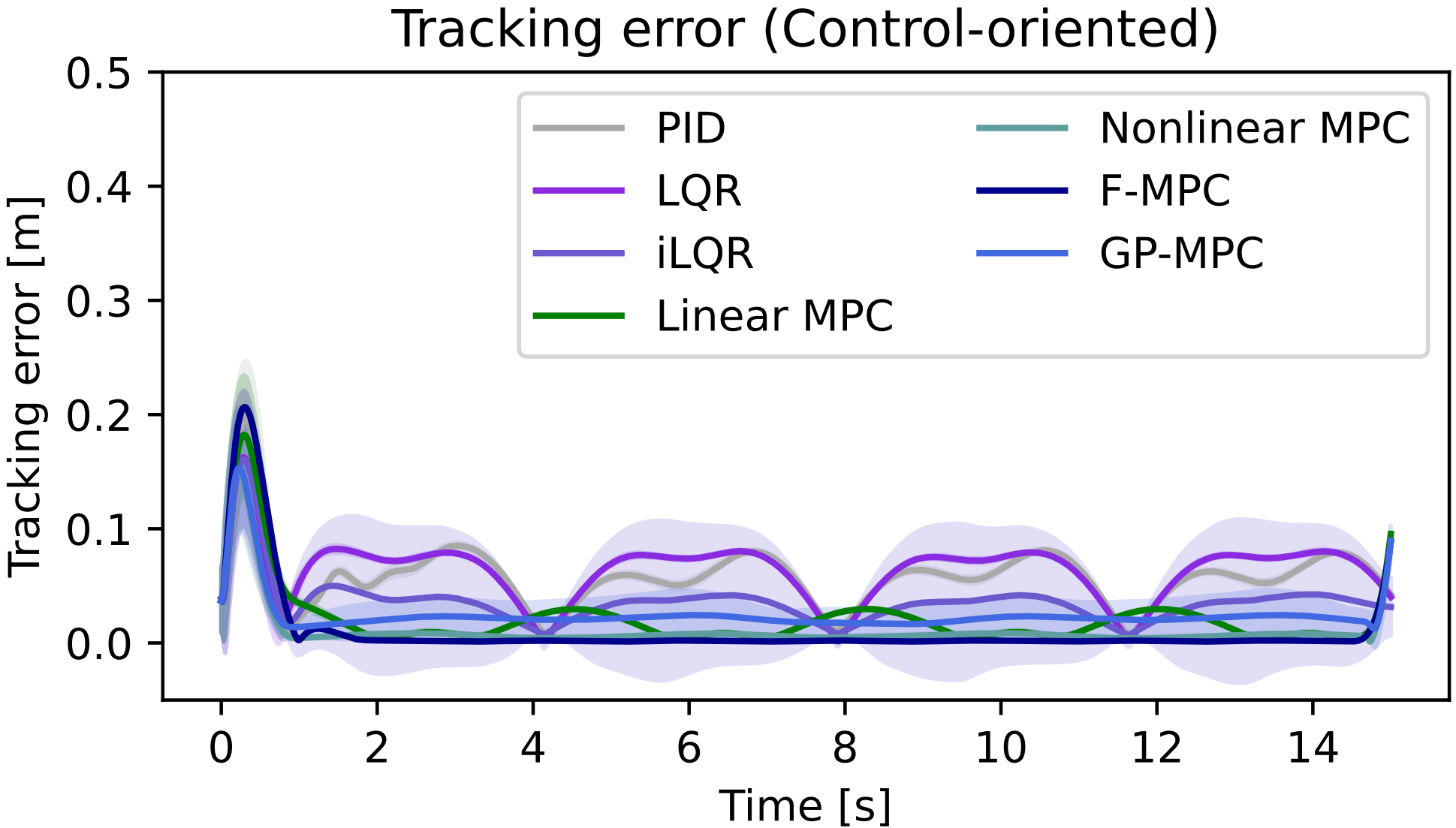
Tracking error (Control-oriented)
PID
LQR
iLQR
Linear MPC
Nonlinear MPC
F-MPC
GP-MPC
Tracking error [m]
Time [s]
0.5
0.4
0.3
0.2
0.1
0.0
0
2
4
6
8
10
12
14