TUGAS KECIL III [IF2211] STRATEGI ALGORITMA IMPLEMENTASI ALGORITMA BFS DAN A* PADA PERSOALAN LABIRIN (*MAZE PROBLEM*)



Dibuat oleh:

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PROGRAM STUDI TEKNIK INFORMATIKA SEKOLAH TEKNIK ELEKTRO DAN INFORMATIKA INSTITUT TEKNOLOGI BANDUNG 2019

BAB I

KODE PROGRAM

Pada tugas besar kali ini kami menggunakan 5 buah kode sumber dengan bahasa pemrograman Python.

1. MainProg.py

```
# Tugas Kecil 3 IF2211 Strategi Algoritma
# NIM / Nama
               : 13517048 / Leonardo
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# Nama File
               : MainProg.py
               : Memanggil algoritma A* dan BFS untuk mendapatkan path pada maze
# Deskripsi
from colorama import init
from AStar import *
from BFS import *
from EksFile import *
if __name__ == '__main__':
    init() #colorama
    try:
        file_name = str(input("Masukkan nama file yang berisi matriks(.txt): "))
        matAStar = AmbilData(file_name)
        matBFS = AmbilData(file_name)
        print("Maze =")
        matAStar.Print()
        x0 = input("Masukkan x1 dan y1 (dipisah spasi) = ")
        x1, y1= int(x0.split()[0]), int(x0.split()[1])
        x0 = input("Masukkan x2 dan y2 (dipisah spasi) = ")
        x2, y2 = int(x0.split()[0]), int(x0.split()[1])
        start_point = Point(x1, y1)
        end_point = Point(x2, y2)
        print("\nHasil Algoritma A* =")
        try:
            path = Astar(matAStar, start_point, end_point)
            for ea in path:
                matAStar.AddData(ea.getX(), ea.getY(), 2)
            matAStar.Print()
        except (TypeError):
            print("Path tidak ditemukan!")
        print("\nHasil Algoritma BFS =")
        try:
            path = BFS(matBFS, start_point, end_point)
            for ea in path:
```

```
matBFS.AddData(ea.getX(), ea.getY(), 2)
    matBFS.Print()
    except (TypeError):
        print("Path tidak ditemukan!")
    except (FileNotFoundError):
        print("File tidak ditemukan")
```

2. EksFile.py

```
# Tugas Kecil 3 IF2211 Strategi Algoritma
# NIM / Nama
               : 13517048 / Leonardo
                  13517054 / Vinsen Marselino Andreas
# Nama File
               : EksFile.py
# Deskripsi
               : Pembacaan file
from ADT import *
def AmbilData(file_name):
   list_input = []
   n \text{ kolom} = 0
    n_{baris} = 1
    check_baris = True
   mat_file = open(file_name, 'r')
   a = mat_file.read(1)
   while (a!=""):
        if(a == '1' or a == '0'):
            list_input.append(a)
            if(check_baris):
                n \text{ kolom} += 1
        elif(a == '\n'):
            n baris += 1
            check_baris = False
        a = mat_file.read(1) #baca 1 karakter
    iter_baris = 0
    iter kolom = 0
   matriks_maze = Matriks(n_baris,n_kolom)
    for i in list_input:
        matriks_maze.AddData(iter_baris,iter_kolom,i)
        iter_kolom += 1
        if(iter_kolom == n_kolom):
            iter_baris += 1
            iter_kolom = iter_kolom % n_kolom
```

3. ADT.py

```
# Tugas Kecil 3 IF2211 Strategi Algoritma
# NIM / Nama
               : 13517048 / Leonardo
                  13517054 / Vinsen Marselino Andreas
# Nama File
               : ADT.py
# Deskripsi
              : Tipe bentukan untuk Point, Matriks
from colorama import Back, Style
import numpy as np
from math import sqrt
class Point:
   def __init__(self, _x = 0, _y = 0):
        self.x = _x
        self.y = _y
   def __eq__(self, other):
        return ((self.x == other.x) and (self.y == other.y))
   def getX(self):
        return self.x
   def getY(self):
        return self.y
   @staticmethod
   def EuclideanDistance(P1, P2): #P1 dan P2 = Point
        return sqrt((P1.x - P2.x)**2 + (P1.y - P2.y)**2)
#matriks NxM
class Matriks:
   def __init__(self, _n = 0, _m = 0):
        self.N = _n
        self.M = _m
        self.data = np.zeros((self.N, self.M), dtype = int)
   def AddData(self, i, j, value):
        self.data[i][j] = value
   def getData(self, i, j):
        return self.data[i][j]
   def Print(self):
```

```
for i in range(self.N):
            for j in range(self.M):
                if (self.getData(i,j) == 1):
                    print(Back.LIGHTBLACK_EX + " ", end = " ")
                    print(Style.RESET_ALL, end = "")
                elif (self.getData(i,j) == 2):
                    print(Back.GREEN + " ", end = " ")
                    print(Style.RESET_ALL, end = "")
                else: #self.getData(i,j) == 0
                    print(Back.WHITE + " ", end = " ")
                    print(Style.RESET_ALL, end = "")
            print(Style.RESET_ALL)
class Node:
   def __init__(self, _pred = None, _position = Point()):
        self.pred = _pred
        self.position = _position
        self.toN = 0
        self.fromN = 0
   def isEqual(self, node2):
        return ((self.position.x == node2.position.x) and
                (self.position.y == node2.position.y))
   def ExistIn(self, listOfNode):
        for v in listOfNode:
            if (self.isEqual(v)):
                return True
            else:
                continue
        #sampai bagian ini jika self tidak exist di listOfNode
        return False
   def search(self, listOfNode):
        for v in listOfNode:
            if (self.isEqual(v)):
                return v.pred
            else:
                continue
        #sampai bagian ini jika self tidak exist di listOfNode
        return False
   def g(self):
        return self.toN
```

```
def h(self):
    return self.fromN

def f(self):
    return self.g() + self.h()
```

4. BFS.py

```
# Tugas Kecil 3 IF2211 Strategi Algoritma
# NIM / Nama
               : 13517048 / Leonardo
                  13517054 / Vinsen Marselino Andreas
# Nama File
               : BFS.pv
# Deskripsi
                : Implementasi algoritma BFS
from ADT import *
def BFS(maze, start, end):
    if(maze.data[start.x][start.y] == 0 and maze.data[end.x][end.y] == 0):
       visited = []
       queue = []
       curr_node = Node(None, start)
       queue.append(curr_node)
       while (queue != [] and curr_node.position != end):
            curr_node = queue.pop(0)
            prev_node = curr_node
            if(not(curr_node.ExistIn(visited))):
                visited.append(curr_node)
                if(curr_node.position.x+1 < maze.N):</pre>
                    if (maze.data[curr_node.position.x+1][curr_node.position.y] == 0):
                        next_pos = Point(curr_node.position.x+1,curr_node.position.y)
                        next_node = Node(prev_node, next_pos)
                        queue.append(next_node)
                if(curr_node.position.x-1 >= 0):
                    if (maze.data[curr_node.position.x-1][curr_node.position.y] == 0):
                        next_pos = Point(curr_node.position.x-1,curr_node.position.y)
                        next_node = Node(prev_node, next_pos)
                        queue.append(next_node)
                if(curr_node.position.y+1 < maze.M):</pre>
                    if (maze.data[curr_node.position.x][curr_node.position.y+1] == 0):
                        next_pos = Point(curr_node.position.x,curr_node.position.y+1)
                        next_node = Node(prev_node, next_pos)
                        queue.append(next_node)
                if(curr_node.position.y-1 >= 0):
                    if (maze.data[curr_node.position.x][curr_node.position.y-1] == 0):
                        next_pos = Point(curr_node.position.x,curr_node.position.y-1)
                        next_node = Node(prev_node, next_pos)
```

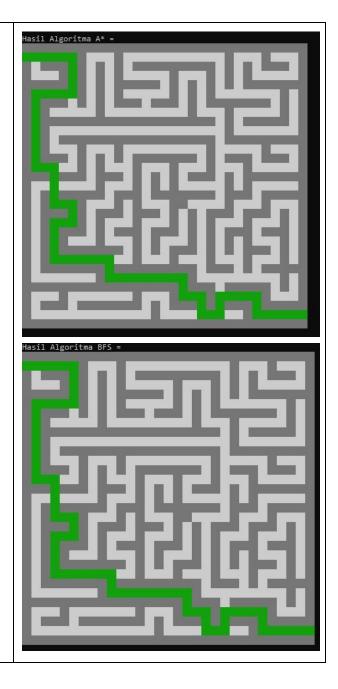
```
queue.append(next_node)
if (curr_node.position == end):
    path = [end]
    start_node = Node(None,end)
    while(start_node.position != start):
        path_node = start_node.search(visited)
        path.append(path_node.position)
        start_node = path_node
    path.append(start)
    return path[::-1]
```

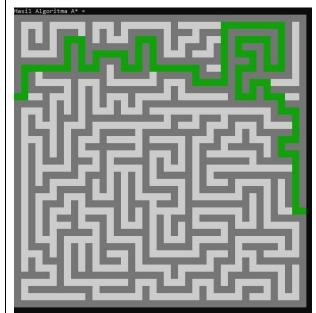
5. AStar.py

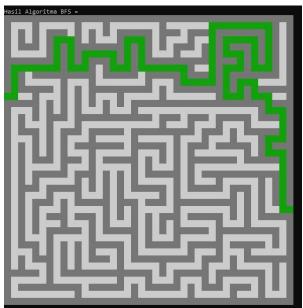
```
# Tugas Kecil 3 IF2211 Strategi Algoritma
# NIM / Nama
               : 13517048 / Leonardo
                  13517054 / Vinsen Marselino Andreas
# Nama File
               : AStar.py
# Deskripsi
               : Implementasi algoritma Astar
from ADT import *
#algoritma A Star
#matriks = Matriks
#Pstart, Pend = Point
def Astar(matriks, Pstart, Pend):
    if (Pstart.getX() != 0):
        node_start = Node(None, Pstart)
        node_end = Node(None, Pend)
        queue = []; visited = []
        queue.append(node_start)
        #selagi queue tidak kosong
        while (len(queue) > 0):
            idx = 0
            node_current = queue[0]
            for i, n in enumerate(queue):
                if (n.f() < node_current.f()):</pre>
                    idx = i
                    node_current = n
            queue.pop(idx); visited.append(node_current)
            if (node_current.isEqual(node_end)):
                path = []
                current = node current
                while current is not None:
                    path.append(current.position)
```

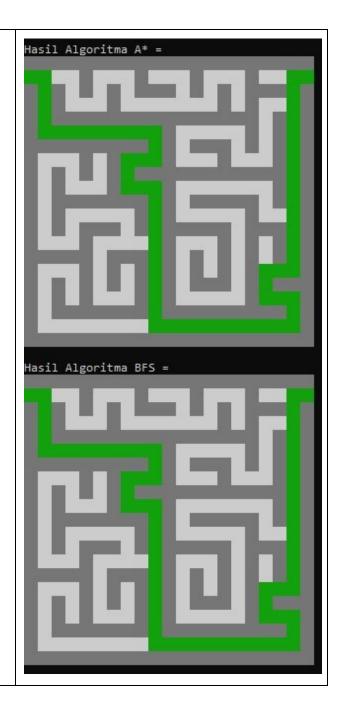
```
current = current.pred
            return path[::-1] #reversed
        melakukan perjalanan sesuai arah jalan
            0,1 = bergerak 1 ke atas
            0,-1 = bergerak 1 ke bawah
            1,0 = bergerak 1 ke kanan
            -1,0 = bergerak 1 ke kiri
        arah_jalan = [(0, 1), (0, -1), (1, 0), (-1, 0)]
        successor = []
        for arah in arah_jalan:
            temp_pos = Point(node_current.position.getX() + arah[0],
                            node_current.position.getY() + arah[1])
            if ((temp_pos.getX() < matriks.N) and</pre>
                (temp_pos.getX() >= 0) and
                (temp_pos.getY() < matriks.M) and</pre>
                (temp_pos.getY() >= 0)):
                #valid (ada di dalam maze)
                if (matriks.getData(temp_pos.getX(), temp_pos.getY()) == 0):
                    #ada jalan
                    node_new = Node(node_current, temp_pos)
                    successor.append(node_new)
        for each in successor:
            if (not each.ExistIn(visited)):
                each.toN = node\_current.g() + 1
                each.fromN = Point.EuclideanDistance(each.position, Pend)
                if (not each.ExistIn(queue)):
                    queue.append(each)
else: #Pstart tidak dimulai dari jalan yang ada
    raise TypeError
```

BAB II LABIRIN INPUT DAN SCREENSHOT HASIL









11111111111	Masukkan x1 dan y1 (dipisah spasi) = 2 0
100000000001	Masukkan x2 dan y2 (dipisah spasi) = 10 10
001111110111	Hasil Algoritma A* =
101000000001	Path tidak ditemukan!
101011111101	Hasil Algoritma BFS =
101010000001	Path tidak ditemukan!
100011011101	
101000010111	
101111000001	
101011111111	
100011000001	
111111011111	

BAB III TABEL PENILAIAN

1	Program dapat menerima input labirin	~
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2	Program dapat mencari lintasan dengan Algoritma BFS	~
3	Program dapat mencari lintasan dengan Algoritma A*	~
4	Program dapat menampilkan lintasan di dalam labirin dengan algoritma BFS	~
5	Program dapat menampilkan lintasan di dalam labirin dengan algoritma a*	~

BAB IV DAFTAR PUSTAKA

 $\frac{http://informatika.stei.itb.ac.id/\sim rinaldi.munir/Stmik/2018-2019/Tucil3-Stima-2019.pdf}{http://informatika.stei.itb.ac.id/\sim rinaldi.munir/Stmik/2018-2019/BFS-dan-DFS-(2019).pdf}{http://informatika.stei.itb.ac.id/\sim rinaldi.munir/Stmik/2017-2018/A-Star-Best-FS-dan-UCS-(2018).pdf}$