



Line 19 :

Using Instruction **JHS**    Jump if higher or same    ( status bits not affected )

JHS label      If C = 1 : Label => PC      ( Jump )

If  $C = 0$  : Execute following instruction ( not jump )

We have : JHS    turnoffLED

Because  $dst < src$  , so not higher or same ( $C = 0$ )  $\Rightarrow$  Not Jump

Namely :

- ☆ When R14 from 0 to 4 then the value dst still lower source ( # 5 ),

So  $dst < src$  and  $N = 1 \Rightarrow C = 0$ . (Not Jump)

- ☆ When R14 from 5 to 65535 then the value `dst >= src (C = 1)`,

So, Instruction JHS turnoffLED will execute Jump to "turnoffLED". ( Line 23 )

3) Study the code and explain the effect(s) of lines 21 and 22. Namely, what will happen to the carry bit and the Program Counter (PC) when P1IN bit 3 is reset (0) and when P1IN bit 3 is set (1)?

```
Line 21  BIT.B  # 008h, &P1IN      ; test only p1.3 (bit 3) by AND'ing with 0b00001000
```

Line 22    JC   turnonLED                  ; if C was set, bit 3 was set (p1.3 was high), if not set p1.3 was low

Line 21 :

Using instruction: **BIT.B** test bits in destination

BIT.B src, dst      src AND dst

The result affected to **status bits**, **src** and **dst** are not affected .

We have: **BIT.B #008h, &P1IN**

<b>P1IN</b>	<b>=</b>	<b>0b 0000 1000</b>	( test only p1.3 - bit 3)
<b># 008h</b>	<b>=</b>	<b>0b 0000 1000</b>	( value of Immediate Mode)
<hr/>			
<b>P1IN</b>	<b>=</b>	<b>0b 0000 1000</b>	bit 3 is set = 1 (high)
		(N = 0 => C = 1)	

- ☆ Because P1IN (dst) bit 3 was set high, and Negative flag = 0  $\Rightarrow$  C = 1



Line 22 :

Using Instruction **JC** Jump if carry was set ( C = 1 )  
**JC label** If C = 1 : Label => PC (Jump)  
If C = 0 : Execute following instruction (not jump)

We have : **JC** turnonLED

Because Carry flag was set (C = 1) => **Jump** to turnonLED (line 26)

4) Connect the development tool to the PC.

TI MSP430 Launch Pad Value Line Development Board connect to PC



5) Click “Download and Debug.”

View the CPU registers.

From the menu select Debug -> Auto step. Enter a value of 500 for the delay and leave the level at Step Into. Click Start.

- When selecting **Debug --> Auto step** => open a small box named delay, enter the value **500** press the **Start** button.
- The program will automatically run according to the code line.



6) Observe the flow of the code when you haven't pressed the P1.3 button. What happens to the program flow and register R14 and the carry flag?

- The program flow will automatically run in a continuous code flow without stopping.
- The value of register R14 remains unchanged. (0000h)
- The carry flag continuously changes from 0 (C = 0) to 1 (C = 1).

7) Press and hold the P1.3 button. What happens to the program flow and register R14 and the carry flag? (Note R14)

When we press and hold the P1.3 button then :

- The program flow still run continuously on the flow of the code.
- The value of register 14 is increased more by 1 after one loop of the program flow.
- The carry flag still continues to change from 0 to 1 until R14 = # 04h

9) Let P1.3 button up and press it again. R14 should increment with each connection to ground (as long as the auto step function of the debugger can keep up). What happens and why after 5 occurrences of pressing P1.3?

Each time P1.3 button is pressed, register R14 will increase by 1, so after 5 times of pressing P1.3, the value of R14 will be 05 and the carry flag will always be one (C = 1) and there will be no 0.

Explain :

- Because when R14 = 05 and increments, the instruction of line 18 is:  
- `CMP.W #005, R14`                      `R14 = 0b 0000 0101`  
   `# 005 = 0b 0000 0101`      ( value of Immediate Mode)

If dst is equal to src,      N = 0, Z = 1, C = 1 ; dst = src

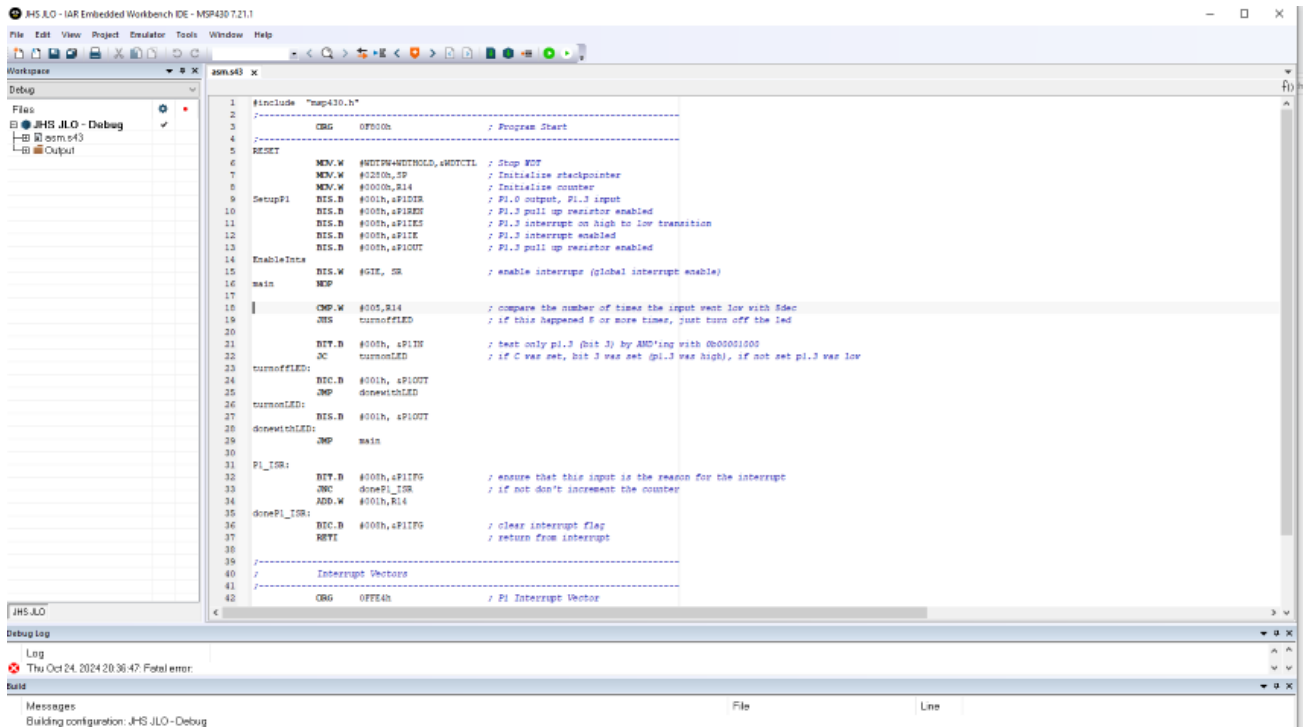
If dst is most than src,      N = 0, Z = 0, C = 1 ; dst > src

Compare dst and src, in the two cases above, we see that dst is Higher or same source (dst >= src)

⇒ The carry flag always is one C = 1 .



✚ The program flow and the flow of the code in file `asm.s43` of project



```
1 #include "map430.h"
2
3 ORG 0F00h          ; Program Start
4
5 RESET
6     MOV.W #WUTPM+WUTIMOLD,&WUTCTL ; Stop WDT
7     MOV.W #0200h,&SP              ; Initialize stackpointer
8     MOV.W #0000h,&R14             ; Initialize counter
9 SetupPI
10    BIS.B #000h,&PI2DIR            ; PI.0 output, PI.3 input
11    BIS.B #000h,&PI2REN            ; PI.3 pull up resistor enabled
12    BIS.B #000h,&PI1IE            ; PI.3 interrupt on high to low transition
13    BIS.B #000h,&PI1IF            ; PI.3 interrupt enabled
14    BIS.B #000h,&PI0OUT            ; PI.3 pull up resistor enabled
15 EnableInts
16    BIS.W #GIE, &SR               ; enable interrupts (global interrupt enable)
17
18 main
19    NOP
20
21    CMP.W #005,&R14               ; compare the number of times the input went low with 5dec
22    BHS turnoffLED                ; if this happened 6 or more times, just turn off the led
23
24    BIT.B #000h,&PI1IN            ; test only pi.3 (bit 3) by AND'ing with 0b00001000
25    JC turnonLED                  ; if C was set, bit 3 was set (pi.3 was high), if not set pi.3 was low
26
27 turnoffLED:
28    BIC.B #000h,&PI0OUT            ; turn off LED
29    JMP doneSwitchLED
30
31 turnonLED:
32    BIS.B #000h,&PI0OUT            ; turn on LED
33    JMP doneSwitchLED
34
35 doneSwitchLED:
36    JMP main
37
38 PI_ISR:
39    BIT.B #000h,&PI1IF            ; ensure that this input is the reason for the interrupt
40    JNC donePI_ISR                ; if not don't increment the counter
41    ADD.W #001h,&R14
42
43 donePI_ISR:
44    BIC.B #000h,&PI1IF            ; clear interrupt flag
45    RETI                           ; return from interrupt
46
47
48
49
50 ORG 0FFFAh          ; PI Interrupt Vector
```

Debug log

Log

Thu Oct 24, 2024 20:36:47 Fatal error:

Build

Messages

Building configuration: JHS JLO-Debug

