Họ tên: Nguyễn Quang Minh

MSSV: 201404024

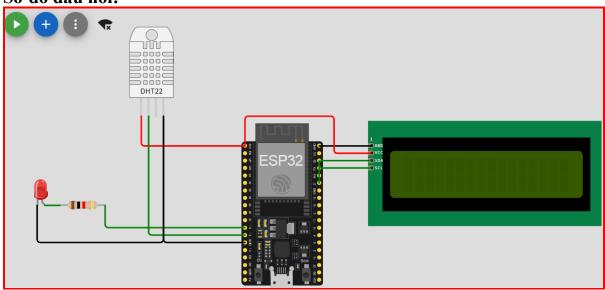
Lớp: Điện tử và tin học công nghiệp 1

Các project

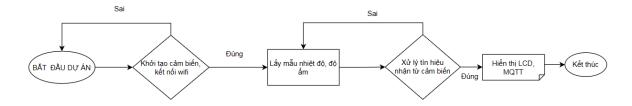
Project 1: Sử dụng giao thức MQTT gửi dữ liệu nhiệt độ, độ ẩm và hiển thị lcd sử dụng vi điều khiển esp32

Bài làm

• Sơ đồ đấu nối:



• Thuật toán:



• Code:

import network

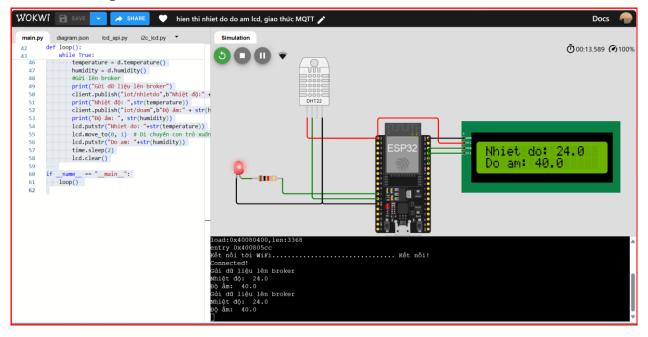
import time import dht from umqtt.simple import MQTTClient import machine from machine import Pin, SoftI2C from utime import sleep_us,sleep from lcd_api import LcdApi

```
from i2c_lcd import I2cLcd
I2C ADDR = 0x27
totalRows = 2
totalCol = 14
led = Pin(14,Pin.OUT)
d = dht.DHT22(Pin(12))
i2c = SoftI2C(scl = Pin(22), sda = Pin(21), freq = 10000)
lcd = I2cLcd(i2c, I2C_ADDR, totalRows, totalCol)
print("Kêt nối tới WiFi", end="")
sta_if = network.WLAN(network.STA_IF)
sta if.active(True)
sta_if.connect('Wokwi-GUEST', ")
while not sta_if.isconnected():
 print(".", end="")
 time.sleep(0.1)
print(" Kết nối!")
# MQTT Server Parameters
client_id="Nguyen Quang Minh"
server = "broker.hivemq.com"
client = MQTTClient(client_id, server)
client.connect()
print("Connected!")
def loop():
  while True:
    d.measure()
    led.on()
    temperature = d.temperature()
    humidity = d.humidity()
    #Gửi lên broker
    print("Gửi dữ liệu lên broker")
    client.publish("iot/nhietdo",b"Nhiệt độ:" + str(temperature))
    print("Nhiệt độ: ",str(temperature))
    client.publish("iot/doam",b"Độ ẩm:" + str(humidity))
    print("Độ ẩm: ", str(humidity))
    lcd.putstr("Nhiet do: "+str(temperature))
```

```
lcd.move_to(0, 1) # Di chuyển con trỏ xuống dòng thứ 2
lcd.putstr("Do am: "+str(humidity))
    time.sleep(2)
    lcd.clear()

if __name__ == "__main__":
    loop()
```

• Kết quả

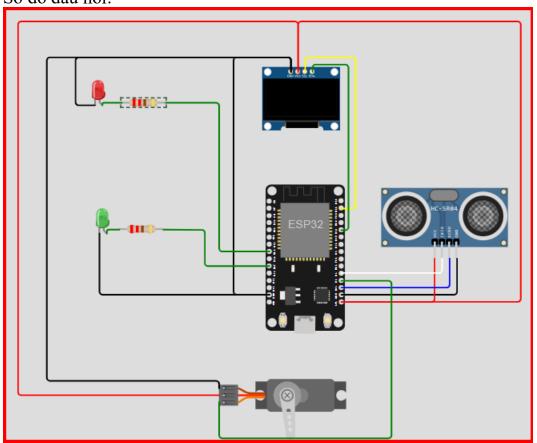


• Link mô phỏng: https://wokwi.com/projects/397511081437933569

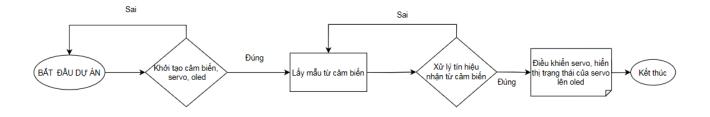
Project 2: Điều khiển đóng mở cổng sử dụng servo và cảm biến siêu âm HC-SR04 và hiển thị trạng thái đóng mở cổng lên màn hình Oled

Bài làm

Sơ đồ đấu nối:



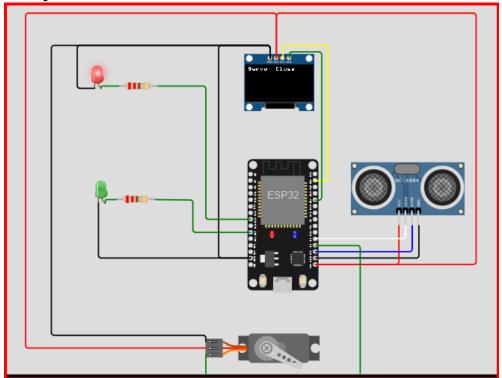
• Thuật toán



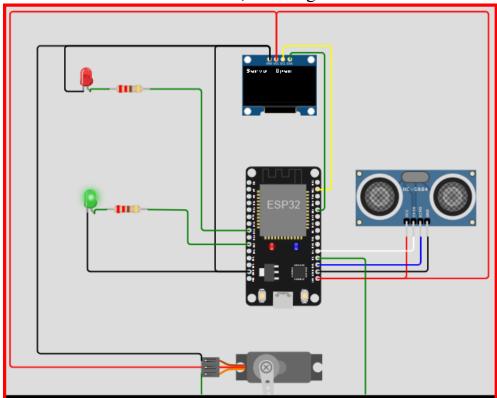
• Code

```
import time
from machine import Pin, PWM, I2C
from SSD1306 import SSD1306_I2C
from HCSR04 import HCSR04
i2c = I2C(0, scl=Pin(22), sda=Pin(21))
oled = SSD1306\_I2C(128, 64, i2c)
red_led = PWM(Pin(25), freq=1000, duty=0)
green\_led = PWM(Pin(27), freq=1000, duty=0)
pwm_servo = PWM(Pin(2), freq=50, duty=0) # Assuming the servo is
sensor = HCSR04(trigger_pin=4, echo_pin=15)
def control_servo_and_leds(distance):
  if distance < 100: # mở cửa
    pwm_servo.duty(120)
    green_led.duty(500)
    red_led.duty(0)
    oled.fill(0)
    oled.text("Servo: Open", 0, 0)
    oled.show()
  else: # đóng cửa
    pwm_servo.duty(90)
    red_led.duty(500)
    green_led.duty(0)
    oled.fill(0)
    oled.text("Servo: Close", 0, 0)
    oled.show()
while True:
  try:
    distance = sensor.distance_cm()
    control_servo_and_leds(distance)
    time.sleep(0.1)
  except OSError:
    print("Sensor error")
```

• Kết quả



Khi servo mở với điều kiện khoảng cách nhỏ hơn 100cm



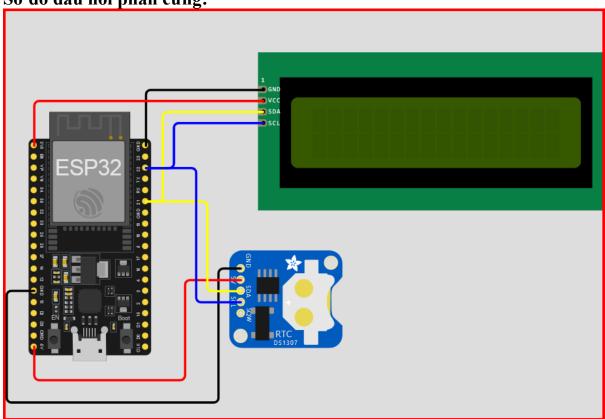
Khi servo đóng với điều kiện khoảng cách lớn hơn 100cm

• Link mô phỏng: https://wokwi.com/projects/391237865000997889

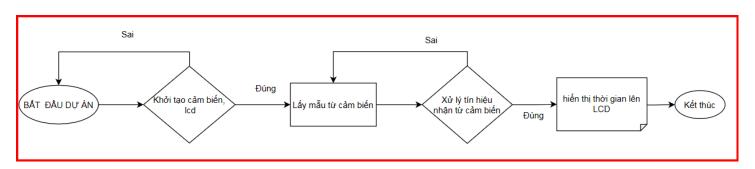
Project 3: Hiển thị đồng hồ thời gian thực sử dụng module RTC-ds1307 hiển thị LCD

Bài làm

Sơ đồ đấu nối phần cứng:



• Thuật toán

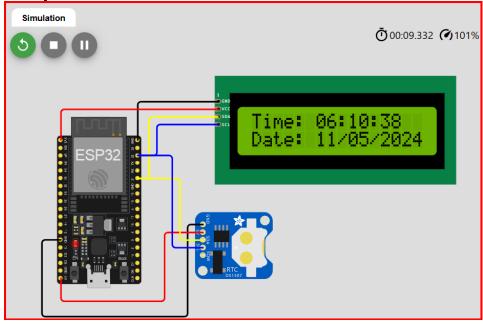


• Code

from machine import Pin, SoftI2C, RTC import ds1307 import time from lcd_api import LcdApi from i2c_lcd import I2cLcd

```
i2c0 = SoftI2C(scl=Pin(22), sda=Pin(21), freq=100000)
i2c_{lcd} = SoftI2C(scl=Pin(22), sda=Pin(21), freq=10000)
I2C ADDR = 0x27
totalRows = 2
totalCol = 16
lcd = I2cLcd(i2c_lcd, I2C_ADDR, totalRows, totalCol)
ds1307rtc = ds1307.DS1307(i2c0, 0x68)
ds1307rtc.disable_oscillator = True
print("disable_oscillator = ", ds1307rtc.disable_oscillator)
ds1307rtc.disable_oscillator = False
print("disable_oscillator = ", ds1307rtc.disable_oscillator, "\n")
while True:
  dt = ds 1307rtc.datetime
  lcd.clear()
  lcd.move\_to(0, 0)
  lcd.putstr("Time: {:02d}:{:02d}:(:02d)".format(dt[6], dt[4], dt[5]))
  lcd.move to(0, 1)
  lcd.putstr("Date: {:02d}/{:02d}/{:04d}".format(dt[2], dt[1], dt[0]))
  time.sleep(1)
```

Kết quả

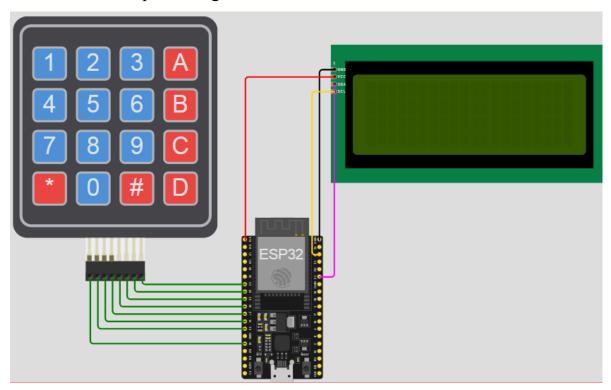


• Link mô phỏng: https://wokwi.com/projects/397551128074201089

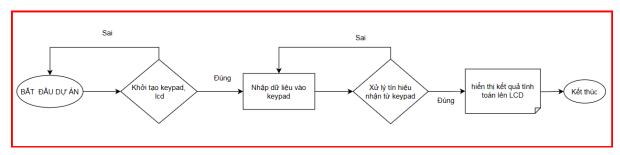
Project 4: làm máy tính cầm tay từ Keypad, LCD

Bài làm

Sơ đồ đấu nối phần cứng



Thuật toán



Code

from time import sleep_ms from machine import Pin, SoftI2C from i2c_lcd import I2cLcd

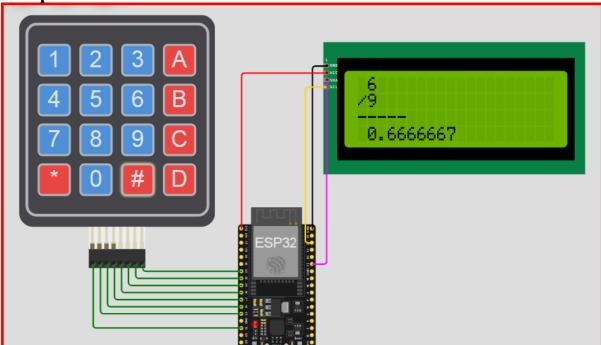
AddressOfLcd = 0x27 i2c = SoftI2C(scl=Pin(22), sda=Pin(21), freq=400000) # connect scl to GPIO 22, sda to GPIO 21 lcd = I2cLcd(i2c, AddressOfLcd, 4, 20)

```
keypad = [
  ['1', '2', '3', '+'],
  ['4', '5', '6', '-'],
  ['7', '8', '9', '*'],
  ['C', '0', '=', '/']
1
row_pins = [Pin(13, Pin.OUT), Pin(12, Pin.OUT), Pin(14, Pin.OUT), Pin(27, Pin.OUT)]
Pin.OUT)]
col_pins = [Pin(26, Pin.IN, Pin.PULL_UP), Pin(25, Pin.IN, Pin.PULL_UP),
Pin(33, Pin.IN, Pin.PULL_UP), Pin(32, Pin.IN, Pin.PULL_UP)]
for row_pin in row_pins:
  row_pin.value(1)
for col_pin in col_pins:
  col_pin.value(0)
user_input = ""
result = None
math_sign = ""
sign_applied = False
def pad_string(input_string, desired_length = 15):
  current_length = len(input_string)
  if current_length >= desired_length:
     return input_string
  spaces_needed = desired_length - current_length
  padded_string = input_string + " " * spaces_needed
  return padded_string
def lcd_print(row, value, start_col = 1, space_padding = True):
  print("move to : " + str(row))
  lcd.move_to(start_col,row)
  if space_padding:
     lcd.putstr(pad_string(str(value)))
     lcd.putstr(str(value))
```

```
def get_key():
  keys_detected = []
  for i, row_pin in enumerate(row_pins):
     row_pin.value(0)
     for j, col_pin in enumerate(col_pins):
       if col_pin.value() == 0:
          keys_detected.append(keypad[i][j])
          return keypad[i][j]
     row_pin.value(1)
  return None
def evaluate_expression():
  global user_input
  global result
  global math_sign
  try:
     calc_result = float(result)
  except ValueError:
     calc_result = 0.0
     print("Invalid Result float format: " + result)
  try:
     calc_user_input = float(user_input)
  except ValueError:
     calc\_user\_input = 0.0
     print("Invalid User Input format: " + user_input)
  try:
     return str(eval(str(calc_result) + " " + str(math_sign) + " " +
str(user_input)))
  except:
     return "Error"
def keyboard_scan():
  global user_input
  global result
  global math_sign
  global sign_applied
```

```
key = get key()
  if key is not None:
     if key == 'C':
       user_input = "
       result = None
       lcd.clear()
       math_sign = ""
       sign_applied = False
       lcd_print(2, "----", 0, False)
     elif key == '=':
       try:
          if user_input:
            result = evaluate_expression()
            #result = evaluate_expression(result if result is not None else "" +
math_sign + user_input)
            lcd_print(3, " " if result is None else str(result))
            user_input = "" # Clear input after result is calculated
       except Exception as e:
          print("Error Occured: ", e)
     elif key == '+' or key == '-' or key == '*' or key == '/':
       math\_sign = key
       lcd_print(1, key, 0, False)
       result = user_input if sign_applied == False else result
       user_input = ""
       sign applied = True
     else:
       user_input += key
       lcd_input_row = 0 if sign_applied == False else 1
       lcd_print(lcd_input_row, str(user_input))
  sleep_ms(100)
lcd_print(2, "----", 0, False)
while True:
  keyboard_scan()
```

• Kết quả

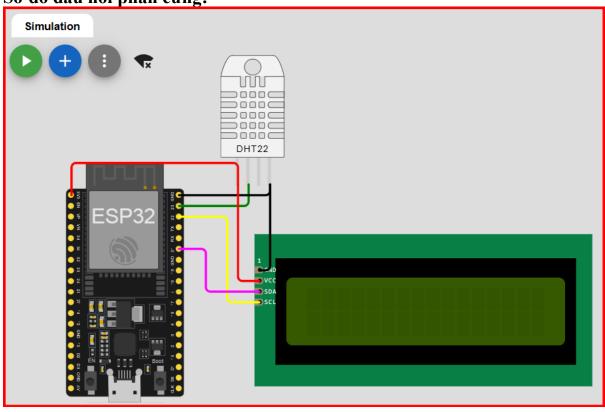


• Link mô phỏng: https://wokwi.com/projects/397559905813595137

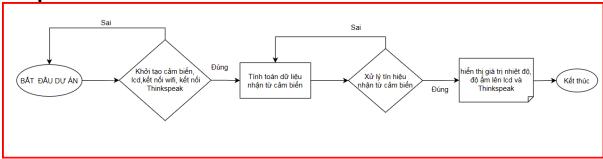
Project 5: Gửi dữ liệu từ cảm biến DHT11 lên Thinkspeak và hiển thị giá trị nhiệt độ, độ ẩm lên LCD.

Bài làm

Sơ đồ đấu nối phần cứng:



• Thuật toán:

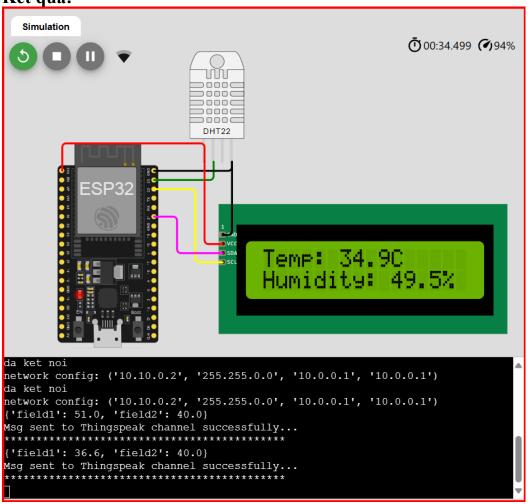


• Code

```
from machine import Pin, Timer, SoftI2C
import network
import urequests
import time
import sys
from dht import DHT22
from i2c_lcd import I2cLcd
dht22 = DHT22(Pin(23))
I2C ADDR = 0x27
totalRows = 2
totalCol = 16
i2c = SoftI2C(scl=Pin(22), sda=Pin(21), freq=10000)
lcd = I2cLcd(i2c, I2C_ADDR, totalRows, totalCol)
# Connect with WiFi
import network
WIFI SSID = "Wokwi-GUEST"
WIFI PASSWORD = ""
def connect_wifi():
  wifi = network.WLAN(network.STA_IF)
  wifi.active(True)
  wifi.disconnect()
  wifi.connect(WIFI_SSID,WIFI_PASSWORD)
  if not wifi.isconnected():
    print('dang ket noi...')
    timeout = 0
    while (not wifi.isconnected() and timeout < 10):
       print(10 - timeout)
```

```
timeout = timeout + 1
      time.sleep(1)
  if(wifi.isconnected()):
    print('da ket noi')
  else:
    print('khong ket noi')
    sys.exit()
  print('network config:', wifi.ifconfig())
connect_wifi()
# Main function
def main():
  connect wifi()
  # Thingspeak HTTP API Protocol (Connection)
  HTTP_HEADERS = {'Content-Type': 'application/json'}
  THINGSPEAK WRITE API KEY = 'P71Z0G5D2PHSAJLX' //thay đổi
theo api của từng người sử dụng
  while True:
    time.sleep(5)
    # đọc giá trị cảm biến DHT11
    dht22.measure()
    temp = dht22.temperature()
    hum = dht22.humidity()
    # Hiển thị LCD
    lcd.clear()
    lcd.putstr("Temp: {}C\n".format(temp))
    lcd.putstr("Humidity: {}%".format(hum))
    dht_readings = {'field1': temp, 'field2': hum}
    # gửi dữ liệu lên Thingspeak
    request = urequests.post('http://api.thingspeak.com/update?api_key=' +
THINGSPEAK_WRITE_API_KEY,
                  json=dht_readings, headers=HTTP_HEADERS)
    request.close()
    print(dht_readings)
    print("Msg sent to Thingspeak channel successfully...")
    if __name__ == "__main__":
  main()
```

• Kết quả:





• Link mô phỏng: https://wokwi.com/projects/397602690620212225

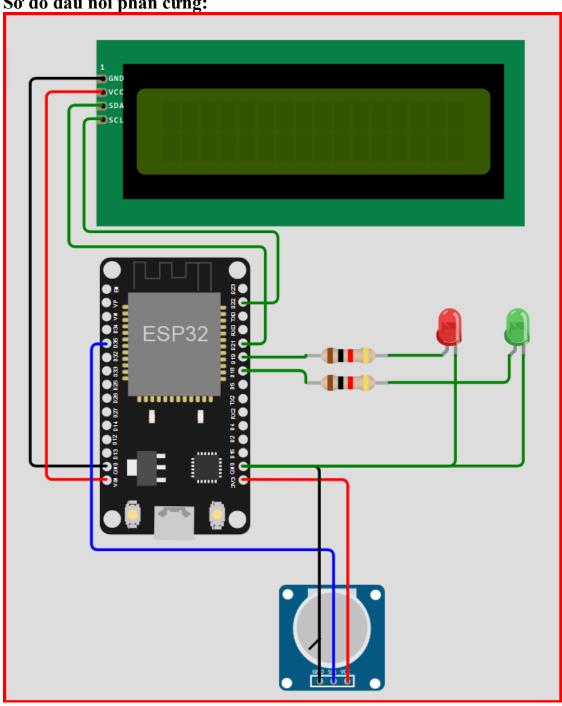
Project 6:

Câu 2:

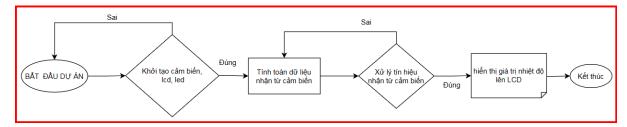
Vẽ sơ đồ ghép nối ESP32 với LCD 1602 và 1 biến trở. Viết chương trình bằng Micropython đọc giá trị đo từ ADC khi vặn thay đổi giá trị của biến trở và hiển thị trên LCD. Kết nối 2 led đơn hiển trị trên và dưới ngưỡng nhiệt độ đặt.

Bài làm

Sơ đồ đấu nối phần cứng:



Thuật toán



```
Code:
from machine import Pin, ADC, I2C
from time import sleep_ms
from lcd_i2c_esp32 import I2cLcd
# Define pin numbers for the LEDs
led1_pin = 19
led2_pin = 18
# Define the I2C address of the LCD
DEFAULT_{I2C}ADDR = 0x27
# Initialize I2C communication
i2c = I2C(0, scl=Pin(22), sda=Pin(21), freq=400000)
# Initialize the LCD
lcd = I2cLcd(i2c, DEFAULT_I2C_ADDR, 2, 16)
# Initialize ADC for temperature reading
adc = ADC(Pin(34)) # Assuming the temperature sensor is connected to pin
34
# Function to map temperature to LED states
def map_temperature_to_led_states(temperature):
  # Map temperature in the range of 0-100 degrees Celsius to LED states
  if temperature <= 50:
    return (1, 0) # LED 1 on, LED 2 off
  else:
    return (0, 1) # LED 1 off, LED 2 on
while True:
  # Read the analog value from the temperature sensor
  temperature_adc = adc.read()
```

```
# Convert the ADC value to temperature in Celsius (assuming linear
relationship)
  temperature_celsius = temperature_adc * (100 / 4095) # Assuming ADC
is 12-bit
  # Map temperature to LED states
  led1_state, led2_state =
map_temperature_to_led_states(temperature_celsius)
  # Control LEDs based on states
  led1 = Pin(led1_pin, Pin.OUT)
  led2 = Pin(led2_pin, Pin.OUT)
  led1.value(led1_state)
  led2.value(led2_state)
  # Display temperature on LCD
  lcd.clear()
  lcd.move\_to(0, 0)
  lcd.putstr("Temp: {:.1f} C".format(temperature_celsius))
  # Wait for a short duration before repeating the process
  sleep_ms(1000)
```

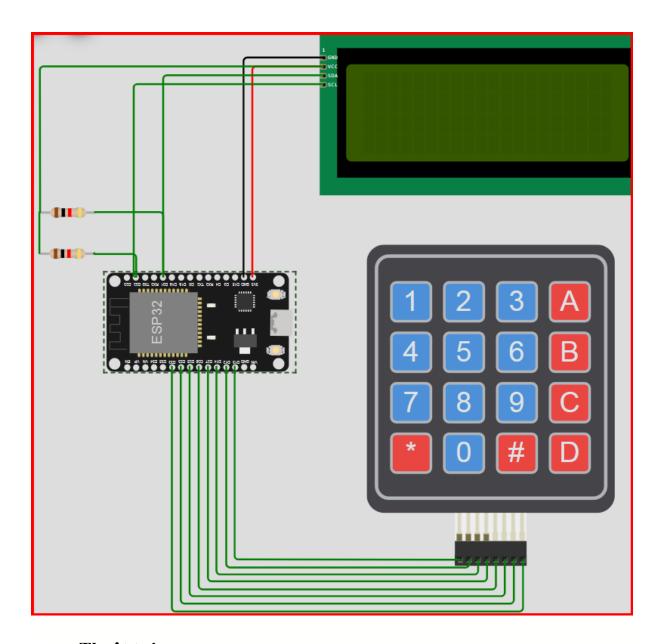
Project 7:

Câu 1:

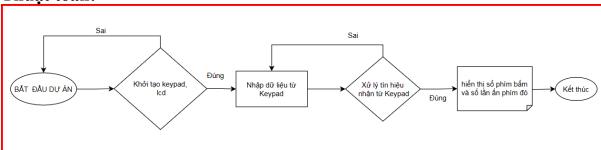
Vẽ sơ đồ ghép nối ESP32 với ma trận phím 4x4 với LCD DM 1602 giao tiếp I2C. Viết chương trình bằng Micropython đọc và hiển thị trên LCD

- 1 Số thứ tự của phím được bấm
- 2 Số lần bấm phím đó.

Bài làm



• Thuật toán:



• Code:

from time import sleep_ms from machine import Pin, SoftI2C from i2c_lcd import I2cLcd

####### Definitions #######

```
# Define LCD params
AddressOfLcd = 0x27
i2c = SoftI2C(scl=Pin(22), sda=Pin(21), freq=400000) # connect scl to GPIO
22, sda to GPIO 21
lcd = I2cLcd(i2c, AddressOfLcd, 4, 20)
# Define keypad layout
keypad = [
  ['1', '2', '3', 'A'],
  ['4', '5', '6', 'B'],
  ['7', '8', '9', 'C'],
  ['*', '0', '#', 'D']
1
# Define the row and column pins
row_pins = [Pin(13, Pin.OUT), Pin(12, Pin.OUT), Pin(14, Pin.OUT),
Pin(27, Pin.OUT)]
col_pins = [Pin(26, Pin.IN, Pin.PULL_UP), Pin(25, Pin.IN, Pin.PULL_UP),
Pin(33, Pin.IN, Pin.PULL_UP), Pin(32, Pin.IN, Pin.PULL_UP)]
# Initialize the row pins to HIGH
for row_pin in row_pins:
  row_pin.value(1)
# Dictionary to keep track of key presses
key_counts = {key: 0 for row in keypad for key in row}
def read_keypad():
  for i in range(4):
    row_pins[i].value(0)
    for j in range(4):
       if col_pins[i].value() == 0:
         sleep_ms(20) # Debounce delay
         # Check again to avoid false positives
         if col_pins[j].value() == 0:
            while col_pins[j].value() == 0:
               pass # Wait for key release
            return keypad[i][j]
    row_pins[i].value(1)
  return None
```

####### Main #######

```
while True:
    key = read_keypad()
    if key is not None:
        key_counts[key] += 1
        lcd.clear()
        lcd.move_to(0, 0)
        lcd.putstr("Key pressed: ")
        lcd.move_to(0, 1)
        lcd.putstr(key)
        lcd.move_to(0, 2)
        lcd.putstr("Count: {}".format(key_counts[key]))
```