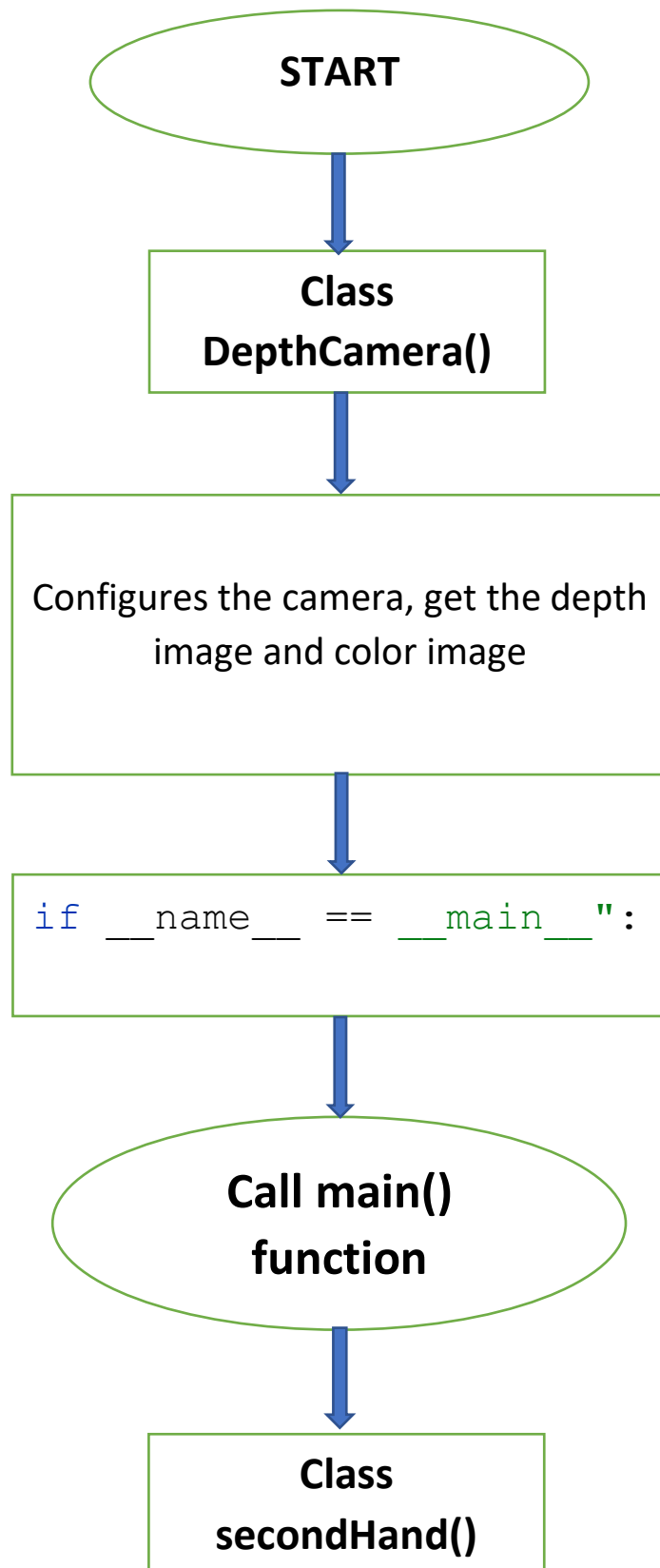
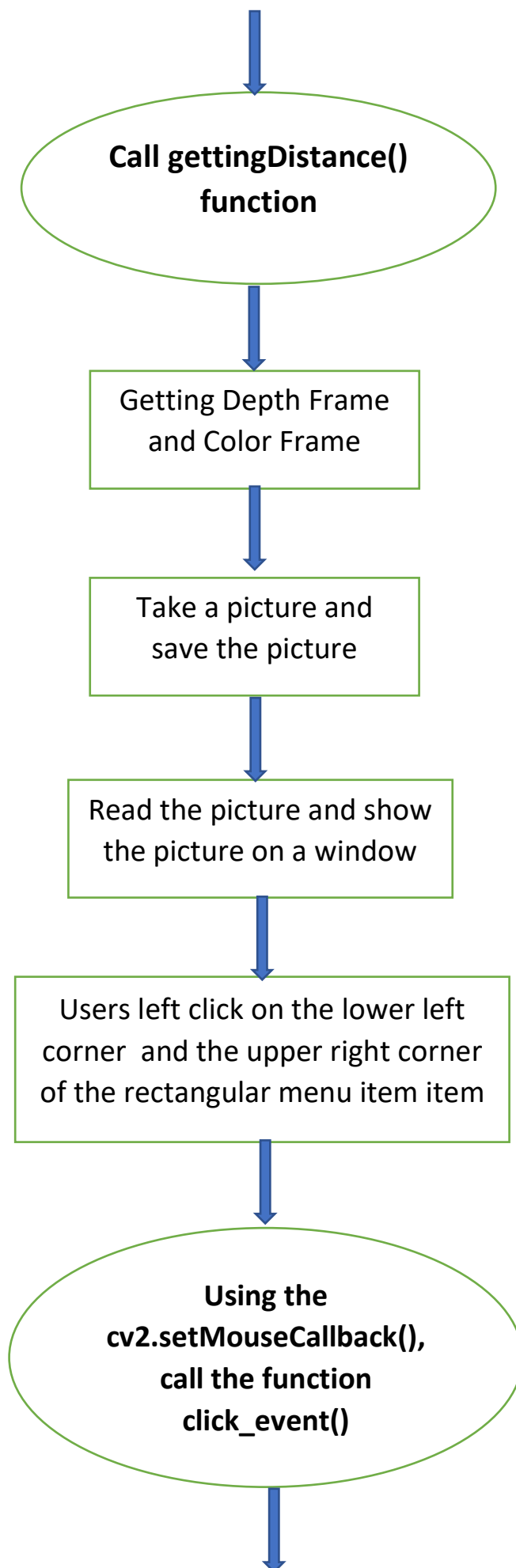


Import necessary libraries – cv2, numpy, pyrealsense2, mediapipe, signal, copy, time, and sys





click_event() receives x and y coordinates of the corners of the menu and get the distance from the camera to the menu item

```
ret,depth_frame,color_frame= dc.get_frame()  
distance = depth_frame[y, x]
```

Put the x, y, z coordinates of the corners in the 3D List

**Call the function
callHand()**

Make a deep copy of the original coordinates of the menu items

Cropped the first menu item and turned into gray image

