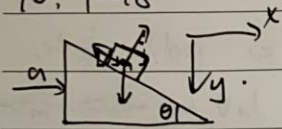


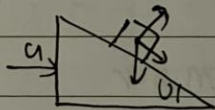
70. 1-48



$a$  最小

$$\begin{cases} mg - F_N \cos \theta - F_f \sin \theta = m a \\ F_N \sin \theta - F_f \cos \theta + m(-a) = 0 \\ F_f \leq F_N \cdot \mu \end{cases}$$

$$\Rightarrow a_{\min} = \frac{\sin \theta - \mu \cos \theta}{\mu \sin \theta + \cos \theta} \cdot g$$



$a$  最大

$$\begin{cases} mg - F_N \cos \theta + F_f \sin \theta = 0 \\ F_N \sin \theta + F_f \cos \theta + m(-a) = 0 \\ F_f \leq F_N \cdot \mu \end{cases}$$

若  $\cos \theta - \mu \sin \theta > 0$  即  $\mu \tan \theta < 1$

$$\Rightarrow a_{\max} = \frac{\sin \theta + \mu \cos \theta}{\cos \theta - \mu \sin \theta} \cdot g$$

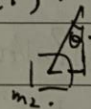
$$\therefore a \in [a_{\min}, a_{\max}]$$

若  $\cos \theta - \mu \sin \theta < 0$  即  $\mu \tan \theta > 1$

70. 1-49

$\therefore a \geq a_{\min}$ , 无最大值

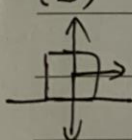
(1)



$$\begin{cases} m_2 g = F_T \cos \theta \\ F_T \sin \theta + m_2(-a) = 0 \end{cases}$$

$$\Rightarrow F_T = m_2 \sqrt{g^2 + a^2}$$

(2)



$$\begin{cases} m_1 g - F_T - F_N = 0 \\ F_N \cdot \mu + m_1(-a) = 0 \end{cases}$$

$$\Rightarrow \mu_{\min} = \frac{m_1 a}{m_1 g - m_2 \sqrt{g^2 + a^2}}$$

20.1-53

$$\vec{v}_h = 7.5\vec{i} - 3\vec{j} \text{ (m/s)} \quad \vec{v}_0 = 5\vec{i} \text{ (m/s)}$$

$$\vec{v}_c = 2\vec{i} + \frac{9}{2}\vec{j} \text{ (m/s)}$$

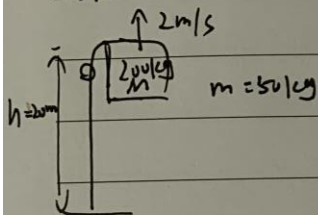
$$\vec{v}_B = v_{xi}\vec{i} + v_{yj}\vec{j} \text{ (m/s)}$$

$$\therefore m_A \vec{v}_A + m_B \vec{v}_B + m_C \vec{v}_C = m \vec{v}_0$$

$$\Rightarrow \vec{v}_B = 3.5\vec{i} + 1.5\vec{j} \text{ (m/s)}$$

$$\therefore \vec{r}_B(2) = 7\vec{i} + 3\vec{j} \quad (7, 3) \text{ (m)}$$

20.1-55



$$M \cdot v_1 + m v_2 = (m+M) v_0$$

$$v_2 \cdot t = h + v_1 \cdot t$$

$$t \leq 10$$

不一定匀速

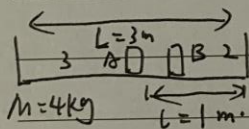
$$\Rightarrow \begin{cases} v_1 = 4 \text{ m/s} \uparrow \\ v_2 = 6 \text{ m/s} \downarrow \end{cases} \quad \begin{aligned} & \frac{(M+m) \cdot h + v_0 t}{m+m} \\ & = \frac{m \cdot 0 + M \cdot L}{m+m} \end{aligned}$$

$$\therefore t = h + v_1 \cdot t$$

$$= 60 \text{ m}$$

$$\Rightarrow L = 50 \text{ m} \quad K < 50 \text{ m}$$

21.1-56



$$(M + m_A + m_B) v_0 = m_A v_A + m_B v_B$$

以小车左端为 0.  $\rightarrow$  为 +

$$v_c = \frac{M \cdot \frac{L}{2} + (m_A + m_B)(L - l)}{M + m_A + m_B} = \frac{M(\frac{L}{2} + \frac{L}{2}) + m_A(\frac{L}{2} + l) + m_B(\frac{L}{2} + l)}{M + m_A + m_B}$$

$$\Rightarrow S = \frac{4}{9} \text{ m} \quad \text{向右运动} \quad \frac{4}{9} \text{ m}$$