

- 2.2. Solution: ① If a set  $S$  is a convex set,  
 $\because$  The intersection of two convex sets is convex  
 $\therefore$  Any line is convex  
 $\therefore$  The intersection of  $S$  and any line is convex.  
② Conversely, we first suppose that the intersection of  $S$  and any line is convex.

Then we take  $\forall x_1, x_2 \in S$ , so the intersection of  $S$  and line that can through  $x_1$  and  $x_2$  is convex.

$\therefore$  convex combinations of  $x_1$  and  $x_2$  belong to  $S$   
 $\therefore S$  is a convex set.

- 2.3. Solution: We can find the midpoint of  $a, b \Rightarrow \frac{1}{2}(a+b)$   
 $\xrightarrow{\text{then we find another midpoint of } a \text{ and } (\frac{1}{2}a+\frac{1}{2}b) \Rightarrow \frac{1}{2}a+\frac{1}{2}(\frac{1}{2}a+\frac{1}{2}b)}$   
after this, we just need to find the midpoint close to  $a$  or  $b$ .

This midpoint can be expressed as:  $\theta_k a + (1-\theta_k)b$

$$\theta_k = C_1 2^{-1} + C_2 2^{-2} + \dots + C_k 2^{-k}$$

If we choose the  $a, b$  on the border of this set ( $C$  is closed),

then we can put  $k$  to infinity

$$\lim_{k \rightarrow \infty} \theta_k = 1, \text{ then } \theta_k \in [0, 1]$$

hence  $\theta x + (1-\theta)y \in C$  for all  $\theta \in [0, 1], x, y \in C$ , then  $C$  is convex.

- 2.10(a) Solution: As we know, The  $\alpha$ -sublevel set of a function  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is defined as  $\{x \in \text{dom } f | f(x) \leq \alpha\}$

sublevel sets of a convex function are convex for any  $\alpha$ .

for this context, the  $\alpha$  is 0.

Then we only need to let the function  $x^T A x + b^T x + c$  be convex function.

It's a quadratic function, to satisfy it's convex, we need to apply second-order conditions on it.  $\nabla^2 f(x) \succcurlyeq 0$

so, only if  $A \succcurlyeq 0$ ,  $C$  is convex.

- 2.12(a) A slab is a set of the form  $\{x \in \mathbb{R}^n | \alpha_i \leq x_i \leq \beta_i, i=1, \dots, n\}$ .

We can know that it's the intersection of two halfspaces.  
halfspace is convex, then slab is convex.

- (b) For the form  $\{x \in \mathbb{R}^n | \alpha_i \leq x_i \leq \beta_i, i=1, \dots, n\}$

It's the finite intersection of halfspaces, then it's convex.

- (c) For the form  $\{x \in \mathbb{R}^n | \alpha_1^T x \leq b_1, \alpha_2^T x \leq b_2\}$

It's also a intersection of two halfspaces, then it's convex.

- (d) For this set  $\{x | \|x - x_0\|_2 \leq \|x - y\|_2 \text{ for all } y \in S\}, S \subseteq \mathbb{R}^n$

So for a fixed  $y$ ,  $\|x - x_0\|_2 \leq \|x - y\|_2$

$$\Leftrightarrow (x - x_0)^T (x - x_0) \leq (x - y)^T (x - y)$$

$$\Leftrightarrow x^T x - 2x^T x_0 + x_0^T x_0 \leq x^T x - 2y^T x + y^T y$$

$$\Leftrightarrow 2(y - x_0)^T x \leq y^T y - x_0^T x_0$$

This is a halfspace, then for all  $y \in S$ , this set is intersection of halfspaces, then it's a convex set.

- 2.21. Solution: The set  $(a, b) \in \mathbb{R}^{n+1}$

$$a^T x \leq b \quad x \in C$$

$$a^T x \geq b \quad x \in D.$$

First, we can find that origin can satisfy both conditions.

Then, from these two conditions we can say that these form an intersection of halfspaces.

Overall, this is a convex cone.

Prove:

- ① Prove the convexity of  $e^{\alpha x}$  on  $\mathbb{R}$  for any  $\alpha \in \mathbb{R}$ .

Solution: Consider the second order condition.

$$\nabla^2 f(x) = \alpha^2 e^{\alpha x} \text{ for any } \alpha \in \mathbb{R}, \nabla^2 f(x) \succcurlyeq 0$$

then  $e^{\alpha x}$  on  $\mathbb{R}$  is convex

- ② Prove the concavity of  $\log x$  on  $\mathbb{R}_{++}$

Solution: Consider the second order condition.

$$\nabla^2 f(x) = \frac{-1/\ln(10)}{x^2 \ln^2(10)} < 0, \text{ then it's concave.}$$

- ③ Prove the convexity of  $-\log \det X$  on  $S_{++}^n$

Solution: Fact: a function is convex if and only if its restriction to any line is convex.

To prove the convexity of  $-\log \det X$  on  $S_{++}^n$

we can first apply  $\log \det X$

Consider the line:  $\{x | x + tv\} g(t) = f(x + tv) = \log \det(x + tv)$

$X$  is positive definite matrix, then  $X^{\frac{1}{2}} X^{\frac{1}{2}} = X$

$$g(t) = \log \det(X^{\frac{1}{2}} X^{\frac{1}{2}} + t X^{\frac{1}{2}} V X^{\frac{1}{2}} X^{\frac{1}{2}})$$

$$= \log \det(X^{\frac{1}{2}} (I + t X^{-\frac{1}{2}} V X^{-\frac{1}{2}}) X^{\frac{1}{2}})$$

$$= \log(\det(X) \det(I + t X^{-\frac{1}{2}} V X^{-\frac{1}{2}}))$$

$$= \log \det(X) + \log \det(I + t X^{-\frac{1}{2}} V X^{-\frac{1}{2}})$$

Assume the eigenvalues of  $X^{-\frac{1}{2}} V X^{-\frac{1}{2}}$  are  $\lambda_1, \lambda_2, \dots, \lambda_d$ , then

$$\log \det(I + t X^{-\frac{1}{2}} V X^{-\frac{1}{2}}) = \log \prod_{i=1}^d (1 + t \lambda_i) = \sum_{i=1}^d \log(1 + t \lambda_i)$$

$$\text{then } g(t) = \log \det(X) + \sum_{i=1}^d \log(1 + t \lambda_i)$$

$$\text{then } -g(t) = -\log \det(X + tv) = -\log \det(X) - \sum_{i=1}^d \log(1 + t \lambda_i)$$

Consider the second order condition:

$$-g''(t) = \sum_{i=1}^d \frac{\lambda_i^2}{(1 + t \lambda_i)^2} \geq 0$$

Thus,  $-g(t)$  is convex, so is  $-f(x)$  which is  $-\log \det X$  on  $S_{++}^n$

- 3.11. Solution:  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is a differentiable convex function.

then  $f(y) \geq f(x) + \nabla f(x)^T (y - x)$ , for all  $x, y \in \text{dom } f$ .

$$f(x) \geq f(y) + \nabla f(y)^T (x - y).$$

then  $(\nabla f(x) - \nabla f(y))^T (x - y) \geq 0$ . satisfy the condition of monotone.

then gradient  $\nabla f$  is monotone.

The converse is not true.

According to the context,  $\psi = \nabla f$

$$\text{Suppose we have } \psi(x) = \begin{bmatrix} x_1 \\ 2x_1 + x_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\psi(y) = \begin{bmatrix} y_1 \\ 2y_1 + y_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$\psi$  is monotone because:  $[\psi(x) - \psi(y)]^T (x - y)$

$$= \begin{bmatrix} x_1 - y_1 \\ 2(x_1 - y_1) + x_2 - y_2 \end{bmatrix}^T \left( \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x_1 - y_1 \\ x_2 - y_2 \end{bmatrix} \right)^T (x - y)$$

$$= (x - y)^T \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} (x - y)$$

$$= [(x_1 - y_1) + (x_2 - y_2)]^2 \geq 0, \text{ for all } x, y.$$

However, there does not exist a function:  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$  that  $\psi(x) = \nabla f(x)$

because if  $\nabla f(x) = \psi(x)$ , then  $\frac{\partial^2 f}{\partial x_1 \partial x_2} = \frac{\partial \psi_1}{\partial x_2} = 0, \frac{\partial^2 f}{\partial x_1 \partial x_2} = \frac{\partial \psi_2}{\partial x_1} = 2$ .

It's impossible.

- 3.18 Solution: (a) define  $g(t) = f(z + tv)$ , where  $z \geq 0, v \in S^n$

$$g(t) = \text{tr}((z + tv)^{-1})$$

$$= \text{tr}(z^{-1} (I + t z^{-1} V z^{-1})^{-1})$$

$z^{-\frac{1}{2}} V z^{-\frac{1}{2}} = Q \Lambda Q^T$  is the Schur decomposition.

$$Q^T Q = Q Q^T = I \quad \Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$$

$$g(t) = \text{tr}(z^{-1} (I + t Q \Lambda Q^T)^{-1})$$

$$= \text{tr}(z^{-1} Q (I + t \Lambda)^{-1} Q^T)$$

$$= \text{tr}(Q^T z^{-1} Q (I + t \Lambda)^{-1})$$

$$= \sum_{i=1}^n (Q^T z^{-1} Q)_{ii} (1 + t \lambda_i)^{-1}$$

$$g''(t) = \frac{\lambda_i (2\lambda_i^2 t + 2\lambda_i)}{(1 + t \lambda_i)^2} \geq 0, \text{ then it's convex.}$$

- (b). Define:  $g(t) = f(z + tv)$  where  $z \geq 0, v \in S^n$

$$g(t) = (\det(z + tv))^{\frac{1}{n}}$$

$$= (\det z^{\frac{1}{2}} \det(I + t z^{-\frac{1}{2}} V z^{-\frac{1}{2}}) \det z^{\frac{1}{2}})^{\frac{1}{n}}$$

$$= (\det z)^{\frac{1}{n}} (\det(I + t z^{-\frac{1}{2}} V z^{-\frac{1}{2}}))^{\frac{1}{n}}$$

$$= (\det z)^{\frac{1}{n}} \left( \prod_{i=1}^n (1 + t \lambda_i)^{\frac{1}{n}} \right)$$

for  $\prod_{i=1}^n (1 + t \lambda_i)^{\frac{1}{n}}$  is a kind of geometric mean.

then  $\nabla^2 f(x) \leq 0, z \geq 0$

hence  $\nabla^2 g(t) \leq 0$ , it's concave.