

# Assignment - 6

GoodLuck

Page No.

Date

Title :- Basic Transformation

Problem Statement :-

Write a c++ program to draw 2D objects & perform basic transformations

Objective :-

i) To understand the concept of scaling, translation & rotation.

ii) To know the different matrices which are used to perform 2D transformation such as scaling, rotation & translation.

Outcome :-

The students will be able to

i) To implement the transformation on various object. ii) To draw 2D object & perform transformation iii) To perform scaling, rotation & translation on 2D object.

S/H Requirements :-

at creator, Linux 64 bit OS.

Theory :-

2D objects are 1st 2D transformation means changing by applying rules.

When a transformation takes on 2D plane, it is called 2D transformation.

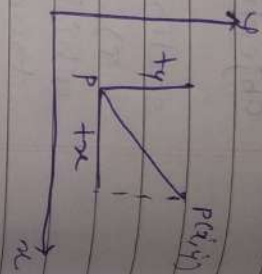
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## Translation :-

- i) A translation moves an object to different position on screen.
- ii) You can translate a point in 2D by adding translation co-ordinates ( $t_x, t_y$ ) to the original co-ordinate  $x, y$  to get the new co-ordinate  $x', y'$ .

$$P' = [x, y, 1]$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ t_x & t_y & 1 \end{bmatrix}$$



$$x' = x + t_x$$

$$y' = y + t_y$$

## Rotation :-

- i) In rotation we rotate the object at particular angle from its origin.
- ii) From following figure we can see that point  $x, y$  is located at angle from horizontal,  $x$  co-ordinate with distance  $x$  from origin.

matrix representation,

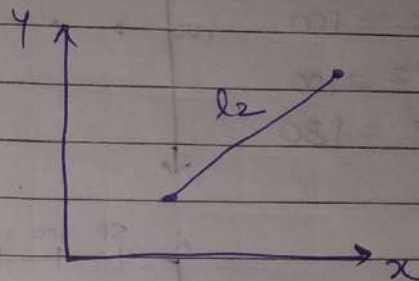
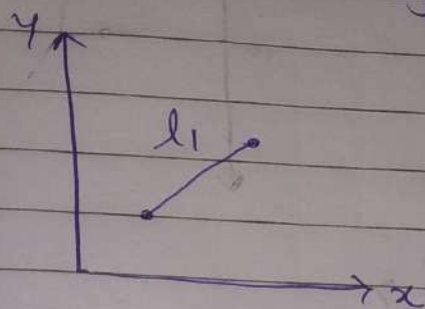
$$R = \begin{bmatrix} \cos \theta & \sin \theta & 0 \\ -\sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

## Scaling :-

- is to change the size of the object scaling is used.
- iii) In scaling process, you either expand or compress the dimension of object.



ii) Scaling can be achieved by multiplying original co-ordinate with scaling factor to get desired result.



Matrix representation

$$S = \begin{bmatrix} S_x & 0 & 0 \\ 0 & S_y & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Application of 2D transformation.

i) Circle ii) Triangle iii) Rectangle

Testcases :-

Input	Expected o/p	Actual o/p	Result
i) $x_1 = 0$ $y_1 = 100$ $x_2 = 100$ $x = 50$ $y = 50$			Success

I/P

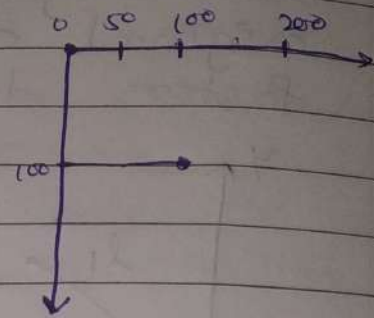
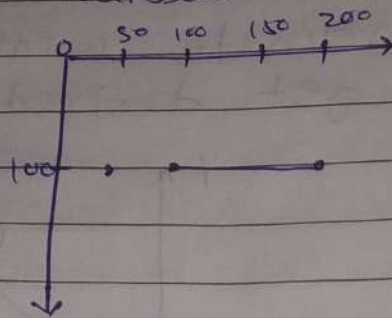
Expected o/p

Actual o/p

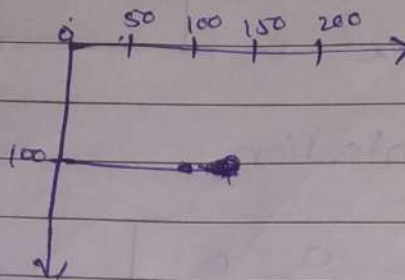
Result

2]  $x_1 = 200$  $y_1 = 100$  $x_2 = 100$  $y_2 = 100$  $c = 180$ 

translation



Success

Conclusion :-

we have successfully implemented  
basic transformations.