

Raymond (Mingguang) Yang

Philadelphia, PA | Willing to relocate

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EDUCATION BACKGROUND

University of Pennsylvania, Philadelphia, PA	Aug 2024 – May 2026 (Expected)
M.S.E. in Mechanical Engineering (Mechatronics and Robotics stream),	GPA 3.95/4.00
University of Toronto, Toronto, Canada	Sep 2019 – June 2024
B.A.Sc. with Honors in Mechanical Engineering (Mechatronics and Manufacturing stream),	GPA 3.77/4.00

SKILLS & QUALIFICATIONS

Design & CAD: SolidWorks (advanced), Creo Parametric, CATIA, GD&T, DFM, machining & prototyping

Simulation & Analysis: ANSYS, Abaqus, COMSOL, MATLAB, FEA (thermal/structural/electromagnetic)

Manufacturing & Testing: Machining, Fixture Design, Quality control, PFMEA, Lean/ISO standards

Programming & Control: Python, robotics kinematics, C++, Control Algorithms

MECHANICAL EXPERIENCES

Multi-Platform Lunar Rover System (NASA LuSTR), UPenn , Philadelphia, PA	Jan 2025 – Feb 2026 (Expected)
<ul style="list-style-type: none">Designed and modeled an aluminum chassis and turret assembly in SolidWorks, supporting a 60 kg combined load while reducing mass by ~15 % through DFM optimization.Performed tolerance and fit analysis on multi-robot docking interfaces; validated ±3 mm alignment and achieved > 95 % docking success in field tests.Collaborated on sensor and motor mount designs, ensuring precise axis alignment and cable routing for clean integration with the ROS2 control stack.	

Automated Adhesive Workstation, UofT , Toronto, Canada	Apr 2023 – Dec 2023
<ul style="list-style-type: none">Designed and assembled a pneumatic adhesive dispensing workstation in SolidWorks using machined aluminum components, linear slides, and press modules for automated production use.Configured pneumatic cylinders and adjustable nozzles to achieve ±0.2 mm coating accuracy across 100+ production trials; documented calibration and safety procedures.Integrated actuator and sensor mounts for automation control, reduced assembly time to less than 10hr and simplified maintenance access during testing.	

Lathe Tool & Grinding Head Assembly, UofT , Toronto, Canada	Jan 2022 – May 2022
<ul style="list-style-type: none">Designed a 3-DOF lathe tool grinding head with bearing-supported spindle and precision ball-screw feed, achieving ±0.05° tool geometry repeatability.Designed mechanical subsystems including cast base, ribbed frame, and bearing-supported spindle to maximize stiffness and minimize thermal growth; improved predicted vibration response by >30 % through load-path optimization.Integrated serviceability and control provisions, such as removable guards, labeled wiring harnesses, and placeholders for servo/PLC drives to support future programmable feed sequences.	

INDUSTRY EXPERIENCES

Process Engineer, Bittele Electronics Inc. , Toronto, Canada	May 2022 – Sep 2023
<ul style="list-style-type: none">Reviewed 300 + PCB and mechanical assemblies for DFM and IPC-A-610 compliance, identifying manufacturability issues early in production.Implemented FMEA-based validation to improve reliability from prototype-level 3σ to 6σ, reducing rework and scrap across pilot builds.	

Mechanical Engineer, Jiangnan Mould & Plastic Technology Co., Ltd , Shanghai, China	Apr 2021 – Aug 2021
<ul style="list-style-type: none">Designed and validated 3 + automotive bumper prototypes in CATIA, performing tolerance analysis and GD&T review for Tier 1 OEM projects.Tested 10+ iterations of full-scale prototypes to meet design specifications and standards.Conducted structural and load analysis with Abaqus, collaborating with CAE engineers to reduce injection molding production failure rate by ~2%.	