CS540 Fall 2024 Homework 3

Due: 30 September 2024, 9:30am

1 Assignment Goals

- Explore Principal Component Analysis (PCA) and the related Python packages (numpy, scipy, and matplotlib)
- Make pretty pictures:)

2 Summary

In this project, you'll be implementing a facial analysis program using PCA, using the skills from **the linear algebra** + **PCA lecture**. You'll also continue to build your Python skills. We'll walk you through the process step-by-step (at a high level).

3 Packages Needed for this Project

You are only allowed to use Python3 standard library as well as NumPy, SciPy, and matplotlib (installation instructions linked). You should use a SciPy version >= 1.5.0 and the following import commands:

```
>>> from scipy.linalg import eigh
>>> import numpy as np
>>> import matplotlib.pyplot as plt
```

4 Dataset

You will be using part of the Label Faces in the Wild (processed). The dataset is saved in the 'face_dataset.npy' file, which you will find in the released hw3 folder. The '.npy' file format is used to store numpy arrays. We will test your code only using this provided dataset.

The dataset contains 13233 sample images, each of size 64×64 . We will use n to refer to the number of images (so n = 13233) and m to refer to the number of features for each sample image (so $m = 4096 = 64 \times 64$). Note, we'll use x_i to refer to the *i*th sample image which is a m-dimensional feature vector.

Note: The setup here is different from the example in the PCA lecture. In the lecture, we have a *single* large image divided into multiple patches, treating each patch as a data point x_i . Here we have multiple (n = 13233) small images, each of which is treated as a data point x_i .

5 Program Specification

Implement these six Python functions in hw3.py to perform PCA on the dataset:

1. load_and_center_dataset(filename): load the dataset from the provided .npy file, center it around the origin, and return it as a numpy array of floats.

- 2. get_covariance(dataset): calculate and return the covariance matrix of the dataset as a numpy matrix $(d \times d \text{ array})$.
- 3. get_eig(S, k): perform eigendecomposition on the covariance matrix S and return a diagonal matrix (numpy array) with the largest k eigenvalues on the diagonal in descending order, and a matrix (numpy array) with the corresponding eigenvectors as columns.
- 4. get_eig_prop(S, prop): similar to get_eig, but instead of returning the first k, return all eigenvalues and corresponding eigenvectors in a similar format that explain more than a prop proproportion of the variance (specifically, please make sure the eigenvalues are returned in descending order).
- 5. project_image(image, U): project each $m \times 1$ image into your k-dimensional subspace (spanned by k vectors of size $m \times 1$) and return the new representation as a $m \times 1$ numpy array.
- 6. display_image(orig, proj): use matplotlib to display a visual representation of the original image and the projected image side-by-side.
- 7. perturb_image(image, U, sigma): use Gaussian distribution with standard deviation σ to perturb the given image. return the reconstructed image as a $m \times 1$ number array.
- 8. combine_image(image1, image2, U, lam): use convex combination to combine two image features into one. return the convex combination image as a $m \times 1$ number array.

5.1 Load and Center the Dataset ([20] points)

You'll want to use the the numpy function load() to load the face_dataset.npy file into Python.

```
>>> x = np.load(filename)
```

This should give you an $n \times m$ dataset, represented as an n-by-d matrix/array \mathbf{x} (recall that n = 13233 is the number of images in the dataset and m = 4096 is the number of dimensions of each image). In other words, each row of \mathbf{x} represents an image feature vector x_i^{T} (as a row vector).

Your next step is to center this dataset around the origin. Recall the purpose of this step from lecture — it is a technical condition that makes it easier to perform PCA, but it does not lose any important information.

To center the dataset is simply to subtract the mean μ_x from each data point x_i (image, in our case), i.e., $x_i^{\text{cent}} = x_i - u_x$, where

$$\mu_x = \frac{1}{n} \sum_{i=1}^n x_i.$$

You can take advantage of the fact that \mathbf{x} (as defined above) is a numpy array and, as such, has this convenient behavior:

After you've implemented this function, it should work like this:

```
>>> x = load_and_center_dataset('face_dataset.npy')
>>> len(x)
13233
>>> len(x[0])
4096
>>> np.average(x)
-2.61654556892539e-15
```

(Its center isn't *exactly* zero, but taking into account precision errors over 421 arrays of 4096 floats, it's what we call "close enough.")

From now on, we will use x_i to refer to x_i^{cent} .

5.2 Find the Covariance Matrix ([15] points)

Recall, from lecture, that one of the interpretations of PCA is that it is the eigendecomposition of the sample covariance matrix. We will rely on this interpretation in this assignment, with all of the information you need below.

The covariance matrix is defined as

$$S = \frac{1}{n-1} \sum_{i=1}^{n} x_i x_i^{\top}.$$

Note that x_i is one of the *n* images in the (centered) dataset and is considered to be a column vector of size $m \times 1$. Therefore, S is a m-by-m matrix; in mathematical notation, we say $S \in \mathbb{R}^{m \times m}$.

To calculate S, you'll need a couple of tools from **numpy** again:

The result of this function for our sample dataset should be a $m \times m$ (that is, 4096×4096) matrix.

5.3 Get the k Largest Eigenvalues and their Eigenvectors ([17] points)

Again, recall from lecture that eigenvalues and eigenvectors are useful objects that characterize matrices. Better yet, PCA can be performed by doing an eigendecomposition and taking the eigenvectors corresponding to the largest eigenvalues.

You may find scipy.linalg.eigh from the scipy library very helpful when writing this function. The optional parameter called subset_by_index might be of particular use.

Return the largest k eigenvalues of S as a k-by-k diagonal matrix Λ , in descending order, and the corresponding normalized eigenvectors as columns in a m-by-k matrix U. That is,

$$\Lambda = egin{bmatrix} \lambda_1 & & & & \ & \lambda_2 & & & \ & & \ddots & & \ & & & \lambda_k \end{bmatrix}$$

and the j-th column of U is u_j , where λ_j is the j-th largest eigenvalue of S and $u_j \in \mathbb{R}^{m \times 1}$ is the corresponding eigenvector (normalized to have Euclidean norm equal to 1).

To return more than one thing from a function in Python, you can do this:

```
def multi_return():
    return "a string", 5
my_string, my_int = multi_return()
```

Make sure to return the diagonal matrix of eigenvalues *first*, then the eigenvectors in corresponding columns. You may have to rearrange the output of **eigh** to get the eigenvalues in decreasing order and *make* sure to keep the eigenvectors in the corresponding columns after that rearrangement.

5.4 Get all Eigenvalues/Eigenvectors that Explain More than a Certain proportion of the Variance ([8] points)

Instead of pre-determining k, the number of top eigenvalues/eigenvectors, one may want to choose k in a way that includes all the "important" eigenvectors. We do this as follows. Recall that λ_i is the *i*th eigenvalue of the covariance matrix S. Then the following quantity,

$$\frac{\lambda_i}{\sum_{j=1}^m \lambda_j},$$

represents the *proportion of variance* in the dataset explained by the *i*th eigenvector. The larger this quantity is, the more important the *i*th eigenvalue/eigenvector are in capturing the information in the original dataset.

For a given number $0 \le p \le 1$, we want to use *all* the eigenvalues/eigenvectors that explain more than a proportion p of the variance. Return the eigenvalues as a diagonal matrix, in descending order, and the corresponding eigenvectors as columns in a matrix. Hint: subset_by_index was useful for the previous function, so perhaps something similar could come in handy here. Hint: what is the trace of a matrix?

Again, make sure to return the diagonal matrix of eigenvalues first, then the eigenvectors in corresponding columns. You may have to rearrange the output of eigh to get the eigenvalues in decreasing order and make sure to keep the eigenvectors in the corresponding columns after that rearrangement.

Below is an example with p = 0.07.

Interlude: Understanding PCA

Optional reading: A rigorous mathematical exploration of PCA.

Before we describe the next task in your assignment, let's explain PCA a little more formally. Recall that we have n data points $x_1, x_2, ..., x_n$, where each x_i is a m-dimensional column vector (Notation: x_i is $m \times 1$ or $x_i \in \mathbb{R}^{m \times 1}$). In this section, we will differentiate

- 1. The PCA Projection of each data point, $\alpha_i \in \mathbb{R}^{k \times 1}$
- 2. The PCA Reconstruction of each data point, $x_i^{pca} \in \mathbb{R}^{m \times 1}$

5.4.1 PCA Projection

Recall that the covariance matrix of our data is

$$S = \frac{1}{n-1} \sum_{i=1}^{n} x_i x_i^{\top} \in \mathbb{R}^{m \times m}$$

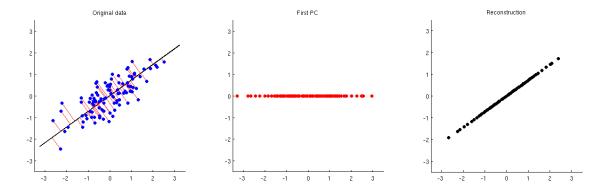


Figure 1: A visualization of PCA [1] with the blue dots representing some data points $x_1, \ldots, x_n \in \mathbb{R}^2$. The black line is the axis along the first principal component u_1 , which minimizes the sum of squared projection errors. The second plot shows the value of the PCA projection as red dots, i.e., $\alpha_1, \ldots, \alpha_n \in \mathbb{R}^1$, where we have reduced the dimensionality of our data from 2 to 1. Finally the last plot shows the reconstructed data points $x_n^{pca}, \ldots, x_n^{pca} \in \mathbb{R}^2$ in black dots, with visible reconstruction error when compared to the original data in the first plot.

Recall that our goal is to **minimize projection error** (sums of squared distances) while reducing the data dimensionality m. To do so, we project each data point $x_i \in \mathbb{R}^{m \times 1}$ on to the linear subspace spanned by the top-m eigenvectors of S. Explicitly, the PCA Projection (also called "score") of x_i is given by

$$\alpha_i = U^{\top} x_i$$

where $U \in \mathbb{R}^{m \times k}$ is the matrix whose columns are the top eigenvectors u_1, \dots, u_k , as defined earlier. As a sanity test, you can verify that α_i is a $k \times 1$ column vector, whose j-th element is $\alpha_{ij} = u_j^\top x_i$.

To summarize PCA Projection, the original data point $x_i \in \mathbb{R}^{m \times 1}$ has been projected to $\alpha_i \in \mathbb{R}^{k \times 1}$, and this projection is determined by the top-k eigenvectors of S contained in U.

5.4.2 PCA Reconstruction

How can we (approximately) reconstruct our data in our original m-dimensional feature space, i.e., compute $x_i^{pca} \in \mathbb{R}^{d \times 1}$ from our PCA projection α_i ? We can use the eigenvectors U again and compute

$$x_i^{pca} = U\alpha_i = UU^{\top}x_i = \sum_{j=1}^k u_j u_j^{\top}x_i = \sum_{j=1}^k \alpha_{ij}u_j.$$

It is an exercise in linear algebra to prove that the three right-hand-side terms above are equal. (You do not need to prove this in this assignment, but feel free to use any of these equivalent expressions in your implementation.)

Figure 1 illustrates the PCA projection and reconstruction when we reduce the dimension from m=2 to k=1.

Hint: if we had not reduced the number of eigenvectors during PCA projection, i.e. maintained k = m, then from linear algebra we know that we would have $UU^{\top} = I$ (the identity matrix) and hence $x_i^{pca} = UU^{\top}x_i = Ix_i = x_i$, in which case we would perfectly reconstruct our original data. You may use this fact while debugging your code.

5.5 Project the Images ([15] points)

Given an image in the dataset and the eigenvectors from get_eig (or get_eig_prop), compute the PCA representation of the image.

Recall that u_j is the jth column of U. Every u_j is an eigenvector of S with size $m \times 1$. If U has k eigenvectors, the image x_i is projected into an k dimensional subspace. The PCA projection represents

images as a weighted sum of the eigenvectors. This projection only needs to store the weight for each eigenvector (k-dimensions) instead of the entire image (m-dimensions). The projection $\alpha_i \in \mathbb{R}^k$ is computed such that $\alpha_{ij} = u_i^T x_i$.

From each α_i we can compute the reconstruction $x_i^{\text{pea}} = \sum_{j=1}^m \alpha_{ij} u_j$. Notice that each eigenvector u_j is multiplied by its corresponding weight α_{ij} . The reconstructed image, x_i^{pea} , will not necessarily equal the original image because of the information lost projecting x_i to a smaller subspace. This information loss will increase as less eigenvectors are used. Implement project_image to compute x_i^{pea} for an input image.

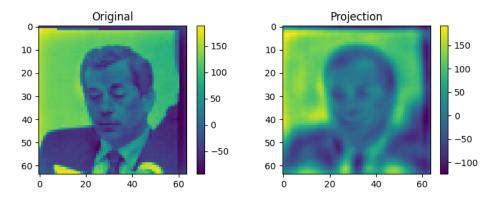
5.6 Visualize ([10] points)

Follow these steps to visualize your images using matplotlib:

- 1. Reshape the images to be 64×64 (before this, they were being thought of as 1 dimensional vectors in \mathbb{R}^{4096}).
- 2. Create a figure with one row of two subplots with fig, ax1 and ax2 objects. ax1 should represent the original image, and ax2 should represent the reconstructed image. Use figsize=(9,3) while initializing the figure (see starter code).
- 3. Title the first subplot (the one on the left) as "Original" (without the quotes) and the second (the one on the right) as "Projection" (also without the quotes).
- 4. Use imshow with the optional argument aspect='equal' to display the images on the correct axes.
- 5. Create a **colorbar** for each image placed to its right (see sample plot below for a visualization. Your plot should match this).
- 6. Return the fig, ax1 and ax2 objects used in step 2 from display_image().
- 7. Testing: Render your plots. Note that if the resulting figure needs rotation, you can transpose the matrix to render it properly. DO NOT include this in your submission, this is only to test your implementation. We suggest calling display_image() from main(), and rendering images there, as shown in the example snippet below.

Below is a simple snippet of code for you to test your functions. Do **not** include it in your submission!

```
>>> x = load_and_center_dataset('face_dataset.npy')
>>> S = get_covariance(x)
>>> Lambda, U = get_eig(S, 100)
>>> projection = project_image(x[50], U)
>>> fig, ax1, ax2 = display_image(x[50], projection)
>>> plt.show()
```



5.7 Reconstruction with Perturbed and Combined Weights ([15] points)

In this section, you will explore how altering the projection weights affects image reconstruction. Specifically, you will (i) randomly perturb the projection weights and then reconstruct the images, and (ii) create convex combinations of the projection weights of different images to create a "hybrid" grass.

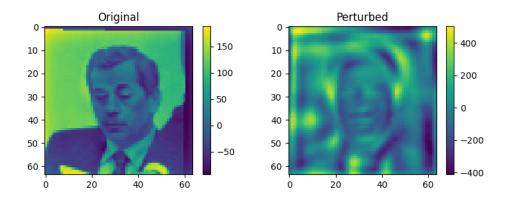
5.7.1 Perturbed Weights Reconstruction

Modify the weights α obtained from the PCA projection of an image by adding small random perturbations. The perturbation should be drawn from a Gaussian distribution with mean 0 and a standard deviation σ . Use these perturbed weights to reconstruct the image using the eigenvectors from PCA. Compare the reconstructed image with the original projection-based reconstruction and the original image. (You don't need to include these image in your submission)

Hint1: You may find np.random.normal is useful for calculating Gaussian distribution Hint2: Perturbed weights are the addition of original weights and perturbation

Below is a simple snippet of code for you to test your functions. Do **not** include it in your submission!

```
>>> x = load_and_center_dataset('face_dataset.npy')
>>> S = get_covariance(x)
>>> Lambda, U = get_eig(S, 100)
>>> perturbed_image = perturb_projection(x[50], U, 1000)
>>> fig, ax1, ax2 = display_image_perturbed(x[50], perturbed_image) # this function is similar to disp
>>> plt.show()
```

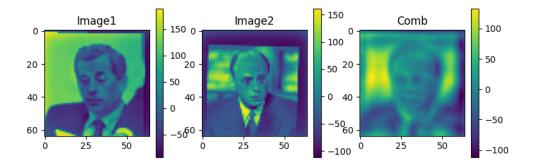


5.7.2 Convex Combination of Weights

Select two different images, say image1 and image2, and compute their PCA projection weights α_1 and α_2 , respectively. Create a new set of weights α_{comb} by taking a convex combination of the two weight vectors, i.e., $\alpha_{\text{comb}} = \lambda \cdot \alpha_1 + (1 - \lambda) \cdot \alpha_2$, where $0 \le \lambda \le 1$. Reconstruct the image from α_{comb} using the same eigenvectors, and display the result. (you don't need to include the image in your submission) Hint: You can utilize the function from section 5.6 to display the image

Below is a simple snippet of code for you to test your functions. Do **not** include it in your submission!

```
>>> x = load_and_center_dataset('face_dataset.npy')
>>> S = get_covariance(x)
>>> Lambda, U = get_eig(S, 100)
>>> combined_image = combine_projections(x[50], x[80], U, 0.5)
>>> fig, ax1, ax2, ax3 = display_image_combo(x[50], x[80], combined_image) # this function is similar
>>> plt.show()
```



6 Submission Notes

Please submit one file named hw3.py to Gradescope. Do not submit a Jupyter notebook .ipynb file.

- Your functions should run silently (except for the image rendering window in the last function).
- No code should be put outside the function definitions (except for import statements; helper functions are allowed).

ALL THE BEST!

References

[1] amoeba. Making sense of principal component analysis, eigenvectors & eigenvalues. Cross Validated. url: https://stats.stackexchange.com/q/140579 (version: 2022-08-31).