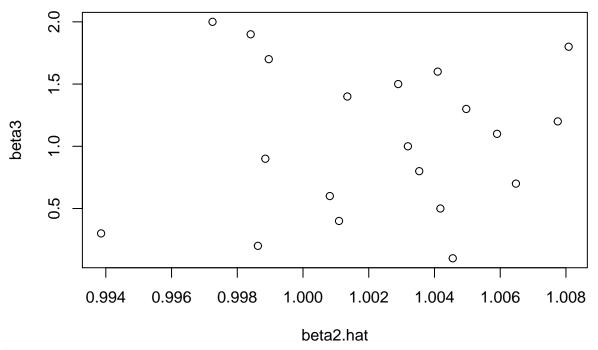
STAT3701HW3

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```
Problem 1
  i.
sim.beta.hat=function(x.mat,beta,sigma,reps){
n=nrow(x.mat)
p=ncol(x.mat)
beta.hat=matrix(NA,reps,p)
for(r in 1:reps){
##generate the error
epsilon.vetc=sigma*(rexp(n,1)-1)
##compute the Y
y.vec=x.mat %*% beta+epsilon.vetc
## compute beta hat
beta.hat[r,]=qr.coef(qr=qr(x.mat),y=y.vec)
}
  return(beta.hat)
}
  ii.
## estimate of beta2
x.mat.1=read.csv("X.mat.1.csv")
x.mat1=as.matrix(x.mat.1)
beta.1=c(-1,1,0,1)
sigma=1.5
reps=5e3
beta.hat=apply(sim.beta.hat(x.mat1,beta.1,sigma,reps),2,mean)
##beta 2
beta.hat[2] ## the result is so closed to the true value of beta2
## [1] 1.001365
 iii.
beta3=seq(0.1,2,by=0.1)
beta2.hat=numeric(length = length(beta3))
for(i in 1:length(beta3)){
  beta.2=c(-1,1,beta3[i],0)
  beta.hat=apply(sim.beta.hat(x.mat1,beta.2,sigma,reps),2,mean)
  beta2.hat[i]=beta.hat[2]
}
plot(beta2.hat,beta3)
```



By this plot, we could see thaht the most of points are around the true value of beta2.

```
Problem 2
```

The linear regressio model is $Son\hat{H}eight = 5.11 + 0.77 * Father.Height + 0.16 * Grandfather.height$.

When father's height and grandfather's height are 0, the expected son's height is on average 5.11 inches.

When father's height increases one inch and grandfather's height is fixed, on average, the son's heights is expected to increase 0.77 inches.

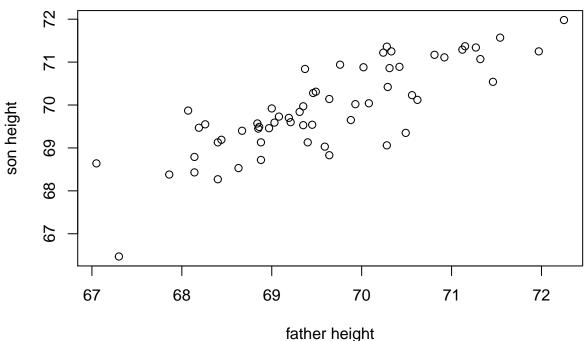
When grandfather's height increases one inch and father's height is fixed , n average , the son's height is expected to increase 0.16 inches.

ii.

```
beta.hat=qr.coef(qr=qr(x=x.mat),y=y)
beta2.hat=beta.hat[2]
n=nrow(x.mat)
p=ncol(x.mat)
alpha=0.05
tper=qt(1-alpha/2,n-p)
xtxin=qr.solve(crossprod(x.mat))
s=sqrt(sum((y-x.mat %*% beta.hat)^2)/(n-p))
```

```
moe=tper*s*sqrt(xtxin[2,2])
left=beta2.hat-moe
right=beta2.hat+moe
ci=c(left,right)
ci
## Father.Height Father.Height
       0.4901989
                       1.0420832
Yes. Because the \hat{\beta}_{FH} is in this interval.
 iii.
The random test statistic is T = \frac{\beta_{GH}^2}{S\sqrt{[X'X]_{33}^{-1}}}
sqrt.form=sqrt(xtxin[3,3])
t.test=beta.hat[3]/(s*sqrt.form)
pval=2*pt(-abs(t.test),n-p)
pval
## Grandfather.height
             0.2301573
Because the p value is greater than 0.05, we fail to reject the null hypothesis.
 iv.
xnew=c(1,67,66)
point.est=xnew %*% beta.hat
## 96% CI
xtxin=qr.solve(crossprod(x.mat))
sqform=sqrt(t(xnew) %*% xtxin %*% xnew)
alpha=0.04
t.per=pt(1-alpha/2,n-p)
m=t.per*s*sqform
ci=c(point.est-m ,point.est+m)
## [1] 66.94346 67.48390
## 96% PI
sqform.pi=sqrt(t(xnew) %*% xtxin %*% xnew +1)
m.pi=t.per*s*sqform.pi
pI=c(point.est-m.pi ,point.est+m.pi)
pΙ
## [1] 66.60356 67.82379
  v.
fh=seq(66,72,by=0.5)
len=length(fh)
## 96% CI
low=numeric(len)
upp=numeric(len)
for(r in 1:len){
  xnew=c(1,fh[r],66)
  beta.hat=qr.solve(crossprod(x.mat)) %*% crossprod(x.mat, y)
  point.est[r]=xnew %*% beta.hat
```

```
xtxin=qr.solve(crossprod(x.mat))
  sqform=sqrt(t(xnew) %*% xtxin %*% xnew)
   alpha=0.04
   t.per=pt(1-alpha/2,n-p)
   m=t.per*s*sqform
   low[r]=point.est[r]-m
   upp[r]=point.est[r]+m
}
## 96% PI
lower.pi=numeric(len)
upper.pi=numeric(len)
point.est.pi=numeric(len)
for(r in 1:len){
  xnew=c(1,fh[r],66)
  beta.hat=qr.solve(crossprod(x.mat)) %*% crossprod(x.mat, y)
  point.est.pi[r]=xnew %*% beta.hat
  xtxin=qr.solve(crossprod(x.mat))
  sqform.pi=sqrt(t(xnew) %*% xtxin %*% xnew+1)
   alpha=0.04
   t.per=pt(1-alpha/2,n-p)
   m.pi=t.per*s*sqform.pi
   lower.pi[r]=point.est.pi[r]-m.pi
   upper.pi[r]=point.est.pi[r]+m.pi
}
plot(x.df.2[,1],x.df.2[,3],xlab = "father height",ylab="son height")
```



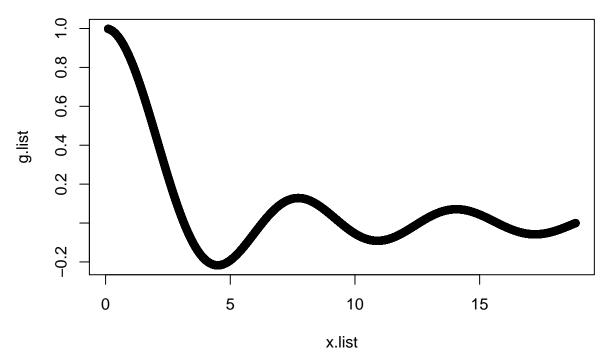
```
##lines(point.est,x.df.2[,3],col="yellow")
##lines(point.est.pi,x.df.2[,3],col="green")
## ci bound lines
##lines(low,x.df.2[,3],col="red")
```

```
##lines(upp,x.df.2[,3],col="red)
##pi bound lines
##lines(lower.pi,x.df.2[,3],col="blue")
##lines(upper.pi,x.df.2[,3],col="blue")
Problem 3
x.mat3=read.csv("X.mat.3.csv")
x.mat.3=as.matrix(x.mat3)
n=nrow(x.mat.3)
p=ncol(x.mat.3)
beta=c(1,2,3,4,5)
x.new=c(1,25,20,15,10)
reps=1e3
sigma=1.5
## coverage probability of a 90% prediction interval
captured.list.pi=numeric(reps)
for(r in 1:reps){
  ## generate the realizations of the n errors
  epsilon.vec=sigma*(rexp(n,1)-1)
  ## compute the y
  y.vec=x.mat.3 %*%beta+epsilon.vec
  ## compute the realization of betahat
  beta.hat=qr.coef(qr=qr(x.mat.3), y=y.vec)
  s=sqrt(sum((y.vec-x.mat.3 %*% beta.hat)^2)/(n-p))
  alpha.pi=0.1
  tper.pi=pt(1-alpha.pi/2,n-p)
  xtxin=qr.solve(crossprod(x.mat.3))
  sqform.pi=sqrt(1+t(x.new) ** xtxin ** x.new)
  moe=tper.pi*s*sqform.pi
  est.mean=sum(beta.hat * x.new)
  left.pi=est.mean-moe
  right.pi=est.mean+moe
  ## generate the realization of Y_new
  ynew=sum(beta*x.new)+ sigma*(rexp(1,1)-1)
  ## check if ynew was captured
  captured.list.pi[r]=1*(left.pi<=ynew)&(ynew<=right.pi)</pre>
mean(captured.list.pi)
## [1] 0.552
prop.test(x=sum(captured.list.pi),n=reps,conf.level = 0.99,correct = FALSE)$conf.int[1:2]
## [1] 0.5112829 0.5920316
## coverage probability of a 90% prediction interval
captured.list.pi=numeric(reps)
for(r in 1:reps){
  ## generate the realizations of the n errors
  epsilon.vec=sigma*sqrt(12)*(runif(n)-0.5)
```

```
## compute the y
  y.vec=x.mat.3 %*%beta+epsilon.vec
  ## compute the realization of betahat
  beta.hat=qr.coef(qr=qr(x.mat.3), y=y.vec)
  s=sqrt(sum((y.vec-x.mat.3 %*% beta.hat)^2 )/(n-p))
  alpha.pi=0.1
  tper.pi=pt(1-alpha.pi/2,n-p)
  xtxin=qr.solve(crossprod(x.mat.3))
  sqform.pi=sqrt(1+t(x.new) %*% xtxin %*% x.new)
  moe=tper.pi*s*sqform.pi
  est.mean=sum(beta.hat * x.new)
  left.pi=est.mean-moe
  right.pi=est.mean+moe
  ## generate the realization of Y_new
  ynew=sum(beta*x.new)+ sigma*sqrt(12)*(runif(1)-0.5)
  ## check if ynew was captured
  captured.list.pi[r]=1*(left.pi<=ynew)&(ynew<=right.pi)</pre>
mean(captured.list.pi)
## [1] 0.578
prop.test(x=sum(captured.list.pi),n=reps,conf.level = 0.99,correct = FALSE)$conf.int[1:2]
## [1] 0.5373866 0.6175852
 iii.
## coverage probability of a 90% prediction interval
captured.list.pi=numeric(reps)
x=apply(x.mat.3,1,sum)
sd=numeric(n)
for( i in 1:n){
 x 1=x[i]
 dom=(sqrt(p* x_1))
  sd[i]=sigma/dom
  for(r in 1:reps){
     ## generate the realizations of the n errors
   epsilon.vec=numeric(n)
   for( i in 1:n){
      epsilon.vec[i]=rnorm(1,0,sd[i])
   }
  ## compute the y
  y.vec=x.mat.3 %*%beta+epsilon.vec
  ## compute the realization of betahat
  beta.hat=qr.coef(qr=qr(x.mat.3), y=y.vec)
  s=sqrt(sum((y.vec-x.mat.3 %*% beta.hat)^2 )/(n-p))
  alpha.pi=0.1
  tper.pi=pt(1-alpha.pi/2,n-p)
  xtxin=qr.solve(crossprod(x.mat.3))
  sqform.pi=sqrt(1+t(x.new) %*% xtxin %*% x.new)
  moe=tper.pi*s*sqform.pi
  est.mean=sum(beta.hat * x.new)
```

```
left.pi=est.mean-moe
   right.pi=est.mean+moe
   ## generate the realization of Y_new
   ynew=sum(beta*x.new)+rnorm(1,mean=0,sd=sigma/sqrt(p*sum(x.new)))
   ## check if ynew was captured
   captured.list.pi[r]=1*(left.pi<=ynew)&(ynew<=right.pi)</pre>
mean(captured.list.pi)
## [1] 0.61
prop.test(x=sum(captured.list.pi),n=reps,conf.level = 0.99,correct = FALSE)$conf.int[1:2]
## [1] 0.5696699 0.6488801
Problem 4
h(a) = (E[a\bar{X} - \mu])^2 + Var(a\bar{X})
Because (E[a\bar{X} - \mu])^2 = (E[a\bar{X}] - E[\mu])^2 = (aE[\bar{X}] - \mu)^2 = (a\mu - \mu)^2 = \mu^2(a-1)^2
Var(a\bar{X}) = a^2 Var(\bar{X}) = a^2 \frac{\sigma^2}{m}
h(a) = \mu^2 (a-1)^2 + \frac{\sigma^2}{n} a^2
\nabla h(a) = 2\mu^2(a-1) + \frac{2\sigma^2}{n}a = 2(\mu^2 + \frac{\sigma^2}{n})a - 2\mu^2
\nabla^2 h(a) = 2(\mu^2 + \frac{\sigma^2}{2})
   ii.
If the \nabla h(\bar{a}) = 2(\mu^2 + \frac{\sigma^2}{n})\bar{a} - 2\mu^2 = 0, then \bar{a} = \frac{\mu^2}{\mu^2 + \frac{\sigma^2}{n}}
Because \nabla^2 h(a) = 2(\mu^2 + \frac{\sigma^2}{n}) is always greater than 0 for every a.
\bar{a} = \hat{a} is the global minimizer of f .
  iii.
Because the \nabla^2 h(a) is not relevant to a.
Problem 5
g=function(x){
   return(sin(x)/x)
}
\nabla g(x) = \frac{x cos x - sin x}{x^2}, x \in (0, 6\pi]
deriv.g=function(x){
   return((x*cos(x)-sin(x))/(x^2))
bsearch=function(df, a, b, L=1e-7, quiet=FALSE, ...){
   while((b-a)>L){
     k=k+1
```

```
## compute the midpoint
    m=(a+b)/2
    ## compute the derivative at the midpoint
    df.at.m=df(m, ...)
    if(df.at.m<0){</pre>
      ## f is decreasing at
      ## the midpoint so the
      ## new interval is (m, b)
      a=m
    }
    else if(df.at.m>0){
      ## f is increasing at the
      ## midpoint so the
      ## new interval is (a, m)
      b=m
      }
    else{
      ## m is a stationary point
      a=m
      b=m
    }
    if(!quiet){
      cat("after iteration k =",k,"the interval is", a, b, "nn")
  }## return the midpoint of the final interval
  return((a+b)/2)
}
a0=0.1
b0=6*pi
xbar=bsearch(df=deriv.g,a=a0,b=b0,L=1e-7,quiet = FALSE)
## after iteration k = 1 the interval is 9.474778 18.84956 nnafter iteration k = 2 the interval is 14.1
xbar
## [1] 17.22076
g(xbar)
## [1] -0.0579718
 iii.
x.list=seq(0.1,6*pi,by=0.001)
g.list=numeric(length = length(x.list))
for(r in 1:length(x.list)){
  g.list[r]=g(x.list[r])
plot(x.list,g.list)
```



Based on this plot, the value of \bar{x} I find in part ii is not a global minimizer.