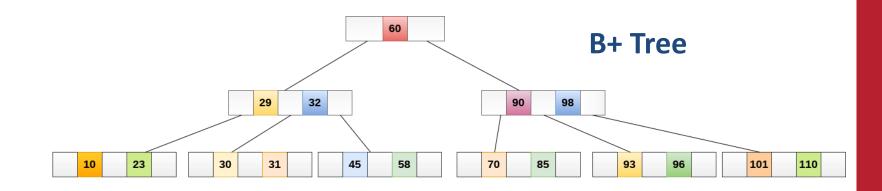
Heap (MinHeap)



Trie







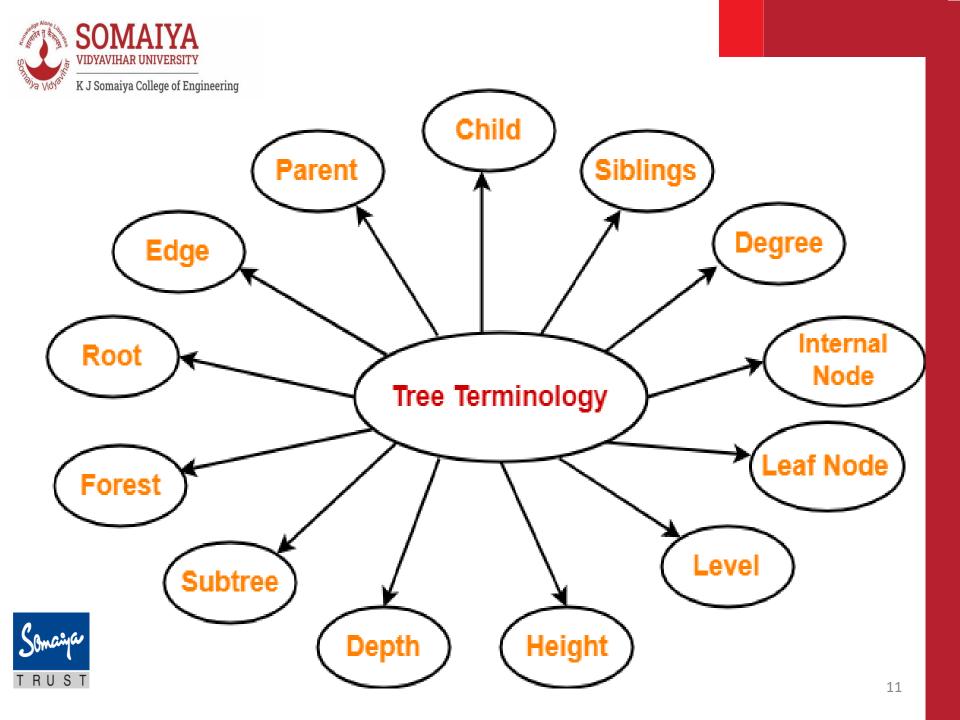




Tree Data structure

- A tree is an abstract model of a hierarchical structure that consists of nodes with a parentchild relationship.
- Tree is a sequence of nodes
- There is a starting node known as a root node
- Every node other than the root has a parent node.
- Nodes may have any number of children

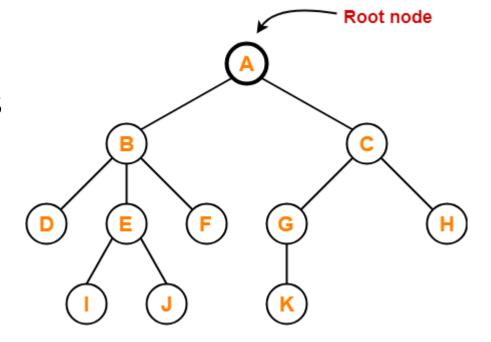






1. Root

- The first node from where the tree originates is called as a root node.
- In any tree, there must be only one root node.
- We can never have multiple root nodes in a tree data structure.

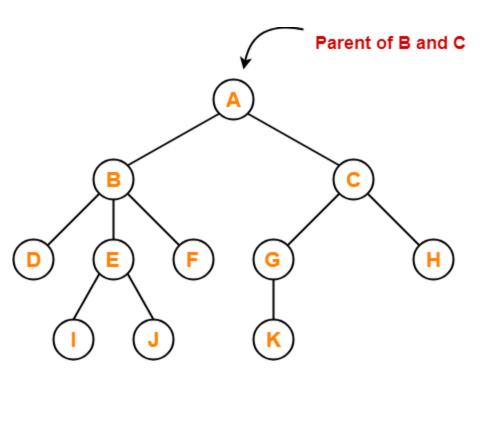






2. Edge

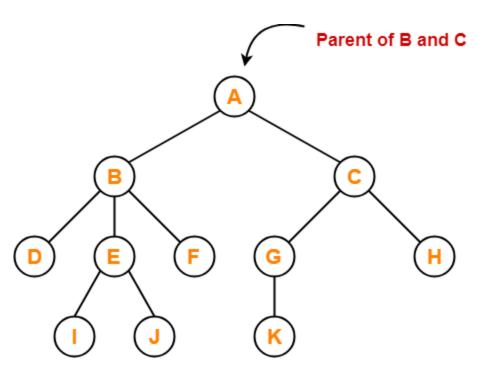
- The connecting link between any two nodes is called as an edge.
- In a tree with n number of nodes, there are exactly (n-1) number of edges.





3. Parent

- The node which has a branch from it to any other node is called as a parent node.
- In other words, the node which has one or more children is called as a parent node.
- In a tree, a parent node can have any number of child nodes.

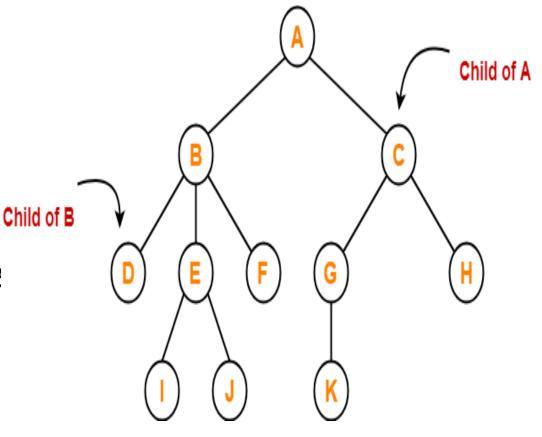






4. Child

- The node which is a descendant of some node is called as a child node.
- All the nodes except root node are child nodes.

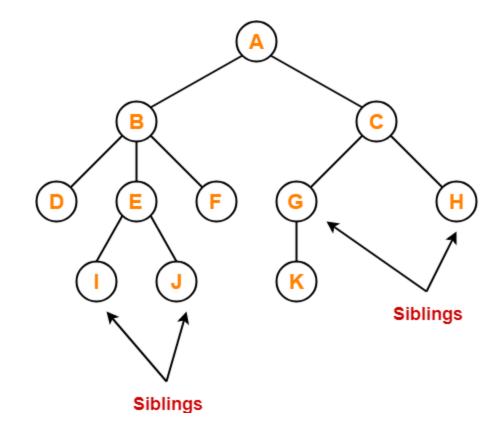






5. Siblings

- Nodes which belong to the same parent are called as siblings.
- In other words, nodes with the same parent are sibling nodes.

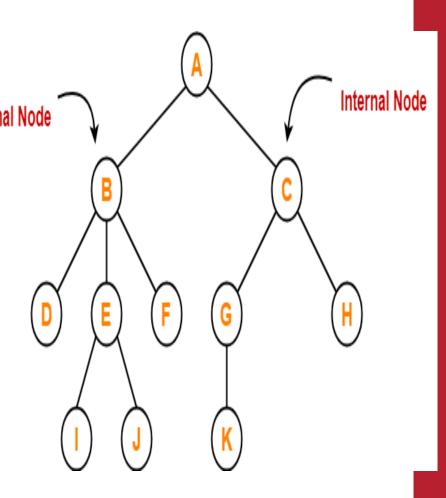






7. Internal Node

- The node which has at least one child is called as an internal Internal Node node.
- Internal nodes are also called as nonterminal nodes.
- Every non-leaf node is an internal node.

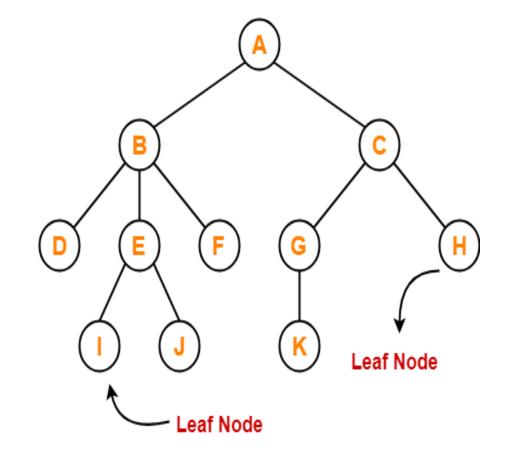






8. Leaf Node

- The node which does not have any child is called as a leaf node.
- Leaf nodes are also called as external nodes or terminal nodes.

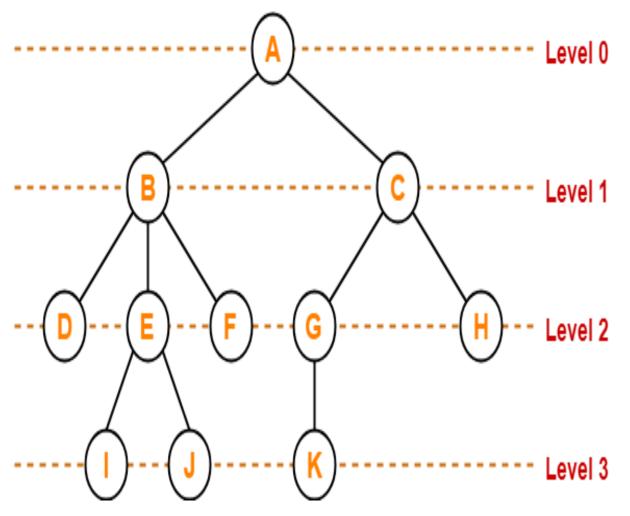






9. Level

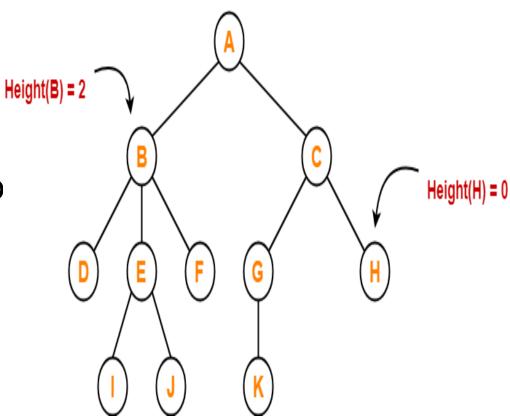
- In a tree, each step from top to bottom is called as level of a tree.
- The level count starts with 0 and increments by 1 at each level or step.





10. Height

- Total number of edges that lies on the longest path from any leaf node to a particular node is called as height o that node.
- Height of a tree is the height of root node.
- Height of all leaf nodes = 0

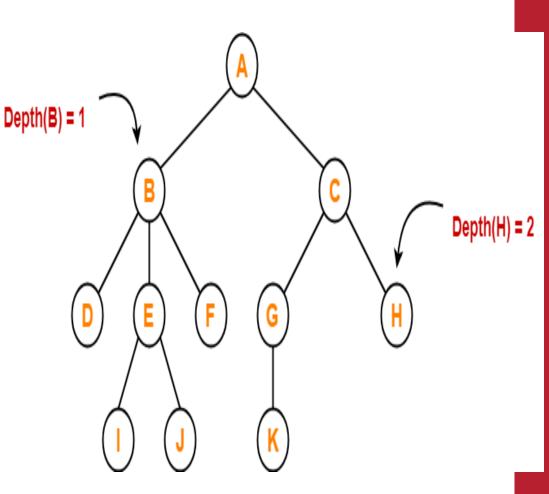






11. Depth

- Total number of edges from root node to a particular node is called as depth of that node.
- Depth of a tree is the total number of edges from root node to a leaf node in the longest path.
- Depth of the root node = 0
- The terms "level" and "depth" are used interchangeably.

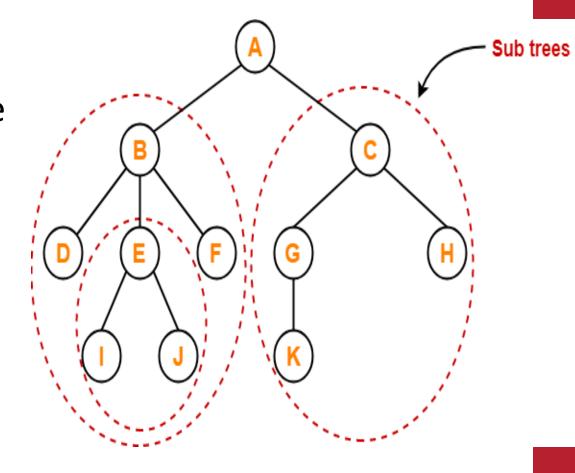






12. Subtree

- In a tree, each child from a node forms a subtree recursively.
- Every child node forms a subtree on its parent node.

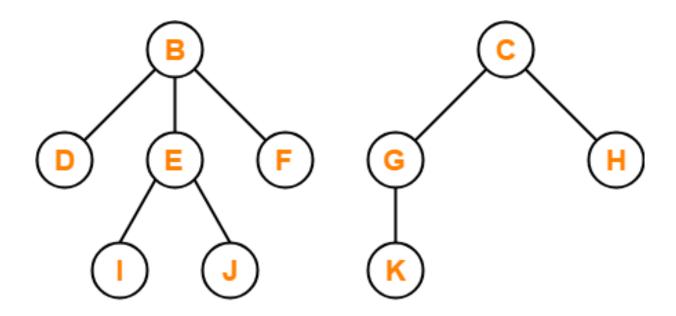






13. Forest

A forest is a set of disjoint trees.



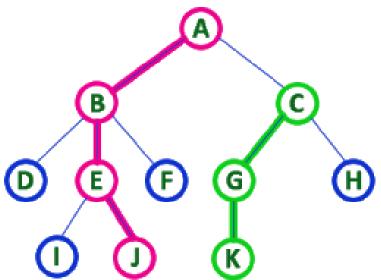
Forest





14. Path

 The sequence of consecutive edges from source node to destination node.



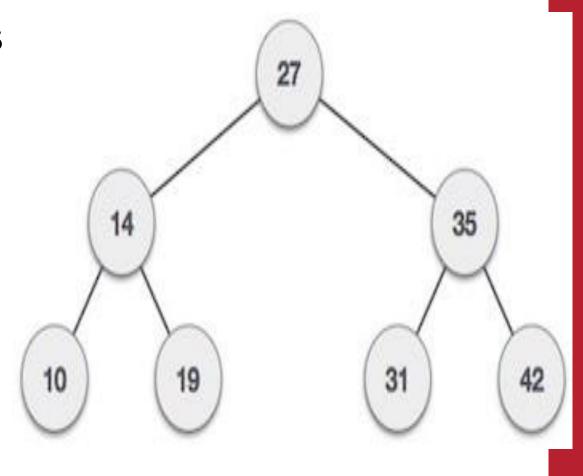
 In any tree, 'Path' is a sequence of nodes and edges between two nodes.





15. Keys

 Key represents a value of a node based on which a search operation is to be carried out for a node.







- Non-linear data structure
- Combines advantages of an ordered array and linked list
- Searching as fast as in ordered array
- Insertion and deletion as fast as in linked list
- Simple and fast





Application

- Directory structure of a file storage
- Structure of an arithmetic expressions
- Used in almost every 3D video game to determine what objects need to be rendered.
- Used in almost every high-bandwidth router for storing router-tables.
- used in compression algorithms, such as those used by the .jpeg and .mp3 file formats
- Game trees





Directory structure of a file storage

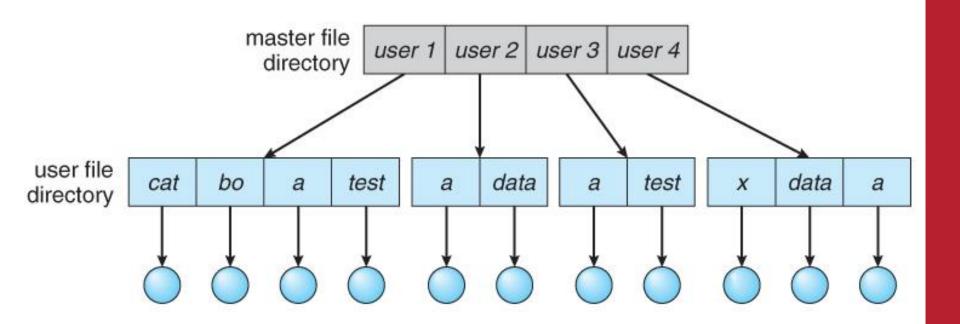


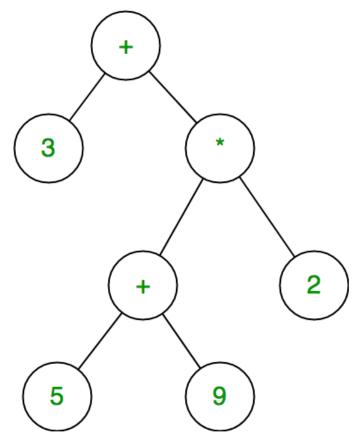


Image courtesy:

https://www.cs.uic.edu/~jbell/CourseNotes/OperatingSystems/images/Chapter11/1 1_10_TwoLevelStructure.jpg



Structure of an arithmetic expressions







Object rendering in 3-D game

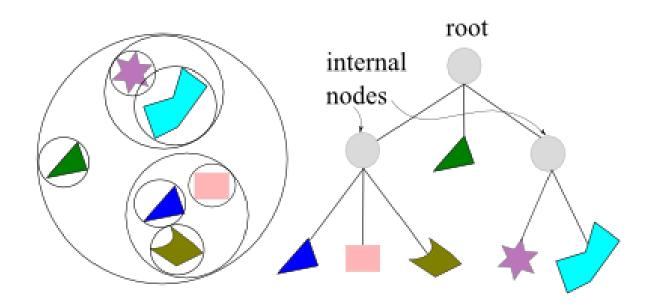
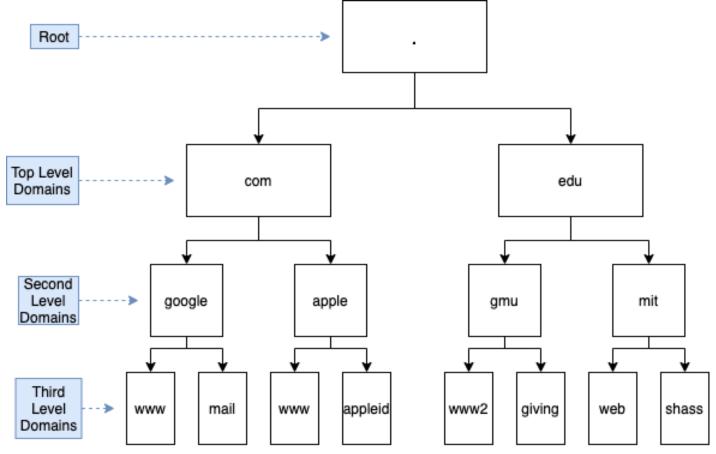




Image Courtesy: https://www.bogotobogo.com/Games/images/BVH.png



DNS Server entries



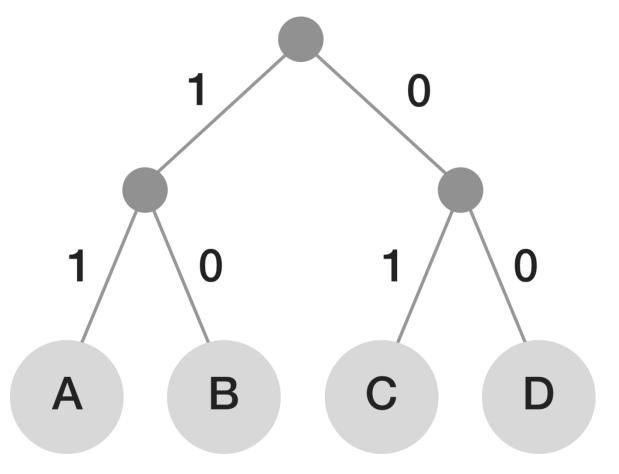
Graphic created by Blake Khan (blakekhan.com)



Image Courtesy: https://res.cloudinary.com/practicaldev/image/fetch/s--b9G6DenD-/c_limit%2Cf_auto%2Cfl_progressive%2Cq_auto%2Cw_880/https://i.imgur.com/xOd VIPZ.png



Compression Algorithm

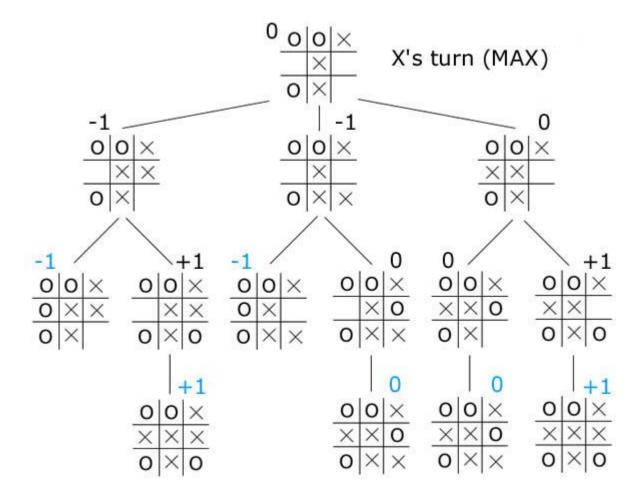




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Game Tree





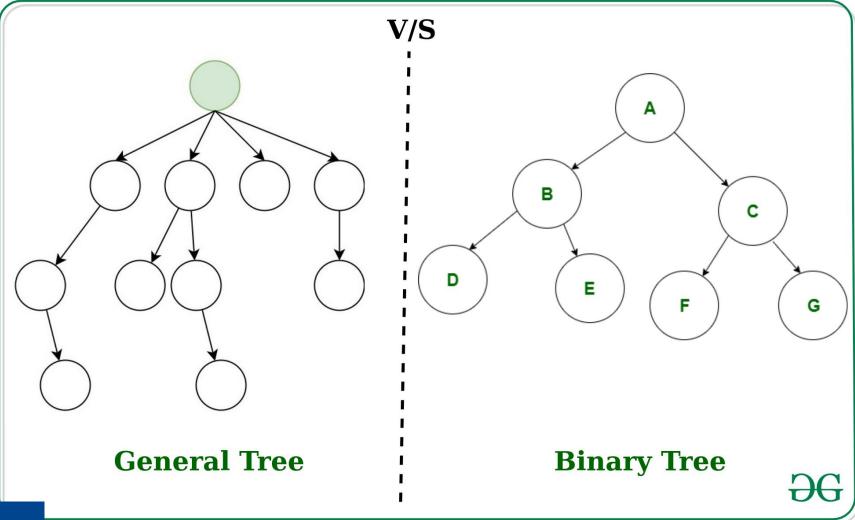


Binary Trees

- A binary tree, T, is either empty or such that
- 1. T has a special node called the root node
- T has two sets of nodes L_T and R_T, called the left subtree and right subtree of T, respectively.
- 3. L_T and R_T are binary trees.











Binary Tree

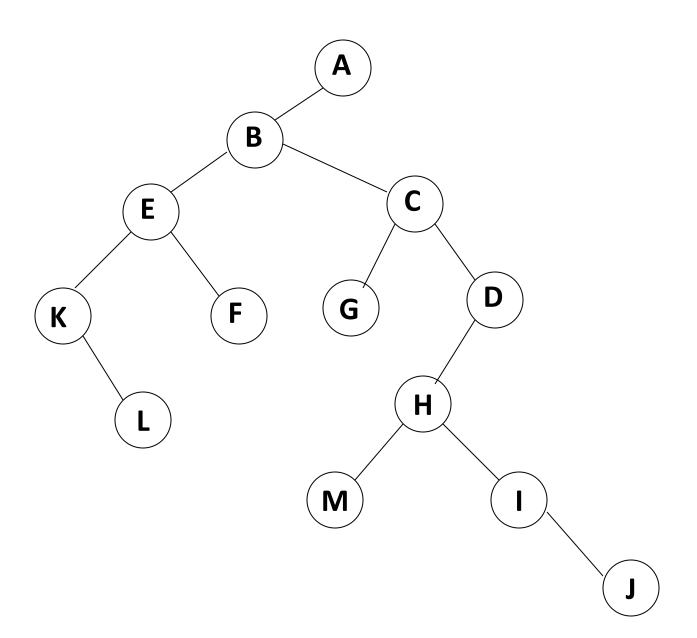
- A binary tree is a finite set of elements that are either empty or is partitioned into three disjoint subsets.
- The first subset contains a single element called the root of the tree.
- The other two subsets are themselves binary trees called the left and right sub-trees of the original tree.
- A left or right sub-tree can be empty.
- Each element of a binary tree is called a node of the tree



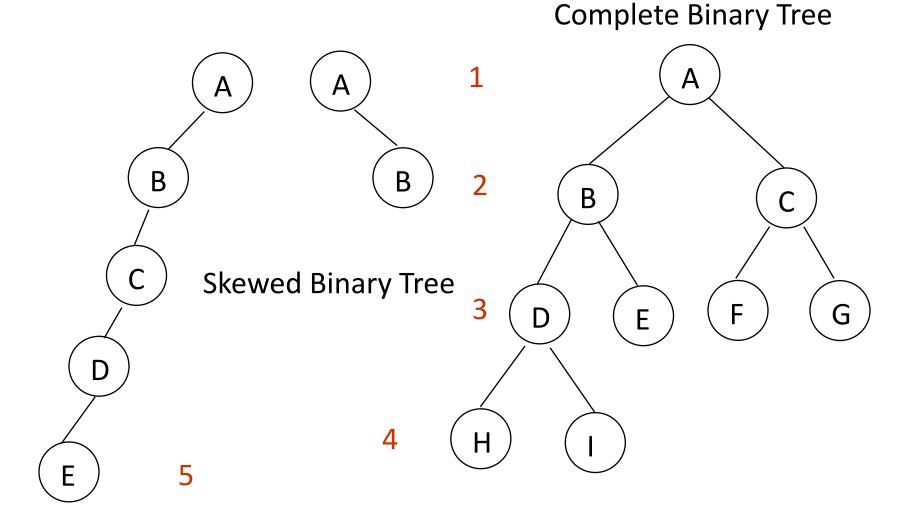
Binary Tree Properties

- If a binary tree contains m nodes at level L, it contains at most 2^m nodes at level L+1
- Since a binary tree can contain at most 1 node at level 0 (the root), it contains at most 2^L nodes at level L.





Samples of Trees





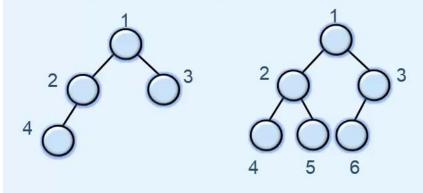
Types of Binary Tree

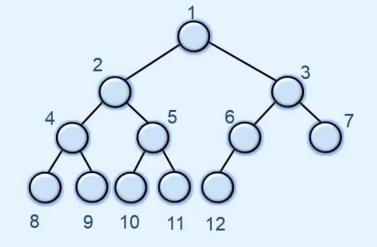
- Complete binary tree
- Strictly binary tree
- Almost complete binary tree



A complete binary tree

Complete Binary Tree





If a node in a complete binary tree is assigned a number k, where $1 \le k \le n$, then



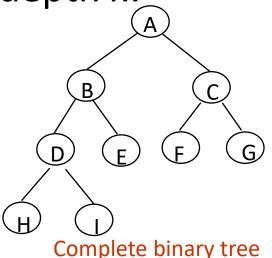


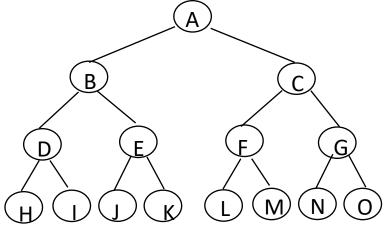
Binary tree types

- Strictly binary trees are binary trees where every node either has two children or is a leaf (has no children).
- A complete binary tree is a binary tree in which every level, except possibly the last level, is completely filled, and all nodes in the last level are as far left as possible.
- Almost complete binary trees are not necessarily strictly binary (although they can be), and are not complete.

Full BT VS Complete BT

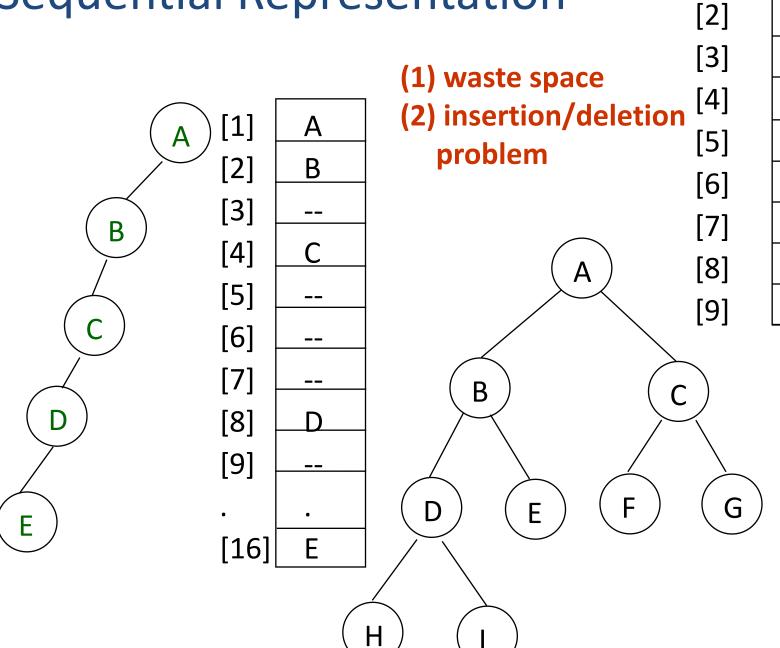
- A full binary tree of depth k is a binary tree of depth k having 2^k -1 nodes, k>=0.
- A binary tree with n nodes and depth k is complete iff its nodes correspond to the nodes numbered from 1 to n in the full binary tree of depth k.





Full binary tree of depth 45

Sequential Representation



Α

В

C

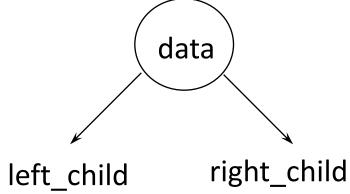
[1]

<u>H</u> .

Linked Representation

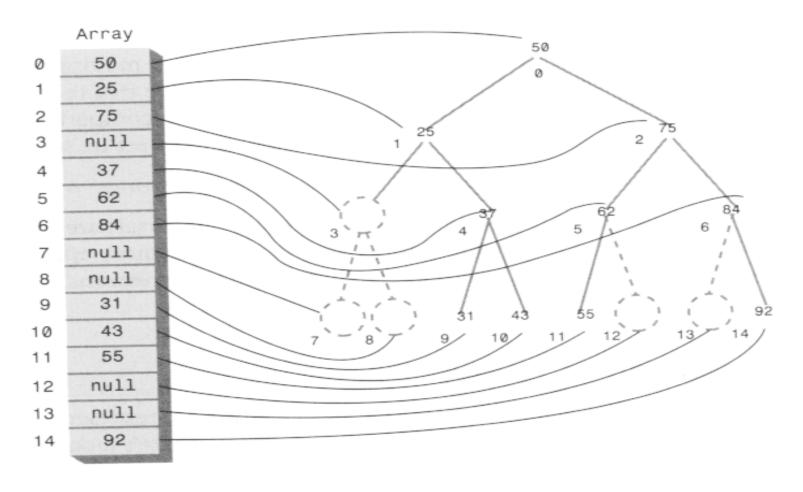
```
typedef struct node *tree_pointer;
typedef struct node {
  int data;
  tree_pointer left_child, right_child;
};
```

left_child data	right_child
-----------------	-------------





KJ Somaiya Charmany representaion of tree







Binary tree traversal

Traversal: visiting each node only once

Traversal methods:

Inorder : Left-Root-Right

Preorder : Root-Left-Right

Postorder : Left-Right-Root

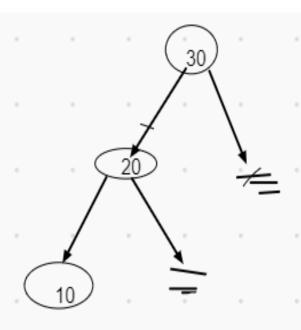




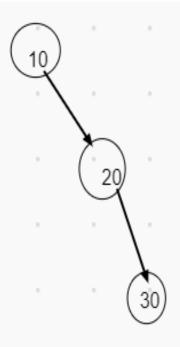
- Let L, V, and R stand for moving left, visiting the node, and moving right.
- There are six possible combinations of travers
 - LVR, LRV, VLR, VRL, RVL, RLV
- Adopt convention that we traverse left before right, only 3 traversals remain
 - LVR, LRV, VLR
 - inorder, postorder, preorder



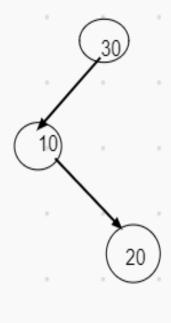




inorder -10, 20,30, Preorder - 30, 20, 10 Postorder - 10, 20,30



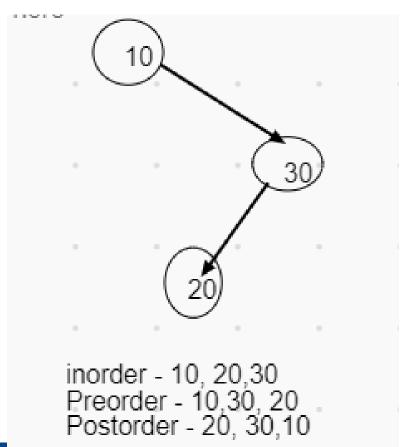
inorder - 10, 20,30 Preorder - 10, 20,30 Postorder - 30, 20,10

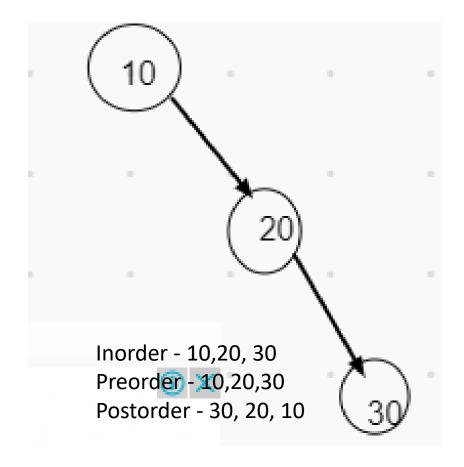


inorder - 10, 20,30 Preorder - 30, 10,20, postorder - 20, 10,30



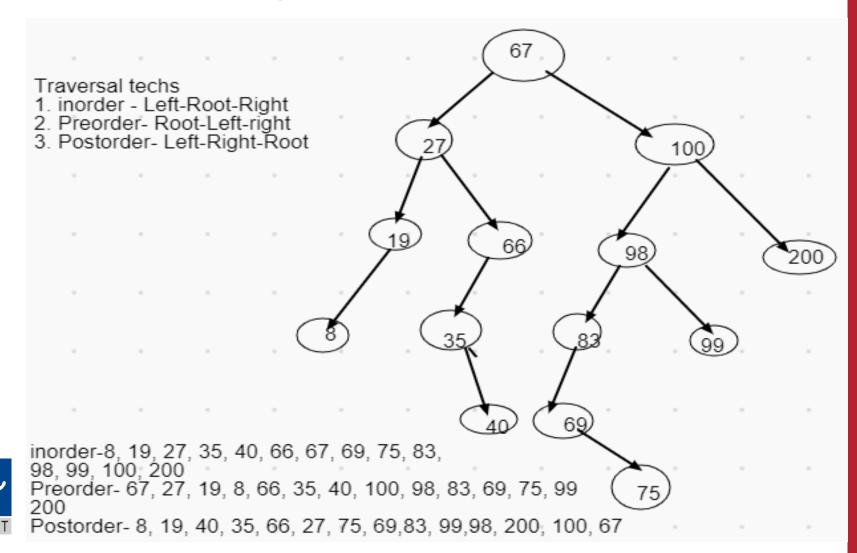






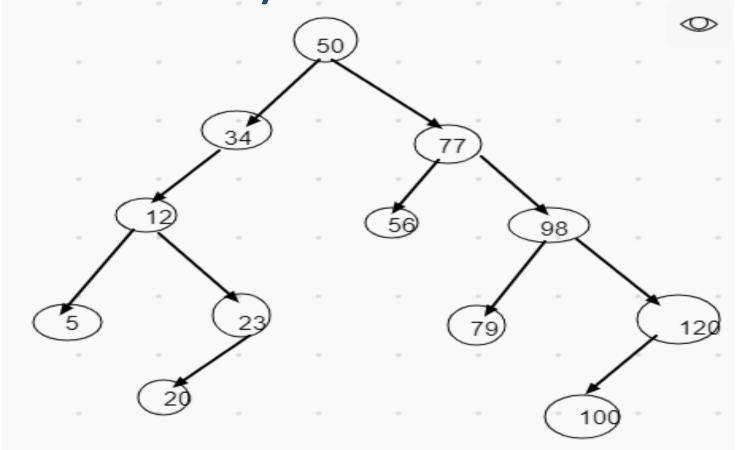








K J Somaiya College of Engine Binary Tree Traversals

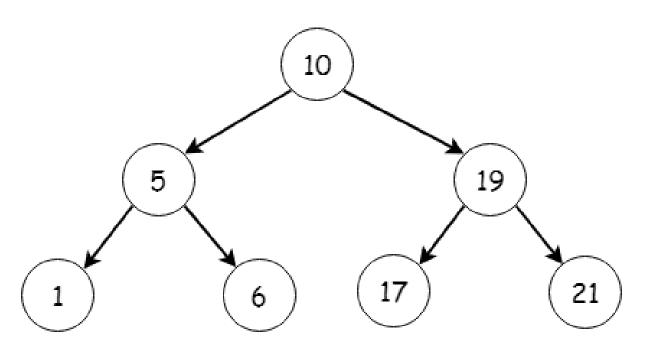




Preorder- 50, 34, 12,5, 23, 20,77, 56,98 79,120, 100, Postorder- 5, 20, 23, 12, 34, 56, 79, 100, 120, 98, 77, 50 Inorder- 5, 12, 20, 23, 34, 50, 56, 77,79, 98, 100, 120



Linary tree Traversal



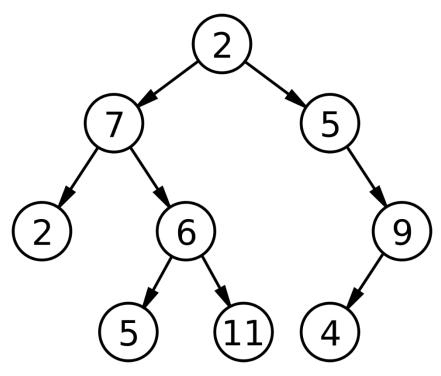
• Inorder: 1-5-6-10-17-19-21

Preorder: 10-5-1-6-19-17-21

Postorder: 1-6-5-17-21-19-10



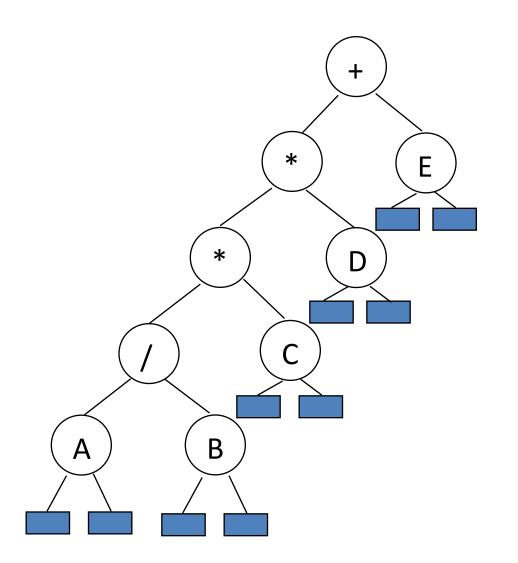
KJ Somaiya College of Engineering Binary tree Traversal



- Inorder: ?
- Preorder: ?
 - Postorder: ?



Arithmetic Expression Using BT



inorder traversal A / B * C * D + E infix expression preorder traversal + * * / A B C D E prefix expression postorder traversal A B / C * D * E + postfix expression level order traversal + * E * D / C A B





Inorder Traversal (recursive version)

```
void inorder(tree pointer ptr)
/* inorder tree traversal */
                          A / B * C * D + E
    if (ptr) {
        inorder(ptr->left child);
        printf("%d", ptr->data);
        indorder(ptr->right child);
```



Preorder Traversal (recursive version)

```
void preorder(tree pointer ptr)
/* preorder tree traversal */
                          + * * / A B C D E
    if (ptr) {
        printf("%d", ptr->data);
        preorder(ptr->left child);
        predorder(ptr->right child);
```



Postorder Traversal (recursive version)

```
void postorder(tree pointer ptr)
/* postorder tree traversal */
                         A B / C * D * E +
    if (ptr) {
        postorder(ptr->left child);
        postdorder(ptr->right child)
        printf("%d", ptr->data);
```



Construction of binary tree from traversals

- Can be done with two pairs of information:
 - Inorder & Preorder
 - Inorder & Postorder

• Inorder: 1-5-6-10-17-19-21

Preorder: 10-5-1-6-19-17-21





Binary Search Tree

Binary Search Tree is a node-based binary tree data structure which has the following properties:

- The left subtree of a node contains only nodes with keys lesser than the node's key.
- The right subtree of a node contains only nodes with keys greater than the node's key.
- The left and right subtree each must also be a binary search tree.



Creation of Binary Search Tree from traversals

For inorder & Preorder traversal pairs:





Creation of Binary Search Tree from traversals

For inorder & Postorder traversal pairs:





Construction of Binary Search Tree

Construct a BST for:

- 10,45,23,90,21,65,100,4,78,50
- 50,78,4,100,65,21,90,23,45,10
- 65,4,50,10,78,45,100,23,90,21





Binary Search implementation

```
Struct tree{
    int data;
    struct tree *left;
    struct tree *right;
    }
Struct tree *t;
```



Insertion in BST

```
Treetype insert(TreeType *root, int key)
     CreateNode(NewNode)
  // find the position to insert the new node
  Treetype *temp = root;
  // Pointer parent maintains the trailing pointer of temp
  Treetype *parent = NULL;
  while (temp != NULL) {
    parent = temp;
    if (key < temp->data) temp = temp->left;
    else
                 temp = temp->right;
  // If the root is NULL i.e the tree is empty. The new node is the root node.
  if (parent == NULL)
                         root = newnode;
  // If the new key is less then the leaf node key Assign the new node to be its left child
  else if (key < parent->data)
                                     parent->left = newnode;
  // else assign the new node its right child
  else
                          parent->right = newnode;
    return root;
```

Count nodes

```
int countNodes(TreeType t)
If (t==Null)
Print "tree is empty"
Else if (Left(t)==Null AND Right(t)==Null)
     return 1
Else
return(CountNodes(Left(t)+CountNodes(Right(t))+1
```



Binary Search tree deletion

Cases:

- 1. Deletion from empty tree
- 2. The key to be deleted doesn't exist in tree
- 3. The node to be deleted is the only node in tree
- 4. The node to be deleted is root
- 5. The node to be deleted has
 - No child
 - 2. Exactly one child
 - 3. Two children



Deletion of a node in BST

```
//Deletion from empty tree
If (root==null)
{ print "Error"
 exit
//Deletion of only node
If(root->data ==key && root->left==Null && root->right==Null)
   temp=root
   Root=null
   Return(temp)
```

```
Parent = null
Temp =root
While(temp!=null && temp->data !=key)
{ if (key< temp->data)
    parent = temp; temp=temp->left
 else
    parent = temp; temp=temp->right
If (temp==null)
Print "Error, element not found" Exit
Elseif (temp->left== null && temp->right==Null)
//node with no children
   { if (temp==parent->left)
         parent->left= Null
     Else
        parent->right=Null
```

```
Elseif(temp->left!= null && temp->right==Null)
//node with only left child
{ if (temp==parent->left)
         parent->left= temp->left
     Else
       parent->right=temp->left
Elseif(temp->left== null && temp->right!=Null)
//node with only right child
{ if (temp==parent->left)
         parent->left= temp->right
     Else
       parent->right=temp->right
```

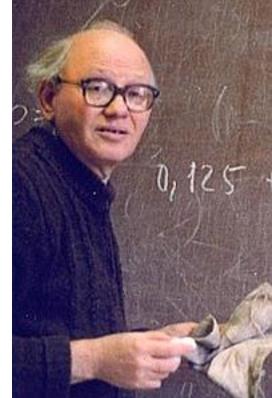
//Deletion of node with two children



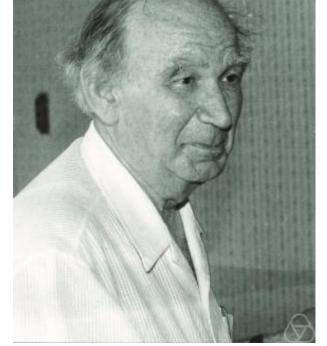
AVL tree

Named after their inventors **Adelson, Velski & Landis**, AVL trees are height balancing binary

search tree.









AVL tree

Let's consider creation of a BST i.e. insert values starting from an empty tree

Insert values 1, 2, 3, 4, 5, 6, 7, 8, 9 into an empty BST

- If inserted in given order, what is the tree?
- Is inserting in the reverse order any better?





BST: Efficiency of Operations?

Problem:

Worst-case running time:

• find, insert, delete

• buildTree





How can we make a BST efficient?

Observation

Solution: Require a Balance Condition that

- When we build the tree, make sure it's balanced.
- BUT...Balancing a tree only at build time is insufficient.
- We also need to also keep the tree balanced as we perform operations.



Potential Balance Conditions

Left and right subtrees

Left and right subtrees





The AVL Tree Data Structure

An AVL tree is a self-balancing binary search tree.

Structural properties
Binary tree property (same as BST)
Order property (same as for BST)

Balance condition: balance of every node is between -1 and 1

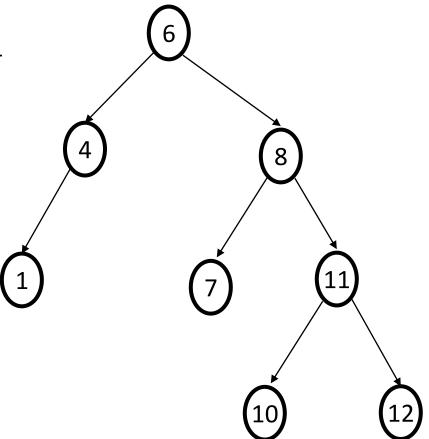
where balance(node) = height(node.left) – height(node.right)



Example #1: Is this an AVL Tree?

Balance Condition:

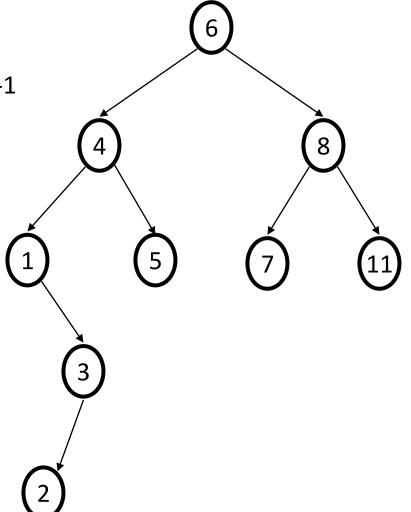
balance of every node is between -1 and 1



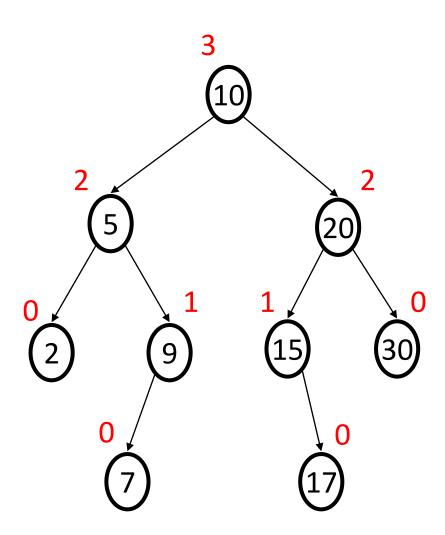
Example #2: Is this an AVL Tree?

Balance Condition:

balance of every node is between -1 and 1



AVL Trees



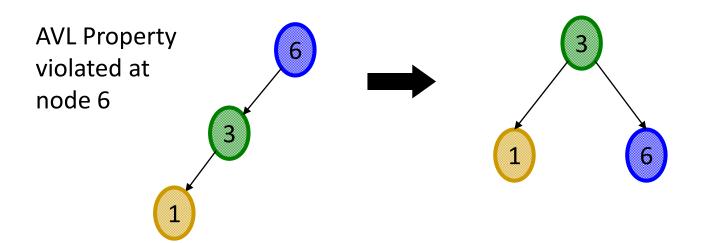
First insert example

```
Insert(6)
Insert(3)
Insert(1)
```

Third insertion

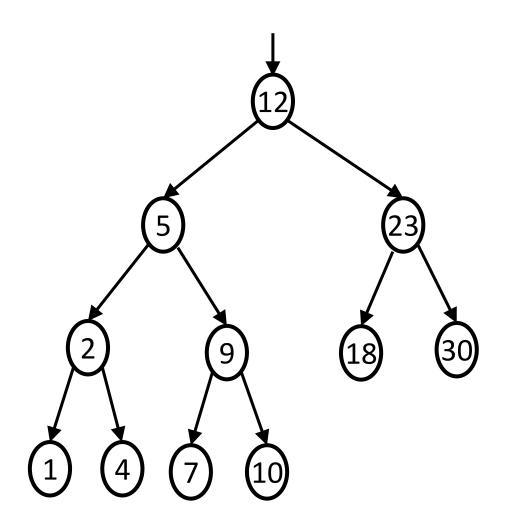
What's the only way to fix it?

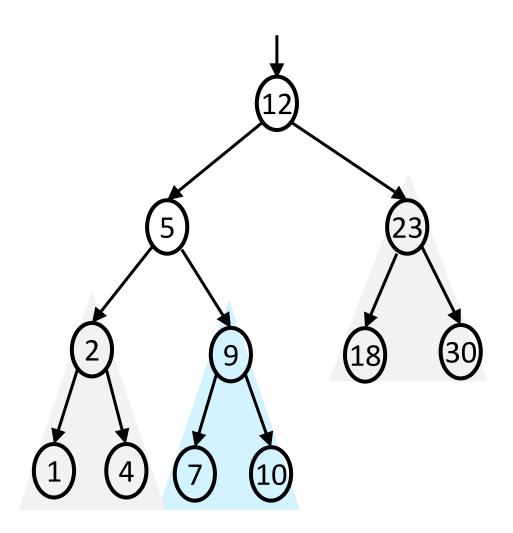
Fix: Apply "Single Rotation"

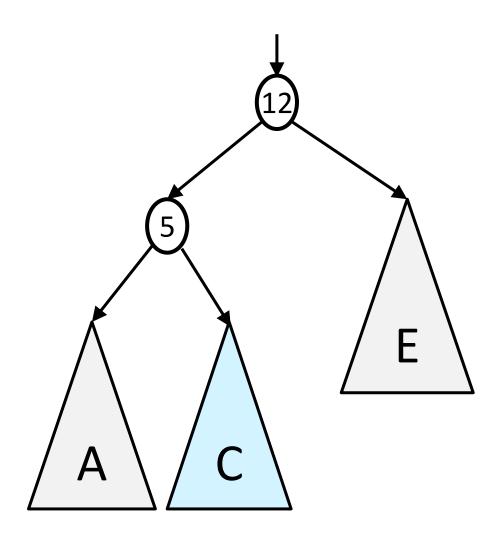


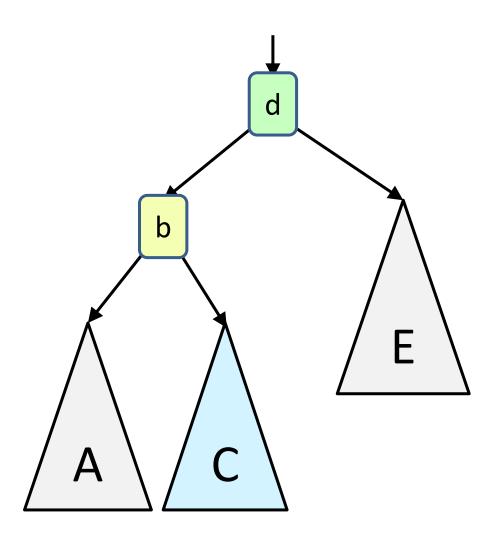
- Single rotation: The basic operation we'll use to rebalance
 - Move child of unbalanced node into parent position
 - Parent becomes the "other" child (always okay in a BST!)
 - Other subtrees move in only way BST allows (we'll see in generalized example)

TREE ROTATIONS: GENERALIZED

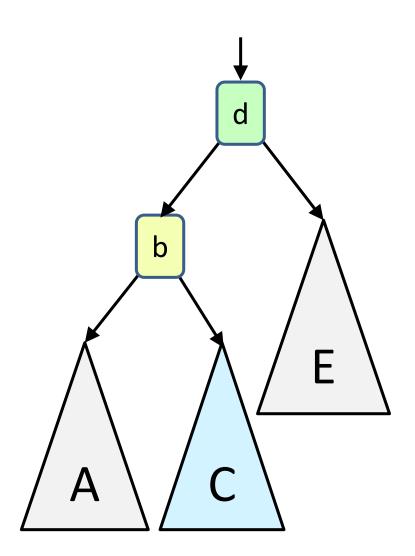




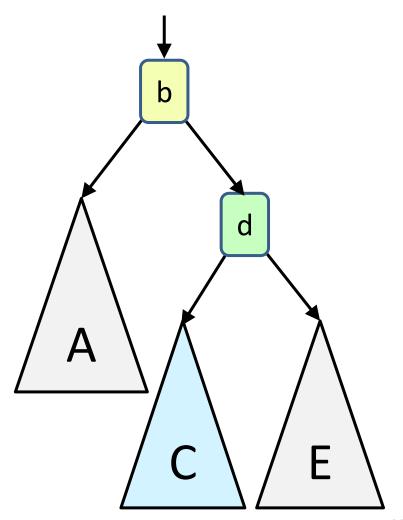




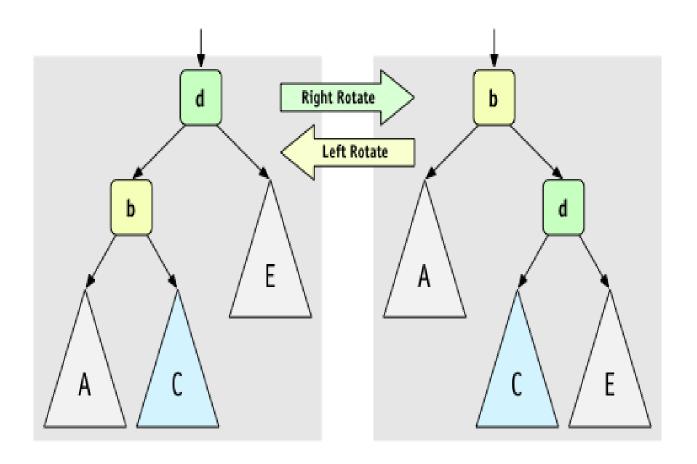
Generalized Single Rotation



Generalized Single Rotation



Single Rotations

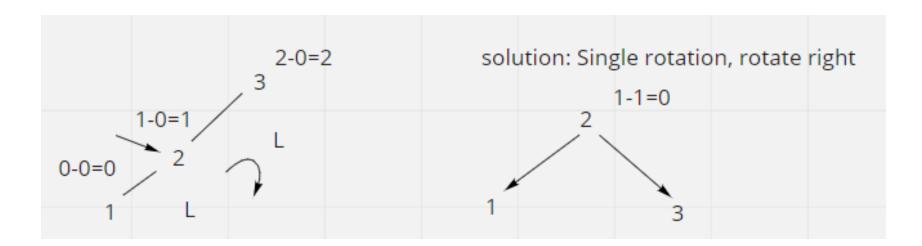


- Insert 1,2,3
- Right-Right or R-R case
- Solution: rotate left

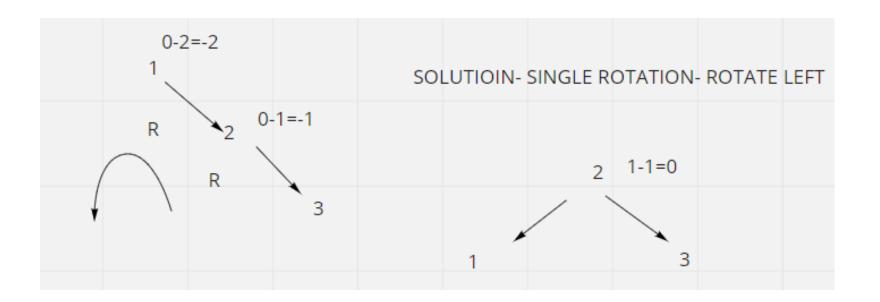
Insertion

- First, insert the new key as a new leaf just as in ordinary binary search tree
- Then trace the path from the new leaf towards the root. For each node x encountered, check if heights of left(x) and right(x) differ by at most 1.
- If yes, proceed to parent(x). If not, restructure by doing either a single rotation or a double rotation
- For insertion, once we perform a rotation at a node x, we won't need to perform any rotation at any ancestor of x.

- Insert 3,2,1
- Left-Left or L-L situation
- Solution: Rotate right

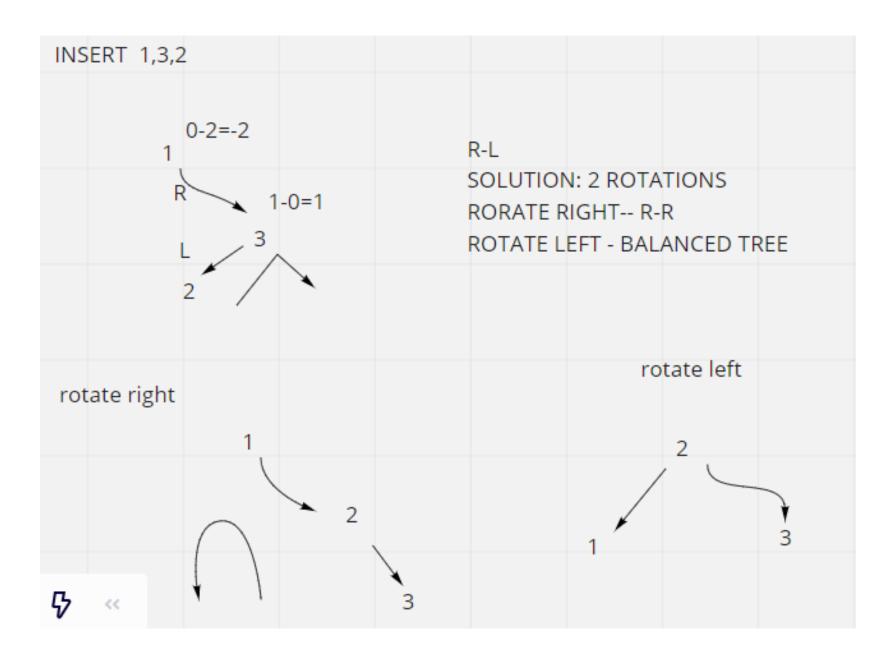


- Insert 1,2,3
- Right-Right or R-Right situation
- Solution: one rotation

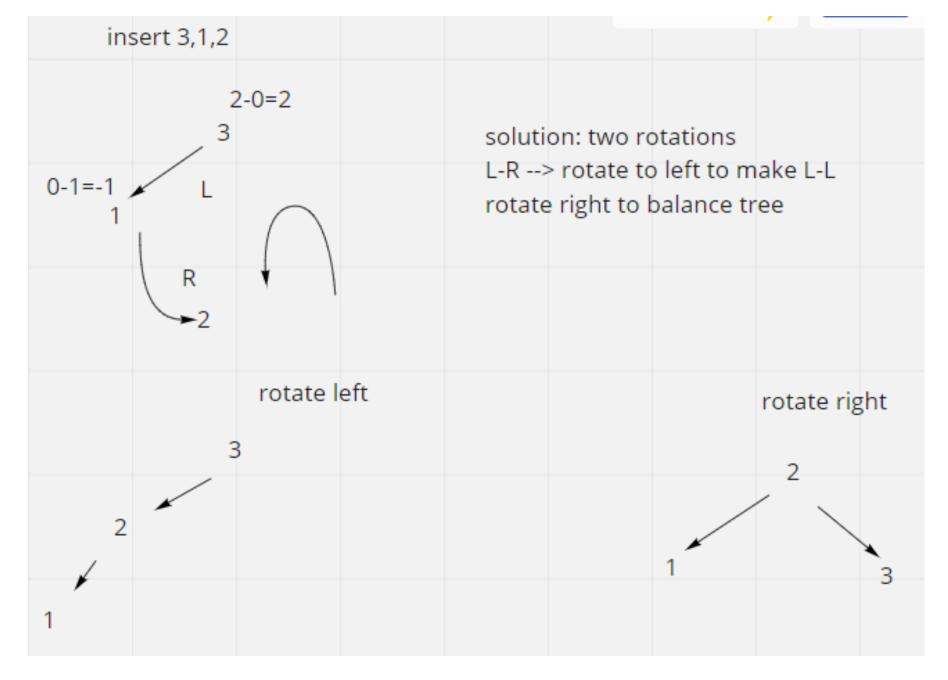


- Insert 1,3,2
- Right-Left or R-L situation
- Solution: Two rotations
 - Rotate right → R-R
 - Rotate left

- Insert 1,3,2
- Right-Left or R-L situation
- Solution: Two rotations
 - Rotate right → R-R
 - Rotate left



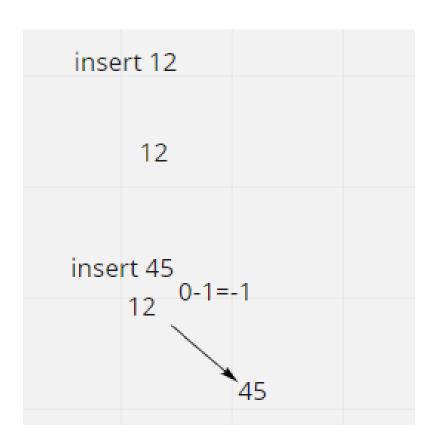
- Insert 3,1, 2
- Left-Right or L-R situation
- Solution: Two rotations
 - Rotate left → L-L
 - Rotate right

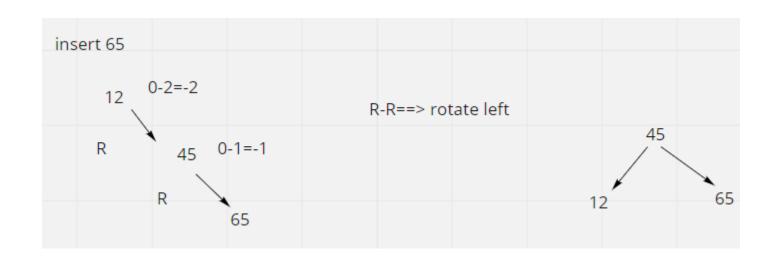


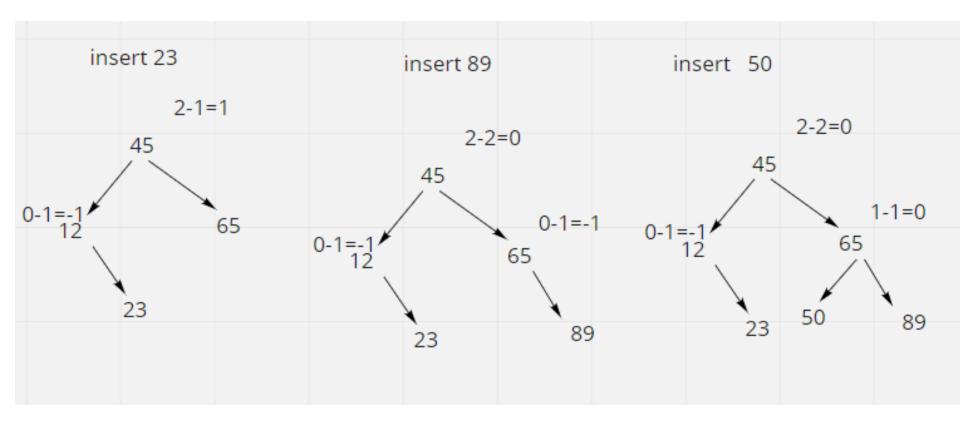
Rotation summary

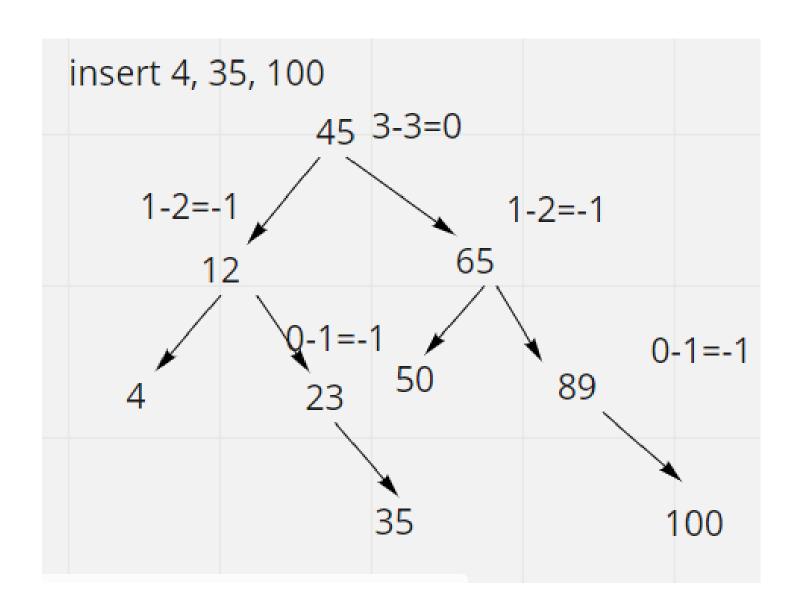
- L-L then single rotation --> rotate right
- R-R then single rotation--> rotate left
- L-R then double rotation --> rotate left to get
 L-L then rotate right
- R-L then double rotation --> rotate right to get
 R-R then rotate left

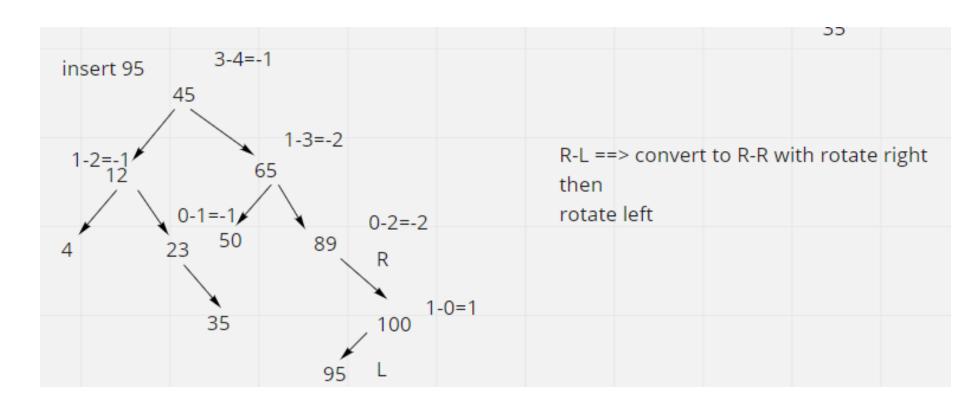
Example- 12, 45, 65, 23, 89, 50, 4, 35,100

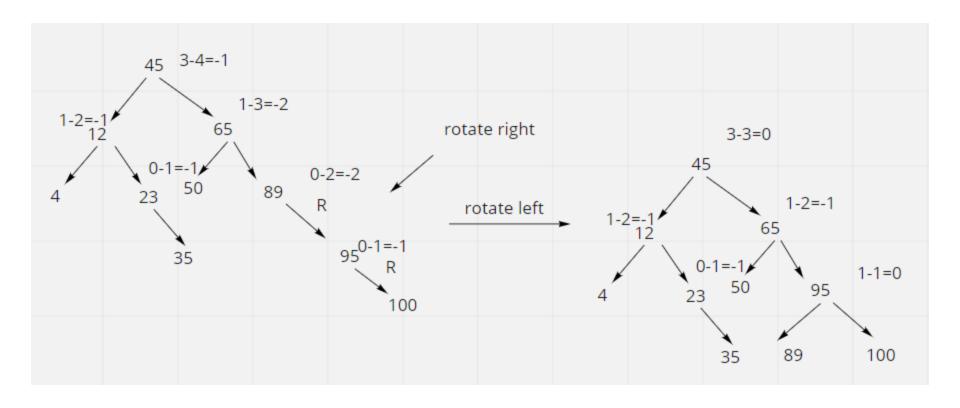




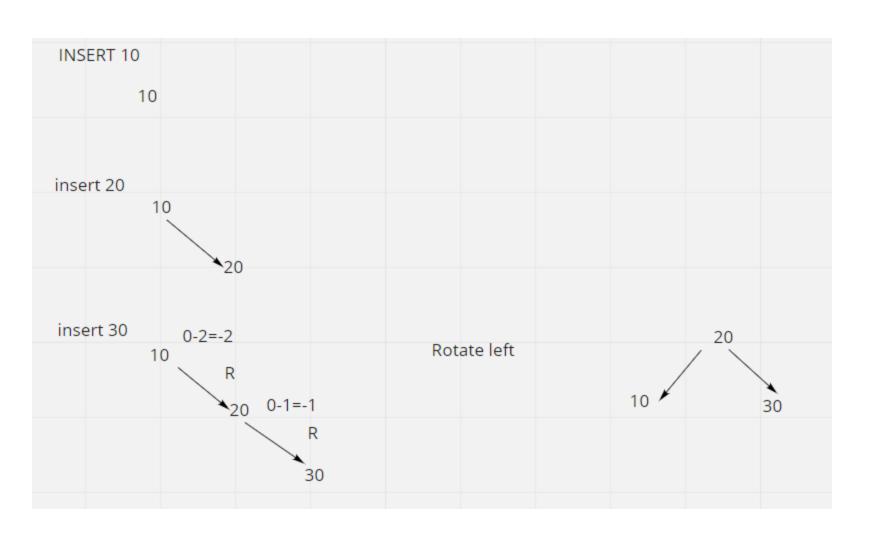


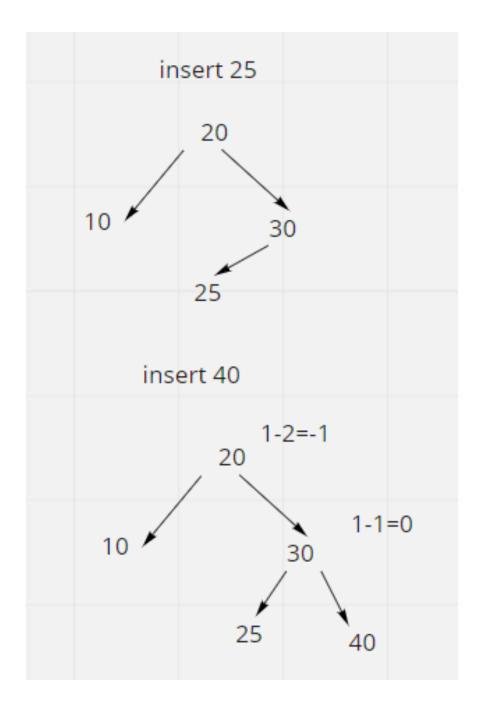




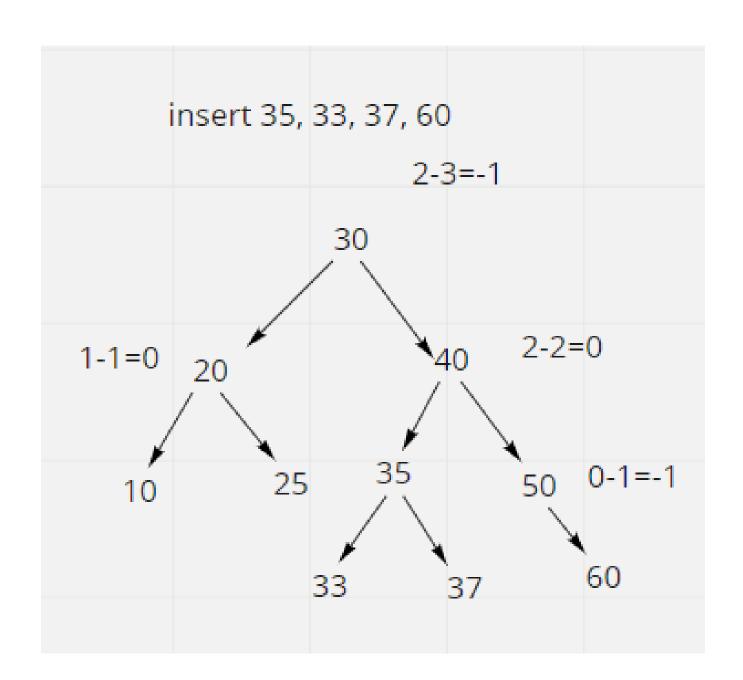


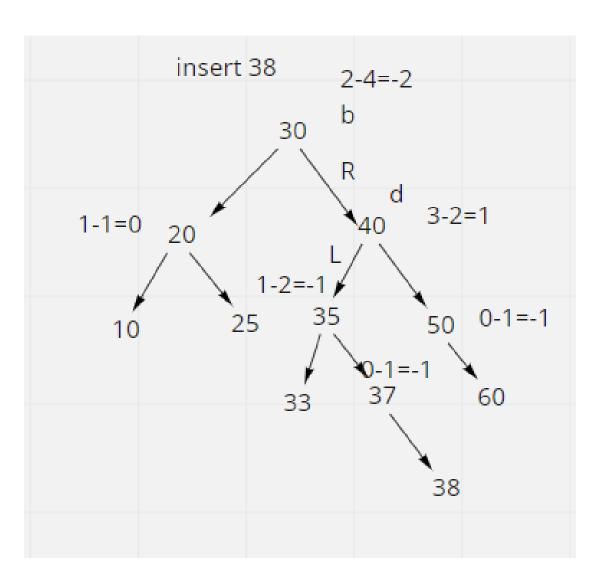
Create AVL tree:10, 20, 30, 25, 40, 50, 35, 33, 37, 60,38



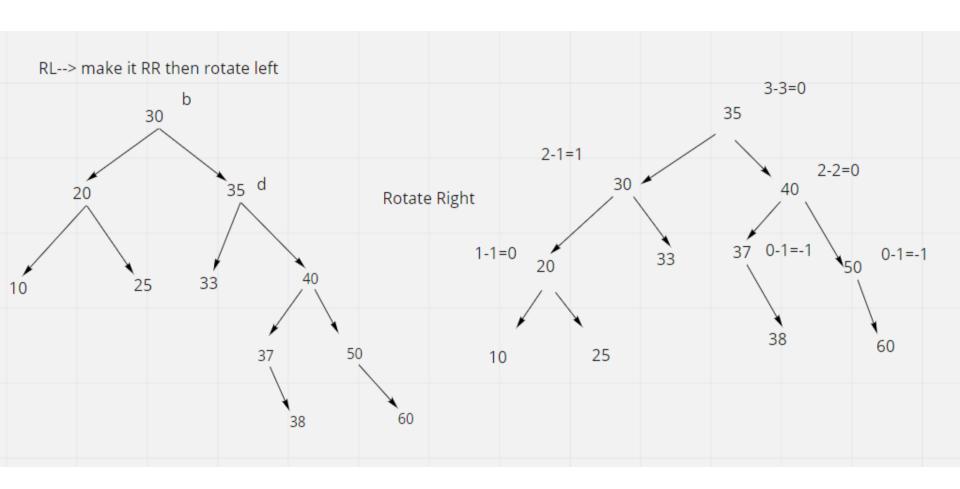




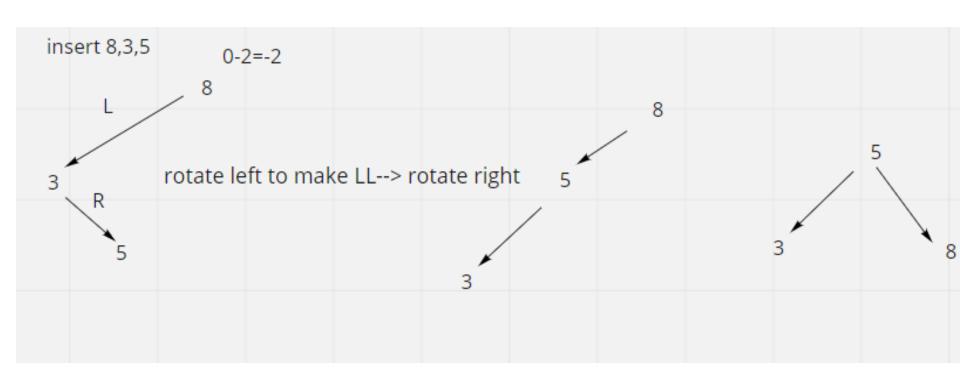


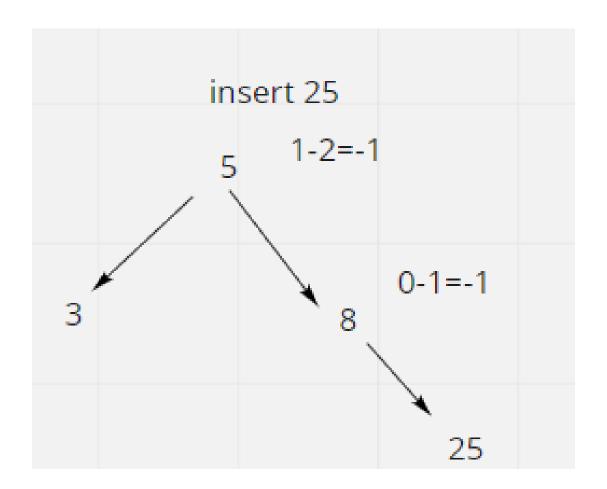


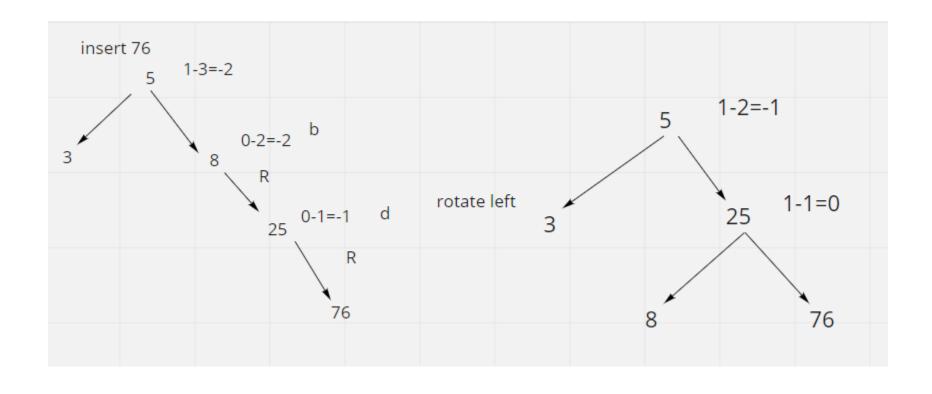
Balance the tree

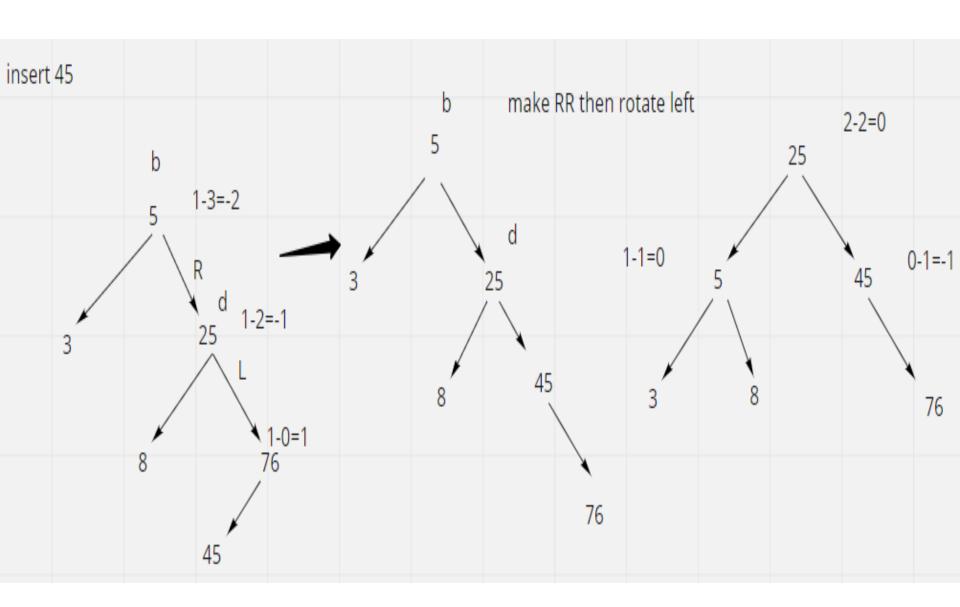


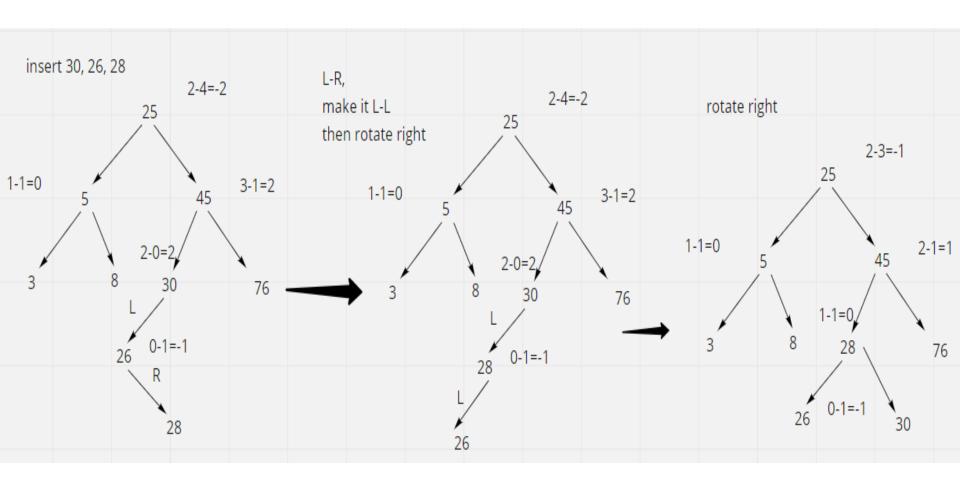
Example 3: 8,3,5,25,76, 45, 30,26,28,27

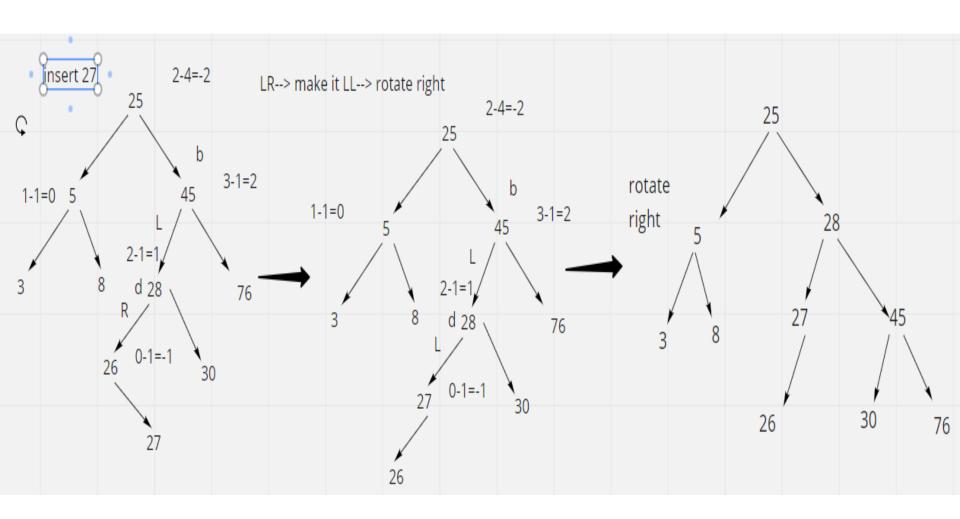




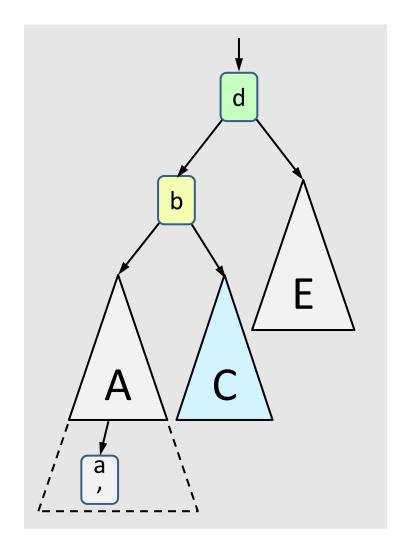








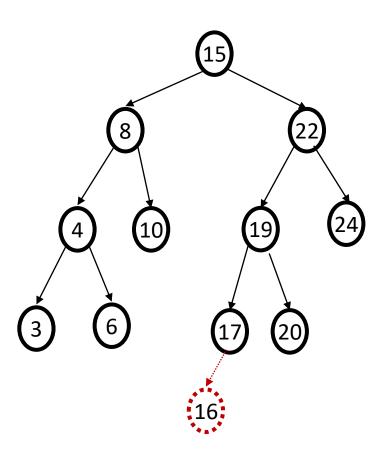
Case #1:



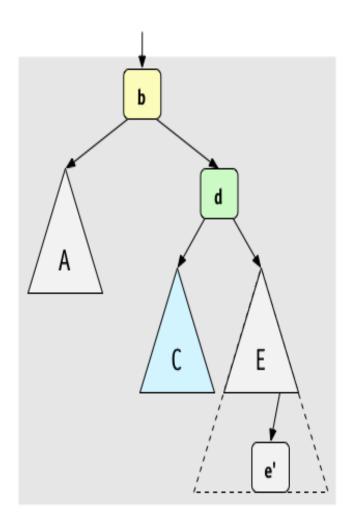
(Figures by Melissa O'Neill, reprinted with her permission to Lilian)

Example #2 for left-left case:

insert(16)

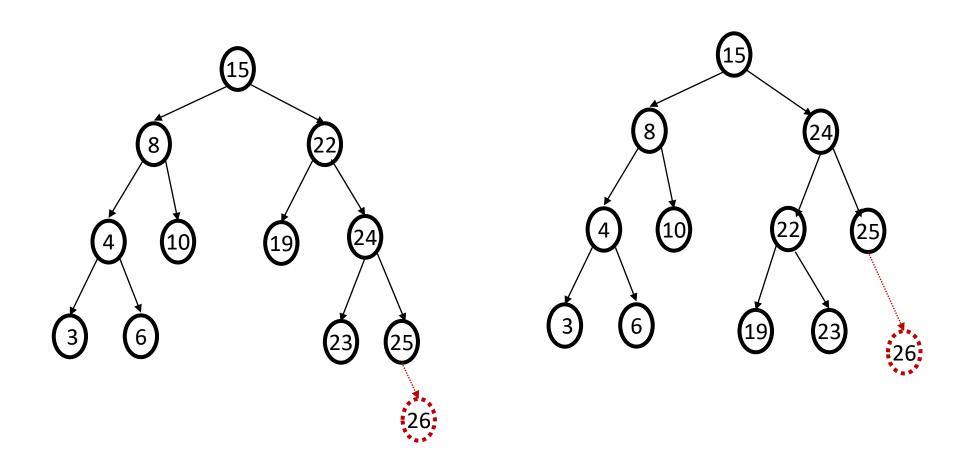


Case #2:

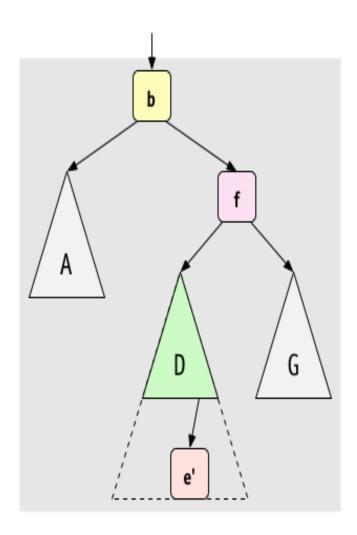


Example for right-right case:

insert (26)

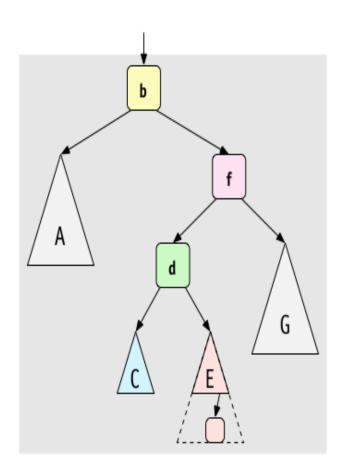


Case #3:

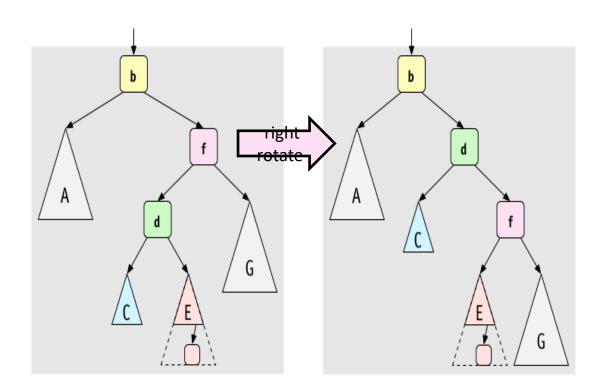


(Figures by Melissa O'Neill, reprinted with her permission to Lilian)

A Better Look at Case #3:



Case #3: Right-Left Case (after one rotation)

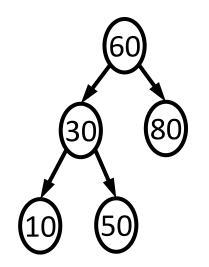


A way to remember it:

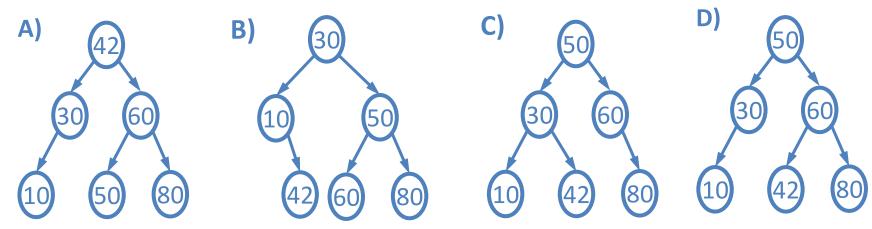
Move d to grandparent's position. Put everything else in their only legal positions for a BST.

Practice time! Example of Case #4

Starting with this AVL tree:



Which of the following is the updated AVL tree after inserting 42?



Pros and Cons of AVL Trees

Arguments for AVL trees:

- 1. All operations logarithmic worst-case because trees are *always* balanced
- 2. Height balancing adds no more than a constant factor to the speed of insert and delete

Arguments against AVL trees:

- Difficult to program & debug [but done once in a library!]
- 2. More space for height field
- 3. Asymptotically faster but rebalancing takes a little time
- 4. If *amortized* logarithmic time is enough, use splay trees (also in the text, not covered in this class)

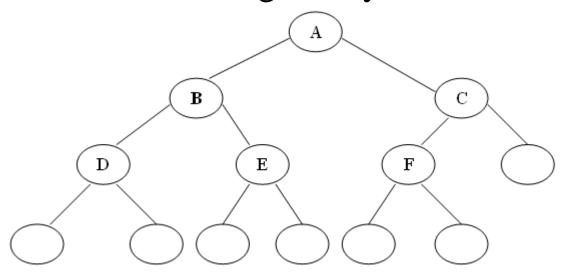






K J Somaiya College of Experimental College of Experim

- In a linked representation of a binary tree, the number of null links (null pointers) are actually more than non-null pointers.
- Consider the following binary tree:







- In above binary tree, there are 7 null pointers & actual 5 pointers.
- In all there are 12 pointers.
- We can generalize it that for any binary tree with n nodes there will be (n+1) null pointers and 2n total pointers.
- The objective here to make effective use of these null pointers.
- A. J. perils & C. Thornton jointly proposed idea to make effective use of these null pointers.
- According to this idea we are going to replace all the null pointers by the appropriate pointer values called threads.





- And binary tree with such pointers are called threaded tree.
- In the memory representation of a threaded binary tree, it is necessary to distinguish between a normal pointer and a thread.





■ Therefore we have an alternate node representation for a threaded binary tree which contains five fields as show bellow:

	lthread	lchild	data	rchild	rthread	_
<u>left</u> →						 right
threaded	tag		•			threaded tag

For any node p, in a threaded binary tree.

lthred(p)=1 indicates lchild (p) is a thread pointer
lthred(p)=0 indicates lchild (p) is a normal
rthred(p)=1 indicates rchild (p) is a thread
rthred(p)=0 indicates rchild (p) is a normal pointer





- Also one may choose a one-way threading or a two-way threading.
- Here, our threading will correspond to the in order traversal of T.





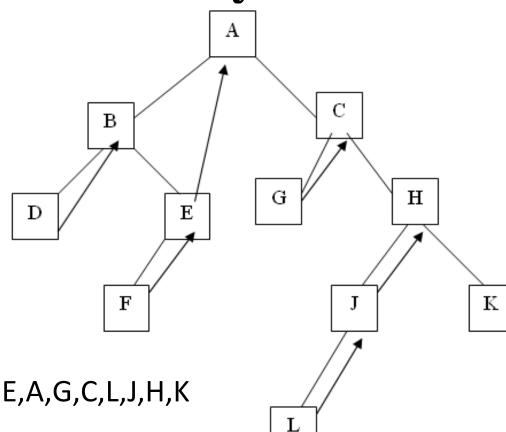
Threaded Binary Tree One-Way

- Accordingly, in the one way threading of T, a thread will appear in the right field of a node and will point to the next node in the **in-order** traversal of T.
- See the bellow example of one-way **in-order** threading.





Threaded Binary Tree: One-Way



Inorder of bellow tree is: D,B,F,E,A,G,C,L,J,H,K





Threaded Binary Tree Two-Way

- In the two-way threading of T.
- A thread will also appear in the left field of a node and will point to the preceding node in the in-order traversal of tree T.
- Furthermore, the left pointer of the first node and the right pointer of the last node (in the **in-order** traversal of T) will contain the null value when T does not have a header node.

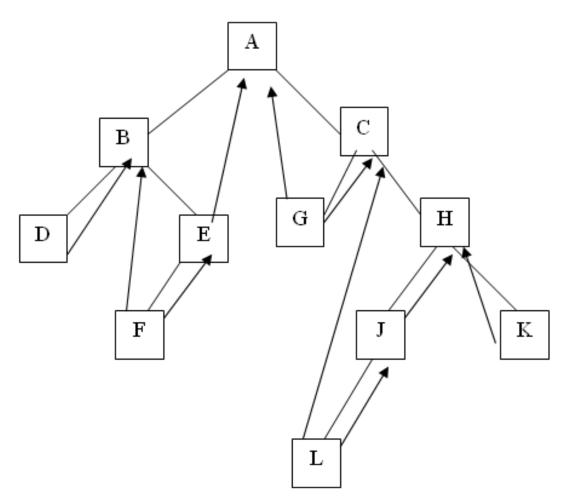




- Bellow figure show two-way in-order threading.
- Here, right pointer=next node of in-order traversal an left pointer=previous node of in-order traversal
- Inorder of bellow tree is: D,B,F,E,A,G,C,L,J,H,K











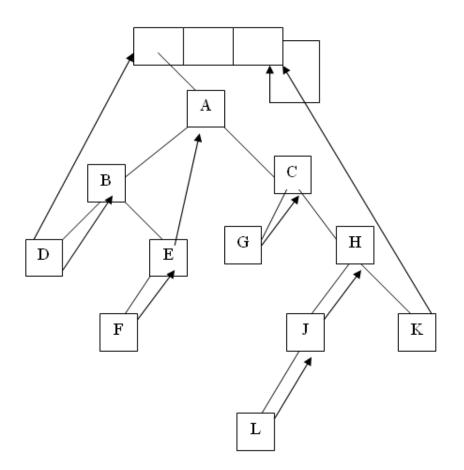
Threaded Binary Tree Two-way Threading with Header node

• Again two-way threading has left pointer of the first node and right pointer of the last node (in the inorder traversal of T) will contain the null value when T will point to the header nodes is called two-way threading with header node threaded binary tree.





• Bellow figure to explain two-way threading with header node.



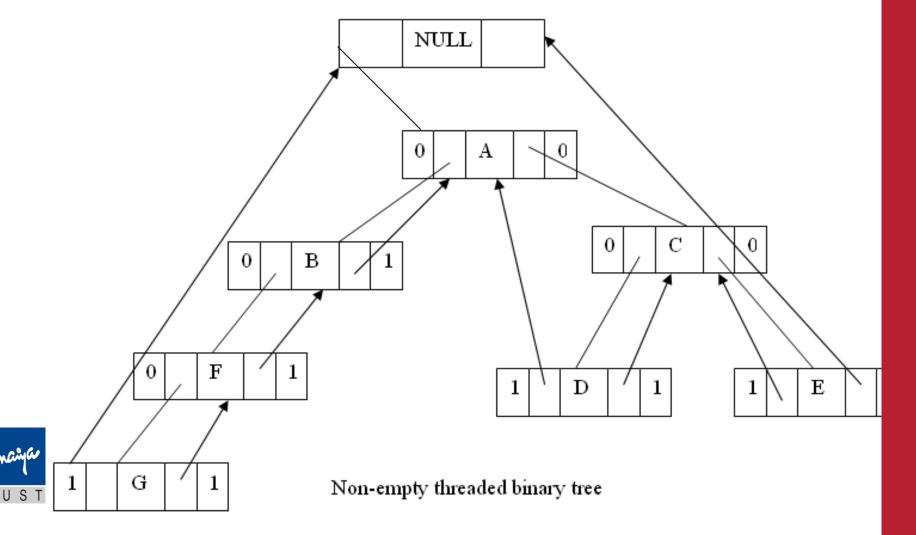




- Bellow example of link representation of threading binary tree.
- **In-order** traversal of bellow tree: G,F,B,A,D,C,E









```
Procedure threadedInorderTraversal(root):
    current = FindLeftmost(root) // Find the leftmost node
   while current is not null:
       Print current.data
       // If there's a thread, follow it to the in-order successor
       if current.rightThread is true:
            current = current.right
        else:
            // Otherwise, move to the leftmost node in the right subtree
            current = FindLeftmost(current.right)
Procedure FindLeftmost(node):
    // Find the leftmost node in the tree rooted at 'node'
   while node is not null and node.left is not null:
        node = node.left
    return node
```





- Advantages of threaded binary tree:
- Threaded binary trees have numerous advantages over non-threaded binary trees listed as below:
 - The traversal operation is more faster than that of its unthreaded version, because with threaded binary tree non-recursive implementation is possible which can run faster and does not require the botheration of stac management.





Advantages of threaded binary tree:

The second advantage is more understated with a threaded binary tree, we can efficiently determine the predecessor and successor nodes starting from any node. In case of unthreaded binary tree, however this task is more time consuming and difficult. For this case a stack is required to provide upward pointing information in the tree whereas in a threaded binary tree, without having to include the overhead of using a stack mechanism the same can be carried out with the threads.





Advantages of threaded binary tree:

- Any node can be accessible from any other node. Threads are usually more to upward whereas links are downward. Thus in a threaded tree, one can move in their direction and nodes are in fact circularly linked. This is not possible in unthreaded counter part because there we can move only in downward direction starting from root.
- Insertion into and deletions from a threaded tree are although time consuming operations but these are very easy to implement.





Disadvantages of threaded binary tree:

- Insertion and deletion from a threaded tree are very time consuming operation compare to non-threaded binary tree.
- This tree require additional bit to identify the threaded link.

