

Some Random Stuff in L^AT_EX to Serve as an Example

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Abstract

This is where you write a quick summary that hopefully will get people interested in reading the entire paper.

Keywords: keyword1, key phrase1, keyword2

1 Introduction

Throughout this document, I include snippets of a paper I wrote with some students years ago, about neural networks. You can ignore that actual text (I deleted a lot, so it won't make sense), and just focus on the L^AT_EX ideas. I left you lots of notes, in *italics*. For this document to be useful to read, make sure you're looking at both the .tex file and the generated pdf, at the same time. That way, you can see how the .tex code corresponds to what is actually in the paper. For example, peek at this paragraph in the .tex file now and note how I made some text italicized.

Please start by looking at all the stuff in the .tex file before the “section Introduction” part. Big picture, it's loading in modules for various types of functionality. Then the part about setting the title, author information, and abstract is easy enough to figure out (just copy to another document if you're making a new paper). I recommend you take a “I'll look into it if I need it” attitude on the details of the code above.

Note that if you're submitting a paper to a particu-

lar venue (conference, journal, edited book), they'll often have a template document loading in what you need and setting things up according to their specifications. The template may also include separate files, like an .sty “style file” that customizes document processing.

You can skip to Section 2 in a moment. First, though, note how I referred to that section in the .tex file, and how that section is labeled. Don't hardcode section numbers!

Do you know about Lorem ipsum? This is just some filler text. You can skip to Section 2 now. Lorem ipsum dolor sit amet, consectetur adipiscing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut enim ad minim veniam, quis nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. Duis aute irure dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur. Excepteur sint occaecat cupidatat non proident, sunt in culpa qui officia deserunt mollit anim id est laborum.

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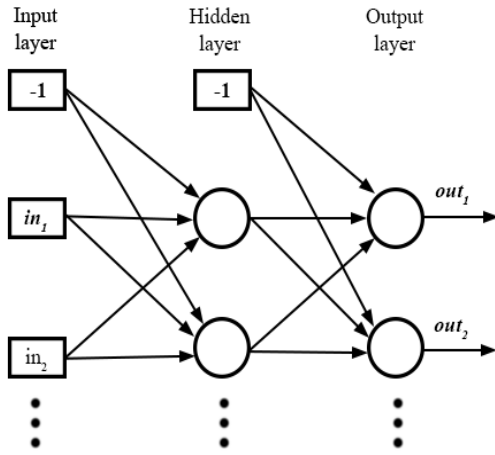


Figure 1: The structure of a simple neural network

quaerat voluptatem. Ut enim ad minima veniam, quis nostrum exercitationem ullam corporis suscipit laboriosam, nisi ut aliquid ex ea commodi consequatur? Quis autem vel eum iure reprehenderit qui in ea voluptate velit esse quam nihil molestiae consequatur, vel illum qui dolorem eum fugiat quo voluptas nulla pariatur?

2 Neural Networks

If you want to quote something, use two single backquotes (the key left of the 1) for the start, and two single quotes for the end: “I’m quoting something correctly”. Don’t do this: “I’m quoting something incorrectly” because it doesn’t render the starting quotes correctly (subtle difference).

A feed-forward neural network [4] maps a set of inputs... Did you see that citation, there? More on citations soon. Figure 1 shows a feed-forward neural network with a single hidden layer. See how to refer to a figure? Don’t hardcode the numbers! Also note the code to include a figure, starting with the begin figure command... I never memorize that. I’ve just been copying from one document to another all my life, figuring out how to make small adjustments via Google as needed. You have to make sure you have a corresponding file, though, like neuralnetwork.png. It’s easiest to stick with .png files, though there

are ways to render other graphics files if you need to look it up sometime.

Also note that Figure 1 “floats”. That is, it doesn’t automatically show up precisely where you put the code for it. \LaTeX determines a good placement. If you don’t like how it’s placed, there are things you can do to force it to be elsewhere.

Each unit’s output is computed based on its inputs as follows:

$$out_k = S \left(\sum_{i=1}^n W_{ik} in_i \right)$$

where n is the number of inputs to node k , W_{ik} is the weight from input i to node k , in_i is the input from i ,

Double dollar signs around some “MathJax” code puts some math on a line by itself. Single dollar signs makes it “inline”. Underscore is for subscript, caret for superscript. Notice the commands for left and right parenthesis (automatically sized), and sum.

Use braces for superscripts and subscripts that are more than one letter. Do this: x_{ij} , not this: $x_i.j$.

and S is the sigmoid function:

$$S(t) = \frac{1}{1 + e^{-t}}$$

I needed to refer to sigmoid so much that I made a command for it. Do a find on “newcommand” at the top of the file to see how.

Study these MathJax examples! You’ll want to write your own equations soon.

The learning rate and momentum are both used in the weight update rules that follow. For the hidden-output weights:

$$\Delta W_{ji} = \alpha \cdot Err_i \cdot S'(in_i) \cdot x_j + \mu(old \Delta W_{ji})$$

such that

$$in_i = \sum_{j=1}^n W_{ji} x_j$$

$$Err_i = f_i(\vec{x}) - S(in_i)$$

For input-hidden weights:

$$\Delta W_{kj} = \alpha \cdot x_k \cdot \Delta_j$$

such that

$$\Delta_j = S'(in_j) \cdot \sum_i W_{ji} \cdot \Delta_i$$

$$\Delta_i = Err_i \cdot S'(in_i)$$

where k is an input unit index, j is a hidden unit index, i is an output unit index, f is the target function (so $f_i(\vec{x})$ is the activation of output unit i in the known example with inputs \vec{x}), x_k and x_j refer to the activation of input and hidden units respectively, α is the learning rate, μ is the momentum, W_{xy} is the weight from node x to node y , n is the number of hidden units, $old\Delta W_{ji}$ is the change made to the weight in the previous update, and S' is the derivative of the sigmoid function:

$$S'(t) = S(t) \cdot (1 - S(t))$$

For more examples of MathJax, check out the *math.tex* and corresponding *math.pdf* files. Then also look at *symbols.pdf*. Be familiar with generally what's in these documents, so you can look up information as needed. Google will help for this too, of course.

3 Experiments

3.1 Setup

Stuff here

3.1.1 Lots of subs!

Indeed. Three subs requires some special library, though.

You can make bulleted lists:

- Itemized lists
- Enumerated lists

and enumerated lists:

1. Itemized lists
2. Enumerated lists

Hey, I commented out a line using the percent sign. So how can I make a percent sign show up in my document? I “escape” it with a backslash. It works 100% of the time. However, if you forget to escape it and write 100

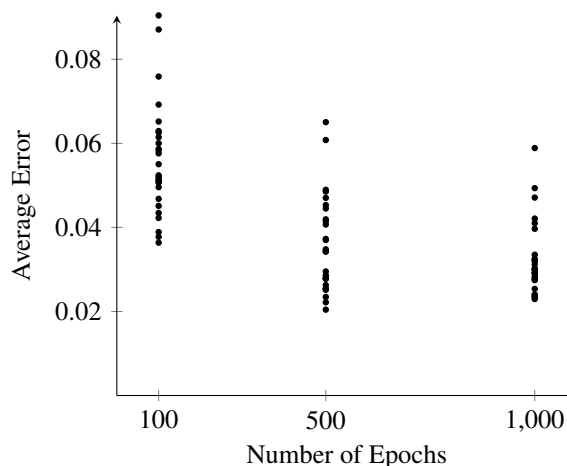


Figure 2: Cars: Effect of the number of epochs on average error.

4 Results

4.1 Cars Data Set Results

Figure 2 shows that.... Note how I generated the graph in the document itself, reading from a .dat file. Usually I just make the graph in Excel or something and load it in as an image, but now you know this is possible too.

Here's a tip, if you're grabbing an image from Excel: Zoom in as much as you can, so that the image is massive, filling up the screen. Then take a screenshot. The image will be too big, but you can reduce its size. The purpose of taking a screenshot all zoomed in is so that the screenshot is a higher resolution. I do this all the time; it makes a big difference.

For screenshots, personally, I like the free tool Cropper at <https://archive.codeplex.com/?p=cropper>. Did you notice just above how that URL is a link? Note how to do that.

When examining batch size, Table 1 summarizes these results. Note the code for generating and referring to a table. This is a floating table, like we had a floating image before. There's a super handy tool for making a table online: <https://www.tablesgenerator.com/>. Try it out a bit.

Table 1: Cars: Amount of results settled below 50% of maximum batch size.

Max Batch Size	Experiments Run	< 50% of Max
50	54	40
100	17	17
150	8	7

Ordinary Least Squares

INPUT $(X = \{\vec{x}^{(i)}\}, Y = \{y^{(i)}\}, \alpha)$

► There are n data elements, each with m independent variable values. That is, $i \in \mathbb{Z}, 1 \leq i \leq n$, and $\forall i, \vec{x}^{(i)}$ has m elements.

OUTPUT $\vec{\theta}$

$\vec{\theta} \leftarrow$ arbitrary initial values

repeat

for $i = 1, n$ **do** ► For each data element $(\vec{x}^{(i)}, y^{(i)})$

$x_0^{(i)} \leftarrow 1$ ► To update θ_0

for $j = 0, m$ **do** ► For each model parameter θ_j

$t_j \leftarrow \theta_j - \alpha x_j^{(i)} (h_{\vec{\theta}}(\vec{x}^{(i)}) - y^{(i)})$

end for

$\vec{\theta} \leftarrow \vec{t}$ ► Batch update

end for

until change in $\vec{\theta}$ is below some threshold

return $\vec{\theta}$

Figure 3: Pseudocode for a batch-update iterative ordinary least squares process.

5 Code

Generally it's not appropriate to put a ton of code in your paper, but some can be useful in some circumstances. It's probably best to put it in a figure, like Figures 3 and 4.

6 Related Work

Just more citation examples here!

The parallelization of neural networks has been the focus of much research. For example, [3] describes... [2] describes a genetic algorithm... Another example of a genetic algorithm applied to neural networks can be found in [5].

How can you include citations? There are a few steps.

```

1 public void runExperiment() {
2     int totalNums = 10000;
3     int[] arr = makeRandomArray(totalNums);
4
5     parallelSum = 0;
6     PartialAdder add1 = new
7         PartialAdder(this, arr, 0,
8             totalNums/2);
9     PartialAdder add2 = new
10        PartialAdder(this, arr, totalNums/2,
11            totalNums);
12
13     add1.start();
14     add2.start();
15     add1.join();
16     add2.join();
17     System.out.println("In parallel, sum: "
18         + parallelSum);
19
20     int sequentialSum =
21         computeSequentialSum(arr);
22     System.out.println("Sequentially, sum: "
23         + sequentialSum);
24 }
25
26 public void receiveMessage(int partialSum)
27 {
28     parallelSum += partialSum;
29 }

```

Figure 4: This method, in the AdderManager class, spawns two child threads to sum the numbers in an array, and then reports their results.

First, check out the end of this document. The line `bibliography{latexIntro}` means that the bibliography for this document is in the file called `latexIntro.bib`. Open up that document now, in a programming text editor like Notepad++ or Sublime. Observe the different ways to specify a document, based on its type and what information you have about it. So the bib file gives the data on the bibliography, and the way it actually shows up is determined by the `bibliographystyle{plain}` line at the end of your .tex file.

Note in the .bib file that the first entry is called "Bache". So you can cite it like this: [1] (note how this is done in the .tex file).

How can you learn the format for a .bib entry? Actually, you usually don't need to. Go to scholar.google.com. Search for something, for example "gradient boosting regressor". Suppose you read one document in the results and decide you want to cite it. Click the little quotes icon (just to the right of the star icon) for that entry. In the

pop-up window, click “BibTeX”. Copy what you see into your .bib file. Cool, huh?

If you need to cite a website, follow the example in latexIntro.bib, for the Bache entry.

- [5] Symone Soares, Carlos Antunes, and Rui Araújo. A genetic algorithm for designing neural network ensembles. In *Proceedings of the 14th Annual Conference on Genetic and Evolutionary Computation*, GECCO '12, pages 681–688, New York, NY, USA, 2012. ACM.

7 Future Work

Win the Super Bowl.

There’s a little extra spacing around these sections because L^AT_EX has decided there’s not enough room to start the “References” section on this page.

8 Conclusion

L^AT_EX has a bit of a learning curve, but you’ll work it out, and then it’s incredibly powerful.

9 Acknowledgment

Should be included if work is funded by some organization (e.g. the NSF), or there’s just someone you want to thank for their professional contribution.

References

- [1] K. Bache and M. Lichman. UCI machine learning repository. “<http://archive.ics.uci.edu/ml>”, 2013. Accessed: 2018-03-29.
- [2] Frederic Gruau. *Neural Network Synthesis Using Cellular Encoding and the Genetic Algorithm*. PhD thesis, jan 1994.
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- [4] Stuart Russell and Peter Norvig. *Artificial Intelligence: A Modern Approach*. Prentice Hall Press, Upper Saddle River, NJ, USA, 3rd edition, 2009.