

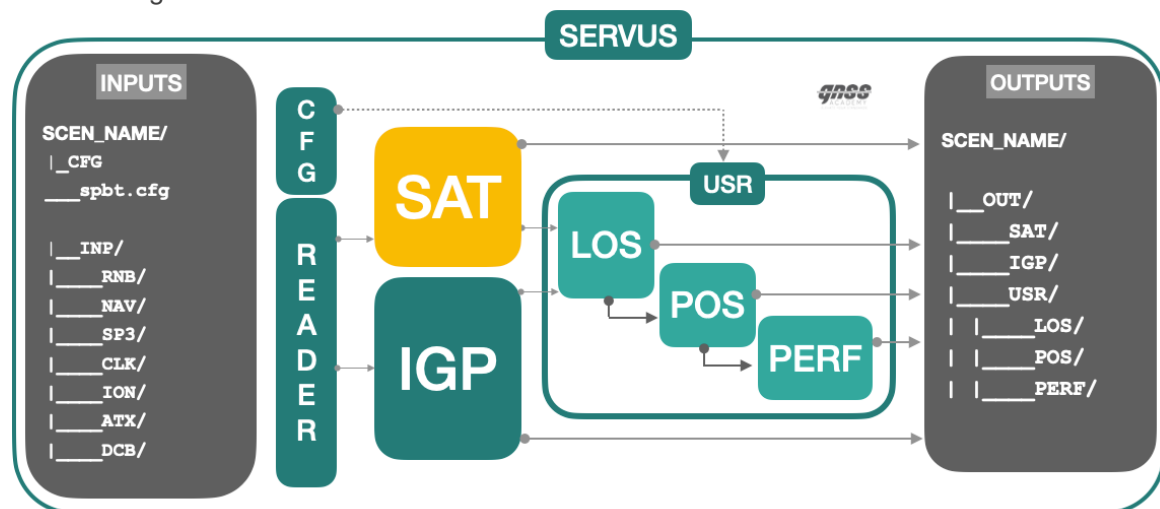
PROJECT: SERVUS		WP Number: WP-0000001
WP TITLE: WP1: Satellite Performance Characterization		Issue: 1.0
LEAD CONTRACTOR	GNSS Academy	
CUSTOMER	ESA	WP LEADER: Student
ESTIMATED EFFORT	20 hours	

OBJECTIVE

The main goal of this Work-Package is to develop the **Satellite Performance Module** of SERVUS tool by providing the daily satellite performance characterization on a EGNOS SIS real data campaign in January 2019

SCOPE

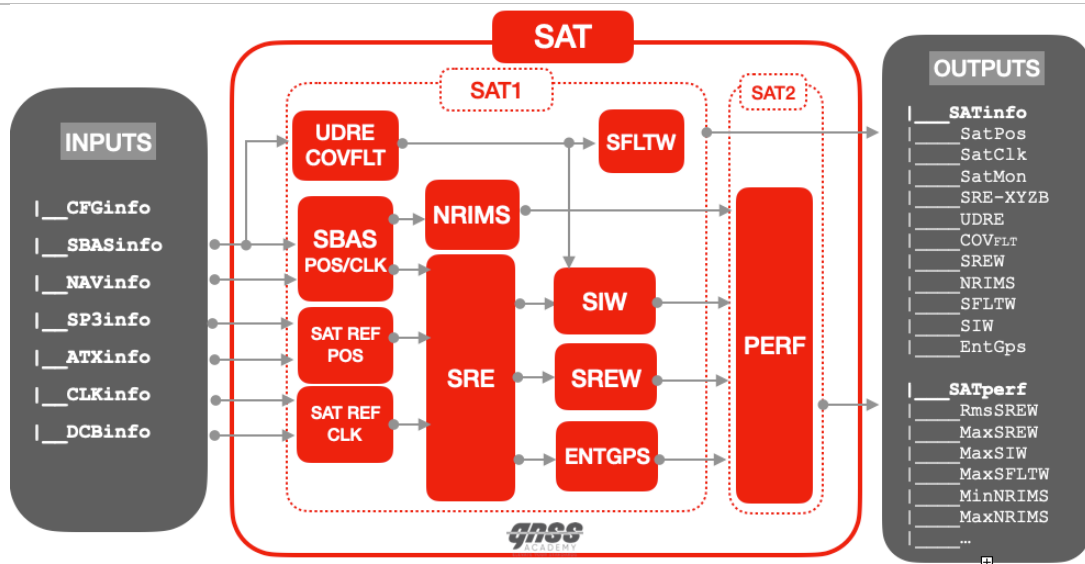
SERVUS high-level Architecture:



The **SERVUS SAT** module, the one in charge of computing SRE and the SigmaFLT as the main satellite indicators, is already implemented producing a daily file with the instantaneous information allowing to later characterize the satellite performance.

The main functions of this module are:

- Compute the Satellite Position and Clock from GPS Navigation Message
- Extract SBAS SIS satellite-related information:
 - FLT Corrections: FC (MT2-5/24), LTC (MT24-M25)
 - FLT Integrity Sigmas: UDRE (MT2-6), COV Matrix (MT27 or MT28)
 - Satellite Monitoring Flags (M/NM/DU) (MT2-6)
 - Degradation Factors (MT7-MT10)
- Compute the Satellite Corrected Position applying the corrections to the Navigation message.
- Compute True Orbit and Clock Information from reference files.
- Compute Satellite level main indicators:
 - Orbit&Clock Error: SRE-XYZ and SRE-ACR and SRE-B → SREW (@WUL)
 - Error Variance: SigmaFLT at the WUL
 - Satellite Safety Index: SREU/5.33 SigmaFLT at WUL
 - Time Scale Offset: ENT-GPS OFFSET
- Assess the Satellite Performance in terms of accuracy (RMS SRE), Integrity (SI) and upper-bound (SigmaFLT)

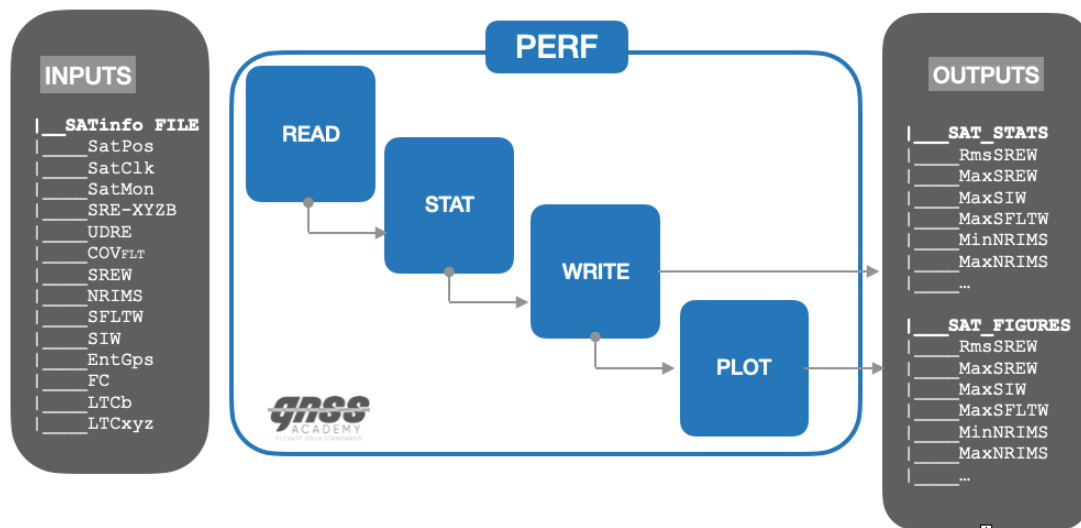


This first Work-package is related to the satellite-level characterization performances in terms of accuracy, integrity, and upper-bound.

- **Satellite Accuracy** is given by different statistics of the SRE (Satellite Residual Error) including the satellite orbit and clock errors.
- **Satellite Upper-bounding** and **Continuity** characterization is given by some statistics related to the SigmaFLT (equivalent to UDRE or SigmaUDRE)
- **Satellite Integrity** is given by the safety index $SREU/5.33\text{SigmaFLT}$ at the Worst User location of the service are in order to ensure that the provided SigmaFLT correctly bounds the Error up to the required confidence levels.

This Work-package aims at developing the SAT2 Module corresponding to SAT PERF.

1. Read Satellite Instantaneous Information file.
2. Compute Satellite Statistics.
3. Write a Satellites Statistics file.
4. Plot Satellite Statistics.



INPUTS

This Work-package uses daily input files as the output of the SAT module.

1. SAT_INFO_Y19D014_G123.dat (See Description Below)

FILENAME: SAT_INFO_Y19D014_G123_50s.dat

Column	Content	Format	Units	Description
C1	SOD	%5d	SEC	Second of Day
C2	DOY	%03d	DAYS	Day of the Year
C3	PRN	%s%02d	No Units	Satellite PRN for GPS, Galileo or GEO
C4	SAT-X	%f	KMS	Satellite Navigation Position (CURRENT) X-Component
C5	SAT-Y	%f	KMS	Satellite Navigation Position (CURRENT) Y-Component
C6	SAT-Z	%f	KMS	Satellite Navigation Position (CURRENT) Z-Component
C7	MONSTAT	%d	No Units	Satellite Monitoring Status (0: NM; 1:M; -1; DU)
C8	SRESTAT	%d	No Units	Satellite SRE Status (0: NOK 1:OK)
C9	SREx	%f	METER	Satellite Residual Error X-Component
C10	SREy	%f	METER	Satellite Residual Error Y-Component
C11	SREz	%f	METER	Satellite Residual Error Z-Component
C12	SREb1	%f	METER	Preliminary Satellite Residual Error Clock Bias Component (containing the ENT-GPS Offset)
C13	SREW	%f	METER	Satellite Residual Error projected at the Worst User Location (WUL)
C14	SFLT-W	%f	METER	SigmaFLT/DFC projected at the Worst User Location (WUL)
C15	UDREI	%d		Satellite UDREI/DFREI Indicator
C16	FC	%f	METER	Satellite Clock Fast Corrections
C17	AF0	%f	METER	Satellite Clock Long Term Corrections Offset (LTCb=AF0+AF1(t-t0))=AF0 in EGNOS V2
C18	AF1	%f	METER	Satellite Clock Long Term Corrections drift This term is NULL in EGNOS V2
C19	LTCx	%f	METER	Satellite Orbit Long Term Corrections X-Component
C20	LTCy	%f	METER	Satellite Orbit Long Term Corrections Y-Component
C21	LTCz	%f	METER	Satellite Orbit Long Term Corrections Z-Component
C22	NRIMS	%d	-	Number of RIMS inside the ECAC that are in view from the satellite over a mask angle for, at least, 10min
C23	RDOP	%f	-	Radial DOP is the inverse DOP as seen from the Satellite to RIMS projected into the Radial direction

2. RIMS_REF_POSITIONS_2019.dat (See Description Below)

FILENAME: RIMS_REF_POSITIONS_2019.dat

Column	Content	Format	Units	Description
C1	RIMS _{FLAG}	%4d	none	Selection flag to activate or deactivate this RIMS from the PAN processing
C2	RIMS _{ACRONYM}	%8s	none	RIMS Acronym with 4 characters (e.g: ACRA)

C3	RIMS_{ID}	%02d	none	RIMS identifier as an integer between 00 and 99.
C4	RIMS_{LOn}	%15.7f	deg	RIMS geographical longitude position
C5	RIMS_{LAT}	%15.7f	deg	RIMS geographical latitude
C6	RIMS_{ALT}	%12.3f	m	RIMS height in meters
C7	RIMS_{MASK}	%10.2f	deg	RIMS Mask angle
C8	RIMS_{ACQ}	%5d	s	RIMS Receiver Acquisition time
C9	RIMS_{SITE}	%20s	none	RIMS site location as the representative name of the city
C10	RIMS_{COUNT}	%20s	none	RIMS Country location

RIMS Parameters

#	p1	p2	p3	p4	p5	p6	p7	p8	p9	p10
1	ABSA	01	31.6168738	22.3584909	199.489	10.00	5	Abu-Simbel	Egypt	
1	ACRA	02	-28.6228066	38.5186833	198.582	10.00	5	Azores	Portugal	
1	ALBA	03	9.8831919	57.0963560	42.678	10.00	5	Alborg	Denmark	
1	ALYA	04	29.9557435	31.1829123	12.531	10.00	5	Alexandria	Egypt	
1	ATHA	05	23.7911121	37.8612226	368.684	10.00	5	Athens	Greece	
1	BRNA	06	13.5410936	52.3569463	83.432	10.00	5	Berna	Switzerland	
1	CNRA	07	-15.3793852	27.9454109	51.123	10.00	5	Canary	Spain	
1	CRKA	08	-8.4962089	51.8446852	201.929	10.00	5	Cork	Ireland	
1	CTNA	09	15.0619850	37.4636507	47.297	10.00	5	Catania	Italy	
1	DJAA	10	10.7717472	33.8801909	36.873	10.00	5	Djerba	Tunisia	
1	EGIA	11	-14.4007338	65.2800856	89.528	10.00	5	Egilsstadir	Iceland	
1	GLGA	12	-4.4456436	55.8706262	64.261	10.00	5	Glasgow	Ireland	
1	GOLA	13	32.8035793	39.6381446	1088.564	10.00	5	Golbasi	Turkey	
1	GVLA	14	17.1331590	60.6663660	53.299	10.00	5	Gavle	Sweeden	
1	JMEA	15	-8.4915201	70.9728644	63.463	10.00	5	Jan-Mayen	Norway	
1	KIRA	16	29.9313365	69.7311459	119.770	10.00	5	Kirkenes	Norway	
1	LAPA	17	27.5553483	60.5388860	35.773	10.00	5	Lappeenranta	Finland	
1	LPJA	18	-17.7603716	28.6196424	137.719	10.00	5	LaPalma	Spain	
1	LSBA	19	-9.1298707	38.7887635	157.600	10.00	5	Lisbon	Portugal	
1	LYRA	20	15.3965961	78.2285265	496.566	10.00	5	Svalbard	Norway	
1	MADA	21	-16.7056705	32.7474268	192.855	10.00	5	Madeira	Portugal	
1	MLGA	22	-4.5144494	36.6846957	60.881	10.00	5	Malaga	Spain	
1	PARA	23	2.3349038	48.8359007	123.380	10.00	5	Paris	France	
1	PDMA	24	2.7387532	39.5636956	51.540	10.00	5	Mallorca	Spain	
1	RKKA	25	-21.9315020	64.1292866	83.945	10.00	5	Reykjavik	Iceland	
1	ROMA	26	12.5837594	41.8039468	172.877	10.00	5	Rome	Italy	
1	SDCA	27	-8.4248159	42.9264046	437.005	10.00	5	Santiago	Spain	
1	SOFA	28	23.4101179	42.6848906	611.360	10.00	5	Sofia	Bulgaria	
1	SWAA	29	-1.2869796	50.8871205	76.428	10.00	5	Swanwich	England	
1	TLSA	30	1.4970244	43.4285678	253.477	10.00	5	Toulouse	France	
1	TRDA	31	10.8993146	63.4568329	43.875	10.00	5	Trondheim	Norway	
1	TROA	32	18.9390987	69.6631570	136.126	10.00	5	Tromsø	Norway	
1	WRSB	33	21.0676369	52.2147521	125.452	10.00	5	Warsaw	Poland	
1	ZURA	34	8.5648888	47.4537484	514.795	10.00	5	Zurich	Switzerland	
1	NOUA	35	-15.9544648	18.0818926	35.278	10.00	5	Nouakchott	Mauritania	
1	HFAA	36	35.0220640	32.7789087	239.597	10.00	5	Haifa	Israel	
1	AGAA	37	-9.4115837	30.3185120	119.179	10.00	5	Agadir	Morocco	
1	HBKA	38	27.7071958	-25.8833373	1548.973	10.00	5	Hartebeesthoek	SouthAfrica	
1	MONA	39	-64.7692785	46.0711908	31.816	10.00	5	Moncton	Canada	

OUTPUTS

Two main kind of outputs for this Work Package are required:

- A Daily file with per satellite performance Statistics with the following format and content:
SAT_STAT_Y19D014_G123_50s.dat

Column	Content	Format	Units	Description
C1	PRN	%s	No Units	Satellite PRN for GPS (e.g: G01)
C2	MON	%6.2f	%	Satellite Monitoring Percentage along the day
C3	RIMS-MIN	%4d	No Units	Minimum Number of RIMS in view during the day
C4	RIMS-MAX	%6d	No Units	Maximum Number of RIMS in view during the day
C5	SREaRMS	%10.3f	METER	RMS of the SRE-A along the day, the Satellite Orbit Residual Error Along-Track component

C6	SREcRMS	%8.3f	METER	RMS of the SRE-C along the day, the Satellite Orbit Residual Error Cross-Track component
C7	SRErRMS	%8.3f	METER	RMS of the SRE-R along the day, the Satellite Orbit Residual Error Radial component
C8	SREbRMS	%8.3f	METER	RMS of the SRE-B along the day: the Satellite Residual Error Clock component SRE-B is computed subtracting the ENT-GPS Offset from the SREb1
C9	SREW RMS	%8.3f	METER	RMS of SREW along the day
C10	SREW MAX	%8.3f	METER	Maximum SREW reached along the day
C11	SFLT MAX	%8.3f	METER	Maximum SigmaFLT@WUL reached along the day
C12	SFLT MIN	%8.3f	METER	Minimum SigmaFLT@WUL reached along the day
C13	SIMAX	%8.3f	No Units	Maximum SI _{SAT} reached along the day $SI_{SAT} = \frac{SREW}{5.33 \cdot SFLT_w}$
C14	FCMAX	%8.3f	METER	Maximum Satellite Clock Fast reached along the day.
C15	LTCb MAX	%8.3f	METER	Maximum Clock Long Term Corrections (LTCb) reached along the day
C16	LTCx MAX	%8.3f	METER	Maximum Satellite Long Term Corrections X-Component (LTCx) reached along the day
C17	LTCy MAX	%8.3f	METER	Maximum Satellite Long Term Corrections Y-Component (LTCy) reached along the day
C19	LTCz MAX	%8.3f	METER	Maximum Satellite Long Term Corrections Z-Component (LTCz) reached along the day
C20	NMI	%8.3f	No Units	Number of Misleading Information (MI). Number of times SIW > 1
C21	NTRANS	%4d	No Units	Number of Transitions from M to NM and M to DU

- A Daily file containing the estimated ENT-GPS per epoch:
ENTGPS_Y19D014_G123_50s.dat

Column	Content	Format	Units	Description
C1	SOD	%5d	SEC	Second of Day
C2	ENT-GPS	%10.4f	SEC	ENT to GPS Offset computed as follows: $ENTGPS = \text{median}(\{SREb1 - SREr\}_{SRESTATUS==1})$ Where SREr is the projection of (SREx, SREy, SREz) into the satellite radial direction And SREb1 is the preliminary Satellite Clock Error including the time scales offset

- Daily Satellite performance plots

TASKS

ID	DESCRIPTION
T0. PRELIMINARY	Downloading and Understanding
T0.1 FOLDER TREE	<p>Download following TAR file:</p> <p>STEP1. Download SERVUS-TOOL folder tree and files</p> <p>→ SBPT-SERVUS_WP1.tgz</p> <p>STEP2. Place it somewhere in the GNSS Academy working directory</p> <p>STEP3 untar the file.</p>

	<pre>tar xvfz SBPT-SERVUS_WP1.tgz</pre> <p>Check that all the following information is available:</p> <p>SBPT/SERVUS/SERVUS_V1.0/SERVUS_WP1_SAT/</p> <pre> ____ SRC ____ SatPerformances.py ____ SatFunctions.py ____ COMMON ____ PlotsConstants.py ____ Plots.py ____ Coordinates.py ____ GnssConstants.py ____ Dates.py ____ SCN ____ SCEN-EGNOS-SIS-GEO123-JAN19 ____ CFG ____ satperformances.cfg ____ INP ____ NAV/brdc0140.19n ____ RNB/M1230140.19b ____ EMS/GEO123/2019/DOY014/h*.ems ____ SP3/igs20361.sp3 ____ DCB/P1C11901.DCB & P1P21901.DCB ____ ATX/igs14.atx ____ ION/igsg0140.19i ____ CLK/igs20361.clk_30s ____ RIMS/RIMS_REF_POSITIONS_2019.dat ____ OUT ____ SAT ____ SAT_INFO_Y19D014_G123_50s.dat ____ SAT_INFO_Y19D015_G123_50s.dat ____ SAT_INFO_Y19D016_G123_50s.dat</pre> <p>Note that there are 3 SAT_INFO files already sampled at 50 seconds in order to speed-up the execution process.</p> <p>Output Files will be generated in:</p> <pre>OUT/SAT/SAT_STAT_Y19D014_G123_50s.dat OUT/SAT/SAT_STAT_Y19D015_G123_50s.dat OUT/SAT/SAT_STAT_Y19D016_G123_50s.dat</pre> <p>Output Figures shall be generated in:</p> <pre>OUT/SAT/figures/*.png</pre>	
T1. IMPLEMENTATION	Functions Implementation: Open/Reading/Loading	
T1.1 Configuration	<p>Check configuration file. 3 configuration parameters, INI_DATE, END_DATE (in order to run only one day, both shall be the same) and TSTEP.</p> <p>CFG/satperformances.cfg</p>	
T1.2 Execution	<p>Execute SatPerformance Module</p> <p>Call Main function from the SRC directory and check that you generate</p>	

	<p><code>python SatPerformances.py ../SCN/SCEN-EGNOS-SIS-GEO123-JAN19</code></p> <p>Check that this runs properly and that already generates the following files: OUT/SAT/SAT_STAT_Y19D014_G123_50s.dat OUT/SAT/ENTGPS_Y19D014_G123_50s.dat</p> <p>These files are partial files that have to be completed with the remaining columns.</p>	
T1.3 Implementation	Implement the necessary Python functions to create the satellite statistics file with all the different columns, in line with following tasks.	
T2. ENTGPS	Create a file including the instantaneous ENT-GPS Offset	
SOD	Seconds of Day	
ENTGPS	<p>ENT-GPS Offset: estimated from the SRE of the monitored satellites with SRE_STATUS OK, as follows:</p> $ENTGPS = \text{median}(\{SREb1 - SREr\}_{SRESTATUS==1})$ <p>Where SREr is the projection of (SREx, SREy, SREz) into the satellite radial direction</p>	
T3. STATISTICS	Create a file including all satellite Statistics with the following information per columns. SAT_STATISTICS	
PRN	PRN: Satellite PRN	
MON	<p>Satellite Monitoring Percentage in the day. Count the number of epochs the satellite has been monitored during the day divided by the total number of seconds in the day.</p>	
MIN RIMS	<p>Minimum number of RIMS in view by the satellite during the day Note that the satellite is monitored by EGNOS when the satellite is seen at least by 3 RIMS.</p>	
MAX RIMS	Maximum number of RIMS in view by the satellite during the day	
RMS-SREr	<p>Root Mean Square of Satellite Orbit Error - Radial Component</p> <p>Note that SREr is not in the input file. It has to be computed by projecting the SREXYZ along the orbit radial component.</p> <p>Radial Direction $U_R = r_s / r_s$</p>	
RMS-SREc	<p>Root Mean Square of Satellite Orbit Error - Cross Track Component</p> <p>Note that SREc is not in the input file. It has to be computed by projecting the SREXYZ along the orbit cross track component.</p> <p>$U_C = U_R \times U_V$</p> <p>where $U_R = r_s / r_s$ in the direction of the satellite position (r_s) $U_V = v_s / v_s$ in the direction of the satellite velocity (v_s)</p> <p>Note that Velocity is obtained by deriving the Satellite Position during the monitoring periods. Care shall be taken for the first epoch of the satellite monitoring pass since</p>	

	<p>no previous position to compute the velocity. First sample will be discarded from the statistics.</p> <p>Do not forget that it is a non-inertial reference frame and you need to add the Earth's Rotation in order to get the absolute velocity.</p> $V_{sat} = \frac{P_{sat}(k) - P_{sat}(k - 1)}{\Delta t} + \Omega_{EARTH} \times P_{sat}(k)$ <p># Earth's rotation rate (rad/sec) OMEGA_EARTH = 7.2921151467e-5</p>																		
RMS-SRE_A	<p>Root Mean Square of Satellite Orbit Error - Along Track Component</p> <p>Note that SRE_A is not in the input file. It has to be computed by projecting the SRE_{XYZ} along the orbit along track component.</p> <p>Along-Track is the cross product between Cross and Radial Track Component. U_A=U_C x U_R</p> $RMS = \sqrt{\frac{\Sigma(X_k)^2}{N}}$																		
RMS-SRE_B	<p>Root Mean Square of SRE-B Clock Component <i>SRE-B is computed subtracting the ENT-GPS Offset from the SREb1</i></p>																		
RMS-SREW	<p>Root Mean Square of SREW: satellite Orbit Error at the Worst User Location</p>																		
MAX-SREW	<p>Maximum SREW Satellite Orbit Error at the Worst User Location</p>																		
MAX-SFLT	<p>Maximum Sigma FLT as the Satellite Orbit and clock Error Sigma at the Worst User Location.</p>																		
MAX-SIW	<p>Maximum Satellite Safety Index as the ratio between the SRE and the SigmaFLT at the Worst User Location The instantaneous SI for each satellite shall be computed as follows:</p> $SI_{SAT} = \frac{SREW}{5.33 \cdot SFLT_W}$																		
MAX-LTC_x	<p>Maximum (absolute)Value of the Satellite Position LTC correction X-Component</p>																		
MAX-LTC_y	<p>Maximum (absolute)Value of the Satellite Position correction LTC Y-Component</p>																		
MAX-LTC_z	<p>Maximum (absolute)Value of the Satellite Position correction LTC Z-Component</p>																		
MAX-LTCb	<p>Maximum (absolute) Value of the Satellite LTC -Clock AF0</p>																		
MAX-FC	<p>Maximum (absolute)Value of the Satellite Clock Fast Corrections</p>																		
NMI	<p>Number of Satellite MIs (Misleading Information) as the number of times SI is higher than 1. (SI>1)</p>																		
NTRANS	<p>Number of transitions Monitored to Not Monitored (MtoNM) or to Don't USE (MtoDU)</p>																		
SAT_STAT_Y19D014_G123_50s.dat																			
#PRN	MON	minRIMS	MaxRIMS	SREaRMS	SREcRMS	SRErRMS	SREbRMS	SREW RMS	SREW MAX	SFLT MAX	SFLT MIN	SIMAX	FOMAX	LTCb MAX	LTCc MAX	LTCy MAX	LTCz MAX	NMI	NTRANS
G01	37.44	4	39	2.663	0.591	0.488	0.470	0.562	1.235	2.384	0.938	0.228	1.750	1.675	2.375	3.625	4.500	0	3
G02	45.43	4	38	2.739	0.581	0.428	0.352	0.630	2.214	2.352	0.938	0.248	2.750	0.977	2.625	1.875	3.000	0	3
G03	39.06	4	38	3.898	0.947	0.691	0.587	0.842	1.807	4.664	0.938	0.286	2.375	2.094	3.000	4.500	4.125	0	5
G05	39.00	3	39	1.421	0.875	0.527	0.807	0.567	1.475	1.700	0.938	0.281	2.000	1.256	1.625	2.125	1.250	0	2
G06	41.55	3	39	2.587	1.160	0.411	0.470	0.671	1.859	4.632	0.938	0.249	1.750	2.094	2.000	2.250	1.625	0	3
G07	40.05	5	39	2.397	0.575	0.479	0.499	0.580	1.136	2.384	0.938	0.210	2.500	2.094	3.000	2.125	1.625	0	3
G08	40.22	3	39	4.232	0.577	1.285	1.209	0.873	2.240	2.352	0.938	0.336	2.875	2.652	5.875	6.625	6.500	0	2
G09	40.28	3	39	2.747	0.620	0.643	0.584	0.562	1.514	4.664	0.938	0.209	1.375	1.256	7.500	3.750	6.500	0	6
G10	40.80	3	38	1.427	0.776	0.241	0.592	0.619	1.706	2.422	0.938	0.315	1.625	2.234	1.250	3.500	4.000	0	7
G11	34.90	5	39	2.082	0.414	0.585	0.782	0.682	1.498	1.510	0.938	0.288	1.250	2.513	2.875	3.125	2.875	0	3
G12	43.00	1	39	4.173	0.435	0.330	0.811	0.970	2.172	1.870	0.938	0.414	2.875	1.117	1.500	2.750	4.625	0	8
G13	37.62	4	39	3.031	1.160	1.142	1.195	0.931	1.996	2.306	0.938	0.272	1.875	3.211	1.875	4.250	4.000	0	5
G14	44.91	4	38	1.675	0.983	0.531	0.589	0.505	1.366	1.896	0.938	0.241	0.875	1.256	1.750	2.250	2.750	0	3

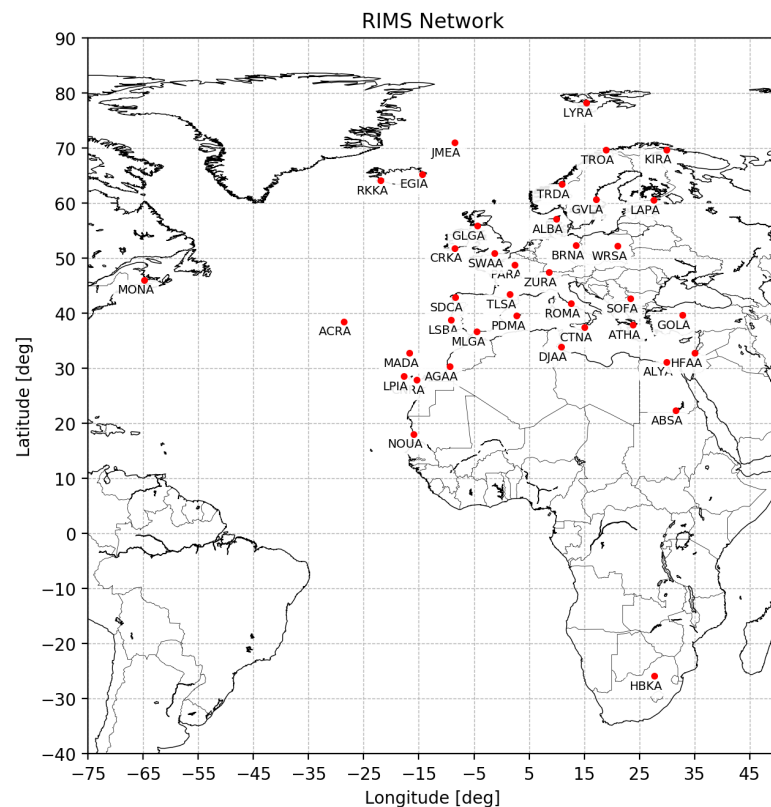
G16	38.31	3	39	2.326	0.937	0.724	0.889	0.617	1.608	1.896	0.938	0.300	1.625	1.117	2.625	1.625	3.375	0	3
G17	45.31	2	38	2.897	0.859	0.557	0.683	0.663	1.701	2.384	0.938	0.201	1.750	0.698	2.125	2.125	2.125	0	2
G18	37.38	4	38	2.216	0.818	0.578	0.754	0.624	1.331	2.352	0.938	0.206	2.375	2.094	2.250	3.000	4.375	0	3
G19	42.88	4	38	2.382	0.331	0.329	0.297	0.600	1.603	1.966	0.938	0.256	2.625	1.117	3.250	0.625	3.875	0	2
G20	43.09	4	38	1.556	1.032	0.662	0.626	0.569	1.723	1.896	0.938	0.245	1.750	1.256	2.375	1.875	1.625	0	3
G21	40.51	3	39	3.364	0.547	1.020	0.949	0.908	1.942	4.664	0.938	0.278	2.000	1.256	2.375	4.250	5.500	0	3
G22	40.45	4	39	3.118	1.214	0.699	0.669	0.806	2.100	4.632	0.938	0.340	3.000	1.675	1.625	1.750	4.000	0	4
G23	39.58	2	39	2.709	0.347	0.390	0.535	0.849	2.306	2.384	0.938	0.336	2.750	2.373	3.375	3.500	4.625	0	2
G24	38.95	4	39	2.462	1.234	1.070	0.930	0.702	1.334	1.928	0.938	0.246	2.000	2.932	1.625	4.000	3.250	0	2
G25	40.62	4	38	2.849	0.595	0.267	0.387	0.663	1.499	4.585	0.938	0.280	1.500	0.977	0.750	2.250	2.875	0	3
G26	38.08	3	39	2.303	0.884	0.747	0.614	0.458	0.941	1.668	0.938	0.184	2.625	2.234	5.375	2.500	5.625	0	3
G27	40.16	3	39	3.131	0.687	0.860	0.765	0.655	1.439	1.472	0.938	0.233	1.500	1.675	3.500	3.125	2.875	0	2
G28	43.63	2	38	3.515	1.183	0.879	1.117	0.871	2.352	4.606	0.938	0.345	1.875	2.513	2.375	2.625	4.125	0	4
G29	40.74	2	39	1.835	0.505	0.636	0.520	0.485	0.922	2.352	0.938	0.180	2.500	2.894	2.000	2.625	1.250	0	3
G30	39.53	2	39	4.745	0.769	0.806	0.905	0.975	2.308	4.632	0.938	0.355	3.750	1.954	4.125	4.875	5.250	0	3
G31	42.30	3	39	1.676	0.364	0.325	0.560	0.545	1.647	4.664	0.938	0.209	2.000	2.094	1.625	1.875	1.250	0	3
G32	44.91	2	37	1.827	1.540	0.262	0.423	0.547	1.468	4.632	0.938	0.201	1.625	1.675	4.000	1.125	2.750	0	3

T4. PLOTS RIMS

RIMS MAP

RIMS NETWORK

Display the network of RIMS configured in the Scenario:



T5. PLOTS STATS

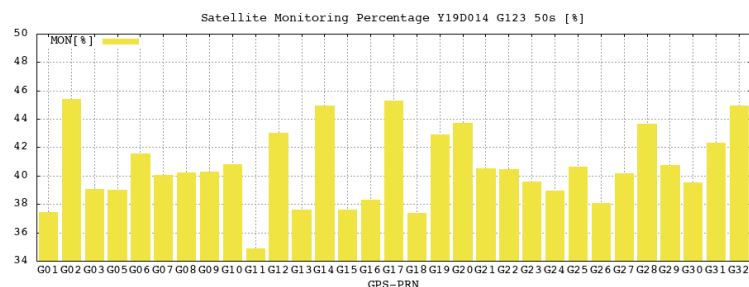
BOX PLOTS

STATISTICS PLOTS

Create a box plot for every column on the Satellite Statistics file where the x-axis is the satellite PRN and the Y-Axis the statistic to plot.

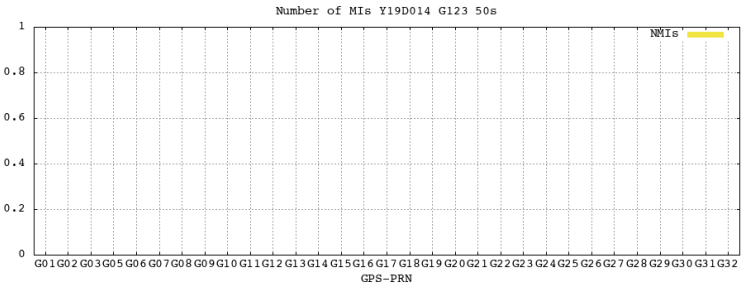
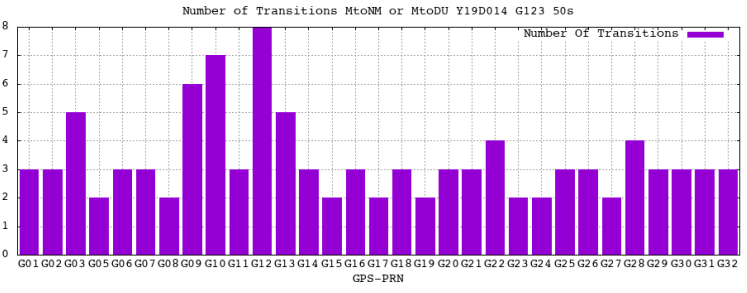
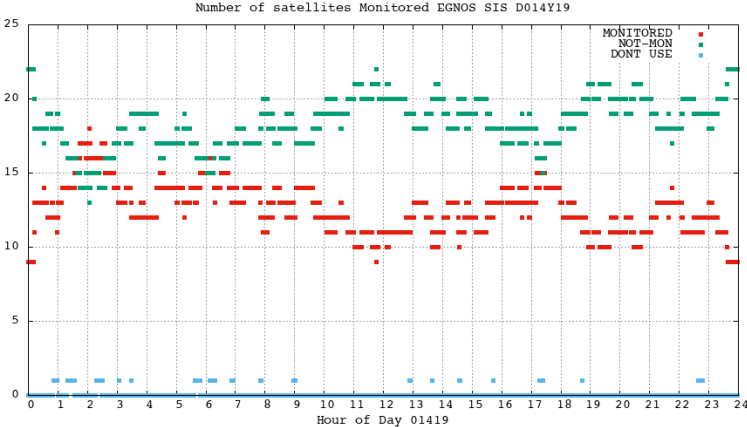
MON

Plot Satellite Monitoring Percentage

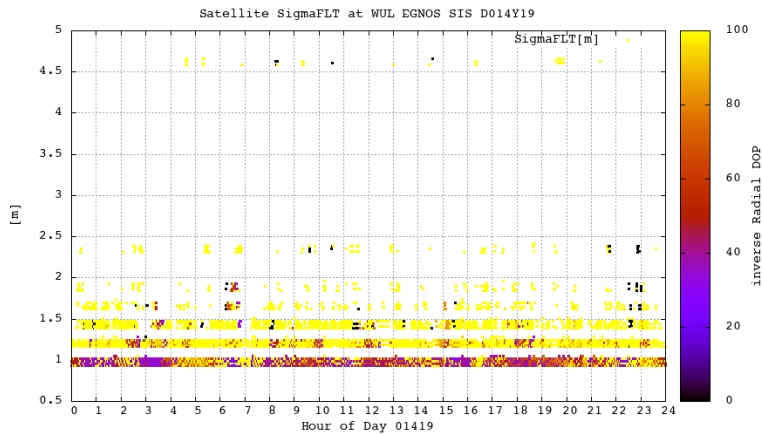
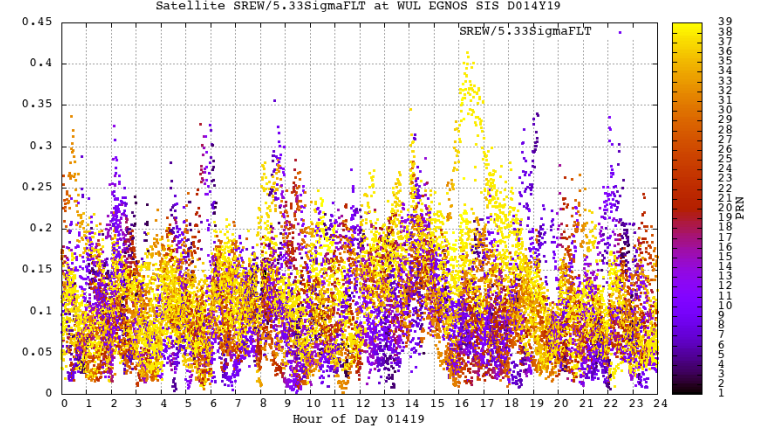


NRIMS	<p>Plot Minimum and Max. Number of RIMS in View</p> <p>Minimum and Maximum Number of RIMS in view Y19D014 G123 50s</p>
RMS-SRE_{ACR}	<p>Plot RMS SREA for all satellites as a box-plot</p> <p>RMS of SREW Along/Cross/Radial along the day</p>
RMS-SRE_B	<p>Plot RMS SREB for all satellites as a box-plot</p> <p>RMS of SRE-B Clock Error Component Y19D014 G123 50s</p>
SREW	<p>Plot RMS and MAX SREW for all satellites as a box-plot</p> <p>RMS and Maximum Value of SRE at the WUL Y19D014 G123 50s</p>
MAX and MIN SFLT	<p>Plot MAX and MIN SigmaFLT for all satellites as a box-plot</p>

	<p>Maximum and Minimum SigmaFLT (=SigmaUDRE) Y19D014 G123 50s</p>	
MAX SIW	<p>Plot MAX SIW for all satellites as a box-plot</p>	
MAX FC and LTCb	<p>Plot MAX Satellite Clock Fast and Long term Corrections for all satellites</p>	
MAX LTCxyz	<p>Plot MAX LTC-XYZ for all satellites</p>	
NMI	<p>Plot Number of MIs for all satellites as a box-plot</p>	

		
NTRANS	<p>Plot Number of Transitions for all satellites as a box-plot</p> 	
T6. PLOTS Vs. TIME	TIME PLOTS	
MON1	<p>Plot the instantaneous number of satellites monitored as a function of the hour of the day</p> 	
MON2	<p>Plot the satellites monitoring windows as a function of the hour of the day</p>	

	<p>Satellite Monitoring EGNOS SIS D014Y19</p>	
MON3	<p>Plot the satellites ground tracks on a map during monitoring periods</p> <p>Satellite Tracks during Monitoring Periods D014Y19</p>	
SREW	<p>Plot the SREW for all satellites as a function of the hour of the day. 2 plots: 1. PRN in the color bar. 2. Number of RIMS in view in the color bar.</p> <p>Satellite SREW EGNOS SIS D014Y19</p>	
SigmaFLT (PRN)	<p>Plot the SigmaFLT for all satellites as a function of the hour of the day. 2 plots: 1. Inverse Radial DOP in the color bar. 2. Number of RIMS in view in the color bar.</p>	

		
<p>SI</p>	<p>Plot the SI for all satellites as a function of the hour of the day 1.PRN in the color bar.</p> 	
<p>ENT-GPS Offset</p>	<p>Plot the ENT-GPS Offset along the day</p> 