

139.3-11

$$F dt = (m - dm)(V + dv) - (m - dm)V = (m - dm)dv$$

$$dm = -q dt, \quad m = m_0 - q t$$

$$\therefore F dt = (m_0 - q t) dv = m_0 dv$$

$$F dt = (m_0 - q t) dv = (m_0 - q t) dv$$

$$\Rightarrow V = \frac{F}{q} \ln \left( \frac{m_0}{m_0 - q t} \right)$$

139.3-12

$$(1) (m - dm)(\vec{v} + d\vec{v}) - dm(\vec{v} - \vec{v} - d\vec{v}) = -mg dt$$

$$\therefore \text{克服重力} \therefore \vec{v} = d\vec{v} = 0$$

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$$\therefore dm \vec{v} = mg dt \Rightarrow \frac{dm}{dt} = \frac{m_0}{t} = 60 \text{ kg}$$

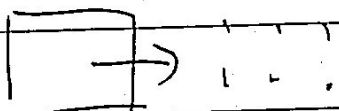
$$(2) \text{此时 } \vec{v} = 0$$

$$\therefore (m - dm)d\vec{v} - \vec{v}dm + dm d\vec{v} = -mg dt$$

$$= m d\vec{v} - \vec{v}dm = -mg dt \quad \frac{d\vec{v}}{dt} = \vec{a}, \quad \frac{dm}{dt} = \text{要求的}$$

$$\therefore \frac{dm}{dt} = 177.6 \text{ kg}$$

139.3-13



$$(m + dm)(\vec{v} + d\vec{v}) - m\vec{v} = 0$$

$$mV = m_0 V_0$$

$$\Rightarrow \begin{cases} \vec{v} \frac{dm}{dt} = -m \frac{d\vec{v}}{dt} \\ m = \frac{m_0 V_0}{V} \end{cases}$$

$$\frac{dm}{dt} = \rho S V$$

$$\Rightarrow \frac{\rho S t}{m_0 V_0} + C = \frac{1}{V}$$

$$\Rightarrow V = \frac{m_0}{m_0 + \rho S V_0 t} V_0$$

139. 3-15

$$(1) \frac{1}{2} k x_0^2 = \frac{1}{2} (m_1 + m_2) V^2 \Rightarrow V = \frac{x_0}{2} \sqrt{\frac{k}{m}}$$

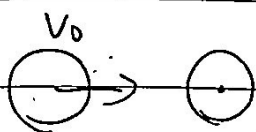
$$(2) \text{ 弹簧回到原长时 } V_B \text{ 有 } \frac{1}{2} k x_0^2 = \frac{1}{2} m_2 V_B^2 \Rightarrow V_B = \sqrt{\frac{k}{m_2}} x_0$$

在此时刻到共速时弹簧一直伸长。

$$m_2 V_B = (m_1 + m_2) V_0, \quad \frac{1}{2} m_2 V_B^2 = \frac{1}{2} (m_1 + m_2) V^2 + \frac{1}{2} k \Delta x_m^2$$

$$\Rightarrow \Delta x_m = \sqrt{\frac{m_1}{m_1 + m_2}} x_0 = \frac{x_0}{2}$$

140. 3-16



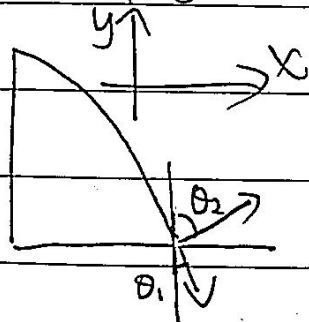
$$(1) m v_0 = 2 m v \Rightarrow v = \frac{v_0}{2}$$

$$(2) \begin{cases} m v_0 = m v_1 + m v_2 \\ e = -\frac{v_2 - v_1}{0 - v_0} = 1 \end{cases}$$

$$\Rightarrow v_1 = 0, v_2 = v_0$$

$$(3) \begin{cases} m v_0 = m v_1 + m v_2 \\ e = \frac{v_2 - v_1}{v_0 - 0} = \frac{1}{2} \end{cases} \Rightarrow \begin{cases} v_1 = \frac{1}{4} v_0 \\ v_2 = \frac{3}{4} v_0 \end{cases}$$

~~141~~ 141. 3-22



$$\text{水平方向 } x \text{ 方向: } m v \sin \theta_1 = m v_1 \sin \theta_2$$

$$y \text{ 方向: } \begin{cases} m v \cos \theta_2 + m v \cos \theta_1 = m \vec{1} \\ e = \frac{v_1 \cos \theta_2 - 0}{0 + v \cos \theta_1} = 1 \end{cases}$$

$$e = \frac{v_1 \cos \theta_2 - 0}{0 + v \cos \theta_1} = 1$$

$$\begin{cases} v \sin \theta_1 = v_0 \\ v \cos \theta_1 = \sqrt{2 h g} \end{cases} \Rightarrow$$

$$\begin{cases} \tan \theta_1 = \frac{v_0}{\sqrt{2 h g}} \\ \tan \theta_2 = \frac{v \cos \theta_1}{v \sin \theta_1} = \frac{\sqrt{2 h g}}{v_0} = \frac{1}{\tan \theta_1} \end{cases}$$

$$\therefore \tan \theta_1 = \tan \theta_2$$

$$\tan \theta_1 = \tan \theta_2$$