

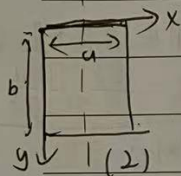
175. 4-5

$$J_c = \frac{1}{4} m a^2, \quad m d^2 = m a^2 \quad \therefore J = \frac{1}{4} m a^2 + \frac{1}{4} m a^2$$

176. 4-7

(1) $\rho = \frac{m}{ab}$ $J_c = \int \frac{1}{12} a^2 dm$ $dm = \rho \cdot a dx$

$$= \int_0^b \frac{1}{12} a^2 \rho a dx = \frac{1}{12} m a^2$$



$$J = J_c + m \left(\frac{b}{2}\right)^2 = \frac{1}{3} m a^2$$

(2) $F = -k S V^2$ $F(x, y) = -k x^2 \omega^2 ds$

$$M = \int \sqrt{x^2 + y^2} \cdot F(x, y) = J \beta = J \cdot \frac{d\omega}{dt}$$

$$\Rightarrow -k \omega^2 \int_0^b \int_0^a \sqrt{x^2 + y^2} x^2 dy dx = J \frac{d\omega}{dt} \quad \text{Let } \int_0^b \int_0^a \sqrt{x^2 + y^2} x^2 dy dx = D$$

$$\Rightarrow \frac{kD}{J} t + C = \frac{1}{\omega} \quad t=0 \text{ 时 } \omega = \omega_0$$

$$\therefore \frac{1}{\omega} = \frac{1}{\omega_0} + \frac{kD}{J} t \quad \therefore \omega = \frac{\omega_0}{1 + \frac{kD}{J} \omega_0 t} \quad t = \frac{4m}{3ka^2 b \omega_0}$$

176. 4-9

(1) $J_c = \frac{1}{12} m L^2$ $J = J_c + m \left(\frac{L}{4}\right)^2 = \frac{7}{48} m L^2$

(2) $\vec{L}_0 = \vec{L}_{oc} + \vec{L}_c$ $\vec{L}_c = 0$

$$|\vec{L}_{oc}| = \frac{1}{4} L \times M V = \frac{1}{4} m V L \quad \therefore \vec{L}_0 = \frac{1}{4} m V L \cdot (-\vec{k})$$

(3) 碰撞后系统相对 O 的角动量没有变化。

$$\therefore \text{左边有 } \vec{L} = \int_{-\frac{L}{4}}^{\frac{L}{4}} x \cdot m \omega x = \int_{-\frac{L}{4}}^{\frac{L}{4}} \frac{1}{2} m \omega x^2 dx$$

$$\text{右边有 } \vec{L}' = \int_{\frac{L}{4}}^{\frac{3L}{4}} m \omega x^2 dx \quad \vec{L} + \vec{L}' = \vec{L}_0$$

$$\Rightarrow \omega = \frac{12}{7} \frac{V}{L}$$

解 $\omega = \frac{12}{7} \frac{V}{L}$ $|\vec{L}| = J_0 \cdot \omega \Rightarrow \omega = \frac{12}{7} \frac{V}{L}$

176.4-10

$$(1) J = J_{\text{cm}} + J_{\text{cm}}', \quad J_{\text{cm}} = \frac{1}{2}MR^2, \quad J_{\text{cm}}' = mR^2$$

$$L_0 = m \cdot Rv = mUR = (\frac{1}{2}MR^2 + mR^2)\omega_0 \Rightarrow \omega_0 = \frac{2mV}{MR+2mR} = \frac{2mV}{MR+2mR}$$

$$(2) M = J\beta, \quad M = \int_0^R f \cdot r \cdot dr \cdot d\theta, \quad f = (m+m')g$$

$$M = \int_0^R r \cdot dr \cdot d\theta, \quad d\theta = \frac{mg}{R} \cdot \frac{M}{2\pi R} \cdot 2\pi R \cdot dr$$

$$\therefore M = \int_0^R 2r^2 mg \frac{M}{R^2} dr = \frac{2}{3}MmgR = J \cdot \beta$$

$$\Rightarrow \beta = \frac{4mg}{3(m+2m)} \quad \therefore t = \frac{\omega_0}{\beta} = \frac{3mV}{2mg}$$

176.4-11

$$J = \frac{1}{2}mk^2 + qtr^2$$

$$M = \frac{dL}{dt} = \frac{dJ\omega}{dt} = \frac{dJ}{dt}\omega + J \frac{d\omega}{dt} = \omega qtr^2 + (\frac{1}{2}mk^2 + qtr^2) \frac{d\omega}{dt}$$

\Rightarrow

$$\frac{1}{2}mk^2 + qtr^2 = \frac{C}{M - \omega qtr^2} \Rightarrow \frac{1}{2}mk^2 + qtr^2 = \frac{\frac{1}{2}mk^2 M}{M - \omega qtr^2}$$

$$\tau = \frac{m_0}{q} \text{ of } \omega = \frac{2M}{q(R^2 + 2r^2)}$$

177.4-14

$$(1) J = \frac{1}{2}mR^2, \quad L_{B0} = J\omega = \frac{1}{2}mR^2\omega_0$$

$$mV_A \cdot R + \frac{1}{2}mR^2 \frac{V_A}{R} = \frac{1}{2}mR^2\omega_0 \Rightarrow V_A = \frac{1}{3}R\omega_0$$

$$(2) \begin{cases} \bar{F}_T + m_0 g M = m a \\ \bar{F}_T R = J \beta \\ \beta \cdot R = a \end{cases}$$

$$\Rightarrow \bar{F} = \frac{1}{3}mgM$$

$$\beta \cdot R = a$$