시뮬레이터 설명
How to use Simulator

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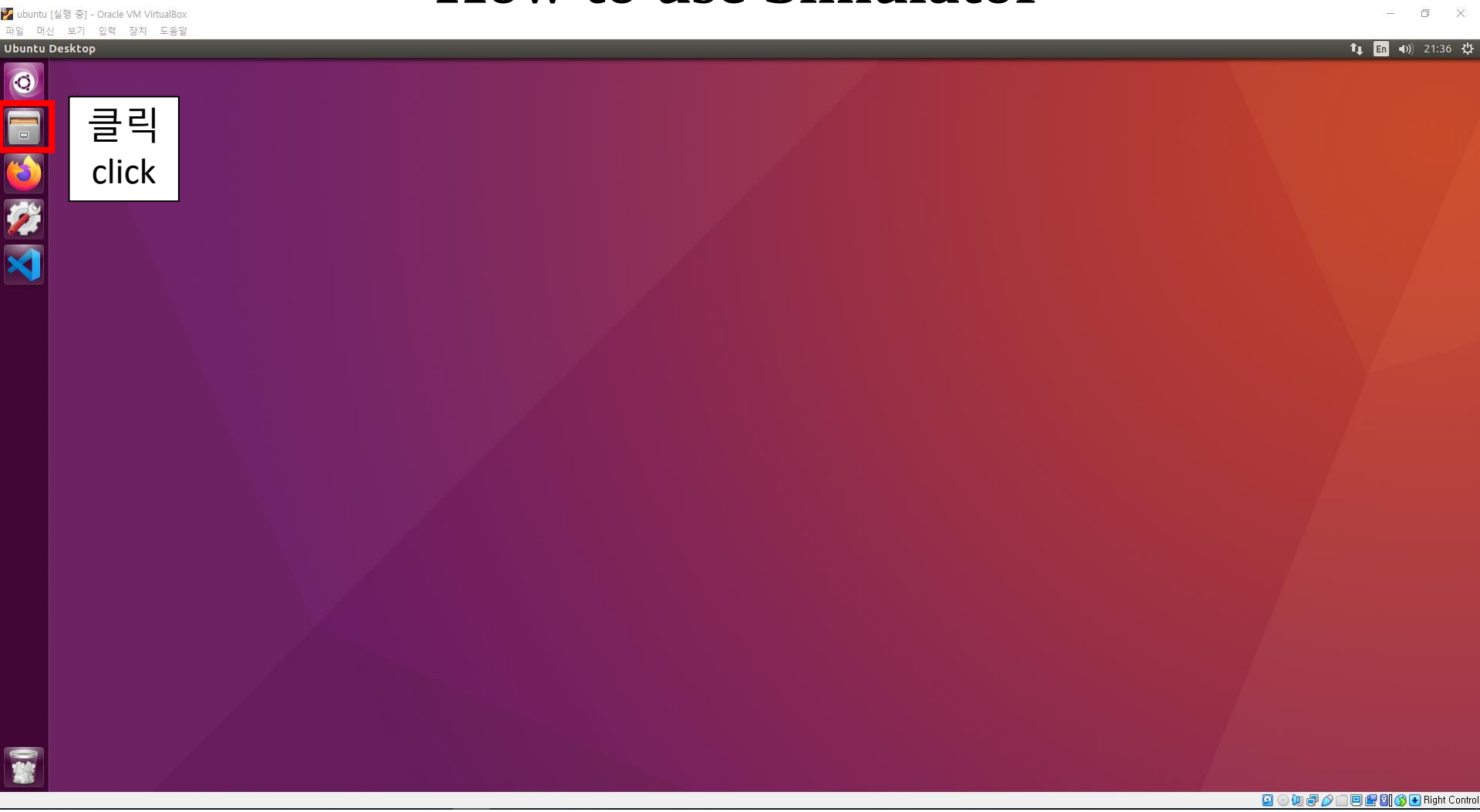
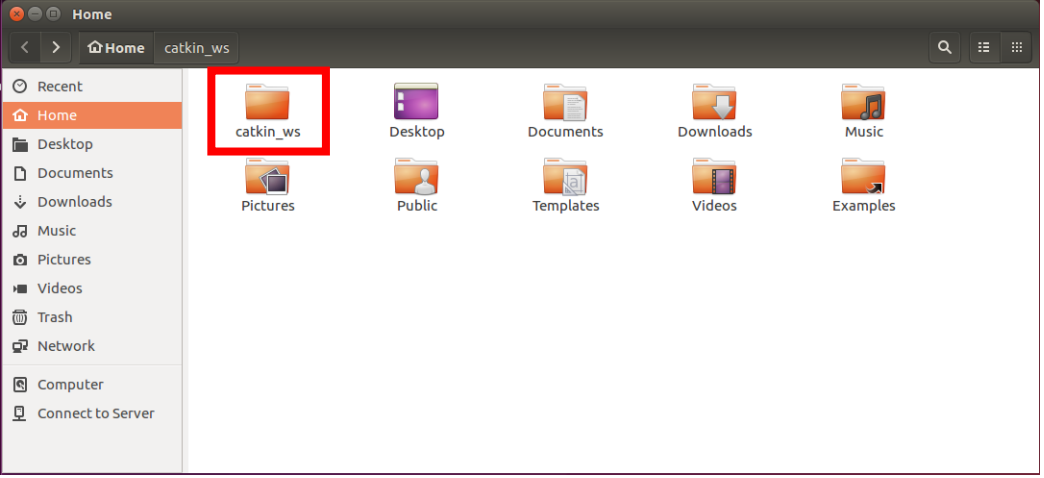
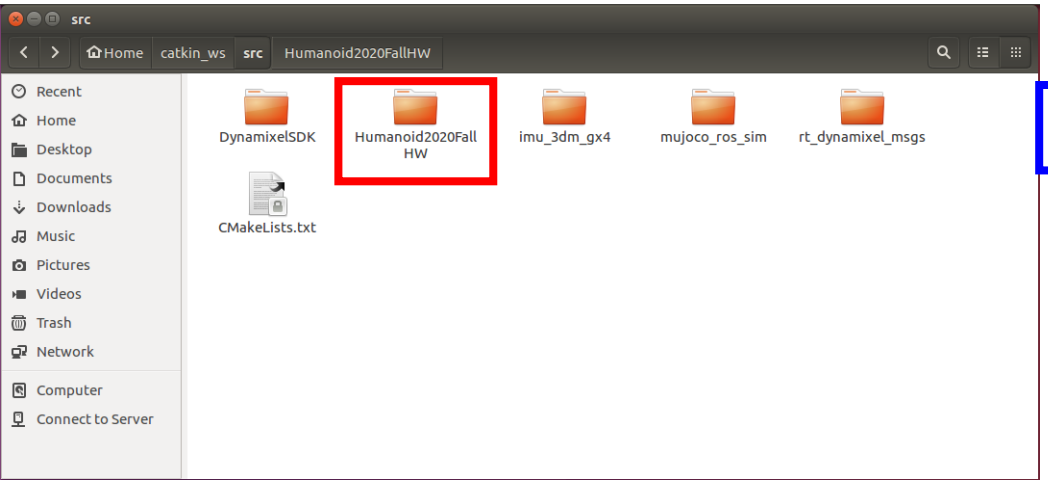
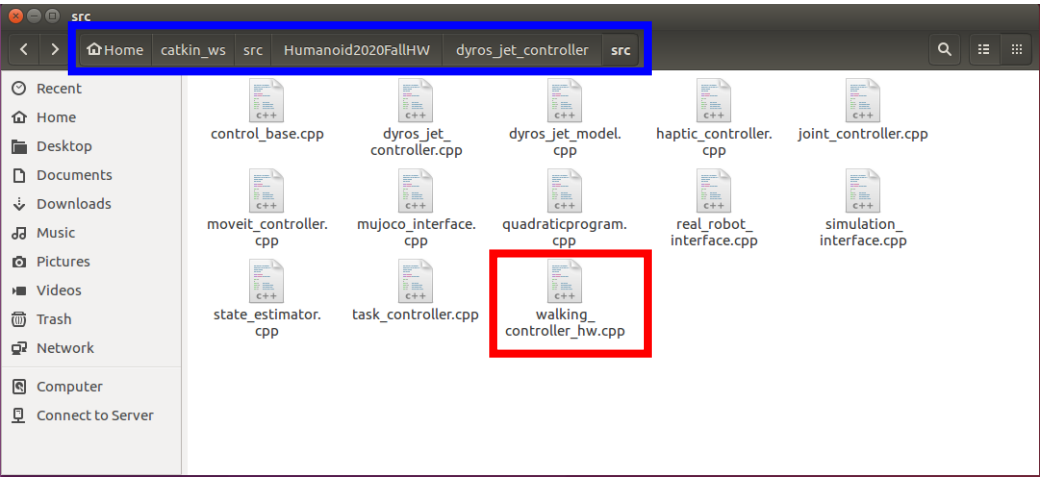


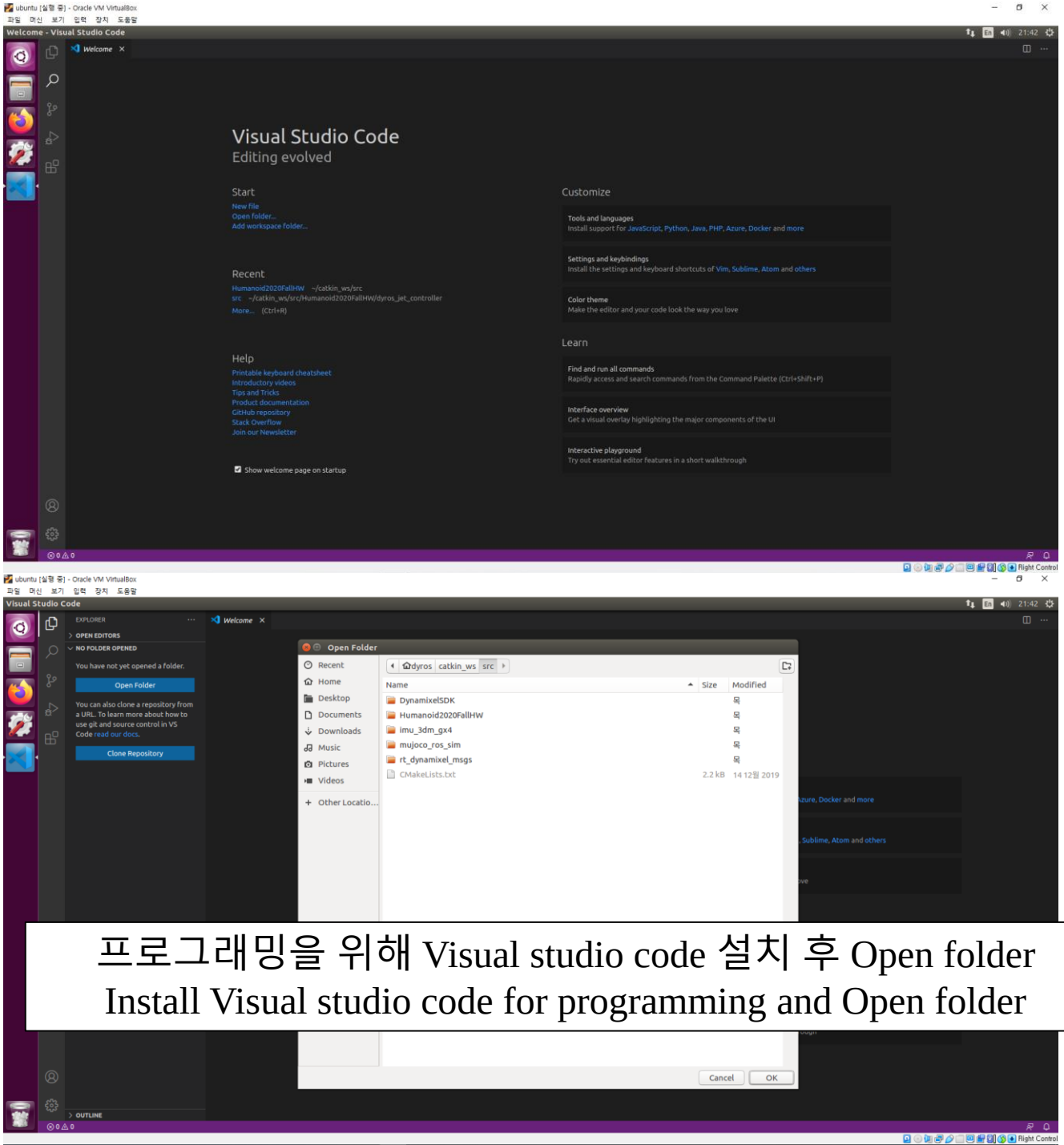






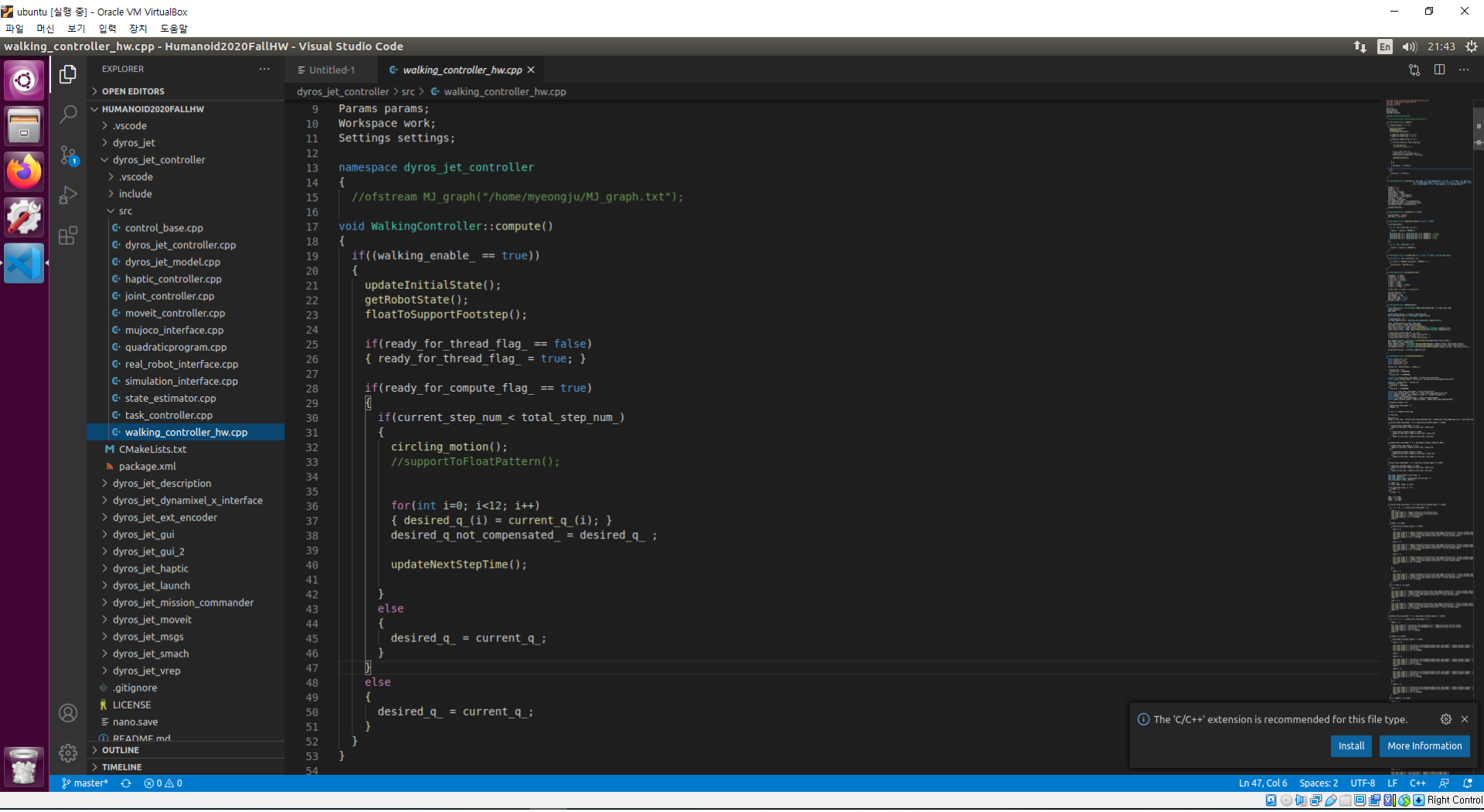
해당 위치에 과제에 활용될 cpp 파일 확인

Check cpp file for HW



프로그래밍을 위해 Visual studio code 설치 후 Open folder

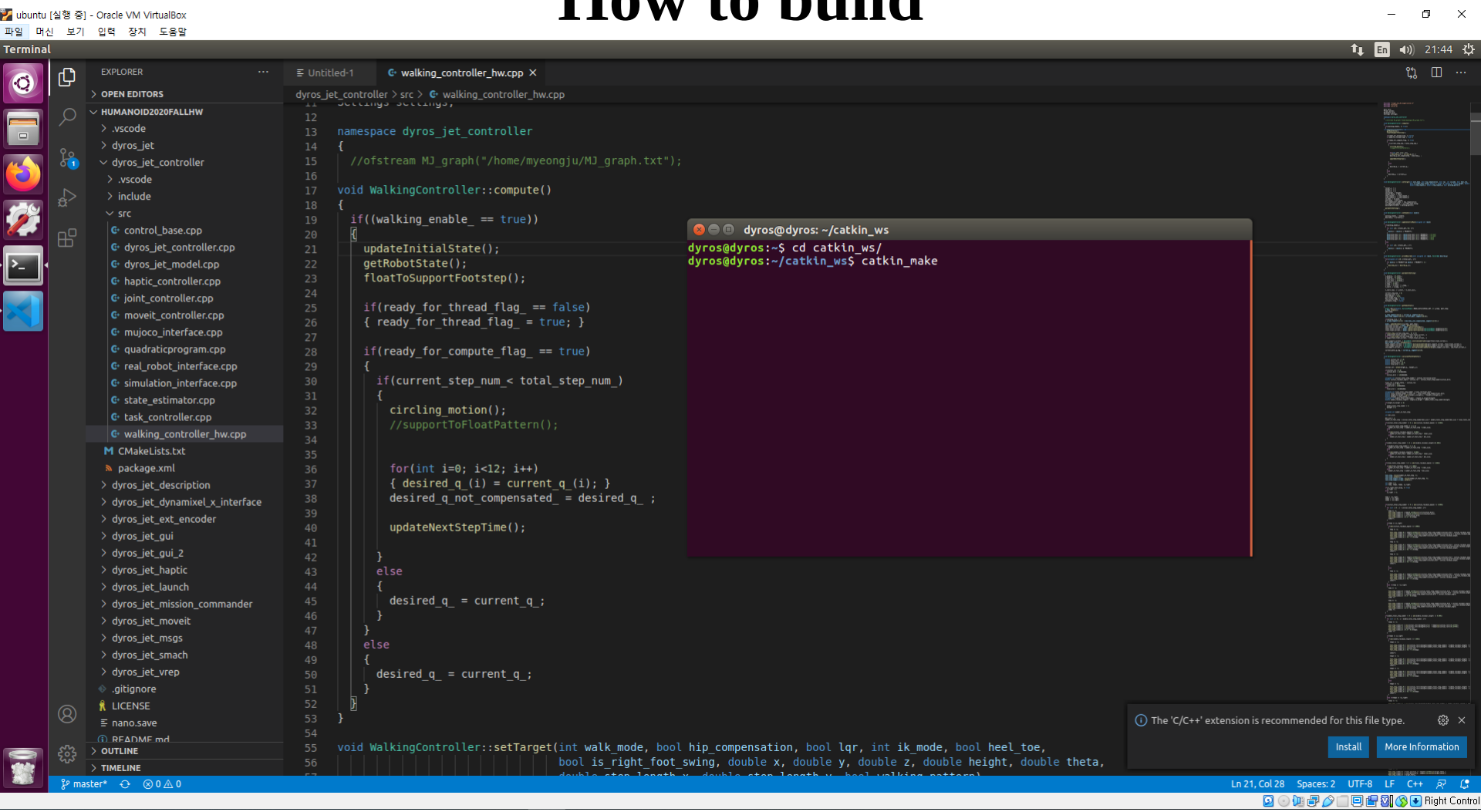
Install Visual studio code for programming and Open folder



한학기 동안 사용할 코드 프레임워크

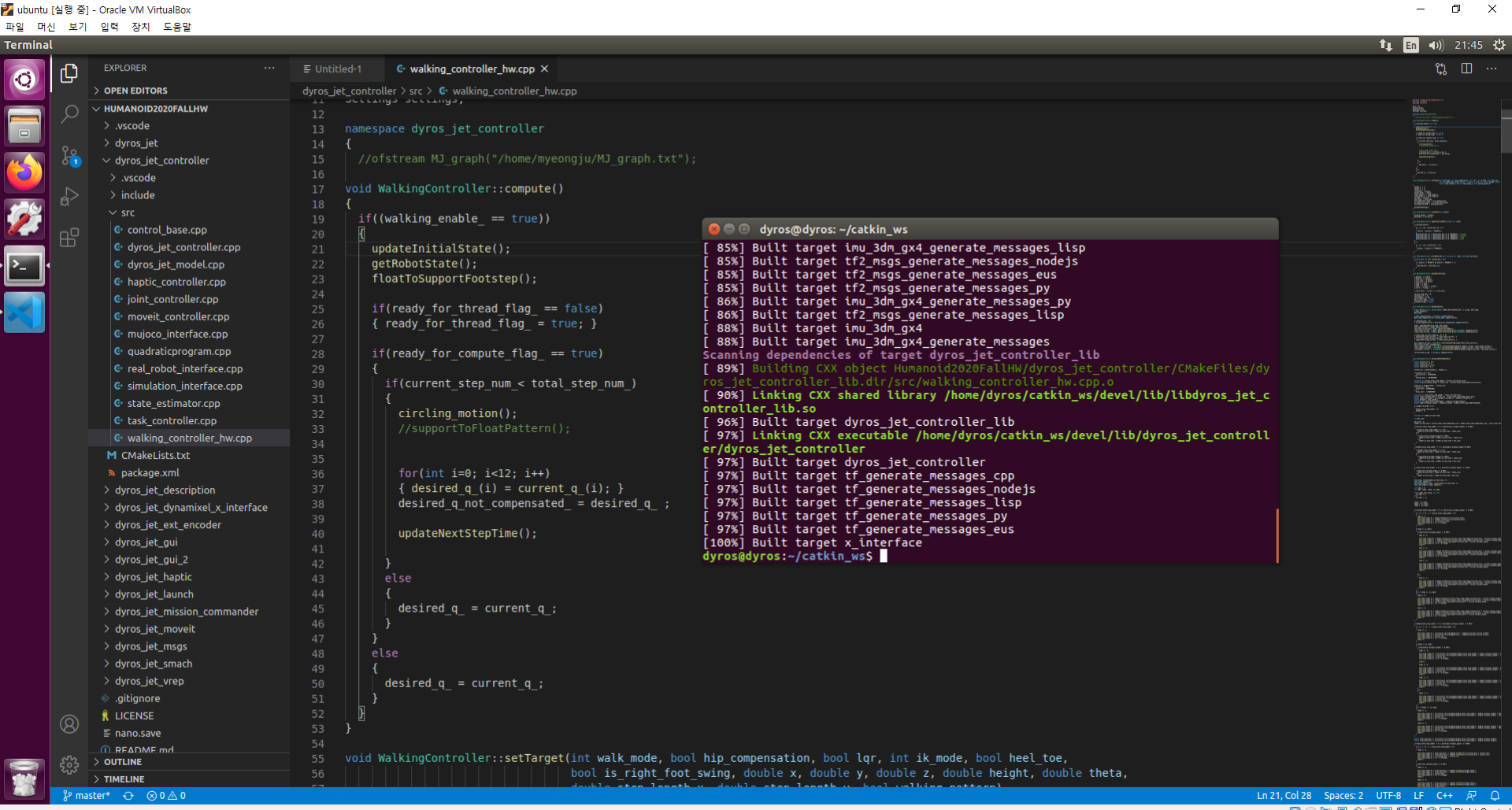
Code Framework for Semester

빌드하는 방법
How to build



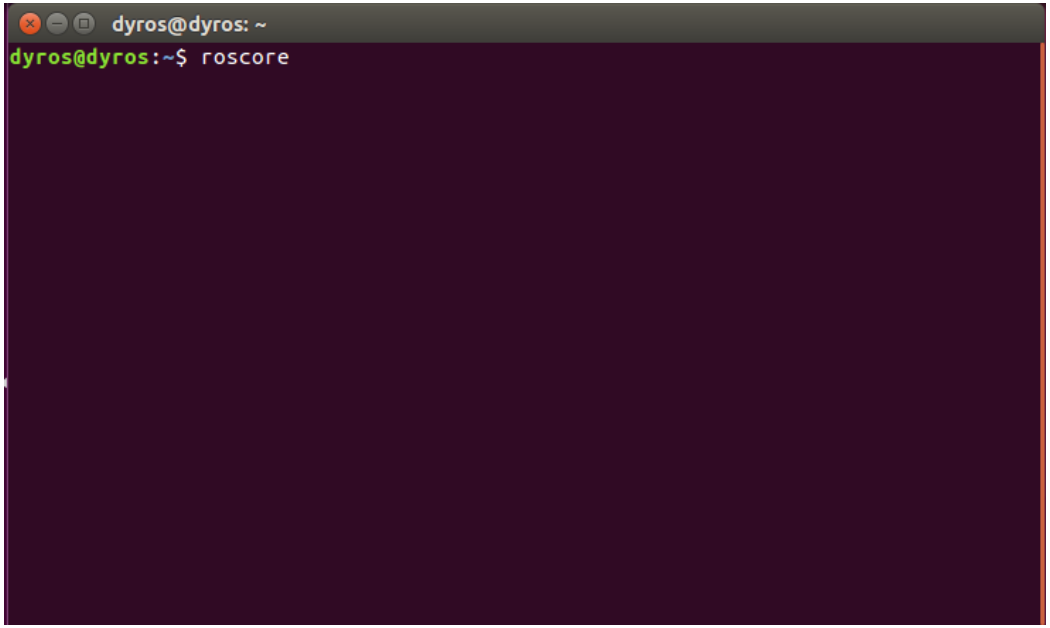
코드를 수정한 후 Ctrl + S를 눌러서 저장한 다음 빌드

Save by Ctrl + S after editing. Build by typing “catkin_make”

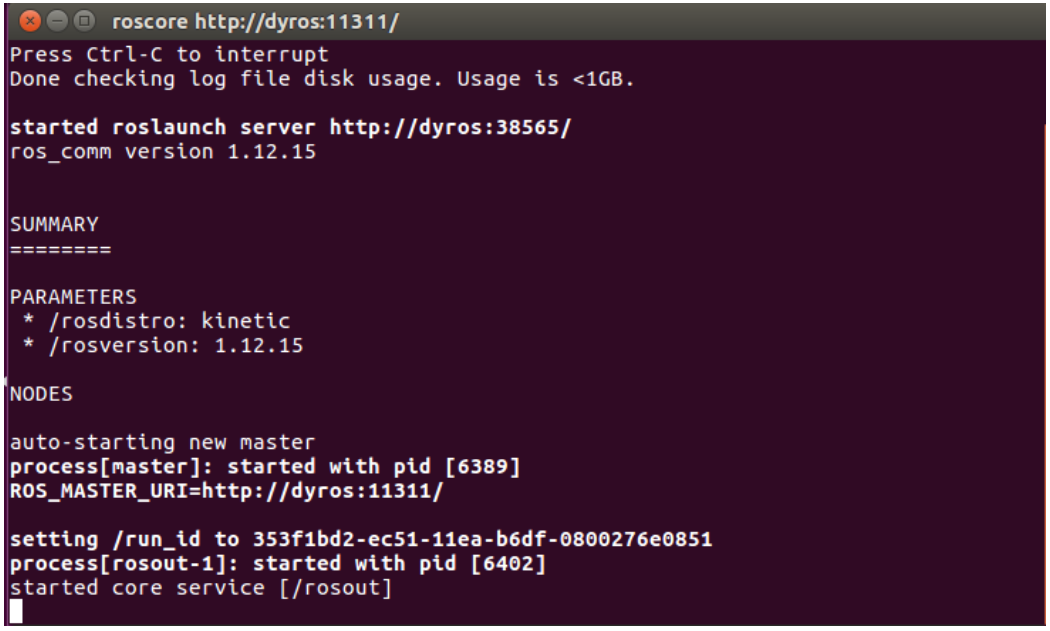


빌드 완료

Build complete

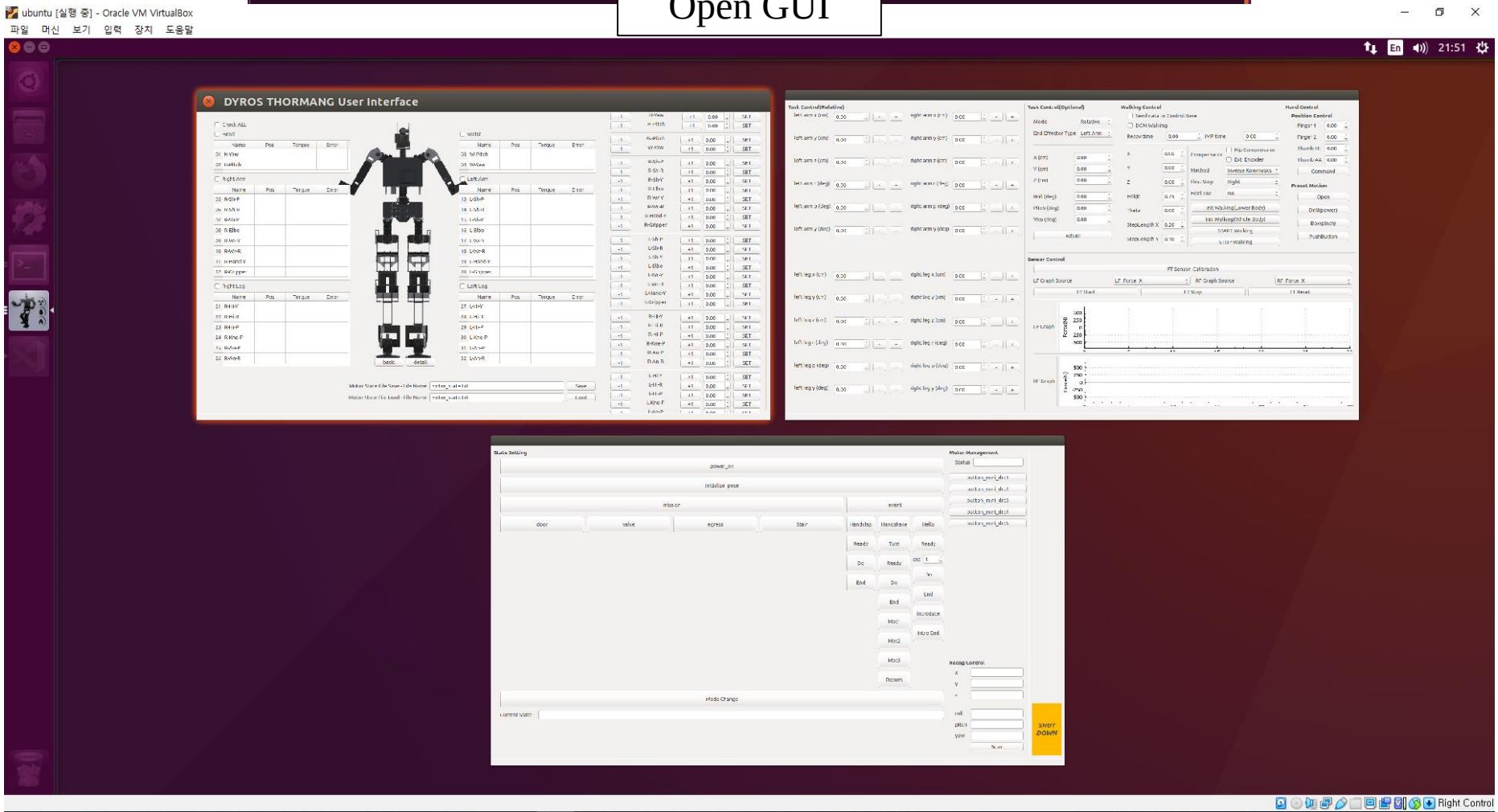

dyros@dyros: ~
dyros@dyros:~$ roscore

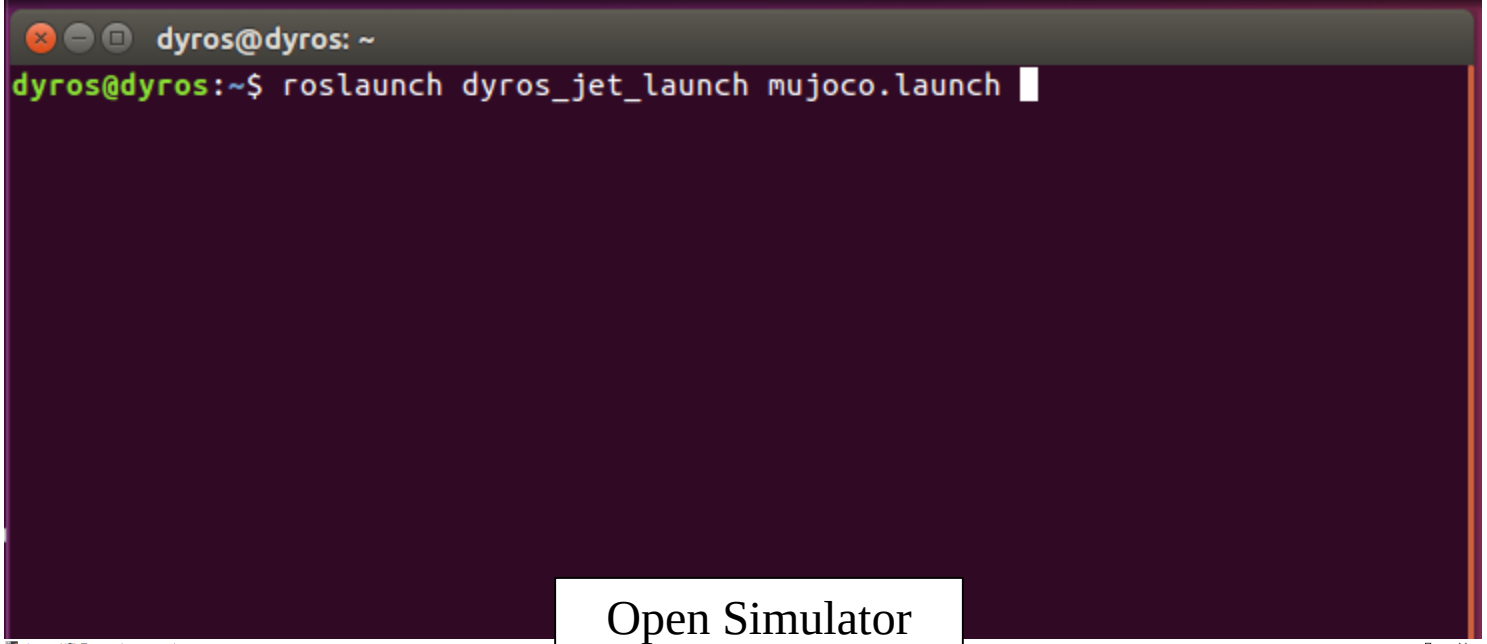
Roscore


roscore http://dyros:11311/
Press Ctrl-C to interrupt
Done checking log file disk usage. Usage is <1GB.
started roslaunch server http://dyros:38565/
ros_comm version 1.12.15
SUMMARY
========
PARAMETERS
* /rosdistro: kinetic
* /rosversion: 1.12.15
NODES
auto-starting new master
process[master]: started with pid [6389]
ROS_MASTER_URI=http://dyros:11311/
setting /run_id to 353f1bd2-ec51-11ea-b6df-0800276e0851
process[rosout-1]: started with pid [6402]
started core service [/rosout]

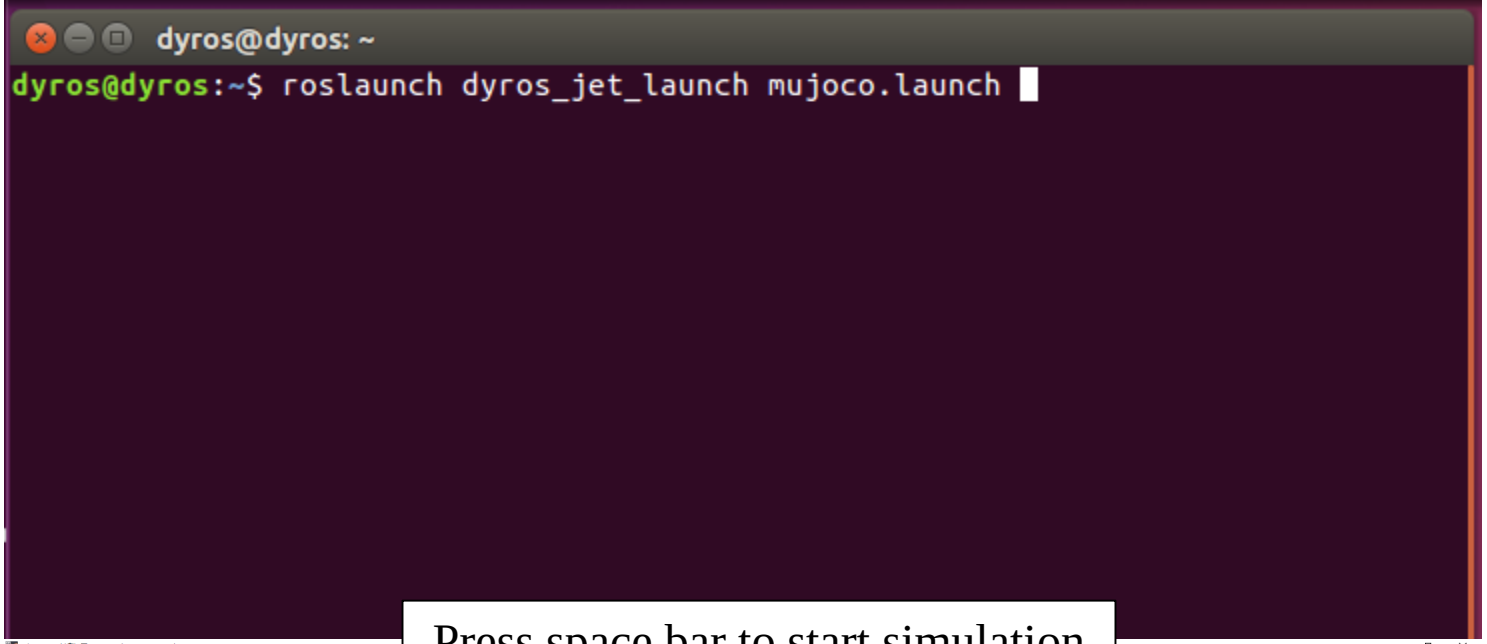
```
dyros@dyros: ~
dyros@dyros:~$ rosrun dyros_jet_gui dyros_jet_gui
```

Open GUI





Open Simulator



Press space bar to start simulation

```
dyros@dyros: ~
dyros@dyros:~$ rosrun dyros_jet_gui dyros_jet_gui
```

Press start walking to start controller