**VIETNAM NATIONAL UNIVERSITY**

**UNIVERSITY OF SCIENCE**

**FACULTY OF INFORMATION TECHNOLOGY**



**PROJECT 01**

**ARTIFICIAL INTELLIGENCE**

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# Assignment plan and overall

|  |  |  |
| --- | --- | --- |
| No. | Specification | Complete |
| 1 | Finish level 1 successfully. |  |
| 2 | Finish level 2 successfully. |  |
| 3 | Finish level 3 successfully. |  |
| 4 | Finish level 4 successfully. |  |
| 5 | Graphical demonstration of each step of the running process. |  |
| 6 | Generate at least 5 maps with difference in number and structure of walls, monsters, and food. |  |
| 7 | Report |  |

# How to play

# Explaning code: Object.py

class pacman(object):

* Initialize pacman character from png image file.
* Draw pacman at position x, y read from the map file.
* Each time the pacman moves, it erases the previous position and redraws it

class monster(object):

* Generate from Monster image file and draw in place on maze.
* Like the pacman, each time Monster moves will be deleted and redrawn in a new position.
* Will initialize random positions from array of positions and Monster will randomly move.
* Chase the pacman calculated according to the distance closest to the pacman.

class food(object):

* Initialize the cells with the value Food as a white circle.
* If the cells are eaten, they will be deleted by themselves.

# Explaning code: pacman.py

Function def random\_Maze():

* Randomly initialize two variables for map size, then create a random matrix with three values of 0, 1, 2 and then surround the matrix with value 1.
* Then random the number and value of Ghost position corresponding to a random position in the matrix.
* Assign matrix into array corresponding to each row of matrix and return the results.

Function def handle\_input():

* Initialize the variable lst as an array, open the file containing the position and matrix.
* For each line read, it is detached and fed into lst

Function def create\_maze(C):

* For each input box from the matrix will be considered at that position as Wall or Food or Ghost.
* For each position there will be additional functions.

Function def create\_data(C):

* If level = 1 then converts the positions with Monster value to 0
* Go through the maze array, if it is a sugar or Food value, enter the ListAdjacency matrix.

Function def update\_adjacent\_list(C):

Function def display\_score():

* Draw a score board

Function def RunAlgorithm():

Function def Controls():

Function def key\_pressed(event):

* If you press the Escape button, delete the canvas.
* If the Enter button is pressed, the algorithm starts.

# Explaning code: Searching\_Algorithm.py

Function def BFS(adjacency\_list, begin, food\_position):

* Create the parent array the size of the passed list.
* Check at start is Food or not, if so then return results.
* Create the queue for the starting value, node at the position taken from the queue. Check to see if it is in the list expanded or not, if the node at location is Food, retrieve it and return the function values.

Function def DFS(adjacency\_list, begin, food\_position):

* Create the parent array the size of the passed list.
* Check at start is Food or not, if so then return results.
* Create a stack array and put the initial value in. The node at position will be populated from the stack and checked to see if it is in expand nodes. If not, will update the stack and parent again.
* If it is at that position, Food will trace back and return the values of the function.

Function def DLS(adjacency\_list, food\_pos, explored, parent, current\_path, depth):

* Implement recursive depth-limited search.
* Base conditions: if the last node in the current path is food\_pos, return True. If the depth is 0 (cut off) return False.
* Iterate adjacency nodes of last node in current path: If the current adjacency node is not in current path, set the parent for adjacency node (parent[adjacency\_node] = last\_node), append current adjacency node to the current path and list of explored nodes.
* Call the DLS function with depth = depth – 1 to explore the current path until cut off or the goal is found, store the result in result. If the goal is found (result == True) return true. Else pop the last node in current path.

Function def IDS(adjacency\_list, current\_position, food\_position, max\_depth):

* Create 2 lists: explored\_ns and path\_fd to store list of explored nodes and list of nodes on the path found.
* If the current\_position is the same node as food\_position: return 0, explored\_ns, path\_fd.
* Iterate the depth from 0 to max\_depth – 1.
* For each depth:
* Create parent list for each node with default value = -1, create explored list to store list of explored nodes in the current depth, current path list to store the path. Call function DLS with arguments: adjacency\_list, food\_position, explored, parent, current\_path, depth, the return value of DLS function is stored in result.
* Append explored to explored\_ns after the call of function DLS. If DLS function return True (result == True), backtrack the current path to find the path and store path in path\_fd, calculate length of explored nodes and store in esc\_time. Return esc\_time, explored\_ns, path\_fd
* Return “”, “”, “” if the path is not found

Function def get\_manhattan\_heuristic(current\_position, food\_position, maze\_size):

* Get position and Food position.
* Then calculate the distance between two positions and return the result.

Function def A\_Star(adjacency\_list , current\_position, food\_position, maze\_size):

* Initialize three arrays: explored, frontier, path
* Initialize the parent array to -1.
* Each node pops out with 2 values, its cost and index. We calculate the fcost and the hcost and then we have the gcost.
* Check if that Food location has the same node value.
* If not, check if that node has been expanded, if not, then enter and update the frontier and parent again.

# References