

# The Empirical Distribution Function and Plug-in Principle

Mingu Qiu

January 4, 2018

## 1 Introduction

- Problems of statistical inference often involve estimating some aspect of a probability distribution  $F$  on the basis of a random sample drawn from  $F$ .
- The *empirical distribution function*, which we will call  $\hat{F}$ , is a simple estimate of the entire distribution  $F$ .
- An obvious way to estimate some interesting aspect of  $F$ , like its mean or median or correlation, is to use the corresponding aspect of  $F$ . This is the "*plug-in principle*."

## 2 The Empirical Distribution Function

**Definition 2.1.** Let  $X_1, X_2, \dots, X_n \stackrel{\text{i.i.d.}}{\sim} F$ . The *empirical distribution function* is defined as

$$\hat{F}(x) = \frac{\text{number of elements in the sample} \leq x}{n} = \frac{1}{n} \sum_{i=1}^n \mathbb{1}_{\{X_i \leq x\}},$$

where  $\mathbb{1}$  is the indicator function.

In other words, the value of the empirical distribution function at a given point  $x$  is obtained by:

1. counting the number of observations that are less than or equal to  $x$ ;
2. dividing the number thus obtained by the total number of observations, so as to obtain the proportion of observations that is less than or equal to  $x$ .

**Example 2.1.** Suppose we observe a sample made of 4 observations:  $x_1 = 3, x_2 = 2, x_3 = 5, x_4 = 2$ . What is the value of the empirical distribution function of the sample at the point  $x = 4$ ?

According to the definition above, it is

$$\begin{aligned}
 \hat{F}(3) &= \frac{1}{4} \sum_{i=1}^4 \mathbb{1}_{\{x_i \leq 3\}} \\
 &= \frac{1}{4} \left( \mathbb{1}_{\{x_1 \leq 3\}} + \mathbb{1}_{\{x_2 \leq 3\}} + \mathbb{1}_{\{x_3 \leq 3\}} + \mathbb{1}_{\{x_4 \leq 3\}} \right) \\
 &= \frac{1}{4} (1 + 1 + 0 + 1) \\
 &= \frac{3}{4}
 \end{aligned}$$

*Note.* It's simply the distribution function of a discrete random variable that places mass  $1/n$  in the points  $X_1, \dots, X_n$  (provided all these are distinct). Namely, the p.m.f. of the empirical distribution is:

$$\Pr(x) = \begin{cases} \frac{1}{n} & \text{if } x = x_{(1)}, \\ \frac{1}{n} & \text{if } x = x_{(2)}, \\ \vdots & \\ \frac{1}{n} & \text{if } x = x_{(n)}, \\ 0 & \text{otherwise.} \end{cases}$$

where  $x_{(1)}, x_{(2)}, \dots, x_{(n)}$  are the sample observations ordered from the smallest to the largest. Then it is easy to see that the empirical distribution function can be written as

$$\hat{F}(x) = \begin{cases} 0 & \text{if } x < x_{(1)}, \\ \frac{1}{n} & \text{if } x_{(1)} \leq x < x_{(2)}, \\ \frac{2}{n} & \text{if } x_{(2)} \leq x < x_{(3)}, \\ \vdots & \\ \frac{n-1}{n} & \text{if } x_{(n-1)} \leq x < x_{(n)}, \\ 1 & \text{if } x \geq x_{(n)}. \end{cases}$$

**Example 2.2.** The table below shows a random sample of  $n = 100$  rolls of a die:  $x_1 = 6, x_2 = 3, \dots, x_{100} = 6$ . The empirical distribution function  $\hat{F}$  put probability  $1/100$  on each of the 100 outcomes. In cases like this, where there are repeated values, we can express  $\hat{F}$  as the vector of observed frequencies  $\hat{f}_k, k = 1, 2, \dots, 6$ ,

$$\hat{f}_k = \#\{x_i = k\}/n.$$

So the empirical distribution is  $(.13, .19, .10, .17, .14, .27)$ .

```

6 3 2 4 6 6 6 5 3 6 2 2 6 2 3 1 5 1
6 6 4 1 5 3 6 6 4 1 4 2 5 6 6 5 5 3
6 2 6 6 1 4 1 5 6 1 6 3 3 2 2 2 5 2
2 4 1 4 5 6 6 6 2 2 4 6 1 2 2 2 5 1
5 3 5 4 2 1 4 6 6 5 6 4 6 4 3 6 4 1
4 5 4 4 2 3 2 1 4 6

```

R provides the very useful function `ecdf()` for working with the empirical distribution function.

```

> data <- read.delim("die.txt")
> Fhat <- ecdf(data$outcome)
> Fhat(1)
[1] 0.13
> Fhat(6)
[1] 1
> summary(Fhat)
Empirical CDF: 6 unique values with summary
Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
1.00   2.25   3.50   3.50   4.75   6.00
> plot(Fhat, verticals = T, do.points = F)

```

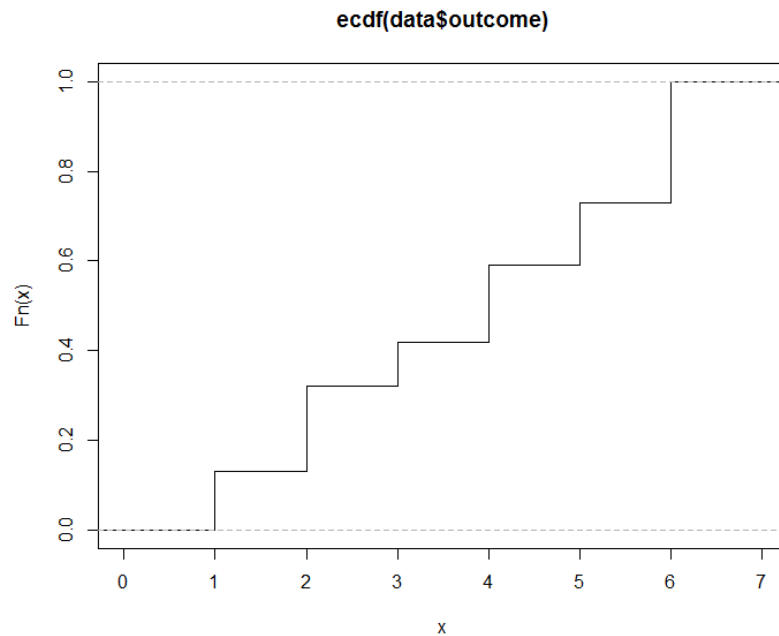


Figure 1: Empirical Distribution Function

**Proposition 2.1.** For a fixed (but arbitrary) point  $x \in \mathbb{R}$  we have that  $n\hat{F}(x) \sim B(n, F(x))$  and

$$\mathbb{E}(\hat{F}(x)) = F(x) \quad \text{and} \quad \text{Var}(\hat{F}(x)) = \frac{F(x)(1 - F(x))}{n}.$$

*Proof.* Since  $\sum_{i=1}^n \mathbb{1}_{\{X_i \leq x\}}$  is the sum of  $n$  independent Bernoulli random variables with success probability  $p = F(x)$ , therefore

$$n\hat{F}(x) = \sum_{i=1}^n \mathbb{1}_{\{X_i \leq x\}} \sim B(n, F(x)).$$

Hence

$$\mathbb{E}(\hat{F}(x)) = \frac{\mathbb{E}(n\hat{F}(x))}{n} = \frac{nF(x)}{n} = F(x)$$

and

$$\text{Var}(\hat{F}(x)) = \frac{\text{Var}(n\hat{F}(x))}{n^2} = \frac{nF(x)(1 - F(x))}{n^2} = \frac{F(x)(1 - F(x))}{n}.$$

□

This implies that:

**Proposition 2.2.** For a fixed (but arbitrary) point  $x \in \mathbb{R}$ ,

- a.  $\hat{F}(x) \xrightarrow{P} F(x) \quad \text{as } n \rightarrow \infty;$
- b.  $\hat{F}(x) \xrightarrow{\text{a.s.}} F(x) \quad \text{as } n \rightarrow \infty;$
- c.  $\sqrt{n}(\hat{F}(x) - F(x)) \xrightarrow{d} N(0, F(x)(1 - F(x))) \quad \text{as } n \rightarrow \infty.$

*Proof.* The first statement of the proposition follows simply by Chebyshev's inequality: for any  $\epsilon > 0$

$$\Pr\{|\hat{F}(x) - F(x)| \geq \epsilon\} \leq \frac{F(x)(1 - F(x))}{n\epsilon^2}.$$

The second statement follows by the strong law of large numbers. Since  $\mathbb{1}_{\{X_i \leq x\}}$  is Bernoulli random variable with success probability  $p=F(x)$ , then

$$\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{1}_{\{X_i \leq x\}} \xrightarrow{\text{a.s.}} \mu = F(x).$$

where  $n$  is the sample size.

The last statement follows by the central limit theorem. □

*Note.* The above results were all about *pointwise* convergence. That is, we examined what happens to  $\hat{F}(x)$  for a fixed point  $x \in \mathbb{R}$ .

There is a stronger result than, called the Glivenko-Cantelli theorem, which states that the convergence in fact happens *uniformly* over  $\mathbb{R}$ :

**Theorem 2.1** (Glivenko-Cantelli Theorem). <sup>1</sup> *The empirical distribution function  $\hat{F}(x)$  converges uniformly to  $F(x)$ , namely*

$$\sup_{x \in \mathbb{R}} |\hat{F}(x) - F(x)| \xrightarrow{\text{a.s.}} 0,$$

as  $n \rightarrow \infty$ .

### 3 Parameter and Statistic

- A *parameter* is a function of the probability distribution  $F$ .
- A *statistic* is a function of the sample  $x$ .

Thus  $f_k$  is a parameter of  $F$  in the die example, while  $\hat{f}_k$  is a statistic,  $k = 1, 2, \dots, 6$ .

We will sometimes write parameters directly as functions of  $F$  as follow :

$$\theta = t(F).$$

For example, if  $F$  is a probability distribution in the real line, the expectation can be thought of as the parameter

$$\theta = t(F) = E_F(x).$$

For a given distribution  $F$  such as  $B(n, p)$ , we can evaluate  $E_F(x) = t(F) = np$ .

### 4 Plug-in Principle

The plug-in principle is a simple method of estimating parameters from samples.

The plug-in estimate of a parameter  $\theta = t(F)$  is defined to be

$$\hat{\theta} = t(\hat{F}),$$

obtained by replacing the distribution function  $F$  with the empirical distribution function  $\hat{F}$ .

**Example 4.1** (the mean). Let  $\mu = \mathbb{E}_F(X) = \sum_{i=1}^n x_i p(x_i)$  be the mean of the distribution  $F$ . Then the plug-in estimator of  $\mu$  is

$$\hat{\mu} = E_{\hat{F}}(X) = \sum_{i=1}^n X_i \hat{p}(X_i) = \sum_{i=1}^n X_i \frac{1}{n} = \bar{X},$$

where  $p(X)$  is the pmf of  $F$  and  $\hat{p}(X_i) = 1/n, i = 1, 2, \dots, n$ .

---

<sup>1</sup>This theorem originates with Valery Glivenko and Francesco Cantelli in 1933.

**Example 4.2** (the variance). Let  $\sigma^2 = Var_F(X) = \mathbb{E}_F(X^2) - (\mathbb{E}_F(X))^2$  denote the variance of  $X$ . The plug-in estimator for  $\sigma^2$  is

$$\hat{\sigma}^2 = Var_{\hat{F}}(X) = \mathbb{E}_{\hat{F}}(X^2) - (\mathbb{E}_{\hat{F}}(X))^2 = \frac{1}{n} \sum_{i=1}^n X_i^2 - \bar{X}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2.$$

**Example 4.3** (the median). Define  $F^{-1}(y) = \inf\{x : F(x) \geq y\}$  and  $F^{-1}(y+) = \inf\{x : F(x) > y\}$ . Let  $\theta = F^{-1}(1/2)$ . The median of distribution  $F$  can be denoted by

$$\theta = \frac{F^{-1}(1/2) + F^{-1}(1/2+)}{2},$$

then the plug-in estimator of the median is

$$\hat{\theta} = \frac{\hat{F}^{-1}(1/2) + \hat{F}^{-1}(1/2+)}{2} = \begin{cases} X_{(\frac{n+1}{2})} & \text{if } n \text{ is odd} \\ X_{(\frac{n}{2})} + X_{(\frac{n}{2}+1)} & \text{if } n \text{ is even} \end{cases}.$$

**Example 4.4.** The law school population  $F$  can be written as  $F = (f_1, f_2, \dots, f_{82})$ . The population correlation coefficient can be written as

$$corr(y, z) = \frac{\sum_{j=1}^{82} f_j(Y_j - \mu_y)(Z_j - \mu_z)}{[\sum_{j=1}^{82} f_j(Y_j - \mu_y)^2 \sum_{j=1}^{82} f_j(Z_j - \mu_z)^2]^{1/2}} \quad (1)$$

where

$$\mu_y = \sum_{j=1}^{82} f_j Y_j, \mu_z = \sum_{j=1}^{82} f_j Z_j. \quad (2)$$

Now for the sample of 1,  $\hat{f}_1 = 0, \hat{f}_2 = 0, \hat{f}_3 = 0, \hat{f}_4 = 1/15$  etc. Plugging these values  $\hat{f}_j$  into (1) and (2) gives  $\hat{\mu}_y, \hat{\mu}_z$  and  $\hat{corr}(y, z)$  respectively. That is,  $\hat{\mu}_y, \hat{\mu}_z$  and  $\hat{corr}(y, z)$  are *plug-in* estimates of  $\mu_y, \mu_z$  and  $corr(y, z)$ .

## 5 How good is the plug-in principle?

- It is usually quite good, if the only available information about  $F$  comes from the sample  $x$ .
- However, the plug-in principle is less good in situations where there is information about  $F$  other than provided by the sample  $x$ .

## A Appendix

### A1. Chebyshev's inequality

Let  $X$  be a random variable and  $c$  be a positive constant, then

$$\Pr\{|X - \mu| \geq c\sigma\} \leq \frac{1}{c^2},$$

where  $\mu = \mathbb{E}(X)$  and  $\sigma^2 = Var(X)$ .

School	LAST	GPA	School	LAST	GPA
1	576	3.39	9	651	3.36
2	635	3.30	10	605	3.13
3	558	2.81	11	653	3.12
4	578	3.03	12	575	2.74
5	666	3.44	13	545	2.76
6	580	3.07	14	572	2.88
7	555	3.00	15	594	2.96
8	661	3.43			

Table 1: *The law school data. A random sample of size  $n=15$  was taken from the collection of  $N=82$  American law schools participating in a large study of admission practices. Two measurements were made on the entering classes of each school in 1973: LAST, the average score for the class on a national law test, and GPA, the average undergraduate grade-point average for the class.*

#### A2. The strong law of large numbers

Assume that  $\{X_n\}_{n=1}^{\infty}$  is a sequence of i.i.d random variables with  $\mathbb{E}(X_n) = \mu \leq \infty$ . Let  $\bar{X}_n = \sum_{i=1}^n X_i/n$ , then

$$\bar{X}_n \xrightarrow{a.s.} \mu.$$

#### A3. The central limit theorem

Let  $\{X_n\}_{n=1}^{\infty}$  be a sequence of i.i.d. random variables with common mean  $\mu$  and common variance  $\sigma^2 > 0$ . Let  $\bar{X}_n = \sum_{i=1}^n X_i/n$  and  $Y_n = \sqrt{n}(\bar{X}_n - \mu)/\sigma$ , then

$$Y_n \xrightarrow{d} Z,$$

where  $Z \sim N(0, 1)$ .

#### A4. Converge in Probability

A sequence of random variables  $\{X_n\}_{n=1}^{\infty}$  is said to converge in probability to a random variable  $X$ , denote by  $X_n \xrightarrow{P} X$ , if for any  $\epsilon > 0$ ,

$$\lim_{n \rightarrow \infty} \Pr\{|X_n - X| \geq \epsilon\} = 0.$$