

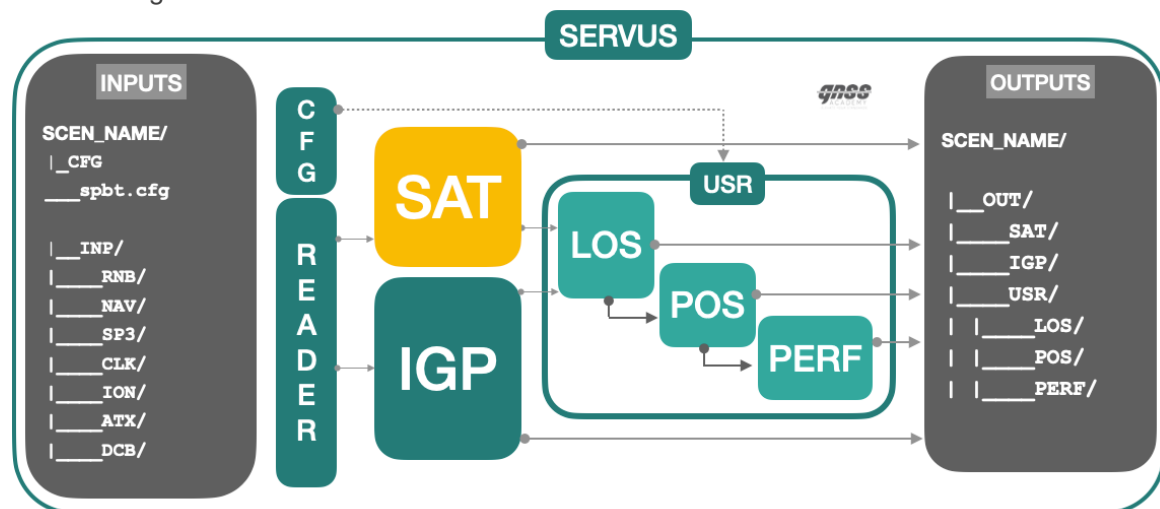
PROJECT: SERVUS		WP Number: WP-0000001
WP TITLE: WP1: Satellite Performance Characterization		Issue: 1.0
LEAD CONTRACTOR	GNSS Academy	
CUSTOMER	ESA	WP LEADER: Student
ESTIMATED EFFORT	20 hours	

OBJECTIVE

The main goal of this Work-Package is to develop the **Satellite Performance Module** of SERVUS tool by providing the daily satellite performance characterization on a EGNOS SIS real data campaign in January 2019

SCOPE

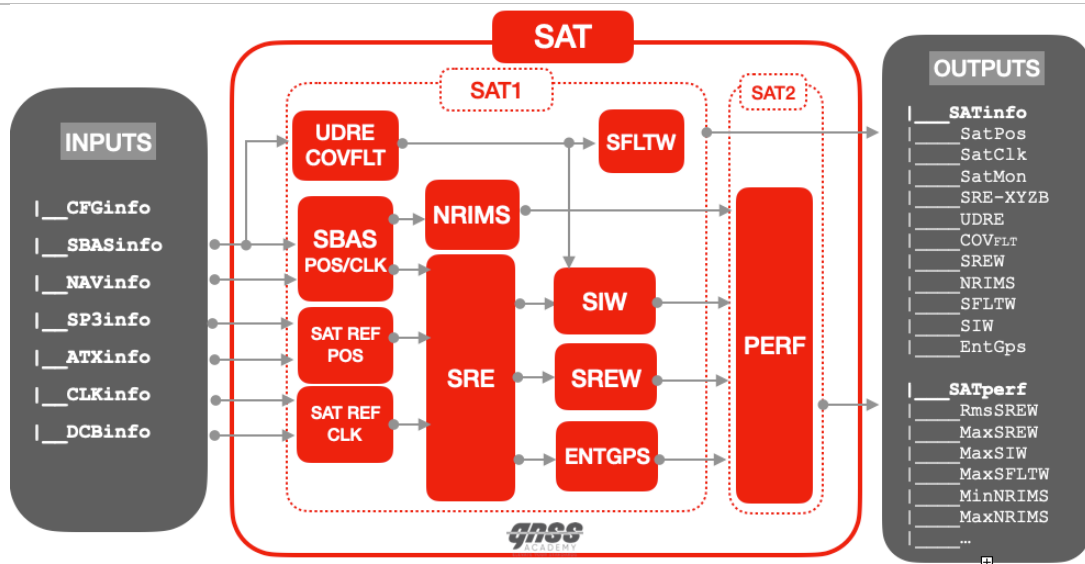
SERVUS high-level Architecture:



The **SERVUS SAT** module, the one in charge of computing SRE and the SigmaFLT as the main satellite indicators, is already implemented producing a daily file with the instantaneous information allowing to later characterize the satellite performance.

The main functions of this module are:

- Compute the Satellite Position and Clock from GPS Navigation Message
- Extract SBAS SIS satellite-related information:
 - FLT Corrections: FC (MT2-5/24), LTC (MT24-M25)
 - FLT Integrity Sigmas: UDRE (MT2-6), COV Matrix (MT27 or MT28)
 - Satellite Monitoring Flags (M/NM/DU) (MT2-6)
 - Degradation Factors (MT7-MT10)
- Compute the Satellite Corrected Position applying the corrections to the Navigation message.
- Compute True Orbit and Clock Information from reference files.
- Compute Satellite level main indicators:
 - Orbit&Clock Error: SRE-XYZ and SRE-ACR and SRE-B → SREW (@WUL)
 - Error Variance: SigmaFLT at the WUL
 - Satellite Safety Index: SREU/5.33 SigmaFLT at WUL
 - Time Scale Offset: ENT-GPS OFFSET
- Assess the Satellite Performance in terms of accuracy (RMS SRE), Integrity (SI) and upper-bound (SigmaFLT)

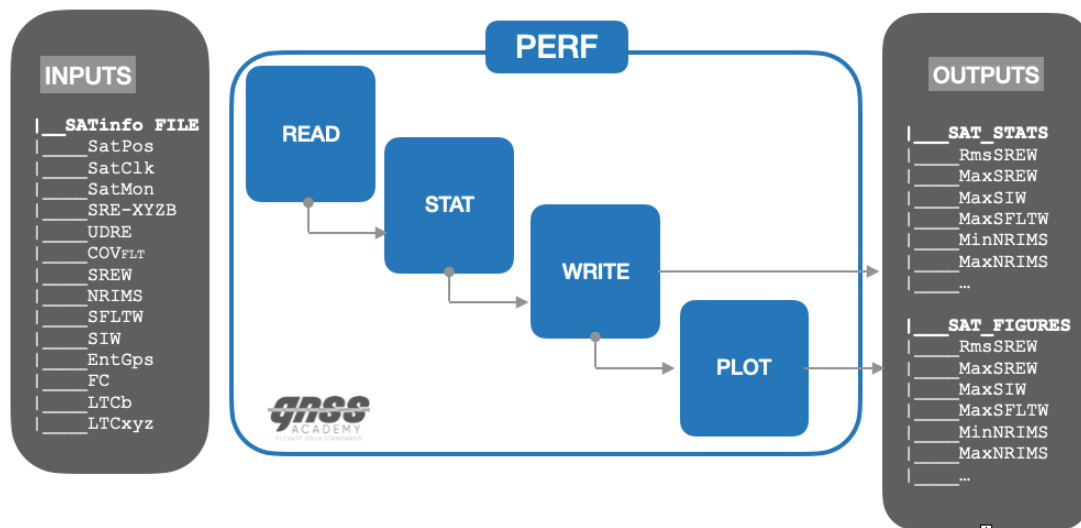


This first Work-package is related to the satellite-level characterization performances in terms of accuracy, integrity, and upper-bound.

- **Satellite Accuracy** is given by different statistics of the SRE (Satellite Residual Error) including the satellite orbit and clock errors.
- **Satellite Upper-bounding** and **Continuity** characterization is given by some statistics related to the SigmaFLT (equivalent to UDRE or SigmaUDRE)
- **Satellite Integrity** is given by the safety index $SREU/5.33\text{SigmaFLT}$ at the Worst User location of the service are in order to ensure that the provided SigmaFLT correctly bounds the Error up to the required confidence levels.

This Work-package aims at developing the SAT2 Module corresponding to SAT PERF.

1. Read Satellite Instantaneous Information file.
2. Compute Satellite Statistics.
3. Write a Satellites Statistics file.
4. Plot Satellite Statistics.



INPUTS

This Work-package uses daily input files as the output of the SAT module.

1. SAT_INFO_Y19D014_G123.dat (See Description Below)

FILENAME: SAT_INFO_Y19D014_G123_50s.dat

Column	Content	Format	Units	Description
C1	SOD	%5d	SEC	Second of Day
C2	DOY	%03d	DAYS	Day of the Year
C3	PRN	%s%02d	No Units	Satellite PRN for GPS, Galileo or GEO
C4	SAT-X	%f	KMS	Satellite Navigation Position (CURRENT) X-Component
C5	SAT-Y	%f	KMS	Satellite Navigation Position (CURRENT) Y-Component
C6	SAT-Z	%f	KMS	Satellite Navigation Position (CURRENT) Z-Component
C7	MONSTAT	%d	No Units	Satellite Monitoring Status (0: NM; 1:M; -1; DU)
C8	SRESTAT	%d	No Units	Satellite SRE Status (0: NOK 1:OK)
C9	SREx	%f	METER	Satellite Residual Error X-Component
C10	SREy	%f	METER	Satellite Residual Error Y-Component
C11	SREz	%f	METER	Satellite Residual Error Z-Component
C12	SREb1	%f	METER	Preliminary Satellite Residual Error Clock Bias Component (containing the ENT-GPS Offset)
C13	SREW	%f	METER	Satellite Residual Error projected at the Worst User Location (WUL)
C14	SFLT-W	%f	METER	SigmaFLT/DFC projected at the Worst User Location (WUL)
C15	UDREI	%d		Satellite UDREI/DFREI Indicator
C16	FC	%f	METER	Satellite Clock Fast Corrections
C17	AF0	%f	METER	Satellite Clock Long Term Corrections Offset (LTCb=AF0+AF1(t-t0))=AF0 in EGNOS V2
C18	AF1	%f	METER	Satellite Clock Long Term Corrections drift This term is NULL in EGNOS V2
C19	LTCx	%f	METER	Satellite Orbit Long Term Corrections X-Component
C20	LTCy	%f	METER	Satellite Orbit Long Term Corrections Y-Component
C21	LTCz	%f	METER	Satellite Orbit Long Term Corrections Z-Component
C22	NRIMS	%d	-	Number of RIMS inside the ECAC that are in view from the satellite over a mask angle for, at least, 10min
C23	RDOP	%f	-	Radial DOP is the inverse DOP as seen from the Satellite to RIMS projected into the Radial direction

2. RIMS_REF_POSITIONS_2019.dat (See Description Below)

FILENAME: RIMS_REF_POSITIONS_2019.dat

Column	Content	Format	Units	Description
C1	RIMS _{FLAG}	%4d	none	Selection flag to activate or deactivate this RIMS from the PAN processing
C2	RIMS _{ACRONYM}	%8s	none	RIMS Acronym with 4 characters (e.g: ACRA)

C3	RIMS_{ID}	%02d	none	RIMS identifier as an integer between 00 and 99.
C4	RIMS_{LOn}	%15.7f	deg	RIMS geographical longitude position
C5	RIMS_{LAT}	%15.7f	deg	RIMS geographical latitude
C6	RIMS_{ALT}	%12.3f	m	RIMS height in meters
C7	RIMS_{MASK}	%10.2f	deg	RIMS Mask angle
C8	RIMS_{ACQ}	%5d	s	RIMS Receiver Acquisition time
C9	RIMS_{SITE}	%20s	none	RIMS site location as the representative name of the city
C10	RIMS_{COUNT}	%20s	none	RIMS Country location

RIMS Parameters

#	p1	p2	p3	p4	p5	p6	p7	p8	p9	p10
1	ABSA	01	31.6168738	22.3584909	199.489	10.00	5	Abu-Simbel	Egypt	
1	ACRA	02	-28.6228066	38.5186833	198.582	10.00	5	Azores	Portugal	
1	ALBA	03	9.8831919	57.0963560	42.678	10.00	5	Alborg	Denmark	
1	ALYA	04	29.9557435	31.1829123	12.531	10.00	5	Alexandria	Egypt	
1	ATHA	05	23.7911121	37.8612226	368.684	10.00	5	Athens	Greece	
1	BRNA	06	13.5410936	52.3569463	83.432	10.00	5	Berna	Switzerland	
1	CNRA	07	-15.3793852	27.9454109	51.123	10.00	5	Canary	Spain	
1	CRKA	08	-8.4962089	51.8446852	201.929	10.00	5	Cork	Ireland	
1	CTNA	09	15.0619850	37.4636507	47.297	10.00	5	Catania	Italy	
1	DJAA	10	10.7717472	33.8801909	36.873	10.00	5	Djerba	Tunisia	
1	EGIA	11	-14.4007338	65.2800856	89.528	10.00	5	Egilsstadir	Iceland	
1	GLGA	12	-4.4456436	55.8706262	64.261	10.00	5	Glasgow	Ireland	
1	GOLA	13	32.8035793	39.6381446	1088.564	10.00	5	Golbasi	Turkey	
1	GVLA	14	17.1331590	60.6663660	53.299	10.00	5	Gavle	Sweeden	
1	JMEA	15	-8.4915201	70.9728644	63.463	10.00	5	Jan-Mayen	Norway	
1	KIRA	16	29.9313365	69.7311459	119.770	10.00	5	Kirkenes	Norway	
1	LAPA	17	27.5553483	60.5388860	35.773	10.00	5	Lappeenranta	Finland	
1	LPJA	18	-17.7603716	28.6196424	137.719	10.00	5	LaPalma	Spain	
1	LSBA	19	-9.1298707	38.7887635	157.600	10.00	5	Lisbon	Portugal	
1	LYRA	20	15.3965961	78.2285265	496.566	10.00	5	Svalbard	Norway	
1	MADA	21	-16.7056705	32.7474268	192.855	10.00	5	Madeira	Portugal	
1	MLGA	22	-4.5144494	36.6846957	60.881	10.00	5	Malaga	Spain	
1	PARA	23	2.3349038	48.8359007	123.380	10.00	5	Paris	France	
1	PDMA	24	2.7387532	39.5636956	51.540	10.00	5	Mallorca	Spain	
1	RKKA	25	-21.9315020	64.1292866	83.945	10.00	5	Reykjavik	Iceland	
1	ROMA	26	12.5837594	41.8039468	172.877	10.00	5	Rome	Italy	
1	SDCA	27	-8.4248159	42.9264046	437.005	10.00	5	Santiago	Spain	
1	SOFA	28	23.4101179	42.6848906	611.360	10.00	5	Sofia	Bulgaria	
1	SWAA	29	-1.2869796	50.8871205	76.428	10.00	5	Swanwich	England	
1	TLSA	30	1.4970244	43.4285678	253.477	10.00	5	Toulouse	France	
1	TRDA	31	10.8993146	63.4568329	43.875	10.00	5	Trondheim	Norway	
1	TROA	32	18.9390987	69.6631570	136.126	10.00	5	Tromsø	Norway	
1	WRSB	33	21.0676369	52.2147521	125.452	10.00	5	Warsaw	Poland	
1	ZURA	34	8.5648888	47.4537484	514.795	10.00	5	Zurich	Switzerland	
1	NOUA	35	-15.9544648	18.0818926	35.278	10.00	5	Nouakchott	Mauritania	
1	HFAA	36	35.0220640	32.7789087	239.597	10.00	5	Haifa	Israel	
1	AGAA	37	-9.4115837	30.3185120	119.179	10.00	5	Agadir	Morocco	
1	HBKA	38	27.7071958	-25.8833373	1548.973	10.00	5	Hartebeesthoek	SouthAfrica	
1	MONA	39	-64.7692785	46.0711908	31.816	10.00	5	Moncton	Canada	

OUTPUTS

Two main kind of outputs for this Work Package are required:

- A Daily file with per satellite performance Statistics with the following format and content:
SAT_STAT_Y19D014_G123_50s.dat

Column	Content	Format	Units	Description
C1	PRN	%s	No Units	Satellite PRN for GPS (e.g: G01)
C2	MON	%6.2f	%	Satellite Monitoring Percentage along the day
C3	RIMS-MIN	%4d	No Units	Minimum Number of RIMS in view during the day
C4	RIMS-MAX	%6d	No Units	Maximum Number of RIMS in view during the day
C5	SREaRMS	%10.3f	METER	RMS of the SRE-A along the day, the Satellite Orbit Residual Error Along-Track component

C6	SREcRMS	%8.3f	METER	RMS of the SRE-C along the day, the Satellite Orbit Residual Error Cross-Track component
C7	SRErRMS	%8.3f	METER	RMS of the SRE-R along the day, the Satellite Orbit Residual Error Radial component
C8	SREbRMS	%8.3f	METER	RMS of the SRE-B along the day: the Satellite Residual Error Clock component SRE-B is computed subtracting the ENT-GPS Offset from the SREb1
C9	SREW RMS	%8.3f	METER	RMS of SREW along the day
C10	SREW MAX	%8.3f	METER	Maximum SREW reached along the day
C11	SFLT MAX	%8.3f	METER	Maximum SigmaFLT@WUL reached along the day
C12	SFLT MIN	%8.3f	METER	Minimum SigmaFLT@WUL reached along the day
C13	SIMAX	%8.3f	No Units	Maximum SI_{SAT} reached along the day $SI_{SAT} = \frac{SREW}{5.33 \cdot SFLT_w}$
C14	FCMAX	%8.3f	METER	Maximum Satellite Clock Fast reached along the day.
C15	LTCb MAX	%8.3f	METER	Maximum Clock Long Term Corrections (LTCb) reached along the day
C16	LTCx MAX	%8.3f	METER	Maximum Satellite Long Term Corrections X-Component (LTCx) reached along the day
C17	LTCy MAX	%8.3f	METER	Maximum Satellite Long Term Corrections Y-Component (LTCy) reached along the day
C19	LTCz MAX	%8.3f	METER	Maximum Satellite Long Term Corrections Z-Component (LTCz) reached along the day
C20	NMI	%8.3f	No Units	Number of Misleading Information (MI). Number of times SIW > 1
C21	NTRANS	%4d	No Units	Number of Transitions from M to NM and M to DU

- A Daily file containing the estimated ENT-GPS per epoch:
ENTGPS_Y19D014_G123_50s.dat

Column	Content	Format	Units	Description
C1	SOD	%5d	SEC	Second of Day
C2	ENT-GPS	%10.4f	SEC	ENT to GPS Offset computed as follows: $ENTGPS = median(\{SREb1 - SREr\}_{SRESTATUS==1})$ Where SREr is the projection of (SREx, SREy, SREz) into the satellite radial direction And SREb1 is the preliminary Satellite Clock Error including the time scales offset

- Daily Satellite performance plots

TASKS

ID	DESCRIPTION
T0. PRELIMINARY	Downloading and Understanding
T0.1 FOLDER TREE	<p>Download following TAR file:</p> <p>STEP1. Download SERVUS-TOOL folder tree and files</p> <p>→ SBPT-SERVUS_WP1.tgz</p> <p>STEP2. Place it somewhere in the GNSS Academy working directory</p> <p>STEP3 untar the file.</p>

	<pre>tar xvfz SBPT-SERVUS_WP1.tgz</pre> <p>Check that all the following information is available:</p> <p>SBPT/SERVUS/SERVUS_V1.0/SERVUS_WP1_SAT/</p> <pre> ____SRC ____SatPerformances.py ____SatFunctions.py ____COMMON ____PlotsConstants.py ____Plots.py ____Coordinates.py ____GnssConstants.py ____Dates.py ____SCN ____SCEN-EGNOS-SIS-GEO123-JAN19 ____CFG ____satperformances.cfg ____INP ____NAV/brdc0140.19n ____RNB/M1230140.19b ____EMS/GEO123/2019/DOY014/h*.ems ____SP3/igs20361.sp3 ____DCB/P1C11901.DCB & P1P21901.DCB ____ATX/igs14.atx ____ION/igsg0140.19i ____CLK/igs20361.clk_30s ____RIMS/RIMS_REF_POSITIONS_2019.dat ____OUT ____SAT ____SAT_INFO_Y19D014_G123_50s.dat ____SAT_INFO_Y19D015_G123_50s.dat ____SAT_INFO_Y19D016_G123_50s.dat</pre> <p>Note that there are 3 SAT_INFO files already sampled at 50 seconds in order to speed-up the execution process.</p> <p>Output Files will be generated in:</p> <pre>OUT/SAT/SAT_STAT_Y19D014_G123_50s.dat OUT/SAT/SAT_STAT_Y19D015_G123_50s.dat OUT/SAT/SAT_STAT_Y19D016_G123_50s.dat</pre> <p>Output Figures shall be generated in:</p> <pre>OUT/SAT/figures/*.png</pre>	
T1. IMPLEMENTATION	Functions Implementation: Open/Reading/Loading	
T1.1 Configuration	<p>Check configuration file. 3 configuration parameters, INI_DATE, END_DATE (in order to run only one day, both shall be the same) and TSTEP.</p> <p>CFG/satperformances.cfg</p>	
T1.2 Execution	<p>Execute SatPerformance Module</p> <p>Call Main function from the SRC directory and check that you generate</p>	

	<p><code>python SatPerformances.py ../SCN/SCEN-EGNOS-SIS-GEO123-JAN19</code></p> <p>Check that this runs properly and that already generates the following files: OUT/SAT/SAT_STAT_Y19D014_G123_50s.dat OUT/SAT/ENTGPS_Y19D014_G123_50s.dat</p> <p>These files are partial files that have to be completed with the remaining columns.</p>	
T1.3 Implementation	Implement the necessary Python functions to create the satellite statistics file with all the different columns, in line with following tasks.	
T2. ENTPGPS	Create a file including the instantaneous ENT-GPS Offset	
SOD	Seconds of Day	
ENTGPS	<p>ENT-GPS Offset: estimated from the SRE of the monitored satellites with SRE_STATUS OK, as follows:</p> $ENTGPS = \text{median}(\{SREb1 - SREr\}_{SRESTATUS=1})$ <p>Where SREr is the projection of (SREx, SREy, SREz) into the satellite radial direction</p>	
T3. STATISTICS	Create a file including all satellite Statistics with the following information per columns. SAT_STATISTICS	
PRN	PRN: Satellite PRN	
MON	<p>Satellite Monitoring Percentage in the day.</p> <p>Count the number of epochs the satellite has been monitored during the day divided by the total number of seconds in the day.</p>	
MIN RIMS	<p>Minimum number of RIMS in view by the satellite during the day</p> <p>Note that the satellite is monitored by EGNOS when the satellite is seen at least by 3 RIMS.</p>	
MAX RIMS	Maximum number of RIMS in view by the satellite during the day	
RMS-SRE_R	<p>Root Mean Square of Satellite Orbit Error - Radial Component</p> <p>Note that SRE_R is not in the input file. It has to be computed by projecting the SRE_{XYZ} along the orbit radial component.</p> <p>Radial Direction</p> $U_R = r_s / r_s $	
RMS-SRE_C	<p>Root Mean Square of Satellite Orbit Error - Cross Track Component</p> <p>Note that SRE_C is not in the input file. It has to be computed by projecting the SRE_{XYZ} along the orbit cross track component.</p> <p>U_C=U_R x U_V</p> <p>where</p> <p>U_R=r_s/ r_s in the direction of the satellite position (r_s)</p> <p>U_V=v_s/ v_s in the direction of the satellite velocity (v_s)</p> <p>Note that Velocity is obtained by deriving the Satellite Position during the monitoring periods. Care shall be taken for the first epoch of the satellite monitoring pass since</p>	

	<p>no previous position to compute the velocity. First sample will be discarded from the statistics.</p> <p>Do not forget that it is a non-inertial reference frame and you need to add the Earth's Rotation in order to get the absolute velocity.</p> $V_{sat} = \frac{P_{sat}(k) - P_{sat}(k-1)}{\Delta t} + \Omega_{EARTH} \times P_{sat}(k)$ <p># Earth's rotation rate (rad/sec) OMEGA_EARTH = 7.2921151467e-5</p>	
RMS-SRE_A	<p>Root Mean Square of Satellite Orbit Error - Along Track Component</p> <p>Note that SRE_A is not in the input file. It has to be computed by projecting the SRE_{XYZ} along the orbit along track component.</p> <p>Along-Track is the cross product between Cross and Radial Track Component. U_A = U_C x U_R</p> $RMS = \sqrt{\frac{\sum (X_k)^2}{N}}$	
RMS-SRE_B	<p>Root Mean Square of SRE-B Clock Component <i>SRE-B is computed subtracting the ENT-GPS Offset from the SREb1</i></p>	
RMS-SREW	Root Mean Square of SREW: satellite Orbit Error at the Worst User Location	
MAX-SREW	Maximum SREW Satellite Orbit Error at the Worst User Location	
MAX SFLT	Maximum Sigma FLT as the Satellite Orbit and clock Error Sigma at the Worst User Location.	
MAX SIW	<p>Maximum Satellite Safety Index as the ratio between the SRE and the SigmaFLT at the Worst User Location The instantaneous SI for each satellite shall be computed as follows:</p> $SI_{SAT} = \frac{SREW}{5.33 \cdot SFLT_W}$	
MAX LTC_x	Maximum (absolute) Value of the Satellite Position LTC correction X-Component	
MAX LTC_y	Maximum (absolute) Value of the Satellite Position correction LTC Y-Component	
MAX LTC_z	Maximum (absolute) Value of the Satellite Position correction LTC Z-Component	
MAX LTC_b	Maximum (absolute) Value of the Satellite LTC -Clock AF0	
MAX FC	Maximum (absolute) Value of the Satellite Clock Fast Corrections	
NMI	Number of Satellite MIs (Misleading Information) as the number of times SI is higher than 1. (SI>1)	
NTRANS	Number of transitions Monitored to Not Monitored (MtoNM) or to Don't USE (MtoDU)	

SAT_STAT_Y19D014_G123_50s.dat																			
#PRN	MON	minRIMS	MaxRIMS	SREaRMS	SREcRMS	SRErRMS	SREbRMS	SREwRMS	SREwMAX	SFLTMAX	SFLTMIN	SIMAX	FOMAX	LTCbMAX	LTCcMAX	LTCyMAX	LTCzMAX	NMI	NTRANS
G01	37.44	4	39	2.663	0.591	0.488	0.470	0.562	1.235	2.384	0.938	0.228	1.750	1.675	2.375	3.625	4.500	0	3
G02	45.43	4	38	2.739	0.591	0.428	0.352	0.630	2.214	2.352	0.938	0.248	2.750	0.977	2.625	1.875	3.000	0	3
G03	39.06	4	38	3.898	0.947	0.691	0.587	0.842	1.807	4.664	0.938	0.286	2.375	2.094	3.000	4.500	4.125	0	5
G05	39.00	3	39	1.421	0.875	0.527	0.807	0.567	1.475	1.700	0.938	0.281	2.000	1.256	1.625	2.125	1.250	0	2
G06	41.55	3	39	2.587	1.160	0.411	0.470	0.671	1.859	4.632	0.938	0.249	1.750	2.094	2.000	2.250	1.625	0	3
G07	40.05	5	39	2.397	0.575	0.479	0.499	0.580	1.136	2.384	0.938	0.210	2.500	2.094	3.000	2.125	1.625	0	3
G08	40.22	3	39	4.232	0.577	1.285	1.209	0.873	2.240	2.352	0.938	0.336	2.875	2.652	5.875	6.625	6.500	0	2
G09	40.28	3	39	2.747	0.620	0.643	0.584	0.562	1.514	4.664	0.938	0.209	1.375	1.256	7.500	3.750	6.500	0	6
G10	40.80	3	38	1.427	0.776	0.241	0.592	0.619	1.706	2.422	0.938	0.315	1.625	2.234	1.250	3.500	4.000	0	7
G11	34.90	5	39	2.082	0.414	0.585	0.782	0.682	1.498	1.510	0.938	0.288	1.250	2.513	2.875	3.125	2.875	0	3
G12	43.00	1	39	4.173	0.435	0.330	0.811	0.970	2.172	1.870	0.938	0.414	2.875	1.117	1.500	2.750	4.625	0	8
G13	37.62	4	39	3.031	1.160	1.142	1.195	0.931	1.996	2.306	0.938	0.272	1.875	3.211	1.875	4.250	4.000	0	5
G14	44.91	4	38	1.675	0.983	0.531	0.589	0.505	1.366	1.896	0.938	0.241	0.875	1.256	1.750	2.250	2.750	0	3
G15	37.62	3	39	2.756	2.210	1.297	1.528	0.872	1.532	1.668	0.938	0.307	2.500	1.256	4.125	4.500	2.375	0	2

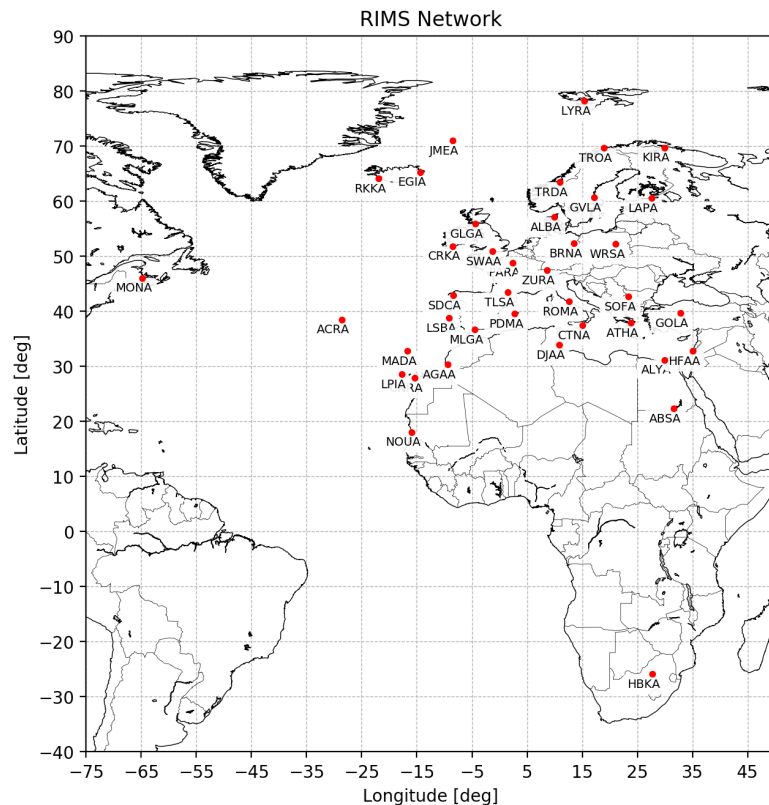
G16	38.31	3	39	2.326	0.937	0.724	0.889	0.617	1.608	1.896	0.938	0.300	1.625	1.117	2.625	1.625	3.375	0	3
G17	45.31	2	38	2.897	0.859	0.557	0.683	0.663	1.701	2.384	0.938	0.201	1.750	0.698	2.125	2.125	2.125	0	2
G18	37.38	4	38	2.216	0.818	0.578	0.754	0.624	1.331	2.352	0.938	0.206	2.375	2.094	2.250	3.000	4.375	0	3
G19	42.88	4	38	2.382	0.331	0.329	0.297	0.600	1.603	1.966	0.938	0.256	2.625	1.117	3.250	0.625	3.875	0	2
G20	43.09	4	38	1.556	1.032	0.662	0.626	0.569	1.723	1.896	0.938	0.245	1.750	1.256	2.375	1.875	1.625	0	3
G21	40.51	3	39	3.364	0.547	1.020	0.949	0.908	1.942	4.664	0.938	0.278	2.000	1.256	2.375	4.250	5.500	0	3
G22	40.45	4	39	3.118	1.214	0.699	0.669	0.806	2.100	4.632	0.938	0.340	3.000	1.675	1.625	1.750	4.000	0	4
G23	39.58	2	39	2.709	0.347	0.390	0.535	0.849	2.306	2.384	0.938	0.336	2.750	2.373	3.375	3.500	4.625	0	2
G24	38.95	4	39	2.462	1.234	1.070	0.930	0.702	1.334	1.928	0.938	0.246	2.000	2.932	1.625	4.000	3.250	0	2
G25	40.62	4	38	2.849	0.595	0.267	0.387	0.663	1.499	4.585	0.938	0.280	1.500	0.977	0.750	2.250	2.875	0	3
G26	38.08	3	39	2.303	0.884	0.747	0.614	0.458	0.941	1.668	0.938	0.184	2.625	2.234	5.375	2.500	5.625	0	3
G27	40.16	3	39	3.131	0.687	0.860	0.765	0.655	1.439	1.472	0.938	0.233	1.500	1.675	3.500	3.125	2.875	0	2
G28	43.63	2	38	3.515	1.183	0.879	1.117	0.871	2.352	4.606	0.938	0.345	1.875	2.513	2.375	2.625	4.125	0	4
G29	40.74	2	39	1.835	0.505	0.636	0.520	0.485	0.922	2.352	0.938	0.180	2.500	2.894	2.000	2.625	1.250	0	3
G30	39.53	2	39	4.745	0.769	0.806	0.905	0.975	2.308	4.632	0.938	0.355	3.750	1.954	4.125	4.875	5.250	0	3
G31	42.30	3	39	1.676	0.364	0.325	0.560	0.545	1.647	4.664	0.938	0.209	2.000	2.094	1.625	1.875	1.250	0	3
G32	44.91	2	37	1.827	1.540	0.262	0.423	0.547	1.468	4.632	0.938	0.201	1.625	1.675	4.000	1.125	2.750	0	3

T4. PLOTS RIMS

RIMS MAP

RIMS NETWORK

Display the network of RIMS configured in the Scenario:



T5. PLOTS STATS

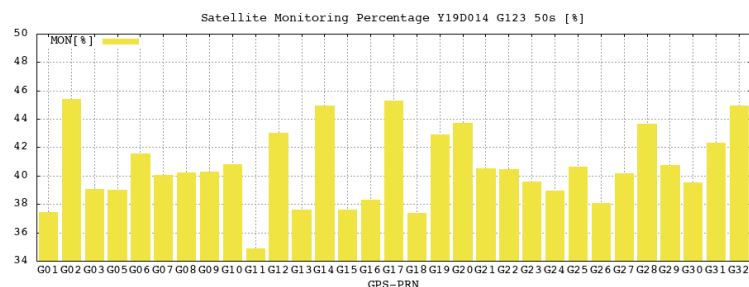
BOX PLOTS

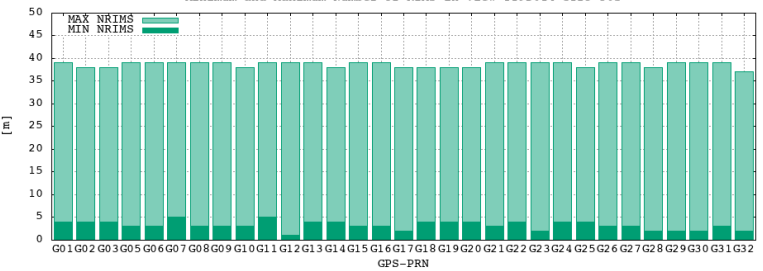
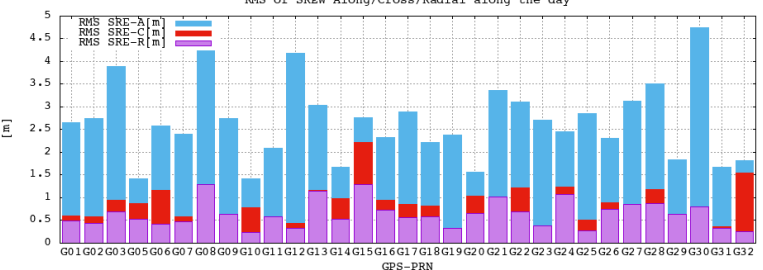
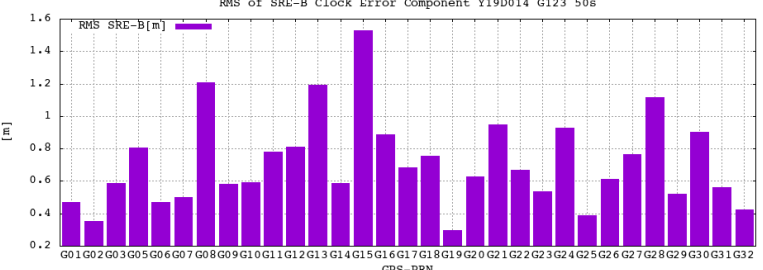
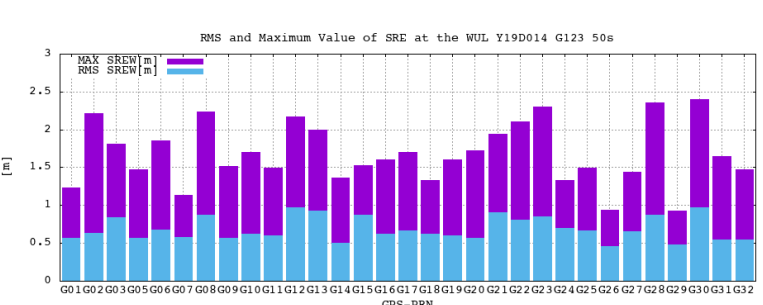
STATISTICS PLOTS

Create a box plot for every column on the Satellite Statistics file where the x-axis is the satellite PRN and the Y-Axis the statistic to plot.

MON

Plot Satellite Monitoring Percentage

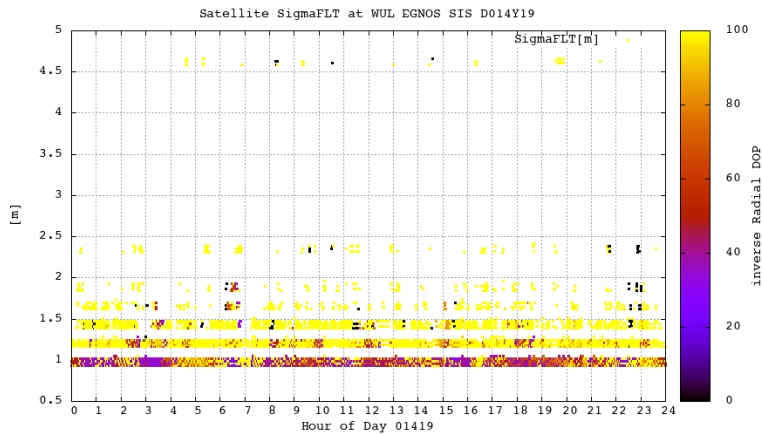
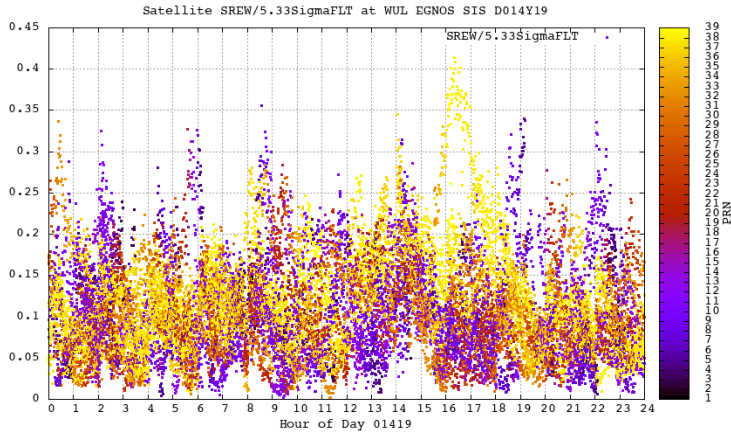


NRIMS	<p>Plot Minimum and Max. Number of RIMS in View</p> <p>Minimum and Maximum Number of RIMS in view Y19D014 G123 50s</p> 	
RMS-SRE _{ACR}	<p>Plot RMS SREA for all satellites as a box-plot</p> <p>RMS of SREW Along/Cross/Radial along the day</p> 	
RMS-SRE _B	<p>Plot RMS SREB for all satellites as a box-plot</p> <p>RMS of SRE-B Clock Error Component Y19D014 G123 50s</p> 	
SREW	<p>Plot RMS and MAX SREW for all satellites as a box-plot</p> <p>RMS and Maximum Value of SRE at the WUL Y19D014 G123 50s</p> 	
MAX and MIN SFLT	<p>Plot MAX and MIN SigmaFLT for all satellites as a box-plot</p>	

MAX SIW	Plot MAX SIW for all satellites as a box-plot	
MAX FC and LTCb	Plot MAX Satellite Clock Fast and Long term Corrections for all satellites	
MAX LTCxyz	Plot MAX LTC-XYZ for all satellites	
NMI	Plot Number of MIs for all satellites as a box-plot	

NTRANS	Plot Number of Transitions for all satellites as a box-plot		
T6. PLOTS Vs. TIME	TIME PLOTS		
MON1	Plot the instantaneous number of satellites monitored as a function of the hour of the day		
MON2	Plot the satellites monitoring windows as a function of the hour of the day		

MON3	<p>Plot the satellites ground tracks on a map during monitoring periods</p>	
SREW	<p>Plot the SREW for all satellites as a function of the hour of the day. 2 plots: 1.PRN in the color bar. 2.Number of RIMS in view in the color bar.</p>	
SigmaFLT (PRN)	<p>Plot the SigmaFLT for all satellites as a function of the hour of the day. 2 plots: 1.Inverse Radial DOP in the color bar. 2.Number of RIMS in view in the color bar.</p>	

		
SI	<p>Plot the SI for all satellites as a function of the hour of the day 1.PRN in the color bar.</p> 	
ENT-GPS Offset	<p>Plot the ENT-GPS Offset along the day</p> 