Machine Learning

Lecture 01-1: Basics of Probability Theory

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Outline

- 1 Basic Concepts in Probability Theory
- 2 Interpretation of Probability
- 3 Bayes' Theorem
- 4 Parameter Estimation

Random Experiments

- Probability associated with a random experiment a process with uncertain outcomes
- Often kept implicit











Tail

Head

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- Often kept implicit









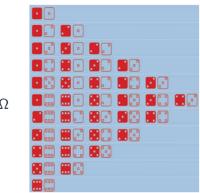
Tail



In machine learning, we often assume that data are generated by a hypothetical process (or a model), and task is to determine the structure and parameters of the model from data.

Sample Space

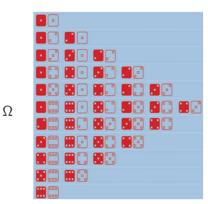
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- Example: Rolling two dice.



Ω

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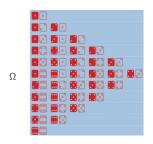
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Elements in a sample space are outcomes.

Events

Event: A subset of the sample space.



Example: The two results add to 4.



Probability Weight Function

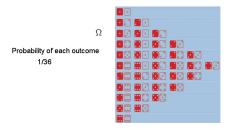
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Probability of each outcome

1/36

Probability Weight Function

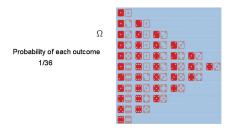
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In a more advanced treatment of Probability Theory, we would start with the concept of probability measure, instead of probability weights.

Random Variables

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 - Example: X = sum of the two results. X((2,5)) = 7; X((3,1)) = 4)



■ Why is it random?

Random Variables

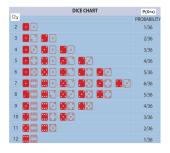
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- **Domain** of a random variable: Set of all its possible values.

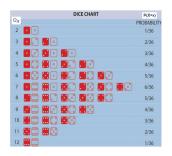
$$\Omega_X = \{2, 3, \dots, 12\}$$



Random Variables and Event

A random variable X taking a specific value x is an event:

$$\Omega_{X=x} = \{\omega \in \Omega | X(\omega) = x\}$$



Probability Mass Function (Distribution)

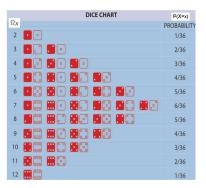
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- $P(X = 4) = P(\{(1,3),(2,2,)(3,1)\}) = \frac{3}{36}.$
- If X is continuous, we have a **density function** p(X).

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■ The frequentist interpretation is meaningful only when experiment can be repeated under the same condition.

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 - Subjectivist: degree of belief based on state of knowledge
 - Primary school student: 0.5
 - Me: 0.8
 - Geographer: 1 or 0
- Arguments such as **Dutch book** are used to explain why one's probability beliefs must satisfy Kolmogorov's axioms.

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 - As more and more data become available, we rely less and less on subjective beliefs.
 - Often, we also use **prior probabilities** to impose some **bias** on the kind of results we want from a machine learning algorithm.
- The subjectivist interpretation makes concepts such as conditional independence easy to understand.

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 - If the doctor finds that the eyes of the patient are yellow, his belief about patient suffering from Hepatitis B would be > 0.1.

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■ Bayes' Theorem:



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That is: posterior \propto prior \times likelihood

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- Task: To estimate parameter $\theta = P(X=H)$.

X: result of tossing a thumbtack







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- $\theta = 0.01$ almost contradicts with the data. It does not explain the data well.

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- So $\theta=0.5$ is more consistent with the data than $\theta=0.01$ because $P(\mathcal{D}|\theta=0.5)>P(\mathcal{D}|\theta=0.01)$ It explains the data the best, and is hence the most likely.

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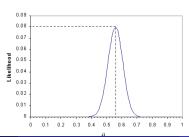
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$$L(\theta^*|\mathcal{D}) = \arg\max_{\theta} L(\theta|\mathcal{D}).$$

MLE best explains data or best fits data.



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Assume the data instances are identically distributed:

$$P(D_i = H) = \theta, P(D_i = T) = 1 - \theta$$
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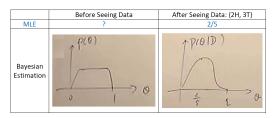
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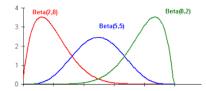
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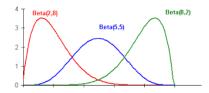
$$p(\theta|\mathcal{D}) \propto \theta^{m_h + \alpha_h - 1} (1 - \theta)^{m_t + \alpha_t - 1} \tag{2}$$



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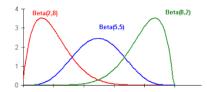
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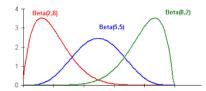
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- Beta distributions are hence called a conjugate family for Binomial likelihood.
- Conjugate families allow closed-form for posterior distribution of parameters and closed-form solution for prediction.

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■ After taking data \mathcal{D} into consideration, now our **updated belief** on X = T is $\frac{m_t + \alpha_t}{m_t + \alpha_t}$.

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■ In case 2,

$$P(D_{m+1} = H|\mathcal{D}) = \frac{30,000 + 100}{100,0000 + 100 + 100} \approx 0.3$$

Data prevail.



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- In this course, we will focus on MLE.