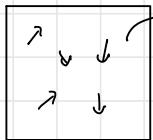


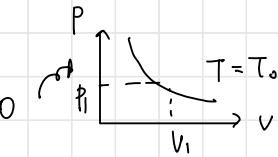
Introduction

Thermodynamics: Transformations between heat and work relationships between macroscopic properties of a macroscopic system.



$$\begin{cases} \dot{\delta}_i = \frac{\partial H}{\partial P_i} \\ \dot{P}_i = -\frac{\partial H}{\partial \dot{\delta}_i} \end{cases}$$

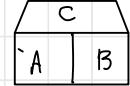
$$N \gg 1 \rightarrow f(P, T, V) = 0$$



↳ Thermodynamic System: Large numbers of particles

⇒ It obeys Thermodynamic Laws

0th Law: Thermal equilibrium ↗ Definition of temperature



1st Law: Conservation of Energy ↗ Form of a Transition

$$\begin{array}{l} T_A = T_C \\ T_B = T_C \end{array} \Rightarrow T_A = T_B$$

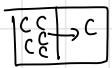
$$\Delta U = Q + W \text{ with } W = \pm P dV \text{ (work done by a system)} \\ Q = \text{Heat observed by a system}$$

2nd Law: Entropy, [$\Delta S \geq 0$ for an isolated system]

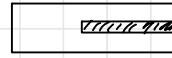
$$\Delta S = \frac{\Delta Q}{T} \quad \text{only if } T.$$

(*) Historical Development.

- 1824, Carnot heat engine : Engine Limitation of Performance
- Misconcept of theory : Heat Particle, Caloric (열고)의 fluid을 이해.



→ Thompson's Cannon Drilling
날부



- 1842, Mayer : Heat & Work thm
- 1850, Clausius, Kelvin : Classical thermodynamics
- Atomic approach : Desire to explain in microscopic scale
 - 1859, Maxwell
 - 1872, Boltzmann ... $\approx n(v_1 v_2 v_3)$] → kinetic theory

Gibbs
Boltzmann
Probabilistic approach
→ Statistical mech.

I. Preliminary Probability Theory

1. Definition and Simple Properties

Let $X \rightarrow S = \{x_1, x_2, \dots, x_n\}$ and $E \subset S$ ($E = \text{events}$)

$\hookrightarrow S$ 의 카테고리

then, Probability of the event $P(E)$ can be defined as

- Objective (Experimental) way : $P(A) = \lim_{N \rightarrow \infty} \frac{N_A}{N}$
- Subjective (Theoretical) way : Lack of information (Uncertainty)
 \rightarrow Theoretical Estimate.

집합이론에 의거, 다음 성질들이 성립한다.

mutually

exclusive

$$P(A \cup B) = P(A) + P(B) - P(A \cap B) \xrightarrow{\text{mutually exclusive}} P(A) + P(B)$$

$$\underbrace{P(B|A)}_{A가 일어났을 때} = \frac{P(A, B)}{P(A)} \rightarrow P(A \cap B) = P(A)P(B) \quad (independence)$$

$$\text{B가 일어날 확률} \Rightarrow P(A|B) = \frac{P(A)}{P(B)} P(B|A)$$

$$\Rightarrow P(B) = \sum_{i=1}^n P(A_i) P(B|A_i) \quad (\text{When } A_i \text{ are mutually exclusive})$$

$$\bullet \text{Permutation (Order-dependence)} = nP_k = \frac{n!}{(n-k)!}$$

\hookrightarrow Binomial Coefficient

$$\bullet \text{Combination (Order-Independence)} = {}_nC_k = \binom{n}{k} = \frac{n!}{(n-k)! k!}$$

(*) Sort of Probability

① Discrete Probability Distribution

$X \rightarrow X_i$ with P_i

$$\sum_i P_i = 1$$

$$\langle X \rangle = \sum X_i P_i \quad (\text{Mean, Expectation, Average})$$

$$\langle f(X) \rangle = \sum f(X_i) P_i$$

② Continuous Prob Distbn

$$\underbrace{P(x)dx}_{\text{density}} = \text{Prob s.t. } E \in [x, x+dx] \quad \begin{cases} \int P(x)dx = 1 \\ \langle x \rangle = \int dx \cdot x P(x) \\ \langle f(x) \rangle = \int dx \cdot f(x) P(x) \end{cases}$$

(*) Variance (Dispersion, mean - squared deviation)

$X - \langle X \rangle \equiv$ Deviation from the mean value.

$$\Rightarrow \langle (X - \langle X \rangle)^2 \rangle = \langle X^2 \rangle - 2\langle X \rangle \langle X \rangle + \langle X \rangle^2 = \langle X^2 \rangle - \langle X \rangle^2 \quad (\because \text{positive \& negative deviation cancel})$$

$$\therefore \sigma_x^2 \equiv \langle (X - \langle X \rangle)^2 \rangle = \langle X^2 \rangle - \langle X \rangle^2$$

$$\rightarrow \sigma_x \equiv \sqrt{\langle (X - \langle X \rangle)^2 \rangle} \quad (\text{Standard Deviation, RMS})$$

(*) Definition of nth moment

$$\mu_n \equiv \langle X^n \rangle = \int dx \cdot x^n P(x)$$

$$\sigma^2 \equiv \left[\int_i (X_i - \langle X \rangle)^2 P_i \right] \int_{-\infty}^{\infty} (X - \langle X \rangle)^2 P(x) dx.$$

(*) Linear Transform

if $y = ax + b$ ($a, b = \text{const}$)

$$① \langle y \rangle = a \cdot \langle x \rangle + b.$$

$$② \langle y^2 \rangle = \langle a^2 x^2 + 2abx + b^2 \rangle = a^2 \langle x^2 \rangle + 2ab \langle x \rangle + b^2.$$

$$\langle y \rangle^2 = a^2 \cdot \langle x \rangle^2 + 2ab \langle x \rangle + b^2$$

$$\Rightarrow \sigma_y^2 = \langle y^2 \rangle - \langle y \rangle^2 = a^2 \cdot (\langle x^2 \rangle - \langle x \rangle^2) = a^2 \cdot \sigma_x^2 \quad \sigma_y = a \sigma_x$$

for continuous variable, $\langle y \rangle = \int_{-\infty}^{\infty} y g(y) dy = \int_{-\infty}^{\infty} (ax+b) f(x) dx$

$$= a \cdot \langle x \rangle + b. \quad \sigma_y^2 = \int_{-\infty}^{\infty} \left[y - (a \langle x \rangle + b) \right]^2 g(y) dy = a^2 \cdot \sigma_x^2.$$

$$\text{Q) Chebychev Inequality} \quad P(|X - \langle X \rangle| \geq k\sigma) \leq \frac{1}{k^2}$$

2. Binomial Distribution

Prob distnb of getting k heads of N independent Bernoulli trials

$$P_N(k) = \binom{N}{k} p^k q^{N-k} = \binom{N}{k} p^k (1-p)^{N-k} \quad (\text{Repeated Individual})$$

$$\Rightarrow \text{By binomial expansion, } (x+y)^N = \sum_{k=0}^N \binom{N}{k} x^k y^{N-k} \text{ or with } x=p, y=q \\ = \sum P_N(k) = 1 \quad (\text{makes sense})$$

$$\begin{aligned} \textcircled{1} \text{ Mean } \langle k \rangle &= \sum_{k=0}^N k \cdot P_N(k) = \sum_{k=0}^N \binom{N}{k} k \cdot p^k \cdot q^{N-k} \\ &= p \cdot \frac{\partial}{\partial p} \sum_{k=0}^N \binom{N}{k} p^k q^{N-k} \\ &= p \cdot \frac{\partial}{\partial p} (p+q)^N = p \cdot N \cdot (p+q)^{N-1} = Np \quad \therefore \langle k \rangle = Np \end{aligned}$$

$$\textcircled{2} \text{ Variance : } \sigma_k^2 = \langle k^2 \rangle - \langle k \rangle^2$$

$$\begin{aligned} \langle k^2 \rangle &= \sum_{k=0}^N k^2 \cdot P_N(k) = \sum_{k=0}^N \binom{N}{k} k^2 p^k q^{N-k} \\ &= \left(p^2 \frac{\partial^2}{\partial p^2} + p \frac{\partial}{\partial p} \right) (p+q)^N \\ &= \left(p^2 \frac{\partial^2}{\partial p^2} + p \frac{\partial}{\partial p} \right) p^k \\ &= N(N-1)p^2 + Np = N^2 p^2 - Np^2 + Np = N^2 p^2 + Np(1-p) \end{aligned}$$

$$\Rightarrow \sigma_k^2 = N^2 p^2 + Np(1-p) - N^2 p^2 = Np q \quad \sigma_k = \sqrt{Npq}$$

$$\textcircled{3} \text{ Relative width } \equiv \frac{\sigma_k}{\langle k \rangle} = \frac{\sqrt{Npq}}{Np} \sim \frac{1}{\sqrt{N}} \xrightarrow{N \gg 1} 0$$

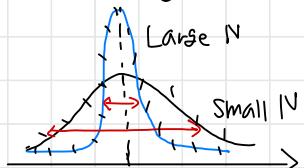
(*) Stirling's Approximation for very large N ($\sim 10^{20}$)

$$n! = \int_0^\infty x^n e^{-x} dx \quad (\text{Gamma function})$$

$$\max \approx e^{f(x)} = e^{n \ln x - x} \quad f(x) = n \ln x - x$$

(부정적 극한 정리)

Sharp, Peak



$$\text{To determine } x^*, \quad f'(x) \Big|_{x^*} = \left(\frac{n}{x} - 1 \right) \Big|_{x^*} = 0. \quad \therefore x^* = n.$$

$$\text{and, } f''(x) = -\frac{n}{x^2} \text{ or } f''(x^*) = -\frac{1}{n} < 0.$$

$$\begin{aligned} \text{Taylor expand, } f(x) &\leq f(x^*) + f'(x^*)(x-x^*) + \frac{f''(x^*)}{2!}(x-x^*)^2 \\ &= (n \ln n - n) + 0 \cdot (x-0) - \frac{1}{2n} \cdot (x-n)^2 \quad (\because x^* = n) \quad (\text{up to 2nd order}) \\ \Rightarrow n! &\simeq \int_0^\infty e^{n \ln n - n - \frac{(x-n)^2}{2n}} dx = \underbrace{e^{n \ln n - n}}_{\sqrt{2\pi n}} \int_{-\infty}^\infty e^{-\frac{(x-n)^2}{2n}} dx \end{aligned}$$

$$\therefore n! \simeq \sqrt{2\pi n} \cdot \left(\frac{n}{e}\right)^n \text{ for Large } n. \quad = \sqrt{2\pi n}, \text{ Gaussian}$$

Integration

$$\Leftrightarrow \ln n! = n \ln n - n + \frac{1}{2} \ln(2\pi n) \simeq \boxed{n \ln n - n}$$

(*) From Binomial to Gaussian

$$-\ln k!$$

$$P_N(k) \text{ for Large enough } N, \quad \ln P_N(k) = \ln N! - \ln(N-k)! + k \ln p + (N-k) \ln g$$

By using Stirling approximation,

$$\begin{aligned} \ln P_N(k) &\simeq \cancel{(N \ln N - N)} - \left[\cancel{(N-k) \ln(N-k)} - \cancel{(N-k)} \right] + k \ln p + (N-k) \ln g \\ &\quad - k \ln k + \cancel{k} \quad \rightarrow \text{이 대각선을 가진는 } k^* \text{ 같은 구해 볼까} \end{aligned}$$

$$\frac{\partial}{\partial k} \ln P(k) \Big|_{k^*} = -\ln k - 1 + \ln(N-k) + 1 + \ln p - \ln g \Big|_{k^*} = 0$$

$$\therefore (N-k) p = k^* g \quad k^*(p+g) = NP = \langle k \rangle \quad \langle k \rangle = k^*$$

$$\begin{aligned} \text{then, } \frac{\partial^2}{\partial k^2} \ln P(k) \Big|_{k^*} &= -\frac{1}{k} - \frac{1}{N-k} \Big|_{k^*=\langle k \rangle} = -\frac{N-k+k}{k(N-k)} \\ &= \frac{-N}{NP(N-Np)} = \frac{-1}{NP(1-p)} = \frac{-1}{NPg} = -\frac{1}{6k^2} \end{aligned}$$

$\xrightarrow{\text{Taylor expansion}}$ $\ln P(k) \simeq \ln P(k^*) + 0 \cdot (k-k^*) + \frac{1}{2!} \left(-\frac{1}{6k^2}\right) (k-k^*)^2$

$$\therefore P_N(k) \cong C_1 e^{-\frac{1}{26k^2} \cdot (k - \langle k \rangle)^2}$$

학률 분포 분석에 의해 C 를 구하면

$$\sum P_N(k) \longrightarrow \int_0^\infty dk \cdot P(k) = \int_{-\infty}^\infty dk \cdot P(k) = \int_{-\infty}^\infty dk \cdot C \cdot e^{-\frac{(k - \langle k \rangle)^2}{26k^2}} = 1$$

$\rightarrow \text{Gaussian Int.} = \sqrt{2\pi 6k^2}$

$$C = \frac{1}{\sqrt{2\pi 6k^2}}$$

$$P_N(k) = \frac{1}{\sqrt{2\pi 6k^2}} e^{-\frac{(k - \langle k \rangle)^2}{26k^2}}$$

: for large N , 이중 분포를 가진다. 분포는
근사로 정규분포다.

Summary

$P(x)dx$: Probability of events

$\langle x \rangle$: Expectation value

$$\sigma^2 \equiv \langle (x - \langle x \rangle)^2 \rangle = \langle x^2 \rangle - \langle x \rangle^2$$

Binomial Distribution $\xrightarrow{N \gg 1}$ Gaussian Distribution

$$\Rightarrow P_N(k) = \binom{N}{k} p^k q^{N-k}$$

$$P(k) = \frac{1}{\sqrt{2\pi \sigma^2}} e^{-\frac{(k - \mu)^2}{2\sigma^2}}$$

ex) Coin Toss HTTH

$$P_4(2) = \binom{4}{2} \left(\frac{1}{2}\right)^4$$

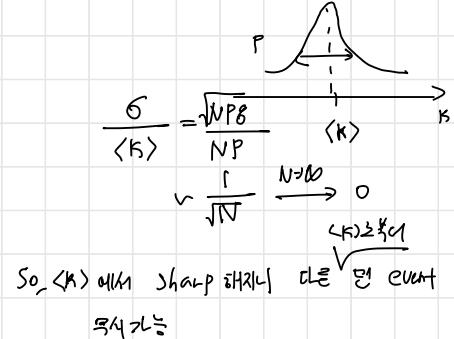
$$\text{as } \bar{k} = \mu = NP$$

$$\sigma^2 = NPq$$

\Rightarrow for sequence $p^k q^{N-k} = P^N$ for "unbiased" events (Randomness)

\Rightarrow for Given Composition (ex: $k=2$) neglecting "sequence"

Events can be predictable



3. Moments & Cumulants

By definition, n th moment of variable x from the origin is $\mu_n = \langle x^n \rangle = \int dx \cdot x^n p(x)$

But, Integration is complex... Let's introduce convenient skill

(*) Characteristic function & moment generating function Cfl) $\tilde{P}(k) =$

$$\text{Def) } \tilde{P}(k) = \langle e^{-ikx} \rangle = \int dx \cdot e^{-ikx} \cdot p(x) \quad \text{Cfl) } \tilde{P}(k) = 1 + \sum \frac{(-ik)^n}{n!}$$

$$= \int dx \cdot \sum_{n=0}^{\infty} \frac{(-ik)^n}{n!} x^n p(x)$$

$$= \sum_{n=0}^{\infty} \frac{(-ik)^n}{n!} \cdot \underbrace{\int dx \cdot x^n p(x)}$$

$$\Rightarrow \left. \frac{\partial^n \tilde{P}(k)}{\partial k^n} \right|_{k=0} = (-i)^n \cdot \mu_n \quad \boxed{\mu_n = \sum_{n=0}^{\infty} \left. \frac{\partial^n \tilde{P}(k)}{\partial k^n} \right|_{k=0}} \quad (\because \frac{1}{(-i)^n} = \frac{1}{i^{3n}})$$

$$\hookrightarrow = \left(-\frac{d}{dk} \right)^n \tilde{P}(k) \Big|_{k=0}$$

(*) Cumulant generating function

$$\text{Def) } \ln \tilde{P}(k) = \ln \langle e^{-ikx} \rangle = \sum_{n=1}^{\infty} \frac{(-ik)^n}{n} \cdot \langle x^n \rangle_c \quad \text{을 통해 } \langle x^n \rangle_c$$

then, 특성함수 정의에 의해 $\langle x^n \rangle_c = (-i)^n \cdot \left. \frac{\partial^n}{\partial k^n} [\ln \tilde{P}(k)] \right|_{k=0}$

$$\begin{aligned} \textcircled{1} \quad \langle x^1 \rangle_c &= -i \cdot \left. \frac{d}{dk} \ln \tilde{P}(k) \right|_{k=0} = -i \cdot \frac{1}{\tilde{P}(k)} \cdot \left. \frac{d \tilde{P}}{dk} \right|_{k=0} \\ &= \frac{1}{\tilde{P}(0)} \cdot \mu_1 = \mu_1 = \langle x \rangle \quad \therefore \langle x^1 \rangle_c = \langle x \rangle \end{aligned}$$

$$(\because \tilde{P}(0) = \langle e^0 \rangle = \langle 1 \rangle = 1)$$

Variance

$$\begin{aligned} \textcircled{2} \quad \langle x^2 \rangle_c &= -i^2 \cdot \left. \frac{d^2}{dk^2} \ln \tilde{P}(k) \right|_{k=0} = -i^2 \left[\frac{1}{\tilde{P}(k)} \cdot \frac{d^2 \tilde{P}(k)}{dk^2} - \frac{1}{(\tilde{P}(k))^2} \left(\frac{d \tilde{P}}{dk} \right)^2 \right]_0 \\ &= \mu_2 - \mu_1^2 = \langle x^2 \rangle - \langle x \rangle^2 = \sigma^2 \quad \therefore \langle x^2 \rangle_c = \sigma^2 \end{aligned}$$

$$\begin{aligned}
 ③ \quad & \langle X^3 \rangle_c = \bar{z}^3 \cdot \frac{\partial^3}{\partial z^3} \cdot \ln p(z) \Big|_{z=0} \\
 & = \bar{z}^3 \cdot \left[\frac{1}{p(z)} \cdot \frac{\partial^3 p(z)}{\partial z^3} - \underbrace{\frac{1}{(p(z))^2} \left(\frac{\partial p}{\partial z} \right) \left(\frac{\partial^2 p}{\partial z^2} \right)}_{-1 \text{ 항}} + \frac{2}{(p(z))^3} \left(\frac{\partial p}{\partial z} \right)^2 \right. \\
 & \quad \left. - \underbrace{\frac{1}{(p(z))^2} \cdot 2 \left(\frac{\partial p}{\partial z} \right) \left(\frac{\partial^2 p}{\partial z^2} \right)}_{-2 \text{ 항}} \right]_{z=0} \quad (\bar{z}^3 \text{은 각 미분항에 분배되는 항이}) \\
 & = \mu_3 - 3 \cdot \mu_1 \mu_2 + 2 \mu_1^3 = \langle X^3 \rangle - 3 \langle X \rangle \langle X^2 \rangle + 2 \langle X \rangle^3
 \end{aligned}$$

(Usefull skill, Diagrammatic representation)

Skewness

nth Cumulant $\langle X^n \rangle_c$: Cluster connected among n points

nth moment $\langle X^n \rangle$: All possible ways of distributing n points into smaller clusters

$$\begin{aligned}
 \text{(ex)} \quad (n=1) \quad & \langle X^1 \rangle = \langle X^1 \rangle_c \quad \xrightarrow{\text{단일这点}} \quad \Rightarrow \langle X^2 \rangle_c = \langle X^2 \rangle - \langle X \rangle^2 \\
 (n=2) \quad & \text{---} + \cdot \cdot \cdot \Rightarrow \langle X^2 \rangle = \langle X^2 \rangle_c + \langle X^1 \rangle_c \langle X^1 \rangle_c \\
 (n=3) \quad & \text{---} + \text{---} + \cdot \cdot \cdot \Rightarrow \langle X^3 \rangle = \langle X^3 \rangle_c + 3 \cdot \langle X^2 \rangle_c \langle X^1 \rangle_c + \langle X^1 \rangle_c^3 \\
 & \quad \quad \quad = \langle X^3 \rangle_c + 3 \cdot [\langle X^2 \rangle - \langle X \rangle^2] \langle X \rangle + \langle X \rangle^3 \\
 & \quad \quad \quad \therefore \langle X^3 \rangle_c = \langle X^3 \rangle - 3 \langle X^2 \rangle \langle X \rangle + 2 \langle X \rangle^3
 \end{aligned}$$

$$\text{After } n=4, 5, 6, \dots \text{ do on.} \quad \langle X^4 \rangle = \langle X^4 \rangle_c + 4 \cdot \langle X^3 \rangle_c \langle X^1 \rangle_c + 6 \cdot \langle X^2 \rangle_c \langle X^1 \rangle_c^2 + \langle X^1 \rangle_c^4 + 6 \cdot \langle X^2 \rangle_c^2$$

$$\begin{aligned}
 \square \quad \Gamma. \quad | \quad : \quad : \quad : \quad \Rightarrow \langle X^4 \rangle_c = \langle X^4 \rangle - 4[\langle X^2 \rangle - 3 \langle X^2 \rangle \langle X \rangle + 2 \langle X \rangle^3] \langle X \rangle \\
 & \quad \quad \quad - 6(\langle X^2 \rangle - \langle X \rangle^2) \langle X \rangle^2 - \langle X \rangle^4 - 3(\langle X^2 \rangle - \langle X \rangle^2)^2 \\
 ① \quad ④ \quad ⑥ \quad ① \quad & = \langle X^4 \rangle - 4 \langle X^3 \rangle \langle X \rangle + 12 \langle X^2 \rangle \langle X \rangle^2 - 8 \langle X \rangle^4 \\
 & \quad \quad \quad - 6 \cancel{\langle X^2 \rangle \langle X \rangle^2} + 6 \langle X \rangle^4 - \cancel{\langle X \rangle^4} - 3 \cancel{\langle X^2 \rangle^2} + 6 \cancel{\langle X^2 \rangle} \langle X \rangle^2 \\
 & \quad \quad \quad - 3 \langle X \rangle^4
 \end{aligned}$$

4. Several Random Variables

(*) Joint Probability distribution: $P(X_1, X_2, \dots, X_N) dX_1 \dots dX_N = \text{Prob} [E \in [\vec{x}, \vec{x} + d\vec{x}]]$ o.d.h.

\rightarrow Joint Characteristic function $\equiv \hat{P}(k_1, k_2, \dots, k_N) = \langle e^{-i(k_1 X_1 + k_2 X_2 + \dots + k_N X_N)} \rangle$

$$= \int \prod_{\alpha=1}^N dX_\alpha e^{-i k_\alpha X_\alpha} P(X_1, X_2, \dots, X_N)$$

$$\begin{aligned} \textcircled{1} \text{ Joint moment } \langle X_1^{m_1} X_2^{m_2} \dots X_N^{m_N} \rangle &= \int \prod_{\alpha=1}^N dX_\alpha X_\alpha^{m_\alpha} P(X_1, X_2, \dots, X_N) \\ &= \left(-\frac{\partial}{\partial i k_1} \right)^{m_1} \left(-\frac{\partial}{\partial i k_2} \right)^{m_2} \dots \left(-\frac{\partial}{\partial i k_N} \right)^{m_N} \hat{P}(k_1, \dots, k_N) \Big|_{\vec{k}=0} \end{aligned}$$

\textcircled{2} Joint Cumulant by symmetry,

$$\langle X_1^{m_1} X_2^{m_2} \dots X_N^{m_N} \rangle_C = \left(-\frac{\partial}{\partial i k_1} \right)^{m_1} \dots \left(-\frac{\partial}{\partial i k_N} \right)^{m_N} \ln \hat{P}(k_1, \dots, k_N) \Big|_{\vec{k}=0}$$

(*) Statistical Independence

$$\text{Def) } P_N(x_1, x_2, \dots, x_N) = p_1(x_1) p_2(x_2) \dots p_N(x_N)$$

$$\begin{aligned} \langle f(x_1) g(x_2) \rangle &= \int dX_1 dX_2 f(x_1) g(x_2) P(X_1, X_2) \text{ or M, if } X_1, X_2 \text{ is statistically} \\ &= \int dX_1 dX_2 f(x_1) p(x_1) g(x_2) p(x_2) = \langle f(x_1) \rangle \langle g(x_2) \rangle \text{ independent,} \end{aligned}$$

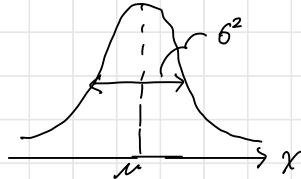
So, under the same condition, the characteristic function becomes

$$\begin{aligned} \Rightarrow \hat{P}(k_1, \dots, k_N) &= \int \prod_{\alpha=1}^N dX_\alpha e^{-i k_\alpha X_\alpha} \underbrace{P(X_1, \dots, X_N)}_{= \prod_{\alpha=1}^N p_\alpha(x_\alpha)} \\ &= \prod_{\alpha=1}^N \int dX_\alpha e^{-i k_\alpha X_\alpha} p_\alpha(x_\alpha) \\ &= \prod_{\alpha=1}^N \hat{p}_\alpha(k_\alpha) \end{aligned}$$

$$\text{Similarly, } \langle X_1^{m_1} X_2^{m_2} \dots X_N^{m_N} \rangle = \langle X_1^{m_1} \rangle \langle X_2^{m_2} \rangle \dots \langle X_N^{m_N} \rangle$$

But, Cumulant became little bit different.

$$\langle X_1^{m_1} X_2^{m_2} \cdots X_N^{m_N} \rangle_C = \left(-\frac{d}{d\bar{k}_1} \right)^{m_1} \cdots \left(-\frac{d}{d\bar{k}_N} \right)^{m_N} \sum_{\alpha=1}^N \ln P_\alpha(k_\alpha)$$
$$= 0 \text{ for any } m_i \cdot m_j \neq 0. \quad (\because \ln P_1 P_2 \cdots P_N = \ln P_1 + \ln P_2 + \cdots)$$



(*) Moments / Cumulants of Gaussian distribution

$$(P.D.F) \quad P(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \cdot e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

(Characteristic Function)

$$\tilde{P}(k) = \langle e^{-ikx} \rangle = \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^{\infty} dx e^{-ikx - \frac{(x-\mu)^2}{2\sigma^2}} \quad (x-\mu = y)$$
$$= \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^{\infty} dy e^{-\frac{y^2}{2\sigma^2} - iky - ik\mu} \quad \left(\text{If } \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^{\infty} dy e^{-\frac{y^2}{2\sigma^2}} = 1 \text{ or } \right)$$
$$= e^{-ik\mu - \frac{\sigma^2 k^2}{2}}$$

$\therefore \ln \tilde{P}(k) = -ik\mu - \frac{\sigma^2 k^2}{2}$ 이다. 따라서, 이는 Cumulant generating function으로 볼 수 있다.

$$\langle X^1 \rangle_C = -\frac{d}{d(k)} \ln \tilde{P}(k) \Big|_{k=0} = \mu = \langle X^1 \rangle$$

$$\langle X^2 \rangle_C = \frac{d^2}{dk^2} \left(\frac{1}{2} \ln \tilde{P}(k) \right) = \sigma^2. \quad (2, \ln \tilde{P}(k) \text{의 } k \text{에 대한 최고차항 } 2 \text{이므로})$$

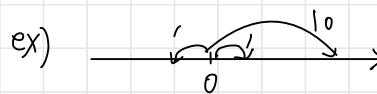
$$\langle X^n \rangle_C = 0 \text{ for } n > 2. \quad \therefore \text{mean} = \mu, \text{variance} = \sigma^2 \text{인 distribution이다.}$$

→ Gaussian distribution의 중요한 성질. $| - |$ mapping으로 이 성질을 가진 분포를 대응할 것.

(*) for arbitrary Gaussian, $\int_{-\infty}^{\infty} e^{-\lambda(x+b)^2} dx = \sqrt{\frac{\pi}{\lambda}}$

5. Probability Distribution for Large N : Central limit theorem

$$(*) X = \sum_i^N X_i \text{ Variable}$$



after N step, final displacement?

$$P(X) = \int \cdots \int P(x_1, \dots, x_N) dx_1 \cdots dx_N$$

$X = \sum X_i \rightarrow \text{Constraint}$

$$\oint_{-\infty}^{\infty} \delta(x) dx = 1$$

$$\int P(X) \cdot \delta(X - \sum x_i) dX = \int_{-\infty}^{\infty} \int_{-\infty}^{X=\infty} \cdots \int_{-\infty}^{X=\infty} dx_1 \cdots dx_N \cdot P(x_1, x_2, \dots, x_N)$$

$$\underbrace{P(x_1, x_2, \dots, x_N)}_{\text{Independence}} \cdot \underbrace{\int (X - \sum x_i) dX}_{= \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{-2k(X - \sum x_i)}}$$

P(X)

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{ikX} \cdot \int \cdots \int (dx_1 e^{-ikx_1} P(x_1)) (dx_2 e^{-ikx_2} P(x_2)) \cdots (\text{up to } N \text{ terms})$$

→ 주어진 확률 분배

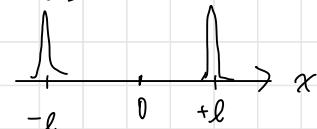
$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{ikX} \cdot \left(\tilde{P}_1(k) \tilde{P}_2(k) \cdots \tilde{P}_N(k) \right)^N = (\tilde{P}(k))^N$$

이 예제에서, $P_1 = P_2 = \cdots$

$$= P_N \left(\frac{k}{N} \right) \text{ (각각 } \frac{1}{N} \text{ 확률)} \quad \text{때문에 } \tilde{P}(k) \text{ 형태 표현}$$

(eg) 예시 상황의 Probability Distribution을 구해보자. ($\frac{p}{2}$ for $+l$, $\frac{q}{2}$ for $-l$. after N step, distribution.)

$$(P.D.F) p(x) = p \cdot \delta(x-l) + q \cdot \delta(x+l) \text{ olcf.}$$



$$(\because P(+l-\varepsilon, +l+\varepsilon) = \int_{l-\varepsilon}^{l+\varepsilon} p(x) dx = p.)$$

$$\text{Then, } (\tilde{P}(k))^N = \langle e^{-ikx} \rangle^N = \left(e^{-ikl} \cdot p + e^{ikl} \cdot q \right)^N \rightarrow \text{Binomial Polynomial}$$

$$= \sum_{n=0}^{\infty} \binom{N}{n} p^n \cdot q^{N-n} \cdot e^{-n \cdot ik l + (N-n) ik l} = (N-2n) \bar{e}^{2kl} \quad (\text{clearly, } g \text{ is chiral})$$

$$P(X) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dk e^{ikX} \cdot \sum_{n=0}^{\infty} \binom{N}{n} p^n q^{N-n} \bar{e}^{-(2n-N)ikl}$$

$$= \frac{1}{2\pi} \sum_{n=0}^{\infty} \binom{N}{n} p^n q^{N-n} \cdot \int_{-\infty}^{\infty} dk e^{ik[X - (2n-N)l]}$$

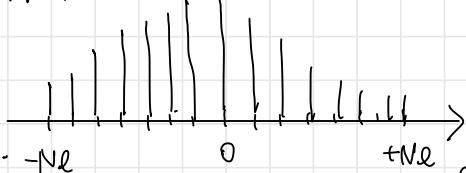
$$= \delta[X - (2n-N)l]$$

$$\therefore P(X) dX = \sum_{n=0}^{\infty} \binom{N}{n} p^n q^{N-n} \cdot S[X - (2n-N)l] dX$$

$$n=0 \quad X = -N.l.$$

1

$$n=N \quad X = N_l$$



$$\Rightarrow X = (2n' - N)l \text{ 이 일 확률 } P(X = (2n' - N)l) = \int_{X = (2n' - N)l - \varepsilon}^{X = (2n' - N)l + \varepsilon} P(X) dX$$

$$= \binom{N}{n'} p^{n'} \theta^{N-n'} \cdot (n': \text{Dummy index})$$

$$\therefore P((2n-N)l) = \binom{N}{n} p^n q^{N-n} \quad \text{for otherwise, } P = 0. \\ (\text{ex: } X = (2n-N)l + \frac{l}{2}).$$

(*) Central Limit Theorem ($N \gg 1$)

Consider $X = \sum_{i=1}^n X_i$, then, for random variable X , characteristic function

$$\begin{aligned}\tilde{P}_X(k) &= \left\langle e^{-ikX} \right\rangle = \left\langle e^{-ik \sum_i x_i} \right\rangle = \left\langle e^{-ikx_1} e^{-ikx_2} \cdots e^{-ikx_N} \right\rangle \\ &= \sum_{n=0}^{\infty} \frac{(-ik)^n}{n!} \cdot \langle x^n \rangle\end{aligned}$$

$$l_n p_X(k) = \sum_{n=0}^{\infty} \frac{(-i\kappa)^n}{n!} \cdot \langle X^n \rangle_C = \sum_{n=0}^{\infty} \frac{(-i\kappa)^n}{n!} \cdot \left((x_1 + x_2 + \dots + x_m)^n \right)_C$$

Let's assume that X_i are statistically independent. Then,

In the cumulant formula, cross terms should disappear (why?)

$$\langle X^n \rangle_c = \langle X_1^n \rangle_c + \langle X_2^n \rangle_c + \dots + \langle X_N^n \rangle_c = \sum_{i=1}^N \langle X_i^n \rangle_c$$

$$\Rightarrow (\text{Sum of random variables} \Leftrightarrow \text{Cumulant}) = (\text{random variable} \Leftrightarrow \text{Cumulant} \Leftrightarrow \text{Sum})$$

\Rightarrow X_1, X_2, \dots, X_n of Identical distribution을 가진다고 하자. distribution

\Rightarrow 이 조건이 Statistical(즉) Independent 조건을 충족시킬 때 I.I.D라고 부른다.

Then, $\langle X^n \rangle_c = N \cdot \langle X^n \rangle_c$ 가 된다.

$$\begin{aligned} P(X_1, \dots, X_N) &= p(x_1)p(x_2) \cdots p_{Nn}(x_N) \\ &= p(x_1)p(x_2) \cdots p(x_N) \end{aligned}$$

Now, Let's introduce $y = \frac{X - \langle X \rangle_c}{\sqrt{N}} = \frac{X - N\langle X \rangle_c}{\sqrt{N}} = \frac{X - N\langle X \rangle}{\sqrt{N}}$

It is the linear transformation of variable X . So, if we calculate cumulant of y ,

$$\langle y^1 \rangle_c = \frac{\langle X \rangle_c - \langle X \rangle_c}{\sqrt{N}} = 0 \quad \dots \textcircled{1}$$

$$\begin{aligned} \langle X^2 \rangle_c - 2\langle X \rangle_c \langle X \rangle_c + N^2 \langle X \rangle_c^2 \\ - N^2 \langle X \rangle_c^2 \\ \langle X \rangle_c = 0 ? \end{aligned}$$

$$\langle y^2 \rangle_c = \frac{\langle X^2 \rangle_c}{N} = \frac{N \langle X^2 \rangle_c}{N} = \langle X^2 \rangle_c \rightarrow \sigma^2. \quad \dots \textcircled{2}$$

? :

↳ Intuition : Linear transform이나, 정규분포가능, 제각각의 차이가 있다.

$$\langle y^m \rangle_c = \frac{\langle X^m \rangle_c}{N^{\frac{m}{2}}} = \frac{N \langle X^m \rangle_c}{N^{\frac{m}{2}}} \sim N^{1-\frac{m}{2}} \rightarrow 0 \quad (\text{for } m > 2)$$

$$\text{즉, } N \gg 1 \rightarrow \infty \text{ 일 때, } m > 2 \text{ 일 때 } \begin{cases} \langle y^m \rangle_c = 0 & N \rightarrow \infty \\ \langle y^1 \rangle_c = 0 & \text{이므로} \\ \langle y^2 \rangle_c = \sigma^2 & \end{cases}$$

이 조건에서 y 의 확률분포는 $N(0, \langle X^2 \rangle_c)$ 인 Gaussian distribution이다.

$$P(y) = \frac{1}{\sqrt{2\pi}\sigma^2} e^{-\frac{y^2}{2\langle X^2 \rangle_c}} \rightarrow N \text{의 관계 } X.$$

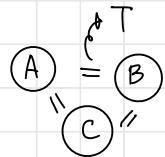
따라서, $P(X) \rightarrow$ 놓았어야지, $N \rightarrow \infty$ 이면 single variable Gaussian으로 변환 가능하다.

$\left(\begin{array}{c} N \gg 1 \\ I.I.D \end{array} \right) \Rightarrow N \text{의 정확한 값을 몰라도 통계적 분석 가능하다.}$

II. Classical Thermodynamics

1. The 0th & 1st Law of Thermodynamics

1) 0th Law : The abstract definition of temperature



⇒ If two systems are in **thermal equilibrium** with a third, the two systems should be in **thermal equilibrium** each other

⇒ **Thermal Contact** for a sufficiently long time, and no "net energy" transfer in the stationary state. Then they should have the same physical quantity, specially named : **Temperature**

definition of thermal contact.

⇒ When the two systems are able to exchange energy while keeping external parameters, they are said to be in thermal contact. $(T_A = T_c \Rightarrow T_A = T_B)$

→ The definition of temperature : Ambiguity

Q. How can we define temperature "rigorously"?



2) Statistical Definition of Temperature.

• We will define the temperature through Ω , the number of microstates.

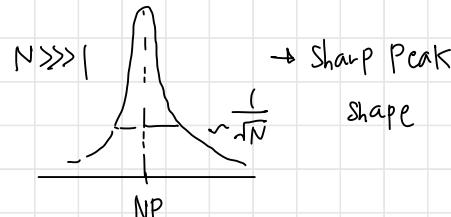
(*) Microscopic states (μ -states)

$N = 100$

H T H H T T ... H T
⋮
T H H T T H ... H H

} Sequences

(*) Macroscopic states (M -states)



Interested in $\kappa = \text{number of H} = \text{composition}$

$$\Rightarrow P_{N(\kappa)} = \frac{N}{\kappa} \cdot p^{\kappa} \cdot e^{-N/\kappa}$$

For unbiased, equally probable

Number of possible configuration = $2^{100} \approx 10^{30}$

All possible μ -states are equally likely.

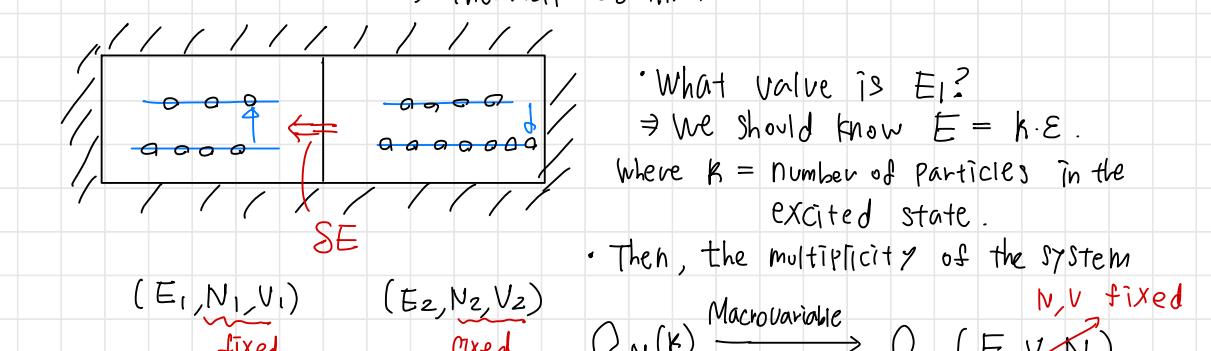
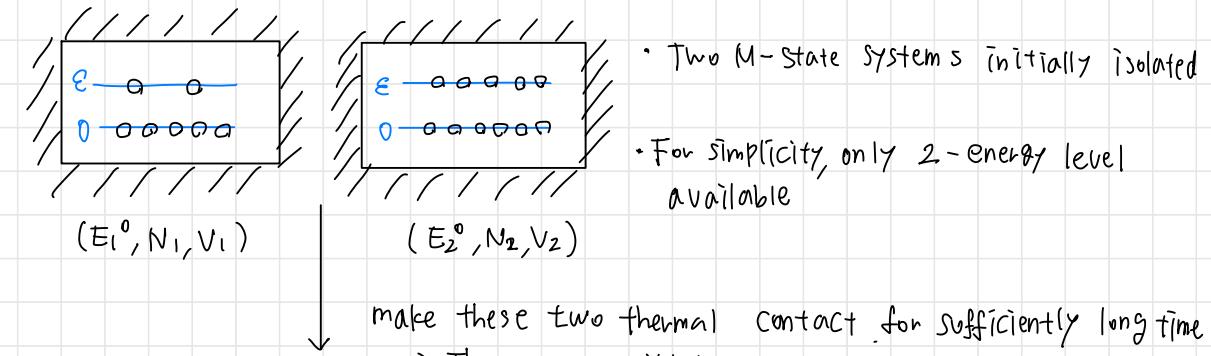
= $\Omega_N(\kappa) = \text{Multiplicity} = \text{Density of state}$

$$(\text{ex}) \frac{P_{1000}(400)}{P_{1000}(500)} \approx 10^{-9} \text{ Huge difference because of } \Omega$$

⇒ From this, we can get the following (Powerful) Postulate, which is true from now on.

- For a system of **large N**, there is a strong tendency that the system tends to be in Macroscopic State that **maximizes the number of microstates** ($= \Omega$) belonging to that macrostate in **thermal equilibrium**

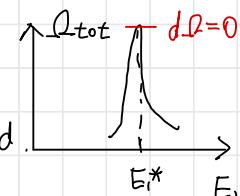
(*) 이제, 간단한 상황을 통해 Ω 의 성질을 확인하고, 이를 통해 온도를 어떻게 정의하길.



$$\Omega_N(k) \xrightarrow{\text{Macrovariable}} \Omega_N(E, V, \cancel{N})$$

N, V fixed

$$= \Omega(E) \text{ where } E_{\text{tot}} = E_1^0 + E_2^0 = E_1 + E_2 = \text{const.}$$



⇒ By the postulate we have seen, $\Omega_{\text{tot}}(E_{\text{tot}})$ should be maximized.

$$\Rightarrow \Omega_{\text{tot}}(E_{\text{tot}}) = \Omega_1(E_1) \times \Omega_2(E_2) \quad (\because \text{Two independent system, think about the multiplicity: composition})$$

$$= \Omega_1(E_1) \times \Omega_2(E_{\text{tot}} - E_1)$$

Now, we are to find E_1^* , where $d\Omega_{\text{tot}} = 0$.

$$\Rightarrow d\Omega_{\text{tot}} = \Omega_2(E_2) \times \frac{\partial \Omega_1(E_1)}{\partial E_1} \cdot dE_1 + \Omega_1(E_1) \times \frac{\partial \Omega_2(E_2)}{\partial E_2} \cdot dE_2$$

$$= \Omega_1(E_1) \cdot \Omega_2(E_2) \cdot \left(\frac{1}{\Omega_1} \cdot \frac{\partial \Omega_1}{\partial E_1} \Big|_{E_1=E_1^*} - \frac{1}{\Omega_2} \cdot \frac{\partial \Omega_2}{\partial E_2} \Big|_{E_2=E_2^*} \right) dE_1 = 0.$$

So, 입자의 E_1 에 대해 흥상 이식이 증가하기 위해서

($\because dE_1 + dE_2 = 0$)

$$\therefore \frac{1}{\Omega_1} \cdot \frac{\partial \Omega_1}{\partial E_1} \Big|_{E_1=E_1^*} = \frac{1}{\Omega_2} \cdot \frac{\partial \Omega_2}{\partial E_2} \Big|_{E_2=E_2^*}$$

식을 $\ln \Omega$ 에 미분형으로 표현하면,

$$\frac{\partial}{\partial E_1} \cdot \ln \Omega_1(E_1) \Big|_{E=E_1^*} = \frac{\partial}{\partial E_2} \cdot \ln \Omega_2(E_2) \Big|_{E=E_2^*}$$

이하. 이는 간단하지만 강연한, 위의
기본에서 유도된식이다.

Condition of thermal equilibrium

\Rightarrow 이 때, 이 조건식의 차원을 살펴보자. $\ln \Omega$ 은 Number이고, E 에 대해 미분되어 $[E^{-1}]$ 의 차원을 가진다. 또한, 0th Law를 보면 이 열평형 조건에서 온도가 정의된다는 사실을 알 수 있다. 따라서, 적절한 상수를 통해 아래와 같이 정의식을 만든다.

$$\frac{1}{k_B \cdot T} = \frac{\partial}{\partial E} \cdot \ln \Omega(E)$$

k_B : Boltzmann Constant [$J \cdot K$]

\Rightarrow 이는 "macrostate observable T" or statistic (Probability) origin을 관계하는 관계식이다!

\Rightarrow 따라서, 계의 엔트로피 (Entropy) S 는 $S = k_B \cdot \ln \Omega(E)$ 로 정의한다면,
아래와 같은 관계식을 알고, 이는 fundamental definition of Temperature 이다.
(absolute temperature)

$$\frac{1}{T} = \frac{\partial}{\partial E} \cdot k_B \cdot \ln \Omega(E) = \frac{\partial S(E)}{\partial E}$$

\Rightarrow Thus, by using this equation, condition of thermal equilibrium is,

$$\frac{1}{T_1} = \frac{1}{T_2}$$

(*) 이제, 열평형 조건식과, 이를 통해 온도를 정의했을 때, Direction of heat flows 를 알아보도록 하자. 주어진 조건에서,

$$(E_1^\circ, T_2^\circ) \xrightarrow{\text{equilibrium}} (E_1^*, E_2^*) \text{이다.}$$

이 때, 평형을 이루는 지점에서 Ω_{tot} 가 최대이므로, 아래 식은 참이다.

$$\Omega_1(E_1^*) \Omega_2(E_2^*) \geq \Omega_1(E_1^\circ) \Omega_2(E_2^\circ) \quad \text{양변에 } \ln \text{을 쓰우고 정리하면} (\because \ln \text{은 증가함})$$

$$\Rightarrow \ln \Omega_1(E_1^*) + \ln \Omega_2(E_2^*) \geq \ln \Omega_1(E_1^\circ) + \ln \Omega_2(E_2^\circ) \quad k_B \text{ 을 대시 정리}$$

$$\Rightarrow S_1(E_1^*) + S_2(E_2^*) \geq S_1(E_1^\circ) + S_2(E_2^\circ)$$

$\therefore \Delta S_{\text{tot}} = \Delta S_1 + \Delta S_2 \geq 0$: For isolated system, total entropy should be increased

Clausius's Statement of 2nd Law

For small $\delta S = S_1(E_1^*) - S_1(E_1^\circ) + S_2(E_2^*) - S_2(E_2^\circ)$, Energy of system can be described as

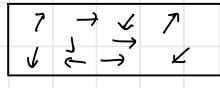
$$\begin{cases} E_1^* = E_1^\circ + \delta E_1 \\ E_2^* = E_2^\circ + \delta E_2 \end{cases} \quad \text{And, by upper statement, } \delta S = \left(\frac{\partial S}{\partial E_1} \cdot \delta E_1 + \frac{\partial S}{\partial E_2} \cdot \delta E_2 \right) \\ = \left(\frac{\partial S}{\partial E_1} \Big|_{E_1^\circ} - \frac{\partial S}{\partial E_2} \Big|_{E_2^\circ} \right) \delta E_1 \\ = \left(\frac{1}{T_1^\circ} - \frac{1}{T_2^\circ} \right) \delta E_1 \geq 0.$$

\Rightarrow This means if $T_2^\circ > T_1^\circ$, $\delta E_1 > 0$. Energy flows from high temperature to low temperature.

3) The first Law of Thermodynamics

< Micro States >

- $6N$ Variables $\{ \vec{P}_i, \vec{S}_i \}$



< Macro states >

- A few macroscopic observables (Variables)

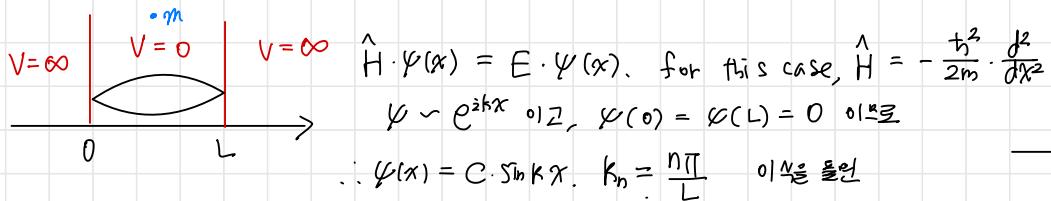
ex) $E, N, V, T, P \dots$

\Rightarrow In thermal equilibrium, the macroscopic properties of system are characterized by a set of functions of states (State variables, 상태함수)

\Rightarrow Macroscopic observables do not change (fixed value) under time evolution or previous history, because they are "functions of States"

→ If not, 0th Law 위반한다.

(Ex) 액간의 양자역학이 가미된, Infinite Potential Well을 고려해보자. (1-D)



$$E_n = \frac{\hbar^2 \cdot k_n^2}{2m} = \frac{\hbar^2 \pi^2}{2m L^2} n^2. \rightarrow \text{Quantized energy level, discrete value.}$$

$$(n = 0, 1, 2, \dots)$$

$$\begin{aligned} H(x_1, x_2, x_3, \dots) \\ \text{Internal Parameter.} \end{aligned}$$

If $L \rightarrow L + \delta L$, E_n shifted, energy changes
(External Parameter)

If $n = i \rightarrow j$, Energy changes (Internal Parameter)

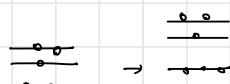
$n=1$
 $n=0$

⇒ 이처럼, 계의 매개변수에 영향을 주는 변화 인수를 구별할 수 있다. 여기서, 아래의 정의가 규칙한다.

(i) Work : Energy changes induced by variation of External parameters

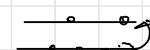
(= due to the changes of energy level)

$$\Delta E = W \quad (\text{Naturally, 계에 가해진 일 개념이다})$$



(ii) Heat : Energy changes when all the external parameters remain fixed

$$\Delta E = Q. \quad (\text{계에 흡수된 열})$$



(iii) Combine (i)(ii) together $\Rightarrow \boxed{\Delta E = W + Q}$... The 1st Law of Thermodynamics

⇒ Note that $\boxed{\Delta E : \text{Energy의 변화량}}$

W, Q should be defined only through the process (= Energy in transit)

All of these discussions are valid during thermal equilibrium.



System go through the points that all satisfy thermal equilibrium,
at every instant moments, so $\int Q$ is maximized

⇒ For infinitesimal process, $dE = dQ + dW$ (or $dQ + dW$)

↳ Inexact differential, which means path-dependent.

(*) Exact vs Inexact.

• Exact is, for $Z = f(x, y)$, $df = f(x+dx, y+dy) - f(x, y) = \left(\frac{\partial f}{\partial x}\right)_y dx + \left(\frac{\partial f}{\partial y}\right)_x dy$

$$\Rightarrow \left[\frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right)_y \right]_x = \left[\frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right)_x \right]_y$$

$$= A(x, y) dx + B(x, y) dy$$

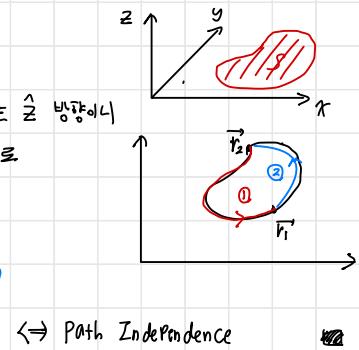
In this case, $\int_a^b df = f(b) - f(a)$ (Path independence)

$$\text{PF} \quad \vec{F} = (A(x,y), B(x,y)) \quad \text{then}, \quad \oint_{\partial S} \vec{F} \cdot d\vec{x} = \int_S d\vec{S} \cdot (\nabla \times \vec{F}) \quad \text{여기서는 } \nabla \times \vec{F} = 0$$

$$(\nabla \times \vec{F})_z = \left(\frac{\partial B}{\partial x} - \frac{\partial A}{\partial y} \right)_z = 0 \quad \text{이라면,} \quad = 0 \quad \text{이므로}$$

$$\left(\int_{r_1}^{r_2} \vec{F} \cdot d\vec{x} \right)_{①} + \left(\int_{r_2}^{r_1} \vec{F} \cdot d\vec{x} \right)_{②} = 0. \quad \text{So,} \quad \left(\int_{r_1}^{r_2} \vec{F} \cdot d\vec{x} \right)_{①} = \left(\int_{r_1}^{r_2} \vec{F} \cdot d\vec{x} \right)_{②} = df.$$

즉, 이 경우 필요 조건이 df 가 exact differential이다.



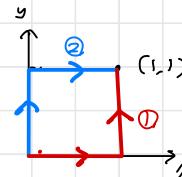
\Leftrightarrow Path Independence

• Inexact differential: naturally, Path-dependent Property.

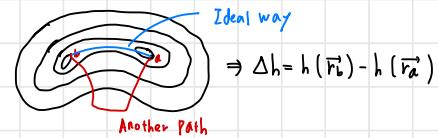
ex) Let $df = xy \cdot dx + x^2 \cdot dy$.

$$\int_{(0,0)}^{(1,1)} df = 0 + \int_{y=0}^{y=1} 1^2 \cdot dy = 1 \quad *$$

$$\int_{(0,0)}^{(1,1)} df = 0 + \int_0^1 xy \, dx = \frac{1}{2}.$$



(cf) Contour map



4) Heat Capacity

< 1st Law : $dQ = dE - dW$ >

Question : How much heat should be added to the system, to increase the temperature?

\Rightarrow The answer comes from new definition, Heat Capacity $C = \left(\frac{dQ}{dT} \right)$
or call, Energy of the system을 T, V 의 함수로 정의하자.

(과연 아래도 풀어야 할까? 그렇다!) $E = E(T, V)$

$$\Rightarrow dE(T, V) = \left(\frac{\partial E}{\partial T} \right)_V dT + \left(\frac{\partial E}{\partial V} \right)_T dV = dQ + dW.$$

$$\Rightarrow dQ = \left(\frac{\partial E}{\partial T} \right)_V dT + \left(\frac{\partial E}{\partial V} \right)_T dV - dW.$$

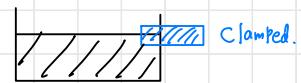
or call, System의 quasi-static process (Slowly enough to remain in thermodynamic equilibrium)

을 대응으로 하면, $dW = -PdV$ or cl.

$$\Rightarrow dQ = \left(\frac{\partial E}{\partial T} \right)_V dT + \left[\left(\frac{\partial E}{\partial V} \right)_T + P \right] dV$$

이제, 이 식을 이용해 Heat Capacity under certain Condition을 구하자.

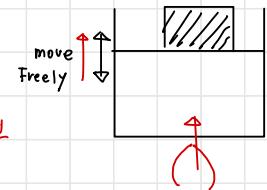
$$\textcircled{1} \text{ Constant Volume, } C_V = \left(\frac{\partial Q}{\partial T} \right)_V = \left(\frac{\partial E}{\partial T} \right)_V$$



\Rightarrow 이 때, (Amount of heat) = (Amount of Internal energy change), 즉에서 가해진 heat가
모두 energy로 전환된다.

$$= C_V$$

$$\textcircled{2} \text{ Constant Pressure. } C_P = \left(\frac{\partial Q}{\partial T} \right)_P = \left(\frac{\partial E}{\partial T} \right)_V + \left[\left(\frac{\partial E}{\partial V} \right)_P + P \right] \left(\frac{\partial V}{\partial T} \right)_P$$



$$\Rightarrow C_P - C_V = \left[\left(\frac{\partial E}{\partial V} \right)_P + P \right] \left(\frac{\partial V}{\partial T} \right)_P \quad \xrightarrow{\text{extra relation이 더해지면}} \text{정리 가능.}$$

$$\therefore C_P > C_V \quad \Rightarrow \gamma \equiv \frac{C_P}{C_V} > 1. \quad (\text{Adiabatic index})$$

2. The Ideal Gas

In general, we can say this using entropy.

$$(C_P - C_V = \frac{\partial^2 V}{\partial S^2})$$

2.1) The Equation of State

(*) The Empirical Statement of gas

$$\text{Boyle's Law : } P \propto \frac{1}{V} \text{ at constant Temperature}$$

$$\text{Charles's Law : } V \propto T \text{ at Constant Pressure}$$

$$P \propto T \text{ at Constant Volume.}$$

$$P \propto N$$

\Rightarrow Empirical Laws combined into one formula:

$$PV = Nk_B T$$

The equation of state.

\Rightarrow These Laws were found experimentally, so physicists wanted how to explain this theoretically.

To explain this, they made a few assumptions.

(*) Assumptions

a) No inter-molecular interactions

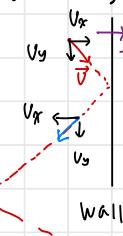
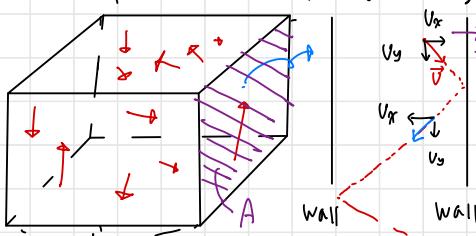
b) Point-like Particles

c) Randomly moving.

d) Elastic Collisions with the wall: No collisions between particles because of a).

With these assumptions,
Let's use kinetic theory.

< N Particles in Rectangular box >



Before & After the collision of a particle, momentum changes

$$\Delta P_i = 2m v_x = m v_x - (-m v_x)$$

$$\Rightarrow F_i = \frac{\Delta P}{\Delta t} = \frac{m v_x^2}{L} \quad \left(\because \Delta t = \frac{2L}{v_x}, \text{ Because no inter-molecular collision} \right)$$

So, the force acting on the wall by N particles is

$$F = \sum_i F_i = \frac{m}{L} \cdot \sum_i (v_{i,x})^2 \Rightarrow P = \frac{F}{A} = \frac{m}{A \cdot L} \sum_i (v_{i,x})^2 = \frac{m}{V} \langle v_x^2 \rangle \quad (\because \text{즉, } \langle v_x^2 \rangle \text{ 의 의미 } X)$$

$$= \frac{2N}{3V} \cdot \left(\frac{1}{2} m \langle v^2 \rangle \right) = \frac{N k_B T}{V} \quad (\therefore \text{The equation of state})$$

$$\therefore \langle K \rangle = \frac{1}{2} m \langle v^2 \rangle = \frac{3k_B T}{2} \quad \Rightarrow \text{so, we can get the relation between } v^2 \text{ and } T \text{ like this.}$$

$$\langle \frac{1}{2} m v^2 \rangle \text{ microscopic} \quad \text{Macroscopic} \quad \text{if } N k_B = n \cdot N_A \cdot k_B = n R, \Rightarrow P V = n R T.$$

2.2 Maxwell-Boltzmann Distribution

- 기체 분자의 속도 분포에 대한 확률밀도 함수를 유도해보자. 여기서, 우리는 속도의 크기에 대해 분석하고 싶으니 v^2 에 대한 확률밀도 함수 $f(v^2)$ 를 찾고, 이때 $v^2 = v_x^2 + v_y^2 + v_z^2$, where v_x, v_y, v_z are independent 이므로 아래와 같다.

$$\Rightarrow f(v^2) = f(v_x^2) f(v_y^2) f(v_z^2) \quad (\text{In thermal equilibrium, } v_x^2, v_y^2, v_z^2 \text{ 의 확률 분포는 같다.})$$

이를 반복하는 함수는 지구점수이므로, f 를 아래와 같이 표현 가능하다.

$$\therefore f(v_x^2) = C \cdot e^{-\alpha v_x^2} \quad (\text{사실, boltzmann distribution } e^{-\beta E} \text{ 에 비례로 통해 각각적 유도 가능.})$$

$$\Rightarrow \int_{-\infty}^{\infty} dx \cdot f(v_x^2) = C \int_{-\infty}^{\infty} dx \cdot e^{-\alpha v_x^2} = 1 \quad (\text{Normalization condition}), \quad C \cdot \sqrt{\frac{\pi}{\alpha}} = 1. \quad \therefore C = \sqrt{\frac{a}{\pi}} \quad \dots \textcircled{1}$$

\Rightarrow Let's use the consequence of the ideal gas: $m \langle v_x^2 \rangle = k_B T$. with probability density $f(v_x^2)$,

$$\Rightarrow m \langle v_x^2 \rangle = m \int_{-\infty}^{\infty} dv_x \left(v_x^2 \cdot \sqrt{\frac{a}{\pi}} e^{-\alpha v_x^2} \right) = k_B T. \Rightarrow 2m \sqrt{\frac{a}{\pi}} \cdot I = k_B T., \quad I = \int_0^{\infty} dv_x \left(v_x^2 e^{-\alpha v_x^2} \right)$$

$$I = \int_0^{\infty} \frac{dt}{2\alpha v_x} \cdot v_x^2 \cdot e^{-t} = \frac{1}{2\alpha a} \int_0^{\infty} t e^{-t} dt \quad (\text{To calculate integral, } t = \alpha v_x^2. \ dt = 2\alpha v_x dv_x)$$

$$= \frac{1}{2\alpha a} \cdot I\left(\frac{3}{2}\right) = \frac{1}{2\alpha a} \cdot \frac{1}{2} I\left(\frac{1}{2}\right) = \frac{\sqrt{\pi}}{4\alpha a} \quad (\because I(n+1) = n I(n), I\left(\frac{1}{2}\right) = \sqrt{\pi})$$

$$\therefore \frac{m}{2a} = k_B T, \quad a = \frac{m}{2k_B T} \quad \dots \textcircled{2} \quad \text{So, in \textcircled{1}, \textcircled{2} we know } C, a.$$

$$f_t(v^2) = f(v_x^2) f(v_y^2) f(v_z^2) = C^3 e^{-\alpha v^2} = \left(\frac{m}{2\pi k_B T} \right)^{\frac{3}{2}} e^{-\frac{mv^2}{2k_B T}}$$

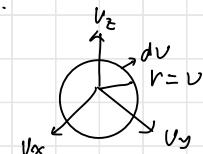
For conventional purpose, we use final representation.

$$f(v) = \left(\frac{m}{2\pi k_B T} \right)^{\frac{3}{2}} e^{-\frac{mv^2}{2k_B T}}$$

... Maxwell-Boltzmann Distribution.

\Rightarrow If we want to change this into the familiar form, be carefull when you integrate! You need to integrate in $d^3 v$, that is, $d^3 v \cdot f(v) = (4\pi v^2 f(v))$.

What we know, $4\pi v^2 f(v)$, is very familiar form.



2.3) Equipartition Theorem.

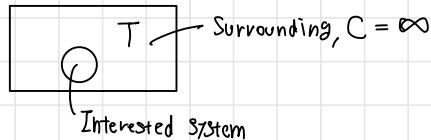
• In the Canonical Ensemble, we can show this statement.

$$P(E) \propto e^{-\beta E}, \quad \beta = \frac{1}{k_B T}$$

→ In this level, we just adopt this is true.

... Boltzmann Distribution

cf) Canonical Ensemble (T fixed ensemble)



$$\text{Probability theory says, } P \sim W = \frac{N!}{n_1! \dots n_s!} \Rightarrow P \sim e^{-\beta E}$$

Then, total energy of the system is the sum of "each degree of freedom energy"

$$E_{\text{tot}} = \sum_i \varepsilon_i(x_i) = \varepsilon_1(x_1) + \varepsilon_2(x_2) + \dots + \varepsilon_n(x_n) \text{ etc. etc.}$$

$$\text{Where, } \langle \varepsilon_i \rangle = \int d\chi_i \varepsilon_i P(E) = \int d\chi_1 d\chi_2 \dots d\chi_n \varepsilon_i e^{-\beta(\varepsilon_1 + \varepsilon_2 + \dots + \varepsilon_n)}$$

$$= \frac{\left(\int d\chi_i \varepsilon_i e^{-\beta \varepsilon_i} \right) \prod_{j \neq i} d\chi_j e^{-\beta \varepsilon_j}}{\int d\chi_1 d\chi_2 \dots d\chi_n e^{-\beta(\varepsilon_1 + \varepsilon_2 + \dots + \varepsilon_n)}} \quad \text{Normalization}$$

$$= \frac{\int d\chi_i \varepsilon_i e^{-\beta \varepsilon_i}}{\int d\chi_i e^{-\beta \varepsilon_i}} = - \frac{\partial}{\partial \beta} \cdot \ln \left[\int_{-\infty}^{\infty} d\chi_i e^{-\beta \varepsilon_i} \right] \Rightarrow \text{여기서, 물리적 적관을 빌드해야 한다.}$$

$$\text{Let } \varepsilon_i(x_i) = \alpha \cdot x_i^2$$

$$\Rightarrow \langle \varepsilon_i \rangle = - \frac{\partial}{\partial \beta} \ln \left[\int_{-\infty}^{\infty} d\chi_i e^{-\beta \alpha x_i^2} \right] = - \frac{\partial}{\partial \beta} \cdot \frac{1}{2} \ln \left[\frac{\pi}{\alpha} \right] = - \frac{1}{2} \frac{\partial}{\partial \beta} \left[\ln \pi - \ln \alpha - \ln \beta \right]$$

$$\langle \varepsilon_i \rangle = \frac{1}{2\beta} = \frac{k_B T}{2}$$

$$\left(\beta \text{의 definition: } \beta = \frac{1}{k_B T} = \frac{\partial \ln \Omega(E)}{\partial E} \right)$$

... Equipartition thm

$$\Rightarrow \text{Single degree of freedom에 해당하는 에너지인 } \langle \varepsilon_i \rangle = \frac{k_B T}{2} \text{ 이다.}$$

$$(ex) \text{ For } n=3, (x_1, x_2, x_3) \Rightarrow K = \sum_i^3 \langle \varepsilon_i \rangle = \frac{3k_B T}{2} \dots \text{ 이는 2.1)에서 걸증한 것이다.}$$

Q. In Quantum mechanics, Energy is discrete value... why integral is ok?

→ $\Delta E \ll k_B T$, It works well in our region!

2.4) Specific Heats

- We can define specific heat of the system like this :

$$C_V = \frac{C_V}{N} \text{ or } \frac{C_V}{n}$$

$$C_P = \frac{C_P}{N} \text{ or } \frac{C_P}{n}$$

where large C means heat capacity.

- Now, ideal gas의 경우에는, $E = \frac{3}{2} N k_B T$ 이므로 다음과 같다. (In monoatomic case)

$$(i) C_V = \frac{1}{N} \left(\frac{\partial E}{\partial T} \right) = \frac{1}{N} \left(\frac{\partial E}{\partial T} \right)_V = \frac{3}{2} k_B; (\because dV = 0)$$

- For constant pressure,

$$C_P = \frac{1}{N} \left(\frac{\partial Q}{\partial T} \right) = \frac{1}{N} \left[\frac{dE - dW}{dT} \right]_P = \frac{1}{N} \left[\left(\frac{\partial E}{\partial T} \right)_V + \left\{ \left(\frac{\partial E}{\partial V} \right)_T + P \right\} \left(\frac{\partial V}{\partial T} \right)_P \right]$$

$$= C_V + \frac{P}{N} \cdot \frac{N k_B}{P}$$

For quasi-static process [P definable]

$$= C_V + k_B. = \frac{5}{2} k_B \quad (\text{For 자유도} = 3).$$

$$\gamma \equiv \frac{C_P}{C_V} = \frac{5}{3}$$

... adiabatic exponent

E 는 T 만의 함수, 아래에서 별도하게 보이겠다.

(*) E 가 ideal gas의 경우, T 만의 항으로 보이겠다. 여기서 우리가 필요한 가정은 "quasi-static" 뿐이다.

$$\cdot \text{Let } E = E(T, V) \text{ then, } dE(T, V) = \left(\frac{\partial E}{\partial T} \right)_V dT + \left(\frac{\partial E}{\partial V} \right)_T dV = dQ + dW$$

• In quasi static, $dW = -P dV$.

⇒ As we will see later, entropy can be related to the heat with temperature : $dQ = T dS$

$$\Rightarrow T dS = dE - dW = \left(\frac{\partial E}{\partial T} \right)_V dT + \left(\frac{\partial E}{\partial V} \right)_T dV + P dV. \quad T \text{로 나누고, 정리해서 } dS \text{에 대한 항등식 구하면,}$$

$$\Rightarrow dS = \underbrace{\frac{1}{T} \left(\frac{\partial E}{\partial T} \right)_V dT}_{①} + \underbrace{\left[\frac{1}{T} \left(\frac{\partial E}{\partial V} \right)_T + \frac{P}{T} \right] dV}_{②} = \underbrace{\left(\frac{\partial S}{\partial T} \right)_V dT}_{①'} + \underbrace{\left(\frac{\partial S}{\partial V} \right)_T dV}_{②'}$$

⇒ This is true for all condition of (T, V) So we can say $① = ①'$, $② = ②'$

$$\left(\frac{\partial S}{\partial T} \right)_V = \frac{1}{T} \left(\frac{\partial E}{\partial T} \right)_V \quad \cdots ①$$

이제, S 가 상태함수이므로 $S_{TV} = S_{VT}$ 이다. 이를 $\frac{\partial}{\partial V} \cdot ① = \frac{\partial}{\partial T} \cdot ②$

$$\left(\frac{\partial S}{\partial V} \right)_T = \frac{1}{T} \left(\frac{\partial E}{\partial V} \right)_T + \frac{P}{T} \quad \cdots ②$$

$$\Rightarrow \underbrace{\frac{1}{T} \cdot \frac{\partial^2 E}{\partial V \partial T}}_{①'} = - \underbrace{\frac{1}{T^2} \cdot \left(\frac{\partial E}{\partial V} \right)_T}_{①'} + \underbrace{\frac{1}{T} \cdot \frac{\partial^2 E}{\partial T \partial V}}_{②'} + \underbrace{\frac{\partial}{\partial T} \left[\frac{N k_B}{V} \right]}_{③'}$$

$\Rightarrow E \in 상태함수로, E_{VT} = E_{TV} \circ \text{cl. } (\text{미분 습성 상관X})$ 즉, ① = ②'으로 위 식을 정리하면,

$$\frac{1}{T^2} \left(\frac{\partial E}{\partial V} \right)_T = 0 \quad \text{for all } T. \text{ 즉자,}$$

$$\left(\frac{\partial E}{\partial V} \right)_T = 0$$

E is not the function of V.

. In Ideal gas system, E only depends on the temperature.

3. The 2nd Law

- The only way to tell the direction of time flows.
- Before we go further, let's talk about thermodynamic process.

Thermodynamic Process : Transformation, Changes of thermodynamic states.

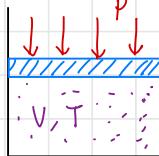
3. 1) Quasi-static Process

→ So slowly performed that the system is in the thermal equilibrium at every moment.

Related \sim 'Reversible process'

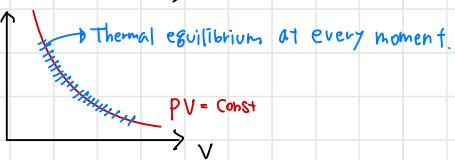
→ Pressure is measured (definable) at every moment: $dW = -PdV$ can be used. Otherwise, you cannot use it.

(ex1)

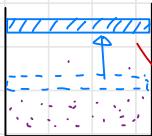


For ideal gas $PV = Nk_B T$, during Quasi-static Process, we can see that;

$$\begin{cases} P \rightarrow P' = P + \delta P \rightarrow P'' \rightarrow \dots \\ V \rightarrow V' = V + \delta V \rightarrow V'' \rightarrow \dots \\ T \rightarrow T' = T + \delta T \rightarrow T'' \rightarrow \dots \end{cases}$$



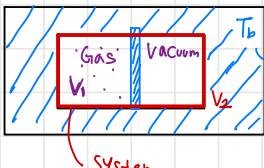
(ex2)



Sudden expansion for very small time interval

Nearly vacuum, molecules not yet reach, Cannot find P.

(*) Isothermal expansion.



Heat bath (Reservoir) : T_b is fixed, because heat capacity $C \rightarrow \infty$

\Rightarrow In thermal equilibrium, $T_b = T_s$.

a) Free expansion : 갑자기 중간 가림판 제거, Non Quasi-static Process



$\Delta T = 0 \Rightarrow \Delta E = 0$ for ideal gas

$\Delta W = 0 \Rightarrow$ No Pushing material, no work!

$\Delta Q = \Delta E - \Delta W = 0 - 0 = 0$. No heat exchange.

b) Quasi-static isothermal expansion (Reversible?)

• Pressure can be defined always: $dW = -PdV$.

$$\cdot \Delta T = 0 \Rightarrow \Delta E = 0$$

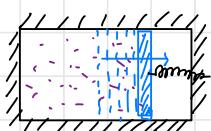
$$\cdot \Delta W = \int_1^2 dW = - \int_{V_1}^{V_2} PdV = - \int_{V_1}^{V_2} Nk_B T \frac{dV}{V} = - Nk_B T \cdot \ln\left(\frac{V_2}{V_1}\right)$$

$$\cdot \Delta Q = \Delta E - \Delta W = -\Delta W.$$

$V_2 > V_1$ (Expansion) : $\Delta W < 0 \quad \Delta Q > 0$

$V_2 < V_1$ (Compression) : $\Delta W > 0 \quad \Delta Q < 0$

(*) Adiabatic expansion : Thermally insulated & Quasi-static

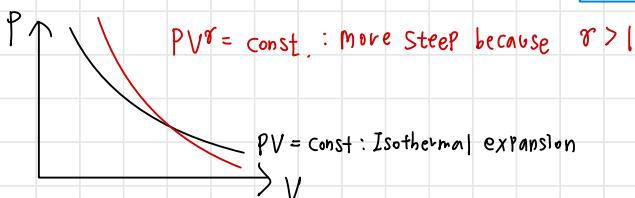


$$\cdot dQ = 0 \Rightarrow dE - dW \quad \boxed{C_V = \left(\frac{\partial E}{\partial T}\right) = \left(\frac{\partial E}{\partial T}\right)_V} \quad (\text{Ideal gas condition})$$

$$\Rightarrow C_V dT + PdV = 0 \quad dT \equiv P, V \text{에 대해 정의하면 아래와 같다.}$$

$$\Rightarrow C_V \cdot \left[\frac{PdV + Vdp}{Nk_B} \right] + PdV = 0 \Rightarrow \underbrace{(C_V + Nk_B)}_{=C_P} PdV + C_V \cdot Vdp \quad \text{양변을 } C_V P \text{로 나누고 정리하면 } \gamma = \frac{C_P}{C_V} \text{ 일 때}$$

$$\Rightarrow \int \frac{P}{V} dV + \int \frac{dp}{P} = 0 \Rightarrow \ln PV^\gamma = C. \quad \boxed{PV^\gamma = \text{const}} \quad \dots \text{state equation of adiabatic expansion.}$$



3.2) The Second Law (Statement based on the observation)

Clausius's statement.

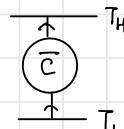
(= No perfect refrigerator)

⇒ No process is possible whose sole effect is the transfer of heat from a colder to hotter body.
= with no other effect. (여타의 징후)

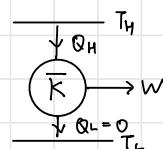
Kelvin's statement

(= No perfect engine)

⇒ No process is possible whose sole effect is the complete



< Clausius violator >



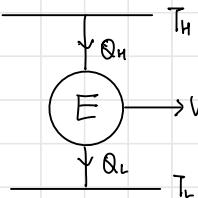
< Kelvin violator >

Q. How about isothermal expansion? Its $\Delta E = 0$. So,

$\Delta Q + \Delta W = 0$. Isn't it Kelvin violator?

A. No! why?

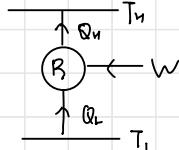
• Engine : A system operating a cyclic process that converts heat into work.



$$\text{Engine's Efficiency } \eta = \frac{W}{Q_H} = \frac{Q_H - Q_L}{Q_H} = 1 - \frac{Q_L}{Q_H} \leq 1$$

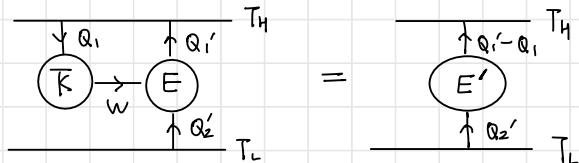
where $Q_H, Q_L > 0$ in this diagram.
(arrow indicate the sign).

c) Refrigerator



(*) Proof of the equivalence of Kelvin & Clausius's statement.

(i) $K \rightarrow C$: Let's assume we have Kelvin violator \bar{K} .

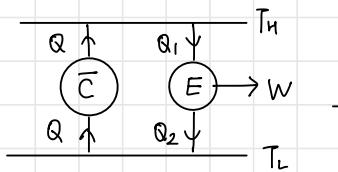


$$Q_1 - Q_2 = W + Q_2' - Q_1 \\ = Q_2' \quad (\because W = Q_1)$$

$$\text{So, } [Q_1 - Q_2] = Q_2' \text{ 이므로,}$$

입복에서 일 없어! T_L 에서 $T_H \geq$ Heat transfer가
발생한다. $\Rightarrow E' = \text{Clausius violator } \bar{C}$

(ii) $C \rightarrow K$: Let's assume we have \bar{C} .

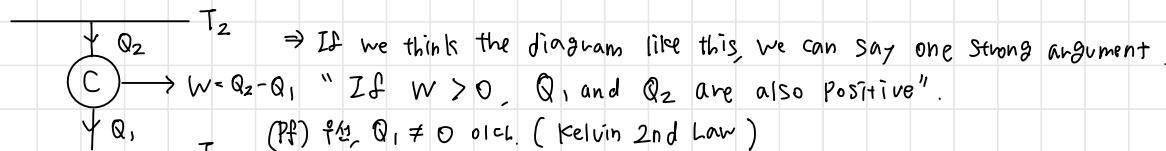


$$\text{Let } Q = Q_2 \rightarrow \begin{array}{c} Q_1 - Q \\ \downarrow \\ E' \end{array} \rightarrow W = Q_2 - Q_1$$

$\therefore E' = \text{Kelvin violator } \bar{K}$

3.3) The Carnot Engine.

Def) Any reversible engine working between two given temperatures. (Based on Carnot's assumption)

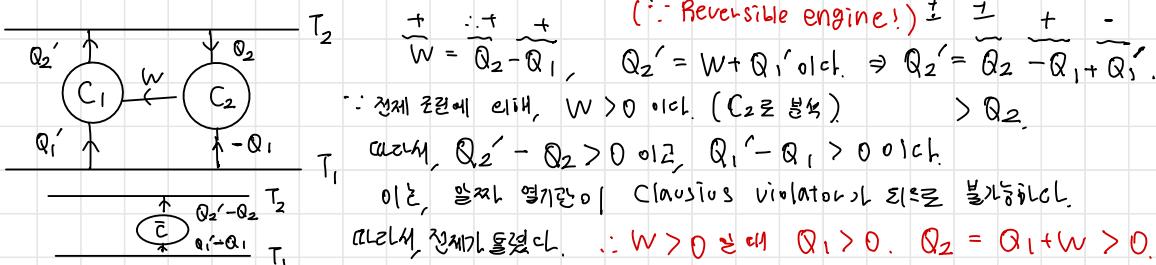


\Rightarrow If we think the diagram like this, we can say one strong argument.

"If $W > 0$, Q_1 and Q_2 are also positive".

(Pf) 푸른 $Q_1 \neq 0$ 이다. (Kelvin 2nd Law)

$Q_1 < 0$ 이고 해보자. 정리에 의해, $Q_1' > 0$ 이다. 그러면 다음과 같이 카르노 엔진 연결이 가능하다.



$$W = \frac{+}{Q_2 - Q_1}, \quad Q_2' = W + Q_1' \text{이다. } \Rightarrow Q_2' = Q_2 - Q_1 + Q_1' \quad (\because \text{Reversible engine!})$$

\therefore 전체 조건에 의해, $W > 0$ 이다. (C_2 로 분석)

따라서, $Q_2' - Q_2 > 0$ 이다. $Q_1' - Q_1 > 0$ 이다.

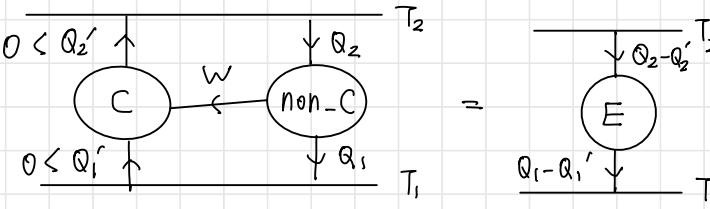
이제, 알짜 열기관이 Clausius violator로 인으로 불가능하다.

따라서, 전세가 끝났다. $\therefore W > 0$ 이 때 $Q_1 > 0$. $Q_2 = Q_1 + W > 0$.

증명은 정리인 카르노 정리를 알아보자.

(*) Carnot's theorem : No engine operating between the two temperatures is more efficient than the Carnot engine.

Pf) Let's assume the following situation



Clausius's

$$W = Q_2 - Q_1 = Q_2' - Q_1' \Rightarrow Q_2' = (Q_1' - Q_1) + Q_2, \text{ then, By 2nd Law, } Q_2 \geq Q_2' \\ Q_1 \geq Q_1'.$$

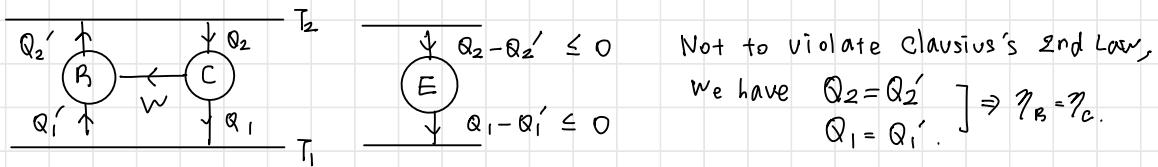
Then, we can now see, $\eta_{nc} = \frac{W}{Q_2}$. $\eta_c = \frac{W}{Q_2'}$ $\Rightarrow \eta_{nc} \leq \eta_c$.

If $\eta_{nc} = \eta_c$, then $Q_2 = Q_2'$. $Q_1 = Q_1'$. so, now non-C is Carnot engine!

(*) Corollary

① All reversible engine have the same efficiency.

Pf) We know $\eta_B \leq \eta_c \Rightarrow \frac{W}{Q_2'} \leq \frac{W}{Q_2} \Rightarrow Q_2' \geq Q_2$.



\therefore So, any reversible engine has the same efficiency!

\Rightarrow Based on these statements ($\eta \leq \eta_c$, $\eta_B = \eta_c$) we can think the simplest condition.

Let's think reversible, ideal-gas working, frictionless idealized engine.

\Rightarrow From reversible, during heat transfer, NO Temperature of system change!

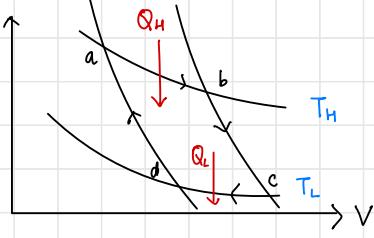
(온도가 바뀐다면; 어느 한 방향에서는 열이 날아온다. 그래서 물리적으로 2 번째 기준)

$\Rightarrow T_H, T_L$ 두 온도의 가역기관에서, 각각의 온도를 고려한 heat transfer 가능 (실제로는 불가능).

\Rightarrow Then, Engine of $T_H \leftrightarrow T_L$ 일 때는 열교환 X : Adiabatic process!

이해...

• 이제, 이러한 배경을 바탕으로, 간단한 Carnot cycle 분석하자.



Engine: Cyclic process, Converts heat into work.

(i) ab (Isothermal Expansion)

$$\Delta T = 0, \Delta E = 0. = \Delta Q_1 + \Delta W_1.$$

$$\Rightarrow \Delta Q_1 = -\Delta W_1 = \int_{V_a}^{V_b} P dV = N k_B T_H \cdot \ln \frac{V_b}{V_a} > 0.$$

(ii) bc (Adiabatic Expansion)

$$\text{or cl}, P_a V_a = P_b V_b \text{ or cl.}$$

$$PV^\gamma = \text{const.} \Rightarrow V^{\gamma-1} \cdot T = \text{const.} (\because \text{ideal gas equation})$$

$$\Rightarrow \left(\frac{V_b}{V_c} \right)^{\gamma-1} = \frac{T_L}{T_H} \quad \Delta Q_2 = 0 \text{ or cl, } \Delta W_2 = \Delta E_2 = C_V \Delta T = C_V (T_L - T_H)$$

(iii) cd (Isothermal Compression)

$$\Delta T = 0, \Delta E_3 = 0, \Delta Q_3 = -W_3 = N k_B T_L \ln \left(\frac{V_d}{V_c} \right) < 0$$

(iv) da (Adiabatic Compression) $\Delta Q_4 = 0$. $\left(\frac{V_a}{V_d} \right)^{\gamma-1} = \frac{T_L}{T_H}$

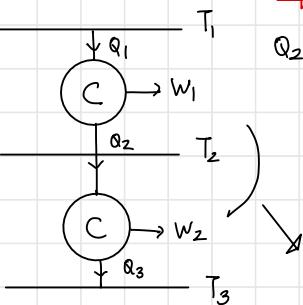
$$\Rightarrow \Delta E_{\text{tot}} = (\Delta E_1 + \Delta E_3) + (\Delta E_2 + \Delta E_4) = 0 \quad \text{also, } \frac{V_b}{V_c} = \frac{V_a}{V_d} \Leftrightarrow \frac{V_b}{V_a} = \frac{V_c}{V_d}.$$

$$\Rightarrow \frac{Q_L}{Q_H} = \frac{-\Delta Q_3}{\Delta Q_1} = \frac{N k_B T_L \ln \left(\frac{V_c}{V_d} \right)}{N k_B T_H \ln \left(\frac{V_b}{V_a} \right)} = \frac{T_L}{T_H} \text{ or cl.} \quad \boxed{\eta_0 = 1 - \frac{Q_L}{Q_H} = 1 - \frac{T_L}{T_H}}$$

$$\therefore \text{For reversible engine} \eta = \eta_0 = 1 - \frac{T_L}{T_H} \text{ or cl.} ; \underline{\eta(T_L, T_H)}$$

(*) Defining Temperature Scale using Carnot engine efficiency.

\rightarrow Universal way to define temperature scale



$$Q_2 = Q_1 - W_1.$$

$$= Q_1 - \eta Q_1$$

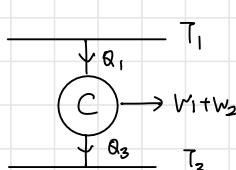
$$= [1 - \eta(T_1, T_2)] Q_1$$

$$Q_3 = Q_2 - W_2.$$

$$= Q_2 - \eta(T_2, T_3) Q_2$$

$$= Q_2 (1 - \eta(T_2, T_3))$$

$$= [1 - \eta(T_1, T_2)] [1 - \eta(T_2, T_3)] Q_1.$$



$$\Rightarrow Q_3 = Q_1 (1 - \eta(T_1, T_3))$$

$$\therefore 1 - \eta(T_1, T_3) = (1 - \eta(T_1, T_2)) (1 - \eta(T_2, T_3))$$

$$\text{Let's guess } 1 - \eta = \frac{f(T_3)}{f(T_1)} = \frac{f_3 \cup \alpha T_3}{f_1 \cup \alpha T_1} = \frac{T_3}{T_1} -$$

\hookrightarrow Linear eq

지금까지 Temperature의 정의는

- 0th law \rightarrow not rigorous

- Ideal gas Law

\rightarrow only for ideal gas

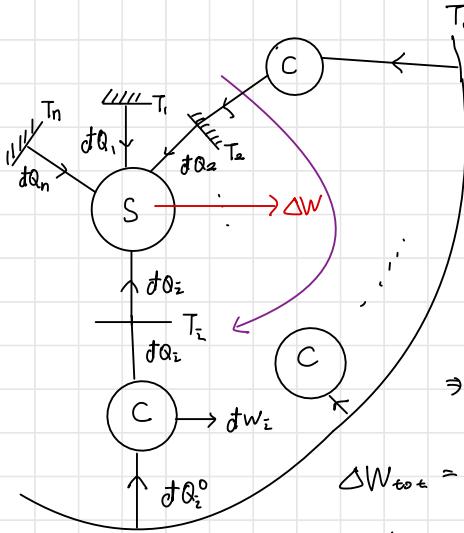
\rightarrow GAS property dependent

3.4) Clausius's theorem



→ In the real world, cycle is not that simple and beautiful.

(*) Let's think about the situation below.



T_o (Thermal constant reservoir).

$\int dQ_2 > 0$: System S absorbs heat
 $\Rightarrow \Delta W = \sum_i \int dQ_i$.

Because of the Carnot engine property, we know

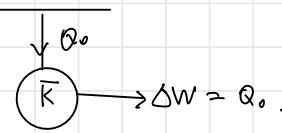
$$\left\{ \frac{\int dQ_i}{\int dQ_i^0} = \frac{T_2}{T_o} \Rightarrow \frac{\int dQ_2}{\int dQ_2^0} = \frac{\int dQ_2^0}{T_2} \right.$$

where $dQ_i^0 = dW_i + dQ_i$.

$$\Rightarrow \int dQ_2^0 = \left(\frac{T_o}{T_2} \right) \cdot \int dQ_2 \quad Q_i^0 = \sum \int dQ_i^0 = T_o \cdot \sum_i \left(\frac{\int dQ_i}{T_2} \right)$$

$$\Delta W_{tot} = \Delta W_2 + \Delta W_C = \Delta W + \sum_i \int dW_i$$

$$= \Delta W + \sum_i \left(\int dQ_i^0 - \int dQ_i \right) = \sum_i \int dQ_i^0 = T_o \cdot \sum_i \left(\frac{\int dQ_i}{T_2} \right) = Q_o$$



If $Q_o > 0$. $\Rightarrow Q_o \leq 0$. $\Rightarrow T_o \cdot \sum_i \left(\frac{\int dQ_i}{T_2} \right) \leq 0$.
 Clausius's Violator!

$\therefore \sum_i \frac{\int dQ_i}{T_2} \leq 0$. if $\int dQ_i$ infinitesimal value, $\int \frac{dQ}{T} \leq 0$.

⇒ For any cycle, $\oint \frac{dQ}{T} \leq 0$. The equality holds for the reversible process.



3.5) Entropy

$$\int_a^b \frac{\int dQ_{rev}}{T} \stackrel{\text{defn.}}{=} 2nd law. \text{ For reversible process, } \oint \frac{\int dQ_{rev}}{T} = \left[\int_a^b \frac{dQ}{T} \right]_1 + \left[\int_b^a \frac{dQ}{T} \right]_2 = 0$$

$$\Rightarrow \left[\int_a^b \frac{dQ_{\text{rev}}}{T} \right]_1 = \left[\int_a^b \frac{dQ_{\text{rev}}}{T} \right]_2 \quad \therefore \int_A^B \frac{dQ_{\text{rev}}}{T} \equiv S(B) - S(A) \quad (dS \equiv \frac{dQ_{\text{rev}}}{T})$$

... Path independence

\Leftrightarrow Exact differential

(*) Property

① For arbitrary process, There is upper bound of heat exchange

$$\text{pf)} \quad \int \frac{dQ}{T} = \int_A^B \frac{dQ}{T} + \int_B^A \frac{dQ_{\text{rev}}}{T} \leq 0. \quad \int_A^B \frac{dQ}{T} \leq \int_A^B \frac{dQ_{\text{rev}}}{T} = S(B) - S(A)$$

$$\text{or, } \frac{dQ}{T} \leq \frac{dQ_{\text{rev}}}{T} = dS \quad \therefore dQ \leq dQ_{\text{rev}} = TdS.$$

... Upper bound

of heat exchange

② For thermally isolated system, $dQ = 0 \Rightarrow T.dS \geq 0$.

\Rightarrow 열적 고온계의 엔트로피는 감소하지 않는다.

\Rightarrow 평형상태에서 $S \rightarrow$ maximized.

$$\therefore dS \geq 0$$

... Another form of 2nd Law
of thermodynamics

Holds for both Rev & Irrev process

• For reversible (quasi-static) process, $dQ = TdS$. $dW = -PdV + \sum_i f_i \underbrace{dx_i}_{\text{displacement}}$

$$dE = dQ_{\text{rev}} + dW_{\text{rev}} = TdS - PdV + M dN + \dots = dE(S, V, N, \dots) \quad (\text{Volume work})$$

$$= dQ_{\text{irrev}} + dW_{\text{irrev}} \Rightarrow dQ_{\text{irr}} \leq dQ_{\text{rev}} = TdS. \quad \text{or, } dW_{\text{irr}} \geq dW_{\text{rev}} = -PdV$$

$\hookrightarrow T, P \in$ generalized force, $ds, dV \rightarrow$ displacement

Temperature, $dS \rightarrow$ flow

= Pressure, $dV \rightarrow$ flow

= Mass, $dN \rightarrow$ flow ...

generalized force

f_i

$(\text{ex. } M \cdot dN)$

(chemical potential) \times (Number of particle)

variables (extensive)

$dV > 0$

ex) Compression $dW_{\text{irr}} \geq dW_{\text{rev}} > 0$ Expansion $dW_{\text{irr}} \geq dW_{\text{rev}}$

$dV < 0$

(System이 확장) $-dW_{\text{irr}} \geq -dW_{\text{rev}}$

$dW' \leq dW_{\text{rev}}$

\Rightarrow 이제, $dE(S, V, N)$ 은 다음과 같이 표현할 수 있다.

$$dE = TdS - PdV + MdN$$

$$= \left(\frac{\partial E}{\partial S} \right)_{V, N} dS + \left(\frac{\partial E}{\partial V} \right)_{S, N} dV + \left(\frac{\partial E}{\partial N} \right)_{S, V} dN \Rightarrow \left(\frac{\partial E}{\partial S} \right)_{V, N} = T, \left(\frac{\partial E}{\partial V} \right)_{S, N} = -P, \left(\frac{\partial E}{\partial N} \right)_{S, V} = \mu$$

$$\Rightarrow \frac{P}{T} = \frac{-\left(\frac{\partial E}{\partial V} \right)_S}{\left(\frac{\partial E}{\partial S} \right)_V} \quad (\text{where } N \text{ is fixed})$$

(*) Mathematical Skills of partial derivatives

In $X(y, z)$, $dX = \left(\frac{\partial X}{\partial y} \right)_z dy + \left(\frac{\partial X}{\partial z} \right)_y dz$, where $dz = \left(\frac{\partial z}{\partial x} \right)_y dx + \left(\frac{\partial z}{\partial y} \right)_x dy$.

$$\Rightarrow dx = \left(\underbrace{\left(\frac{\partial x}{\partial z} \right)_y \left(\frac{\partial z}{\partial x} \right)_y}_{=1} \right) dx + \left[\underbrace{\left(\frac{\partial x}{\partial z} \right)_y \left(\frac{\partial z}{\partial y} \right)_x + \left(\frac{\partial x}{\partial y} \right)_z}_{=0} \right] dy = 0 \quad \text{for } \forall x(y, z)$$

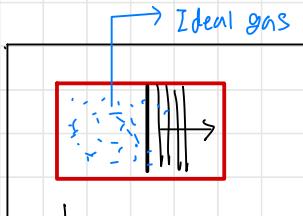
$$\therefore \left(\frac{\partial x}{\partial z} \right)_y = \frac{1}{\left(\frac{\partial z}{\partial x} \right)_y} \quad \text{...①} \quad \left(\frac{\partial x}{\partial z} \right)_y \left(\frac{\partial z}{\partial y} \right)_x \left(\frac{\partial y}{\partial x} \right)_z = -1 \quad \text{...② 이제, 이를 이용하자.}$$

$$\frac{P}{T} = - \left(\frac{\partial E}{\partial V} \right)_S \cdot \left(\frac{\partial S}{\partial E} \right)_V = - \left(\frac{\partial E}{\partial V} \right)_S \cdot \left(\frac{\partial S}{\partial E} \right)_V \quad (\because \text{①})$$

$$\Rightarrow \frac{P}{T} \cdot \left(\frac{\partial V}{\partial S} \right)_E = -1 \times -1 = 1. \quad (\because \text{②}) \quad \boxed{\therefore \frac{P}{T} = \left(\frac{\partial S}{\partial V} \right)_E}$$

3.6) Examples

① Reversible (Isothermal) expansion ($\Delta T = 0$)



For ideal gas, we know $E = E(T)$. $\Rightarrow \Delta E = \Delta Q + \Delta W = 0$

$$\Rightarrow \Delta Q = -\Delta W = N k_B T \ln \left(\frac{V_2}{V_1} \right)$$

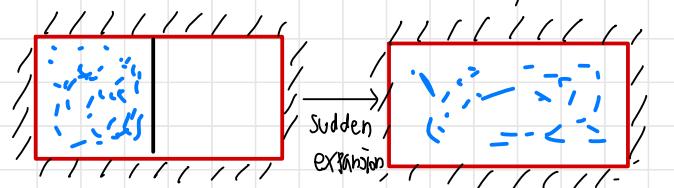
\hookrightarrow Reservoir ($T = \text{fixed}$) • How about Entropy?

$$\Rightarrow \Delta S = \int_1^2 dS = \int_1^2 \frac{dQ_{\text{rev}}}{T} = \frac{\Delta Q}{T} \quad (\because T = \text{fixed})$$

$$(i) (\Delta S)_{\text{sys}} = \frac{\Delta Q}{T} = N k_B \ln \left(\frac{V_2}{V_1} \right) > 0 \quad] \quad (\Delta S)_{\text{tot}} = (\Delta S)_{\text{sys}} + (\Delta S)_{\text{bath}} = \underline{\underline{0}}$$

$$(ii) (\Delta S)_{\text{bath}} = \frac{-\Delta Q}{T} = -N k_B \ln \left(\frac{V_2}{V_1} \right) < 0. \quad] \quad (\because \text{reversible})$$

② Joule's expansion (Irreversible)



$$\Delta Q = 0 \quad (\because \text{Adiabatic process})$$

$$\Delta W = 0 \quad (\because \text{Free expansion})$$

$$\Rightarrow \Delta E = \Delta Q + \Delta W = 0 = \Delta E(T),$$

$$\therefore T_1 = T_2.$$

• How about Entropy? → It is irreversible, so we cannot say directly " ΔS "

⇒ Instead, Let's consider reversible path from $(V_1, P_1, T_1) \rightarrow (V_2, P_2, T_2)$

(∴) 가역과정/비가역과정 모두, initial → final state가 동일하면, ΔS 가 가역과정으로 구해진다.
→ 엔트로피는 상태함수이기 때문.

(Assume Isothermal reversible process)

$$\Rightarrow TdS = dQ_{rev} = dE + PdV \Rightarrow N \cdot k_B T \cdot \ln\left(\frac{V_2}{V_1}\right) = \int TdS \quad \therefore \Delta S = Nk_B \ln\left(\frac{V_2}{V_1}\right)$$

$$\Rightarrow -(\Delta S)_{sys} = Nk_B \ln\left(\frac{V_2}{V_1}\right) > 0.$$

$$\Rightarrow (\Delta S)_{bath} = 0 \quad (\because \text{No heat exchange}) \quad] \quad \Delta S_{tot} = Nk_B \ln\left(\frac{V_2}{V_1}\right) > 0. \quad (\because \text{Irreversible})$$

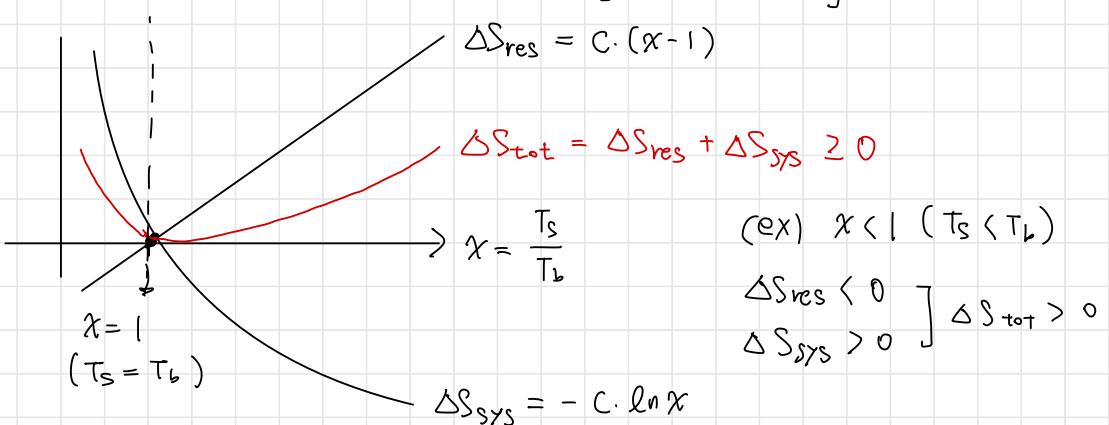
(*) How to get $(\Delta S)_{tot}$ only using system variables

$$(\Delta S)_{sys} = \int \frac{dQ_{rev}}{T} = \int \frac{C dT}{T} = C \cdot \ln\left(\frac{T_b}{T_s}\right) \quad (C: \text{constant})$$

$$\Rightarrow (\Delta S)_{res} = C \cdot \left(\frac{T_s}{T_b} - 1\right)$$

$$\Delta S_{tot} = (\Delta S)_{sys} + (\Delta S)_{res} = C \cdot \left[-\ln x + x - 1\right] \geq 0 \quad (x = \frac{T_s}{T_b})$$

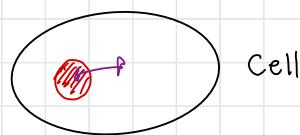
$$\Delta S_{res} = C \cdot (x-1)$$



(*) Limitation of $\Delta S \geq 0$

(i) System should be isolated in order to apply $\Delta S \geq 0$

⇒ Example case: Test tube, Cell



⇒ The red area (System) is the region we are interested in, which is interacting with the surrounding. (Non-isolated system)

(ii) Measurable / Controllable : $S(E, V, N)$

4. Thermodynamic Potentials

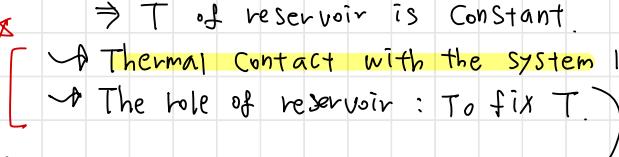
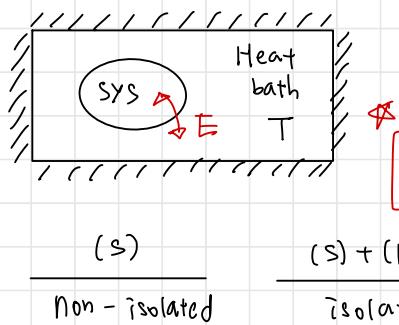
4.1) Extremum principles

관심 있는 system은 바깥의 미상체인 heat bath과 털려놓고 있다고 가정하자.

• $E_{res} \gg \Delta E$: Assume E_{res} is constant
(ideal reservoir)

⇒ T of reservoir is constant.

↳ Thermal Contact with the system long enough time
→ The role of reservoir : To fix T .



$\Rightarrow \Delta S \geq 0$. System temperature → T

$$\begin{aligned}\Delta S_{tot} &= (\Delta S)_{sys} + (\Delta S)_{bath} \quad \text{where } (\Delta S)_{bath} = \int \frac{dQ_{rev}}{T} = \frac{\Delta Q_{bath}}{T} = -\frac{\Delta Q_{sys}}{T} \\ &= \left[(\Delta S)_{sys} - \frac{\Delta E_{sys} - \Delta W_{sys}}{T} \right] \rightarrow \text{이는 } T \text{은 System quality } (= \text{Reservoir}) \\ &= \frac{1}{T} [T\Delta S - \Delta E + \Delta W] \geq 0 \quad \text{detailed information이 필요 없다. "Sys" subscript is dropped.}\end{aligned}$$

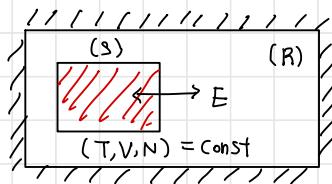
$$\therefore \Delta E - T\Delta S \leq \Delta W$$

... System information off 부족

⇒ T 가 충분히 오랜 시간이 지난 뒤 열循環에서 System의 운동이고 $\Delta E, \Delta S, \Delta W$ 는 각각 System의 내부에너지 변화 / 엔트로피 변화 / System에 해준 일의 변화이다.

• 이제, 이 식을 기반으로 여러 주어진 상황에서 계의 Potential을 나타내는 물리량을 정의해보자.

(*) Helmholtz Free energy



- T, V, N이 일정하게 유지되는 시스템에서 교환이 가능한 System이 주어졌다.
 - 이는 isothermal process (?) including no mechanical work
⇒ 위상을 ($\Delta E - T\Delta S \leq \Delta W$) 바로 변환에 대해 보일,
- $$\Rightarrow d(E - TS) \leq dW \quad (\because dT = 0)$$
- $$\equiv F \text{ (Helmholtz free energy)}$$

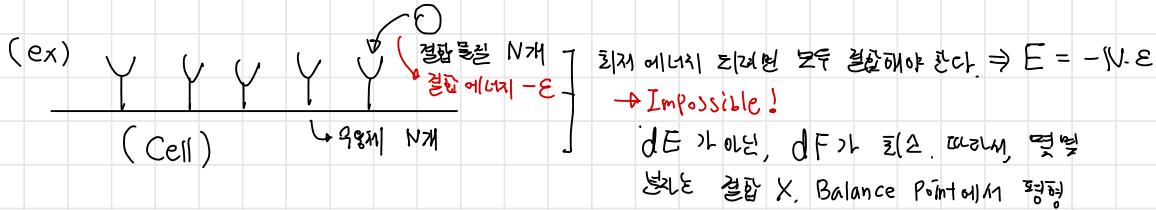
⇒ No mechanical work, $dF \leq 0$ → In equilibrium, $dF = 0$, $F \rightarrow F_{\min}$.

(i) Described by itself (System)

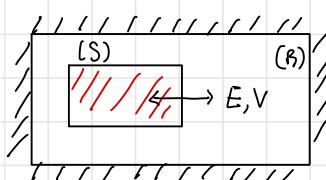
(ii) Reservoir only fixes Temperature: Don't need to consider detailed informations

(iii) New Extremum Principle: upper bound exist.

(iv) "Balance" between $dE \leq 0$ and $dS \geq 0$.



(*) Gibbs Free energy



- 이번에는, E와 V가 변할 가능하고 (T, P, N) 이 constant.
(P가 일정하니 V가 변함)

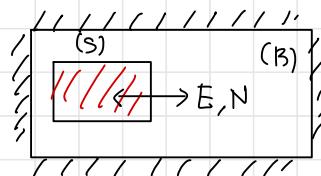
- Isothermal and Isobaric involving mechanical work,
 $dW = -PdV + dW_{\text{other}}$
Volume Work

$$\Rightarrow dE - TdS + PdV = d(E - TS + PV) \leq dW_{\text{other}}$$

$$\equiv G \text{ (Gibbs Free energy)}$$

⇒ If no other work ($\Leftrightarrow dW_{\text{other}} = 0$), $dG \leq 0$. → In equilibrium, $dG = 0$, $G \rightarrow G_{\min}$

(*) Grand Potential



• 이번에는 E 와 N 이 고정 가능하고, (T, V, μ) 가 constant.
 $\Rightarrow dW = \cancel{\mu dN} + \delta W_{\text{other}}$ 이면, 바깥에서 빼거나 더해도
Chemical work

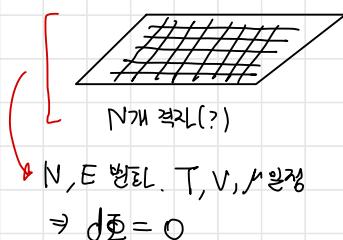
$$\Rightarrow d(E - TS - \mu N) \leq \delta W_{\text{other}}$$

≡ \Phi (Grand Potential)

\Rightarrow If no other work ($\delta W_{\text{other}} = 0$), $d\Phi \leq 0$ \rightarrow In equilibrium, $d\Phi = 0$, $\Phi \rightarrow \Phi_{\min}$

\Rightarrow 이 3가지 상황에서 정의된 계의 Potential은, 계를 무엇으로 접근느냐에 따라 사용해야 하는데
달라진다.

(Ex) \rightarrow N개 병자



(T, V, N) 일정, E 만 변화 $\Rightarrow dF = 0$.

\Rightarrow Depending on the picture, different Potential

\Rightarrow But, answer must be same!

(*) Enthalpy

+ Isobaric

A diabatic involving mechanical work.

$$\Rightarrow dQ = 0, dE = \cancel{dQ} + \delta W^{\text{rev}} = -PdV + \delta W_{\text{other}}^{\text{rev}}$$

$$\Rightarrow (dE + PdV) = d(E + PV) = \cancel{\delta W_{\text{other}}^{\text{rev}}} \leq \delta W_{\text{other}}^{\text{irr}} \equiv H(\text{Enthalpy})$$

\Rightarrow If no other work ($\delta W_{\text{other}} = 0$), $dH \leq 0$ \rightarrow In equilibrium, $dH = 0$, $H \rightarrow H_{\min}$

(*) What kind of Constraint Condition is given in the Problem?

문제 풀기 전

Check Point.

4.2) Legendre Transformation

$$\cdot dE = TdS - PdV + \underbrace{\mu dN}_{\text{Particle exchange}} = dE(S, V, N) \longrightarrow S(E, V, N)$$

[External Parameter : S, V, N]



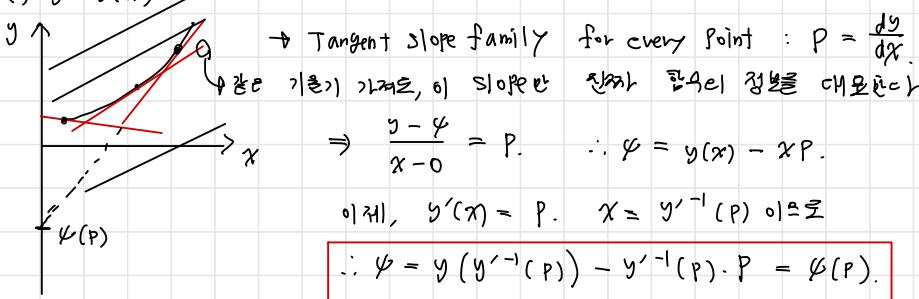
[Internal parameter : T, P, μ]



More easy to control / measure.

$$\Rightarrow \text{Let } y = y(x_1, x_2, \dots, x_n) \text{ then } p_i \equiv \frac{\partial y}{\partial x_i} \quad y \text{은 } p_i \text{의 function으로 표현된다.}$$

$$(i) y = y(x)$$



$$\text{Now, we have } y = y(x) \Leftrightarrow \psi = \psi(P). \quad dy = Pdx \longleftrightarrow d\psi = -xdP$$

$$d\psi(P) = \underbrace{dy - Pdx - xdp}_{=0} = -xdP$$

① Entropy : we now use ($V \rightarrow P$)

일반적 가정

$$H = E + PV \Rightarrow dH = dE + d(PV) = TdS - PdV + \cancel{\mu dN} + PdV + VdP = TdS + VdP$$

$$\Rightarrow dH(S, P) = TdS + VdP = \left(\frac{\partial H}{\partial S} \right)_P dS + \left(\frac{\partial H}{\partial P} \right)_S dP$$

$$\therefore \left(\frac{\partial H}{\partial S} \right)_P = T, \quad \left(\frac{\partial H}{\partial P} \right)_S = V$$

② Helmholtz Free Energy ($S \rightarrow T$)

$$\cdot F = E - TS$$

$$= \left(\frac{\partial F}{\partial T} \right)_V dT + \left(\frac{\partial F}{\partial V} \right)_T dV$$

$$\Rightarrow dF = dE - d(TS) = TdS - PdV - TdS - SdT = - (PdV + SdT)$$

$$\therefore S = - \left(\frac{\partial F}{\partial T} \right)_V, \quad P = - \left(\frac{\partial F}{\partial V} \right)_T.$$

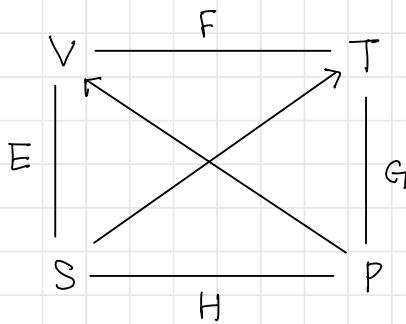
③ Gibbs Free Energy ($S \rightarrow T, V \rightarrow P$)

$$G = E - TS + PV$$

$$\Rightarrow dG = dE - d(TS) + d(PV) = -SdT + VdP = \left(\frac{\partial G}{\partial T}\right)_P dT + \left(\frac{\partial G}{\partial P}\right)_T dP$$

$$\therefore S = -\left(\frac{\partial G}{\partial T}\right)_P, \quad V = \left(\frac{\partial G}{\partial P}\right)_T$$

(*) Thermodynamic Rectangle.



$\cdot (T, S) \quad (P, V)$ conjugate.
• Arrow 방향은 + sign.

$$\text{ex)} \left(\frac{\partial E}{\partial V}\right)_S = -P.$$

$$\left(\frac{\partial F}{\partial T}\right)_V = -S$$

$$\left(\frac{\partial G}{\partial P}\right)_T = V$$

4.3) Maxwell's relation

$$\cdot dE = TdS - PdV \rightarrow 4 \text{ 가지가 각각 독립이 아니라, 원관련이 있음. } dE(S, V)$$

$$\Rightarrow \left(\frac{\partial}{\partial V}\right)_S \underbrace{\left(\frac{\partial E}{\partial S}\right)_V}_{=T} = \left(\frac{\partial}{\partial S}\right)_V \underbrace{\left(\frac{\partial E}{\partial V}\right)_S}_{-P} \Rightarrow \left(\frac{\partial T}{\partial V}\right)_S = -\left(\frac{\partial P}{\partial S}\right)_V$$

$$\cdot dH(S, P) \in ?$$

$$\Rightarrow \left(\frac{\partial}{\partial P}\right)_S \left(\frac{\partial H}{\partial S}\right)_P = \left(\frac{\partial}{\partial S}\right)_P \left(\frac{\partial H}{\partial P}\right)_S \Rightarrow \left(\frac{\partial T}{\partial P}\right)_S = \left(\frac{\partial V}{\partial S}\right)_P$$

?) rectangle

학인 가능.

$$\cdot dF(T, V) \in ?$$

$$\Rightarrow \left(\frac{\partial}{\partial V}\right)_T \left(\frac{\partial F}{\partial T}\right)_V = \left(\frac{\partial}{\partial T}\right)_V \left(\frac{\partial F}{\partial V}\right)_T \Rightarrow \left(\frac{\partial S}{\partial V}\right)_T = \left(\frac{\partial P}{\partial T}\right)_V$$

$$\cdot dG(T, P) \in ?$$

$$\left(\frac{\partial}{\partial P}\right)_T \left(\frac{\partial G}{\partial T}\right)_P = \left(\frac{\partial}{\partial T}\right)_P \left(\frac{\partial G}{\partial P}\right)_T \Rightarrow -\left(\frac{\partial S}{\partial P}\right)_T = \left(\frac{\partial V}{\partial T}\right)_P$$

(*) General relationship between C_V and C_P . through Maxwell relation,

- $\oint E = \oint Q + \oint W = T dS - P dV$
- $\oint Q|_V = T dS = C_V dT \quad (dV=0)$
- $\oint Q|_P = dE + P dV = d(E+PV) = dH|_P = C_P dT \quad (dP=0)$

$$\left[\begin{array}{l} C_P = T \left(\frac{\partial S}{\partial T} \right)_V \\ C_V = T \left(\frac{\partial S}{\partial T} \right)_P \end{array} \right. \Rightarrow \begin{aligned} \oint Q &= T dS(T, P) \\ &= T \left(\frac{\partial S}{\partial T} \right)_P dT + T \left(\frac{\partial S}{\partial P} \right)_T \underbrace{dP}_{C_P}(T, V) \\ &= \left(\frac{\partial P}{\partial T} \right)_V dT + \left(\frac{\partial P}{\partial V} \right)_T dV \end{aligned}$$

$$\therefore \oint Q = \left[C_P + T \cdot \left(\frac{\partial S}{\partial P} \right)_T \left(\frac{\partial P}{\partial T} \right)_V \right] dT + T \cdot \left(\frac{\partial S}{\partial P} \right)_T \left(\frac{\partial P}{\partial V} \right)_T dV$$

if $dV=0$, $\oint Q = C_V dT \Rightarrow C_V = C_P + T \left(\frac{\partial S}{\partial P} \right)_T \left(\frac{\partial P}{\partial T} \right)_V$

→ But, $\frac{\partial S}{\partial P}$ 같은 항은 대체로 미려움 Maxwell relation 이용해.

We know, $\left(\frac{\partial S}{\partial P} \right)_T = - \left(\frac{\partial V}{\partial T} \right)_P = -\alpha V$. $\alpha = \frac{1}{V} \cdot \left(\frac{\partial V}{\partial T} \right)_P$... Isobaric expansion coefficient

$\left(\frac{\partial P}{\partial T} \right)_V \Sigma$, T 가 높아짐에 따라 P 가 증가, 즉 정수율적 관계. (즉 쪽은 실현이 가능!)

지금 조건에서, $dV=0 = \left(\frac{\partial V}{\partial T} \right)_P dT + \left(\frac{\partial V}{\partial P} \right)_T dP$

$$\Rightarrow \left(\frac{\partial P}{\partial T} \right)_V = - \frac{\left(\frac{\partial V}{\partial T} \right)_P}{\left(\frac{\partial V}{\partial P} \right)_T} = \frac{-\alpha V}{-kV} = \frac{\alpha}{k} \quad K = -\frac{1}{V} \cdot \left(\frac{\partial V}{\partial P} \right)_T \quad \dots \text{Isothermal Compressibility}$$

$$\therefore C_P - C_V = VT \cdot \frac{\alpha^2}{K} \quad (\because T \cdot -\alpha V \cdot \frac{\alpha}{K})$$

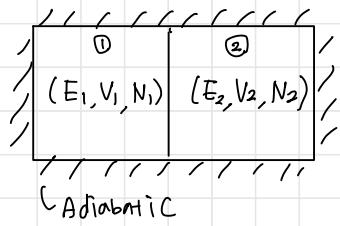
↑ For any material

$$(eg) PV = Nk_B T \quad (\text{Ideal gas}), \quad V = \frac{Nk_B T}{P} \quad \text{or} \Leftrightarrow \left\{ \begin{array}{l} \alpha = \frac{1}{V} \cdot \left(\frac{\partial V}{\partial T} \right)_P = \frac{Nk_B}{PV} = \frac{1}{T} \\ K = -\frac{1}{V} \cdot \left(\frac{\partial V}{\partial P} \right)_T = \frac{1}{V} \cdot \frac{Nk_B T}{P^2} = \frac{1}{P} \end{array} \right.$$

$$\Rightarrow C_P - C_V = VT \left[\frac{1}{\left(\frac{1}{P} \right)} \right] \times \frac{1}{T^2} = \frac{PV}{T} = Nk_B$$

$$\therefore C_P - C_V = Nk_B$$

4.4) Equilibrium Conditions



• 초기 각각 분리된 평형에서, Partition 통해 E, V, N 변화.

• In Final, equilibrium,

$$\delta S_{\text{tot}} = \delta S_1 + \delta S_2 (E_2, V_2, N_2)$$

$$= \left(\frac{\partial S_1}{\partial E_1} \delta E_1 + \frac{\partial S_1}{\partial V_1} \delta V_1 + \frac{\partial S_1}{\partial N_1} \delta N_1 \right) + \left(\frac{\partial S_2}{\partial E_2} \delta E_2 + \frac{\partial S_2}{\partial V_2} \delta V_2 + \frac{\partial S_2}{\partial N_2} \delta N_2 \right)$$

$$\text{where } \delta S_1 = -\delta S_2, \delta V_1 = -\delta V_2, \delta N_1 = -\delta N_2$$

대입해서 $\delta E_1, \delta V_1, \delta N_1 \geq 0$ 일 때 정리하면

$$\Rightarrow \left(\frac{1}{T_1} - \frac{1}{T_2} \right) \delta E_1 + \left(\frac{P_1}{T_1} - \frac{P_2}{T_2} \right) \delta V_1 - \left(\frac{\mu_1}{T_1} - \frac{\mu_2}{T_2} \right) \delta N_1 \geq 0.$$

• If $T_1 > T_2, \delta E_1 < 0 \Rightarrow T_1 = T_2 \dots \text{Thermal equilibrium}$

• If $P_1 > P_2, \delta V_1 > 0 \Rightarrow P_1 = P_2 \dots \text{mechanical equilibrium}$

• If $\mu_1 > \mu_2, \delta N_1 < 0 \Rightarrow \mu_1 = \mu_2 \dots \text{chemical equilibrium}$

(*) Helmholtz energy ≤ 0 Condition 필요함.

\Rightarrow Isothermal Condition.

①	$T = T$	②
(V_1, N_1)		(V_2, N_2)

Heat bath

$$\delta F_{\text{tot}} = \delta F_1 + \delta F_2$$

$$= \left(\frac{\partial F_1}{\partial V_1} \delta V_1 + \frac{\partial F_2}{\partial V_2} \delta V_2 \right) = -(P_1 - P_2) \delta V_1 \leq 0.$$

$$\text{If } P_1 > P_2, \delta V_1 > 0 \rightarrow P_1 = P_2$$

4.5) Euler's equation

$$\cdot dE = TdS - PdV + \mu dN \rightarrow E(S, V, N)$$

if we change the size of the system : $E(\alpha S, \alpha V, \alpha N) = \alpha E$.

$$\Rightarrow E((1+\varepsilon)S, (1+\varepsilon)V, (1+\varepsilon)N) = E(S, V, N) + \frac{\partial E}{\partial S} \varepsilon S + \frac{\partial E}{\partial V} \varepsilon V + \frac{\partial E}{\partial N} \varepsilon N$$

$$= E(S, V, N) + \varepsilon(TS - PV + \mu N) = (1+\varepsilon)E.$$

$$\therefore E = TS - PV + \mu N$$

... Euler's equation

derivative $\rightarrow dE = TdS + SdT - PdV - VdP + \mu dN + Nd\mu$

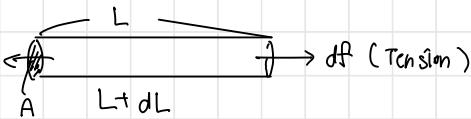
$$S_0, \boxed{SdT - VdP + Nd\mu = 0} \quad \dots \text{Gibb's Duhem relation}$$

(?)

→ Not independent, somehow related (?)

4.6) Examples

#1. Elastic rod



at constant T .

• Young's modulus

$$\gamma = \frac{T}{\varepsilon} = \frac{\frac{f}{A}}{\frac{dL}{L}} = \frac{L}{A} \left(\frac{\partial f}{\partial L} \right)_T$$

• We know α_f (expansion coefficient at constant f)

$$\alpha_f = \frac{1}{L} \cdot \left(\frac{\partial L}{\partial T} \right)_f$$

\uparrow
 \downarrow
 P

→ Isothermal expansion \Leftrightarrow 等温膨胀.

$$\cdot dE = TdS + f dL \quad \underbrace{dL}_{dW_{\text{other}}}$$

$$\cdot \text{Isothermal } \Rightarrow dF = d(E - TS) \Rightarrow dF(T, L) = -SdT + f dL$$

$$= \left(\frac{\partial F}{\partial T} \right)_L dT + \left(\frac{\partial F}{\partial L} \right)_T dL$$

$$\therefore S = - \left(\frac{\partial F}{\partial T} \right)_L \quad f = \left(\frac{\partial F}{\partial L} \right)_T$$

$$\xrightarrow{\text{Maxwell}} \left(\frac{\partial S}{\partial L} \right)_T = - \left(\frac{\partial f}{\partial T} \right)_L = \left(\frac{\partial f}{\partial L} \right)_T \left(\frac{\partial L}{\partial T} \right)_f = \left(\frac{YA}{L} \right) \left(L \alpha_f \right) = YA \alpha_f$$

$$\text{relation} \quad \text{So, } \Delta Q = T \Delta S = T \cdot YA \alpha_f (\Delta L) > 0 \text{ if } \alpha_f > 0.$$

⇒ Polymer: → $\xrightarrow{\text{reduce}} \text{if } \alpha_f < 0$

#2 Paramagnetism



(Independent magnetic moment)

$$dE = TdS - MdH \quad (M = \text{total magnetic moment} \approx mV)$$

$$\chi \equiv \lim_{H \rightarrow 0} \frac{M}{H} \quad (\text{magnetic susceptibility}) \longrightarrow m = \chi \cdot H \quad (\text{small volume})$$

• Isothermal magnetization ($H \uparrow$)

$$\Rightarrow dF = d(E - TS) = -SdT - MdH = \left(\frac{\partial F}{\partial T} \right)_H dT + \left(\frac{\partial F}{\partial H} \right)_T dH$$

$$\therefore S = - \left(\frac{\partial F}{\partial T} \right)_H \quad M = - \left(\frac{\partial F}{\partial H} \right)_T$$

Constant ($V, \epsilon, \mu_0, \mu_0 C_L$)

$$\longrightarrow \left(\frac{\partial S}{\partial H} \right)_T = \left(\frac{\partial M}{\partial T} \right)_H = \underbrace{\left(\frac{\partial \chi H V}{\partial T} \right)_H}_{H \cdot V} = H \cdot V \left(\frac{\partial \chi}{\partial T} \right)_H$$

From Curie's Law, $\chi \propto \frac{1}{T}$ $\Rightarrow \left(\frac{\partial S}{\partial H} \right)_T = H V \cdot \underbrace{\left(\frac{\partial \chi}{\partial T} \right)_H}_{(-) \text{ sign}} < 0$.

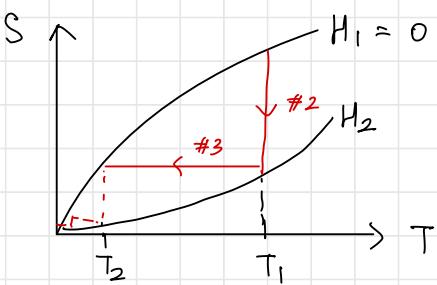
$$\Rightarrow \Delta Q = T \Delta S = H V \cdot \left(\frac{\partial \chi}{\partial T} \right)_H \Delta H < 0 \quad (-) \text{ sign.}$$

#3. Adiabatic demagnetization

From #2, $dS(T, H) = \left(\frac{\partial S}{\partial T} \right)_H dT + \left(\frac{\partial S}{\partial H} \right)_T dH = 0$. (Adiabatic)

$$\left(\frac{\partial T}{\partial H} \right)_S = - \frac{\left(\frac{\partial S}{\partial H} \right)_T}{\left(\frac{\partial S}{\partial T} \right)_H} = - H V \frac{\left(\frac{\partial \chi}{\partial T} \right)_H}{C_H} = - \frac{T H V}{C_H} \left(\frac{\partial \chi}{\partial T} \right)_H > 0$$

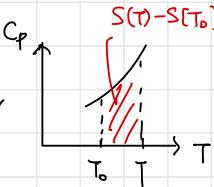
($\because C_H \equiv \left(\frac{\partial Q}{\partial T} \right)_H = T \left(\frac{\partial S}{\partial T} \right)_H$) \Rightarrow Demagnetization \longrightarrow cooling.



~ Midterm

4.7) The Third Law

One notices $C_p = T \cdot \left(\frac{\partial S}{\partial T} \right)_p \Rightarrow S(T) - S(T_0) = \int_{T_0}^T \frac{C_p(T')}{T'} dT'$



Q. What is reference value? \rightarrow Third law: $S(T=0)$ as ref.

$$S = k_B \cdot \ln \Omega(E)$$

$$E \rightarrow E_0 : \underline{\Omega(E_0) = 1} \Leftrightarrow \text{Non-degenerate}$$

(ground state) (Quantum mechanics에서 1인 경우)
→ What about degeneracy?

As $T \rightarrow 0$, $S \rightarrow 0$

... The Third Law

$$(cf) \Delta G = \Delta H - T \Delta S$$

$$\text{Plank: } T \rightarrow 0; S \rightarrow 0$$

In internal equilibrium

(부록) Nuclear spins : Crystal $\Omega = \langle T \sim T_0 \rangle$

$$I \rightarrow 2I+1$$

very weak spin-spin interaction

$$\Rightarrow \frac{1}{2} \rightarrow 2 \cdot \frac{1}{2} + 1 = 2, \quad \begin{array}{c} \uparrow \\ \text{↑} \end{array} \dots \begin{array}{c} \downarrow \\ \text{↓} \end{array} \dots \begin{array}{c} \uparrow \\ \text{↑} \end{array} \quad \Omega = 2^N, \quad S_0 = N \cdot k_B \ln 2$$

$$\hookrightarrow T \rightarrow 0 \text{ or } \begin{array}{c} \uparrow \\ \text{↑} \end{array} \dots \begin{array}{c} \uparrow \\ \text{↑} \end{array} \dots \begin{array}{c} \uparrow \\ \text{↑} \end{array} \quad (T \ll T_0)$$

Interaction each other \rightarrow 강한 영향,

As $T \rightarrow 0+$, $S \rightarrow S_0$ (각각의 각각에 대해서)
 $= 0$

(*) Classical System

$$\Omega = \frac{1}{h_0^N} \int d\vec{p}_1 d\vec{p}_2 \dots d\vec{p}_N \int d\vec{\theta}_1 d\vec{\theta}_2 \dots d\vec{\theta}_N$$

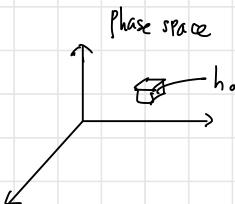
$$\Rightarrow S = k_B \cdot \ln \left[\frac{1}{h_0} \int d\vec{p}_1 \int d\vec{\theta}_1 \right]^N$$

$$= Nk_B \cdot \ln \left[\int d\vec{P} \int d\vec{\theta} \right] - N \cdot k_B \ln h_0.$$

(cf) Simon's 3rd Law Statement.

- The contribution to the entropy of a system by each aspect of the system which is in (=different subsystem) the internal

thermodynamic equilibrium
tends to zero as $T \rightarrow 0$



(*) Consequences

$$i) S(T=0, X) \rightarrow 0. \quad \left(\frac{\partial S}{\partial X} \right)_T \rightarrow 0 \quad \text{as } T \rightarrow 0$$

$$(cf) C_x = T \cdot \left(\frac{\partial S}{\partial T} \right)_X = \left(\frac{\partial S}{\partial \ln T} \right)_X = 0 \quad (\ln T \rightarrow -\infty \quad S \rightarrow 0)$$

$$ii) S(T, X) - S(T=0, X) = \int_0^T \frac{C_x(T')}{T'} dT' \quad T'=0 \text{ 은 } \frac{1}{T'} \text{ diverges, } \text{so}$$

$$\therefore \lim_{T \rightarrow 0} C_x(T) \rightarrow 0$$



ex) $C_V = \frac{3}{2} N k_B$

in classical mode

$$\text{iii) } \left(\frac{\partial S}{\partial P}\right)_T = 0 \Leftrightarrow \alpha = \frac{1}{V} \cdot \left(\frac{\partial V}{\partial T}\right)_P = 0$$

at $T \rightarrow 0$

Thermal expansion stops.

$$\text{iv) } S = C_V \ln T + B \cdot \ln V + \text{const}$$

$C_P - C_V = B$

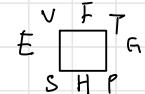
$$C_V \rightarrow 0, \ln T \rightarrow -\infty$$

$$\text{v) Curie's Law } (x \propto \frac{1}{T}) \quad v - \frac{c}{T^2}$$

$$\left(\frac{\partial S}{\partial H}\right)_T = \left(\frac{\partial M}{\partial T}\right)_H = VH \left(\frac{\partial X}{\partial T}\right)_H \rightarrow \text{breaks down}$$

\downarrow by 3rd Law \downarrow

$0 \Leftarrow T \rightarrow 0 \Rightarrow \text{diverge}$



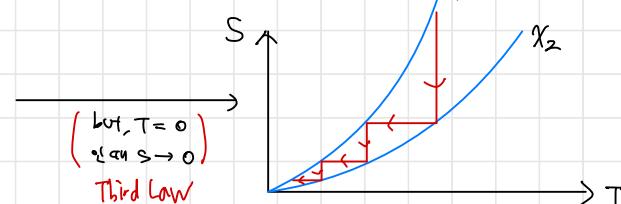
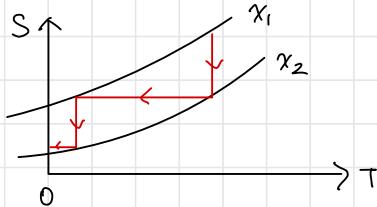
$$T \rightarrow 0,$$

Interaction이 제한적이다.

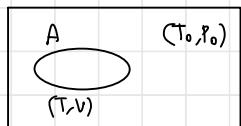
기존의 유한모델은 불가능 / 모델이

breaks down.

vi) Never reach $T=0$ in a finite numbers of steps



4.8) Stability



N: fixed. (T, V) 변화 가능

$$\Rightarrow G = E - T_0 S + P_0 V$$

Q. Carnot engine with $T_L = 0$?

$$\epsilon = 1 - \frac{T_L}{T_H} = 1, \text{ Kelvin Violator?}$$

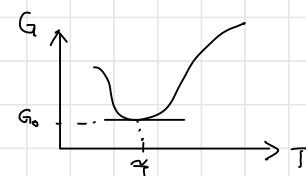
$\Rightarrow 3\text{번역} 2\text{번역} \text{ 다른, 흥미로운 } \text{번역}.$

i) $V \rightarrow \text{fixed}, T \rightarrow \text{fluctuates around } \tilde{T}$

$$\Rightarrow G(T) = G_0(\tilde{T}) + \left(\frac{\partial G}{\partial T}\right)_V \Delta T + \frac{1}{2} \left(\frac{\partial G}{\partial T}\right)_V^2 (\Delta T)^2 + \dots$$

$$\Rightarrow \left(\frac{\partial G}{\partial T}\right)_{T=\tilde{T}} = 0 = \left(\frac{\partial E}{\partial T}\right)_V - T_0 \left(\frac{\partial S}{\partial T}\right)_V = \left(1 - \frac{T_0}{\tilde{T}}\right) \left(\frac{\partial E}{\partial T}\right)_V \Big|_{T=\tilde{T}}$$

$$(TdS = dE + PdV)$$



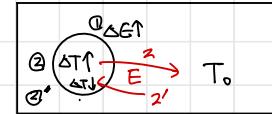
$$\therefore \tilde{T} = T_0 \quad \text{평형 조건}$$

Either max / min 가능. min은 정정자. (which mean stability)

$$\left(\frac{\partial^2 G}{\partial T^2} \right)_V \geq 0 \Rightarrow \left[\frac{T_0}{T^2} \left(\frac{\partial E}{\partial T} \right)_V + \left(1 - \frac{T_0}{T} \right) \left(\frac{\partial^2 E}{\partial T^2} \right)_V \right] \geq 0$$

$\therefore \left(\frac{\partial E}{\partial T} \right)_V \geq 0 \text{ or } C_V \geq 0$

... Le Chatelier's principle.



ii) T fixed ($T = T_0$) V fluctuates around \tilde{V}

$$\Rightarrow G(V) = G_0(\tilde{V}) + \left(\frac{\partial G}{\partial V} \right)_T \Delta V + \frac{1}{2} \left(\frac{\partial^2 G}{\partial V^2} \right)_T (\Delta V)^2 + \dots$$

$$\Rightarrow \left(\frac{\partial G}{\partial V} \right)_T = 0 = \left(\frac{\partial E}{\partial V} \right)_T - T_0 \left(\frac{\partial S}{\partial V} \right)_T + P_0. \quad dE = TdS - PdV$$

$$= (T - T_0) \left(\frac{\partial S}{\partial V} \right)_T - (P - P_0) \quad \therefore P = P_0 \quad \text{평형 조건}$$

$$\left(\frac{\partial^2 G}{\partial V^2} \right)_T \geq 0. \Rightarrow -\left(\frac{\partial P}{\partial V} \right)_T \geq 0. \quad \text{or} \quad \kappa \geq 0. \quad \left(\text{Remind: } \kappa = \frac{-1}{V} \cdot \left(\frac{\partial V}{\partial P} \right)_T \right)$$

iii) Density fluctuations. (?)

$$\text{Density } n = \frac{N}{V} \Rightarrow \text{mean value } \tilde{n} = \frac{N}{\tilde{V}}$$

$$\frac{\tilde{V} - V}{N \cdot V \tilde{V}}$$

$$\Delta n = n - \tilde{n} = N \cdot \left(\frac{1}{V} - \frac{1}{\tilde{V}} \right) = -\frac{\tilde{n} \Delta V}{\tilde{V}^2} \quad \left(= \frac{N}{\tilde{V}} \cdot \left(\frac{-\Delta V}{V} \right) \right)$$

$$\Rightarrow \langle (\Delta n)^2 \rangle = \left(\frac{\tilde{n}}{\tilde{V}} \right)^2 \langle (\Delta V)^2 \rangle$$

$$\Rightarrow P(V) dV \propto e^{-\beta G(V)} dV \quad \text{where} \quad G(V) = G_0(\tilde{V}) + \frac{1}{2} \left(\frac{\partial^2 G}{\partial V^2} \right)_T (\Delta V)^2$$

$$\Rightarrow P(V) dV = B \cdot \exp \left[-\frac{1}{2} \cdot \frac{(\Delta V)^2}{k_B T_0 \tilde{V} \kappa} \right] dV \quad = \frac{1}{2} \frac{1}{\tilde{V} \kappa} (\Delta V)^2$$

$$\therefore \langle (\Delta n)^2 \rangle = k_B T_0 \tilde{V} \kappa.$$

$$\text{For critical point : } \left(\frac{\partial P}{\partial V} \right)_T = 0.$$

$$\Rightarrow \kappa \rightarrow \infty, \langle (\Delta n)^2 \rangle \rightarrow \infty.$$

5. Phase Transitions

5.1) Phase equilibrium

- a single component system of two phases, 1 & 2 at constant T & P

⇒ Gibbs Potential

⇒ can exist together (coexist or mixed)

$$G = E - TS + PV$$

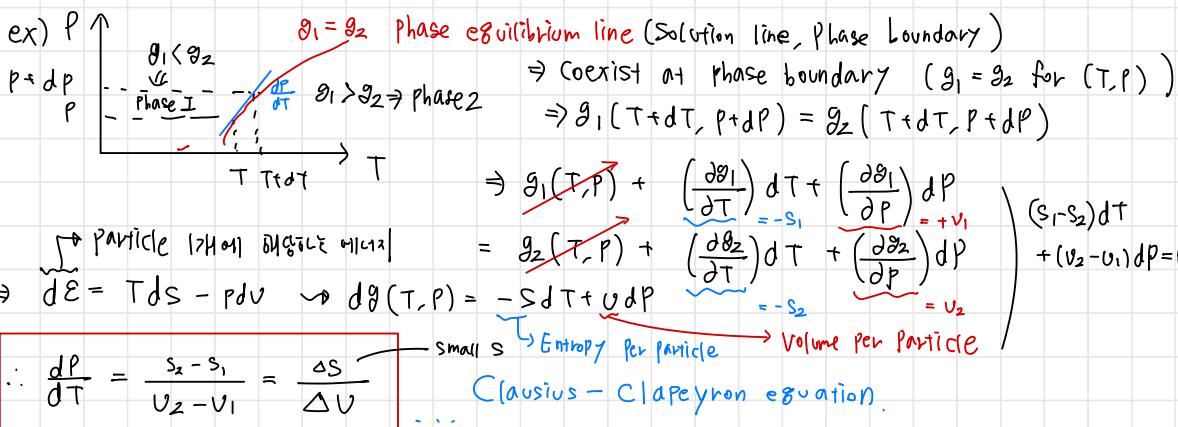
⇒ $G = g_1 N_1 + g_2 N_2$ [g_i : i phase el Gibbs energy per particle. is minimized at equilibrium
 N_i : numbers of particle in phase i]

$$\frac{dG}{dN_i} = VdP - SdT + \sum \mu_i dN_i = g_i$$

< At equilibrium > $dG = 0 \Rightarrow g_1 dN_1 + g_2 dN_2 = 0 \quad (N_1 + N_2 = N)$ (sec 22.5)
 $\Rightarrow (g_1 - g_2) dN_1 = 0$

$$g_1(T, P) = g_2(T, P)$$

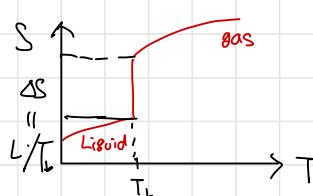
... Def of coexistence of 2 phases (phase equilibrium)



Remind) $C_x = T \cdot \left(\frac{\partial S}{\partial T}\right)_x$, $L = \Delta Q_{rev} = T \Delta S$ (Latent heat) ($x = P, V, H \dots$) Capital S

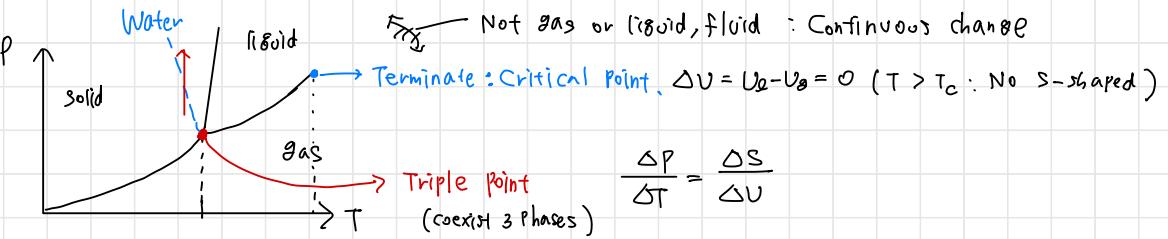
$$\frac{dP}{dT} = \frac{\Delta S}{\Delta V} = \frac{\Delta S/N}{\Delta V} = \frac{L/N}{T \Delta V} = \frac{L}{T \cdot \Delta V} \quad \hookrightarrow C_p \text{ bei } T = T_c \text{ mit } \stackrel{?}{=} \text{ steile}$$

$$(l = T \Delta S = T \cdot \frac{\Delta S}{N} = \frac{L}{N})$$



(G) $dP = \frac{L}{T \Delta V} dT \Rightarrow \Delta P = \frac{L}{\Delta V} \cdot \ln\left(\frac{T}{T_0}\right) \quad (\because L, \Delta V \text{ T independent})$

$\therefore P = P_0 + \frac{L}{\Delta V} \ln\left(\frac{T}{T_0}\right)$ ↑ → $\frac{dP}{dT}$ is steep for liquid-gas phase boundary
 Very small



< Typical phase diagram >

ex) Vapor pressure : Determine phase boundary of liquid and gas (L = temperature independent^{NL})

gas	$\frac{dP}{dT} = \frac{l}{T\Delta V} = \frac{l}{TUV_2}$
liquid	

$$(\Delta V = V_2 - V_1 \cong V_2 \text{ where } V_2 \gg V_1)$$

$$\text{An ideal gas} \Rightarrow PV_2 = k_B T. \quad (\text{각각 } N \text{ 층})$$

$$\int \frac{dP}{P} = \frac{\ell dT}{k_B T^2} \quad \left(\frac{dP}{dT} = \frac{\ell P}{k_B T^2} \right)$$

$$\Rightarrow \ln P = - \frac{1}{k_B T} . \quad \therefore P = P_0 \exp \left(- \frac{\ell}{k_B T} \right)$$

5.2. The van der Waals gas

이상기재 \Rightarrow 통지간 interaction X. 다른 model 필요.

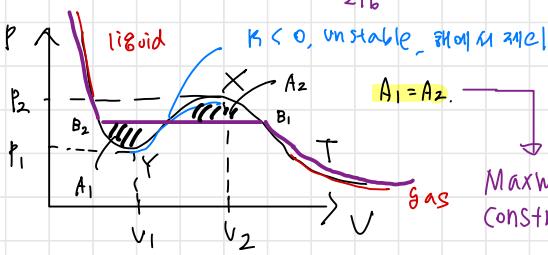
- The equation of State for the VDW gas of one mole. (at $V \gg b$, $V \gg \sqrt{\frac{a}{P}}$)

$$\left(P + \frac{\alpha}{V^2} \right) \left(V - b \right) = RT \Leftrightarrow PV^3 - (Pb + RT)V^2 + \alpha V - \alpha b = 0 \Rightarrow PV = RT$$

Intermolecular interaction

excluded volume

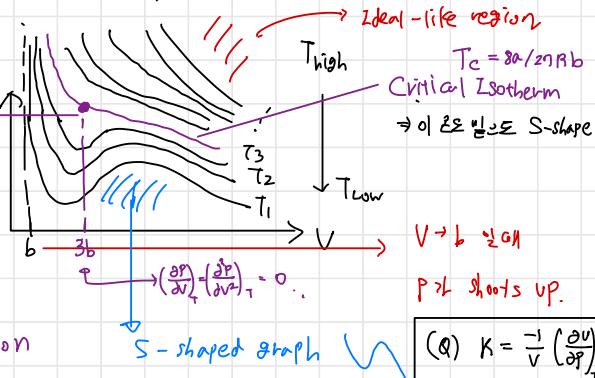
$$P_c = \frac{a}{27b^2} \quad \text{Critical point}$$



$$\text{For } \begin{cases} p > p_2 \\ p < p_1 \end{cases}, \quad \left(\frac{\partial p}{\partial v} \right)_T \leq 0 \implies \kappa = -\frac{1}{v} \left(\frac{\partial v}{\partial p} \right)_T \geq 0 \Rightarrow \text{stable.}$$

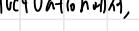
Where $\left| \frac{\partial P}{\partial V} \right|_T$ is small $\Rightarrow k$ is large. \Rightarrow gas

where $\left| \frac{\partial P}{\partial V} \right|_T$ is large $\Rightarrow k$ is small \Rightarrow liquid.



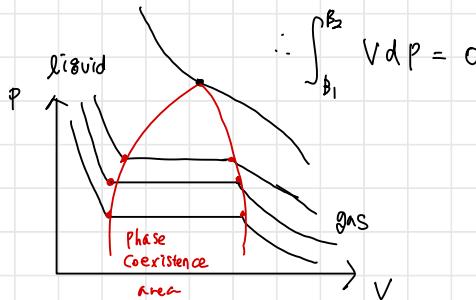
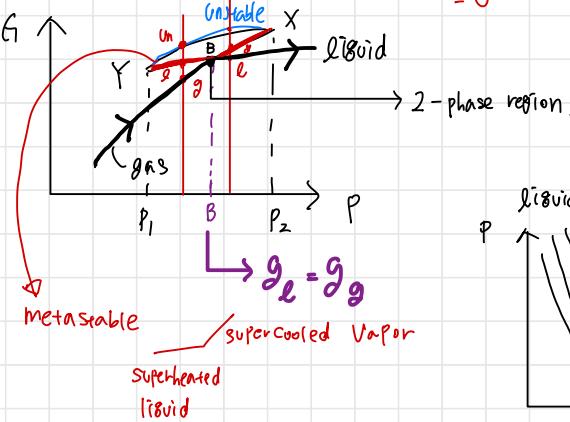
$$(Q) \quad K = \frac{-1}{V} \left(\frac{\partial V}{\partial P} \right)$$

$\Rightarrow k < 0$ 은 불안정
(Unstable)

Then,  $P \uparrow$ $V \uparrow$ dV $dW = -PDV < 0.$ \Downarrow Instability

For $P_1 < P < P_2$, $dG = -SdT + VdP \Rightarrow G(P_1, T) - G(P_0, T_0) = \int_0^{P_1} V dP = (\text{Area between } V(P) \text{ and } P \text{ axis})$

$$(\because V = \left(\frac{\partial G}{\partial P}\right)_T)$$



5.3. Nucleation

At constant T, P , $G = E - TS + PV$ ($dE = TdS - PdV + \sum_i \mu_i dN_i$)

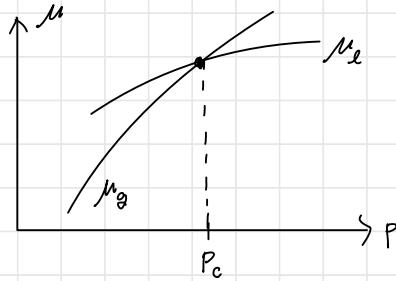
$$\Rightarrow dG = -SdT + VdP + \sum_i \mu_i dN_i = \mu_1 dN_1 + \mu_2 dN_2 = (\mu_1 - \mu_2) dN_1 = 0.$$

$$= 0$$

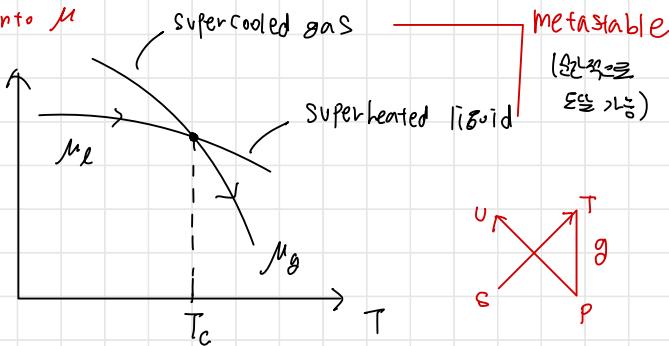
$$\therefore \mu_1 = \mu_2$$

... Rewriting θ into μ

$$\begin{matrix} V & F & T \\ S & H & P \end{matrix}$$



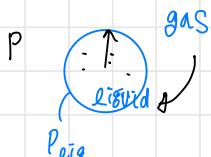
$$\Rightarrow \left(\frac{\partial \mu}{\partial P}\right)_T = V > 0$$



$$\Rightarrow \left(\frac{\partial \mu}{\partial T}\right)_P = -S < 0$$

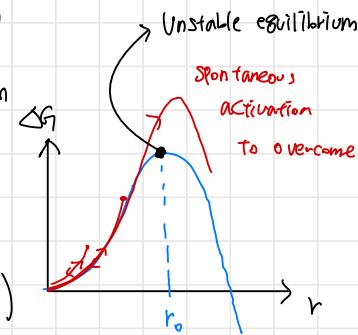
Q. Why the thermodynamically most stable state sometimes doesn't form?

\Rightarrow Suppose a liquid droplet in equilibrium with vapor



$$\Delta G = T \cdot A + (\mu_1 - \mu_2) \cdot V \cdot \frac{P_{\text{vap}}}{m}$$

$$= 4\pi T r^2 - (\Delta \mu) \cdot \frac{P_{\text{vap}} \cdot 4\pi r^3}{m} \quad (\Delta \mu = \mu_2 - \mu_1 > 0)$$



5.4. Gibbs Phase rule.

$$\Delta G = \sum \mu_i dN_i + \sum \mu_g dV_g + \sum T dA.$$

$$\left. \frac{\partial G}{\partial T} \right|_{P_0} = 0.$$

Consider a multi component, multi phase system. ($j = 1, 2, \dots, J$ Component) ($k = 1, 2, \dots, K$ phases)

\hookrightarrow different substances

(T, P) is fixed (controlled)

$$\sum_{j=1}^J C_j = C \quad (\text{Total concentration})$$

$$[(J-1) \text{ eqns}] \times (K \text{ phase eqns}) \Rightarrow (T, P)$$

$$\theta_j = \frac{C_j}{C} \Rightarrow D = [2 + (J-1)K] - (K-1)J$$

, ferro/paramagnetic,
superconducting ---

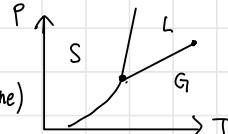
$$= 2 + J - K \quad \dots \text{Gibbs phase rule}$$

For J , Gibbs equilibrium $M_j^1 = M_j^2 = \dots = M_j^K \hookrightarrow$ For J substances

ex) $J=1, K=1$ (water) $\Rightarrow D=2$.

$J=1, K=2$ (S & f) $\Rightarrow D=1$ (line)

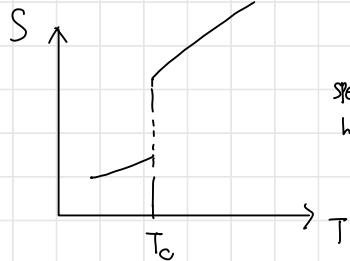
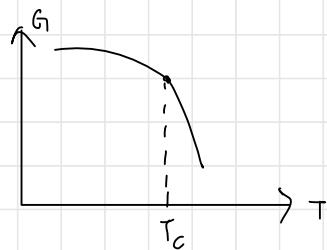
$J=1, K=3$ $\Rightarrow D=0$



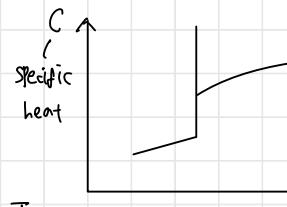
5.5. Classifications of Phase Transitions

Ehrenfest's law

i) 1st-order

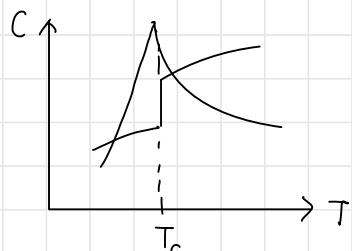
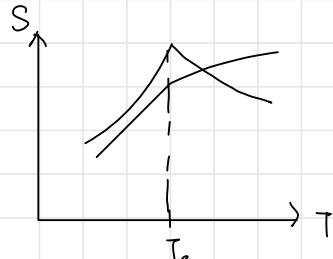
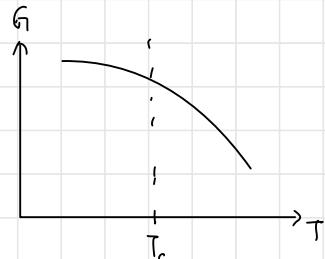


$$L = T \Delta S$$



\Rightarrow Discontinuous
Phase

ii) 2nd-order (also Higher-order) \Rightarrow Continuous Phase transition



CH 5 & 6.

$$g(v_x) \sim e^{-\beta E} = e^{-\frac{1}{k_B T} \frac{1}{2} m v_x^2}$$

$$g(v_x) = \sqrt{\frac{m}{2\pi k_B T}} e^{-\frac{m v_x^2}{2 k_B T}}$$

Same to v_y, v_z

$$\left. \begin{aligned} g(\vec{v}) &= g(v_x)g(v_y)g(v_z) dv_x dv_y dv_z \\ &\sim \exp\left(-\frac{1}{2} m v^2 / k_B T\right) dv_x dv_y dv_z \end{aligned} \right\} v_x: -\infty \text{ to } \infty$$

$$V = 4\pi v^2 dv \cdot f(v) dv \propto V \cdot g(\vec{v})$$

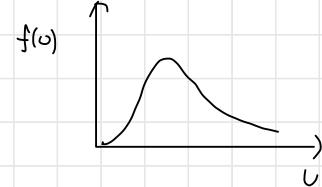
$$= v^2 \exp\left(-\frac{m v^2}{2 k_B T}\right)$$

Normalize

$$f(v) dv = \frac{4}{\sqrt{\pi}} \left(\frac{m}{2 k_B T} \right)^{\frac{3}{2}} \cdot v^2 \exp\left(-\frac{m v^2}{2 k_B T}\right) dv. \quad \text{-- M.B speed distribution}$$

$$v_{max}, \langle v \rangle, v_{rms}$$

$$\langle v \rangle = \sqrt{\frac{8 k_B T}{\pi m}}, \quad \langle v^2 \rangle = \frac{3 k_B T}{m}$$



III Kinetic Theory.

O. Brief Introduction

Classical Mechanics : Newtonian, Hamiltonian. (질점론적)

$$(\vec{P}, \vec{\theta}) = (p_1, \dots, p_{3N}, \theta_1, \dots, \theta_{3N}) \quad \text{where } \dot{\theta}_i = \frac{\partial H}{\partial P_i} \quad \dot{p}_i = -\frac{\partial H}{\partial \theta_i}$$

$\in \mathbb{R}^{6N}$

19th,
kinetic
Theory

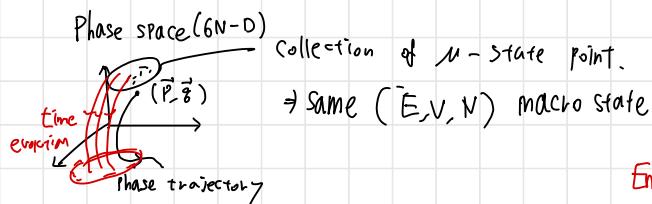
Thermodynamics : Carnot, Clausius, Maxwell, Gibbs ...

$(t \rightarrow -t, \text{ same symmetry})$
 $\Rightarrow \text{impossible}$

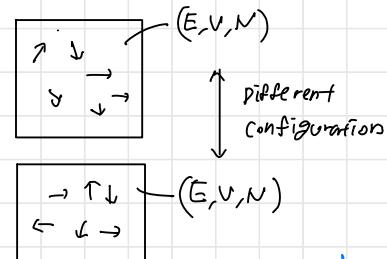
$E, N, T, V, P, \dots \Rightarrow \text{Equation of states : Phenomenological Laws}$
 $\longrightarrow S, W, Q$ (Empirical)

Boltzmann

• Statistical Mechanics : ?



Ensemble



\Rightarrow Density function $\rho(\vec{P}, \vec{\theta}, t) : \Omega$ on the left MACROSTATE (宏观态)
 weight function (?) $\tilde{f}(\vec{P}, \vec{\theta}, t)$ (but different microstate)

$$\rho d\Gamma = \lim_{N \rightarrow \infty} \frac{dN}{N}$$

I. Liouville Theorem

- Consider a closed system of N Classical Particles

- A set of representative points $(\vec{P}, \vec{\theta}) \Rightarrow$ Gibbs (Statistical) Ensemble

• Phase space Probability density.

$\Rightarrow \int \frac{d\vec{P} \cdot d\vec{\theta}}{N! h^{3N}} \rho(\vec{P}, \vec{\theta}, t) :$ Probability that your system is in the volume element around $(\vec{P}, \vec{\theta})$

= 1 (Normalized)

(*) Time evolution of $\rho(\vec{P}, \vec{\theta}, t)$

Volume element
 $\prod_i dv_i$

$$(\text{Energy}) = (\text{Energy}) X - 1$$

$$\frac{dn}{dt} = \frac{d}{dt} \int_V N \rho(\vec{P}, \vec{\theta}, t) d\vec{P} d\vec{\theta} = N \int_V \frac{\partial \rho}{\partial t} d\vec{P} d\vec{\theta} = -N \cdot \int_{\partial V} (\rho \vec{u}) \cdot \hat{n} dS \quad (\vec{u} = (\dot{P}_i, \dot{\theta}_i))$$

↳ Phase velocity

$$(\nabla \equiv \sum_i \left(\frac{\partial}{\partial P_i} \hat{P}_i + \frac{\partial}{\partial \theta_i} \hat{\theta}_i \right)) \quad (?)$$

$$\therefore \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) = 0$$

$$\Rightarrow \frac{\partial P}{\partial t} + P \cdot (\nabla \cdot \vec{u}) + \vec{u} \cdot (\nabla P) = 0$$

$$\Rightarrow \frac{\partial P}{\partial t} + \sum_{i=1}^N P \left(\frac{\partial \dot{q}_i}{\partial q_i} + \frac{\partial \dot{p}_i}{\partial p_i} \right) + \sum_i \left(\frac{\partial P}{\partial q_i} \dot{q}_i + \frac{\partial P}{\partial p_i} \dot{p}_i \right) = 0$$

3N?

$$= \frac{\partial H}{\partial p_i \partial q_i} - \frac{\partial^2 H}{\partial p_i \partial q_i} = 0$$

$$= \frac{\partial P}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial P}{\partial p_i} \frac{\partial H}{\partial q_i} \rightarrow \text{No Bracket.}$$

$\therefore \frac{\partial P}{\partial t} + \{P, H\} = 0$

$\hat{L} P \quad (L \equiv \text{Liouville Operator})$

$$\begin{cases} \dot{q}_i = \frac{\partial H}{\partial p_i} \\ \dot{p}_i = -\frac{\partial H}{\partial q_i} \end{cases}$$

- Consider $A(\vec{P}, \vec{q}, t)$

$$\Rightarrow \frac{dA}{dt} = \frac{\partial A}{\partial t} + \sum_i \left(\frac{\partial A}{\partial q_i} \dot{q}_i + \frac{\partial A}{\partial p_i} \dot{p}_i \right) = \frac{\partial A}{\partial t} + \{A, H\} = \frac{\partial A}{\partial t} + \sum_i \lambda_i A$$

Liouville operator

(?)

$$\therefore \frac{dP}{dt} = \frac{\partial P}{\partial t} + \sum_i \lambda_i P = 0.$$

P 가 시간에 지나면서도 유팽하지만 총 밀도는 변동하지 않으니 (역제) 같다.

\therefore phase space density P 는 t 에 대해 invariant. (Incompressible)

$$\Rightarrow \frac{\partial P}{\partial t} + \sum_i \lambda_i P = 0 \Leftrightarrow P(\vec{P}, \vec{q}, t) = e^{-\sum_i \lambda_i t} P(\vec{P}, \vec{q}, 0)$$

where $\lambda_i P_0 = \lambda_i P_0$ Hermitian E/B.

Poincare recurrence theorem

\Rightarrow Time-reversal symmetry: Not consistent with daily life observation

(*) Average of $\langle A \rangle$ $A(\vec{P}, \vec{q})$

$$\langle A \rangle = \frac{1}{N! h^{3N}} \int A(\vec{P}, \vec{q}) \underbrace{P(\vec{P}, \vec{q}, t)}_{= e^{-\sum_i \lambda_i t} P(\vec{P}, \vec{q})} d\vec{P} d\vec{q} \Rightarrow \frac{d\langle A \rangle}{dt} = \frac{1}{N! h^{3N}} \cdot (-\sum_i \lambda_i) \cdot \int A \underbrace{\frac{\partial P}{\partial t}}_{= \{H, P\}} d\vec{P} d\vec{q} \quad \dots \textcircled{1}$$

$$A(\vec{P}(t), \vec{q}(t)) \Rightarrow \langle A \rangle = \frac{1}{N! h^{3N}} \int A(\vec{P}(t), \vec{q}(t)) P(\vec{P}, \vec{q}) d\vec{P} d\vec{q}$$

$$\Rightarrow \frac{dA(\vec{P}(t), \vec{q}(t))}{dt} = \frac{\partial A}{\partial t} + \sum_i \left(\frac{\partial A}{\partial p_i} \dot{p}_i + \frac{\partial A}{\partial q_i} \dot{q}_i \right) = \sum_i \left(\frac{\partial A}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial A}{\partial p_i} \frac{\partial H}{\partial q_i} \right) = \sum_i \lambda_i A$$

$= 0$

(A의 시간derivative는 P, q 로 됨)

$$\therefore A = e^{\sum_i \lambda_i t} A(\vec{P}, \vec{q})$$

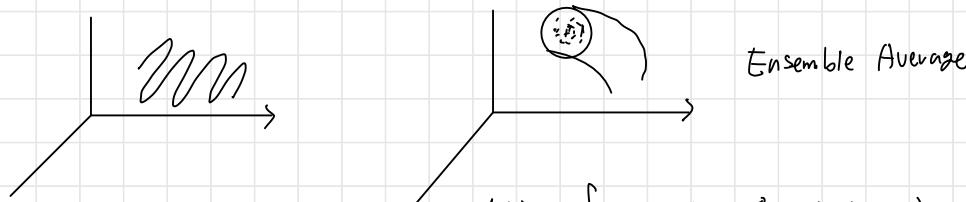
$$\Rightarrow \frac{d\langle A \rangle}{dt} = \frac{1}{N! h^{3N}} \bar{z} \int d\vec{p} d\vec{\theta} 2A P. \quad \dots \textcircled{2}$$

From ①, ① $\Rightarrow - \sum_i \int A \left(\frac{\partial P}{\partial \theta_i} \frac{\partial H}{\partial P_i} - \frac{\partial H}{\partial \theta_i} \frac{\partial P}{\partial P_i} \right) d\vec{p} d\vec{\theta}$

$$= A \cdot P \frac{\partial H}{\partial P_2} \Big|_S - \int d\vec{p} d\vec{\theta} P \cdot \{H, A\} = \langle \{A, H\} \rangle$$

$$\frac{d\langle A \rangle}{dt} = \langle \{A, H\} \rangle$$

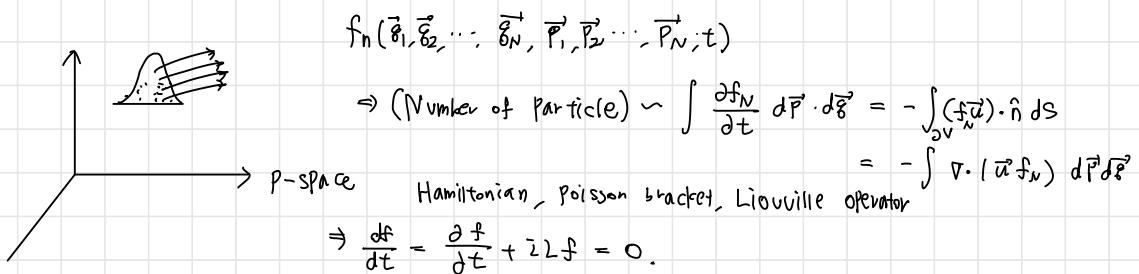
\neq 흐름방정식 / 운동량 대수 2 Approach identical result.



$$\bar{A} = \frac{1}{T} \int_0^T A(\vec{P}(t), \vec{\theta}(t)) d\vec{p} d\vec{\theta}$$

//? (Ergodic hypothesis, not been proved (?))

(Experiment)



↪ Precise, but cannot explain time-irreversibility, too many equations, difficult to solve.

Non-interacting \Leftrightarrow self adjoint (?)

↪ Exact, but useless

2. BBGKY Hierarchy

- Consider a classical system of identical N particles

f_N : Probability finding N particles having specified $\vec{P}, \vec{\epsilon}$

$$\textcircled{1} \quad \langle A_1(t) \rangle = \int \left[\sum_{z=1}^N A_1(z_i) \right] f_N(z_1, z_2, \dots, z_N, t) dz_1 \dots dz_N$$

$$= A_1(z_1) + A_1(z_2) + \dots + A_1(z_N)$$

$$= \int dz_1 A_1(z_1) \cdot N \int dz_2 \dots dz_N f_N = \int dz_1 A_1(z_1) f_1(z_1, t) \quad \text{N4H.}$$

$\Rightarrow f_1(z_1, t) \rightarrow N \text{개 중 } 1\text{개가 } z_1 \text{인 } \vec{p}_1, \vec{\epsilon}_1 \text{ 존재할 확률}\}$

$$\textcircled{2} \quad \langle A_2(t) \rangle = \int \left[\sum_{i \neq j} A_2(z_i, z_j) \right] f_N(z_1, \dots, z_N, t) dz_1 \dots dz_N \quad (\text{Interaction})$$

$$= \int dz_1 dz_2 A_2(z_1, z_2) N(N-1) \int dz_3 \dots dz_N f_N = \int dz_1 dz_2 A_2(z_1, z_2) f_2(z_1, z_2, t)$$

$\Rightarrow f_2(z_1, z_2, t) \dots S \text{ particle reduced distribution function}$

$$\therefore f_S(z_1, z_2, \dots, z_S, t) = \frac{N!}{(N-S)!} \cdot \int dz_{S+1} \dots dz_N f_N(z_1, \dots, z_N, t)$$

$$(\text{Ex}) \text{ For kinetic energy, } A_i = \frac{\vec{p}_i^2}{2m} ; \quad \langle K \rangle = \int dz_1 \frac{\vec{p}_1^2}{2m} \cdot f_1(z_1, t)$$

$$\text{For potential energy, } U_{ij} \Rightarrow \langle U \rangle = \frac{1}{2} \int dz_1 dz_2 U(\vec{\epsilon}_1, \vec{\epsilon}_2) f_2(z_1, z_2, t)$$

$$(\because U(\vec{\epsilon}_1, \vec{\epsilon}_2) = U(\vec{\epsilon}_2, \vec{\epsilon}_1) = \text{증복, 대칭이 } \frac{1}{2} \text{배 계산해야 한다})$$

\Rightarrow Single or 2-particle distribution \equiv average value

(*) Some Properties

$$\int dz_1 f_1(z_1, t) = N$$

$$\int dP_1 f_1(z_1, t) = n(\vec{\epsilon}_1, t) \rightarrow \text{Particle number density, function of position}$$

$$\int dP_1 \left(\frac{\vec{p}^2}{2m} \right) f_1(z_1, t) \Rightarrow \frac{3}{2} n(\vec{\epsilon}, t) \cdot T(\vec{\epsilon}, t)$$

$$\int dP_1 \cdot \vec{P} f_1(z_1, t) \equiv m \cdot n(\vec{\epsilon}, t) U(\vec{\epsilon}, t) \quad \text{Continuum Temperature}$$

Momentum

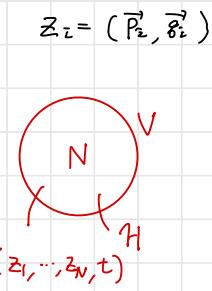
(*) BBGKY 方程.

$$\cdot \text{Suppose } H = \left[\sum_{i=1} \frac{\vec{p}_i^2}{2m} + \sum u_i(\vec{\epsilon}_i) \right] + \sum_{i < j} u_{ij}(\vec{\epsilon}_i - \vec{\epsilon}_j) \quad \text{for } N \text{ particles}$$

$$\Rightarrow i \mathcal{L}_N = \sum_{j=1} \left(\frac{\partial H}{\partial P_{jx}} \frac{\partial}{\partial \epsilon_{jx}} - \frac{\partial H}{\partial \epsilon_{jx}} \frac{\partial}{\partial P_{jx}} \right) \quad (\text{평의성 } P_x = \vec{P}_x, \epsilon_x = \vec{\epsilon}_x \text{ 의 미})$$

$$= \sum_i \frac{P_i}{m} \mathcal{S}_{ix}$$

$$= \sum_i \frac{\partial u_i}{\partial \epsilon_{ix}} \mathcal{S}_{ix} + \sum_{i < j} \left(\frac{\partial u_{ij}}{\partial \epsilon_{ix}} \mathcal{S}_{ix} + \frac{\partial u_{ij}}{\partial \epsilon_{jx}} \mathcal{S}_{ix} \right)$$



$$\begin{aligned}
 &= \sum_i \frac{P_i}{m} \frac{\partial}{\partial \dot{z}_i} - \sum_i \frac{\partial u_{iz}}{\partial \dot{z}_i} \frac{\partial}{\partial P_i} - \sum_{izj} \left(\frac{\partial u_{izj}}{\partial \dot{z}_i} \frac{\partial}{\partial P_j} + \frac{\partial u_{izj}}{\partial \dot{z}_j} \frac{\partial}{\partial P_i} \right) \Leftrightarrow u_{izj}(\dot{z}_i - \dot{z}_j) \\
 &= \sum_{iz}^N \left(\frac{P_i}{m} \frac{\partial}{\partial \dot{z}_i} + F_{iz}^{\text{ext}} \frac{\partial}{\partial P_i} \right) + \sum_{izj} F_{izj} \left(\frac{\partial}{\partial P_i} - \frac{\partial}{\partial P_j} \right) \quad (\text{지금까지는 Constraint X. 쓰는 풀이}) \\
 &\quad (1 \dots s) \equiv S_i \quad (s+1 \dots N) \equiv P_{ij} \quad (\text{Integration}) \quad (\text{or we decompose it to}) \\
 &\Rightarrow \bar{z}_{iN} = \sum_{i=1}^s S_i + \sum_{\substack{i < j \\ i=j+1}}^s P_{ij} + \sum_{i=s+1}^N S_i + \sum_{\substack{j > i \\ (i,j)}}^N P_{ij} + \sum_{i=1}^s \sum_{j=s+1}^N P_{ij} \\
 &\quad \bar{z}_{is} \quad \textcircled{1} \quad \bar{z}_{N-s} \quad \textcircled{2} \quad + \textcircled{3} \quad N \left(\begin{array}{|c|c|} \hline 0 & s \\ \hline 0 & N-s \\ \hline \end{array} \right) \\
 &\text{From Liouville, } \frac{\partial f_N}{\partial t} + \bar{z}_{iN} f_N = 0. \text{ and we defined } f_s \text{ before.}
 \end{aligned}$$

$$(\text{LHS}) \Rightarrow \bar{z}_{iN} f_N = - \frac{\partial f_N}{\partial t} \quad \text{양변을 } \frac{N!}{(N-s)!} \int dz_{s+1} dz_{s+2} \dots dz_N. \text{ 적분하면, } f_N \rightarrow f_s \text{ 이다.}$$

$$(\text{LHS}) = - \frac{\partial}{\partial t} f_s. \underset{\text{Simplifying}}{\textcircled{1}} = \bar{z}_{is} f_s. \quad (\text{No integration by part, 그대로 적분함수로}) \quad f_N|_S = 0.$$

$$\textcircled{2} = \frac{N!}{(N-s)!} \int dz_{s+1} \dots dz_N \bar{z}_{N-s} f_N. = \frac{N!}{(N-s)!} \int dz_{s+1} \dots dz_N \left[\sum_{i=s+1}^N \left(\frac{P_i}{m} \frac{\partial f_N}{\partial \dot{z}_i} + F_i^{\text{ext}} \frac{\partial f_N}{\partial P_i} \right) \right]$$

$$= 0. \quad (\because i = s+1 \dots N \text{ 뿐만 아니라 } \frac{\partial f_N}{\partial \dot{z}_i} d\dot{z}_i = f_N|_S = 0 \text{ for surface } S) \quad + \sum_{i,j=s+1}^N \left(\frac{\partial f_N}{\partial P_i} - \frac{\partial f_N}{\partial P_j} \right)$$

$\Rightarrow \textcircled{2}$ term vanishes. (Other 's+1~N'의 evolution은 상관없이 전혀 영향이 없다)

$$\textcircled{3} = \frac{N!}{(N-s)!} \int dz_{s+1} \dots dz_N \sum_{i=s+1}^s \sum_{j=s+1}^N F_{ij} \left(\frac{\partial f_N}{\partial P_i} - \frac{\partial f_N}{\partial P_j} \right) \rightarrow j = s+1 \dots N, \textcircled{3} \text{에 대해 } f_N|_S = 0$$

$$= \sum_{i=1}^s \frac{N!}{(N-s)!} \int dz_{s+1} \dots dz_N \sum_{j=s+1}^N F_{ij} \frac{\partial f_N}{\partial P_i} = \sum_{i=1}^s \frac{N! (N-s-1+1)}{(N-s)!} \int dz_{s+1} \dots dz_N F_{i,s+1} \frac{\partial f_N}{\partial P_i}$$

$$= \left[\sum_{i=1}^s \int dz_{s+1} F_{i,s+1} \frac{\partial}{\partial P_i} \right] \left[\frac{N!}{(N-s-1)!} \int dz_{s+2} \dots dz_N f_N \right] \quad (\text{하지만 } j = s+1 \text{ 고려})$$

$$\text{Now, 위 결과를 합하면, } - \frac{\partial}{\partial t} f_s = \bar{z}_{is} f_s + \textcircled{3}, \quad [\bar{z}_{is} + \frac{\partial}{\partial t}] f_s = -\textcircled{3}.$$

$$\Rightarrow \left[\frac{\partial}{\partial t} + \bar{z}_{is} \right] f_s (z_1, z_2, \dots, z_s, t) = - \sum_{i=1}^s \int dz_{s+1} F_{i,s+1} \frac{\partial}{\partial P_i} f_{s+1} (z_1, \dots, z_{s+1}, t)$$

... Bogoliubov-Born-Green-Kirkwood-Yvon hierarchy (BBGKY)

$$\frac{df_s}{dt} \neq 0.$$

$$S=1 : \left(\frac{\partial}{\partial t} + \frac{p_1}{m} \frac{\partial}{\partial x_1} + F_1 \frac{\partial}{\partial p_1} \right) f_1(x_1, p_1, t) = - \int d\vec{x}_2 F_{1,2} \frac{\partial}{\partial p_1} f_2(x_1, p_1, x_2, p_2, t)$$

$$S=2 : \left(\frac{\partial}{\partial t} + \frac{p_1}{m} \frac{\partial}{\partial x_1} + \frac{p_2}{m} \frac{\partial}{\partial x_2} + F_1 \frac{\partial}{\partial p_1} + F_2 \frac{\partial}{\partial p_2} + F_{12} \left(\frac{\partial}{\partial p_1} - \frac{\partial}{\partial p_2} \right) \right) f_2 = - \int d\vec{x}_3 \left(F_{12} \frac{\partial}{\partial p_1} + F_{23} \frac{\partial}{\partial p_2} \right) f_3(x_1, p_1, x_2, p_2, x_3, p_3, t)$$

S=3... ↳ 계곡에서 반복되는 '계단 구조'. How to terminate?

⇒ 틀리적 직관을 동원한 approximation,

3. Vlasov Equation.

$$\cdot \left(\frac{\partial}{\partial t} + \vec{P} \cdot \frac{\partial}{\partial \vec{x}} + \vec{F} \cdot \frac{\partial}{\partial \vec{P}} \right) f_1(\vec{x}, \vec{P}, t) = \int d\vec{x}' d\vec{P}' \cdot \frac{\partial u(\vec{x}, \vec{x}')}{\partial \vec{x}} \cdot \frac{\partial}{\partial \vec{P}'} f_2(\vec{x}, \vec{P}, \vec{x}', \vec{P}', t)$$

$$= f_1(\vec{x}, \vec{P}, t) \cdot f_2(\vec{x}', \vec{P}', t)$$

(vector notation 생략, Drop off 1 subscript)

... Vlasov Equation

$$(RHS) = \int d\vec{x}' d\vec{P}' \frac{\partial u}{\partial \vec{x}} \cdot f(\vec{x}', \vec{P}', t) \cdot \frac{\partial f}{\partial \vec{P}'} = - \vec{F}(x, t) \frac{\partial f(x, p, t)}{\partial \vec{P}}$$

$$= \int d\vec{x}' \frac{\partial u}{\partial \vec{x}} \cdot n(x', t) = \frac{\partial}{\partial \vec{x}} \int d\vec{x}' u(x, x') n(x', t)$$

→ Interaction with others in system

$$\frac{Df}{Dt} = - \vec{F}(x, t) \quad \text{↑ Mean field force}$$

$$\Rightarrow \left[\frac{\partial}{\partial t} + \frac{p}{m} \frac{\partial}{\partial \vec{x}} + (F^{\text{ext}} + \vec{F}) \frac{\partial}{\partial \vec{P}} \right] f(x, p, t) = 0.$$

Let 0

→ Time-reversible Invariant (Symmetry)

(*) Let's see what happening in the plasma,

$$\cdot \text{Plasma Parameter } P_p = \frac{e^2 / d}{k_B T}. \quad (d = \text{average distance})$$

$$\approx \frac{e^2 n^{-\frac{1}{3}}}{k_B T}$$

$$= \frac{1}{4\pi} \cdot \frac{d^2}{\lambda_D^2} \ll 1 \quad \left[\frac{1}{\lambda_D^2} \sim \frac{4\pi e^2 n}{k_B T} \quad (\lambda_D: \text{Debye length}) \right]$$

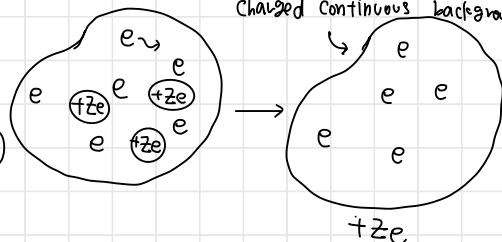
↳ Electric potential ≈ parameter 간의 관계. : weakly coupled plasma.
perturbation

Now, by Vlasov E8,

$$\frac{\partial f}{\partial t} + \vec{P} \cdot \frac{\partial f}{\partial \vec{r}} + e \left(\vec{E} + \frac{1}{c} \vec{v} \times \vec{H} \right) \frac{\partial f}{\partial \vec{P}} = 0. \quad \rightarrow \text{nonlinear equation}$$

$$\text{where } \vec{F} = e \vec{E}_{(r,t)} - \frac{\partial}{\partial r} \int dr' u(r-r') n(r', t) \stackrel{\int f dp = n}{\rightarrow} \Rightarrow \text{perturbative approach}$$

One component plasma
System with positively charged continuous background



E场에 f에 영향

$$\text{Let } f(\vec{r}, \vec{p}, t) = f_0(\vec{p}) + \delta f(\vec{r}, \vec{p}, t) \quad \left(f_0(p) = n \cdot \left(\frac{\beta}{2\pi m} \right)^{\frac{3}{2}} e^{-\frac{\beta p^2}{2m}} \right)$$

Vlasov equation 대입.

weak Coulomb interaction all effect term

弱 Coulomb interaction all effect term

$$\Rightarrow \frac{\partial}{\partial t} (f_0 + \delta f) + \frac{p}{m} \frac{\partial}{\partial r} (f_0 + \delta f) = -e \vec{E} \cdot \frac{\partial}{\partial p} (f_0 + \delta f) \quad n(r, t) = n_0 + \delta n(r, t) = \int_{\vec{p}}^{\vec{p}'} (\delta f + \delta f') d\vec{p}'$$

Then, (BHS): $\frac{\partial f_0}{\partial t} + \frac{p}{m} \frac{\partial f_0}{\partial r} = 0, \quad \boxed{\frac{\partial}{\partial t} \delta f + \frac{p}{m} \frac{\partial}{\partial r} \delta f = -e \vec{E} \cdot \frac{\partial f_0}{\partial p}}$

(final)

이제, Wave-like solution idea를 이용하자. P 는 vel. 변화하는 물리량이니, Linearized Vlasov equation.

우학적으로 다음과 같이 편리한 변환 가능하다.

$$\begin{cases} \delta f(\vec{r}, \vec{p}, t) = \delta f(\vec{r}, \vec{k}, \omega) e^{i(\vec{k} \cdot \vec{r} - \omega t)} \\ \delta n(\vec{r}, t) = \delta n(\vec{k}, \omega) e^{i(\vec{k} \cdot \vec{r} - \omega t)} \end{cases}$$

이를 위식에 대입하여 정리하면,

$$\Rightarrow -i\omega \delta f(\vec{r}, \vec{k}, \omega) + i\vec{k} \cdot \vec{v} \delta f(\vec{r}, \vec{k}, \omega) = -e \vec{E}(\vec{k}, \omega) \frac{\partial f_0}{\partial p} \quad \vec{e} \vec{E} = -\vec{j}^{-1}$$

where $e \vec{E} = -\frac{\partial}{\partial r} \int dr' u(r-r') \delta n(r', t) = -i\vec{k} \cdot u(\vec{k}) \delta n(\vec{k}, \omega)$.

$$\Rightarrow (\text{BHS}) = +i u(\vec{k}) \delta n(\vec{k}, \omega) \cdot \vec{k} \cdot \frac{\partial f_0}{\partial p} = i(\vec{k} \cdot \vec{v} - \omega) \delta f(\vec{r}, \vec{k}, \omega)$$

$$\therefore \delta f = -\frac{u(\vec{k}) \delta n(\vec{k}, \omega)}{\omega - \vec{k} \cdot \vec{v}} \cdot \vec{k} \cdot \frac{\partial f_0}{\partial p}$$

이제, δf 를 구했으니, 다음식을 이용하자.

$$\int d\vec{p} \delta f(u, k, \omega) = \delta n(\vec{k}, \omega).$$

$$\Rightarrow \delta n = - \int \frac{u(\vec{k}) \delta n(\vec{k}, \omega)}{\omega - \vec{k} \cdot \vec{v}} \cdot \vec{k} \cdot \frac{\partial f_0}{\partial p} \cdot d\vec{p} \Rightarrow \text{Dispersion relation을 구할 수 있음.}$$

이때, $u(\vec{k})$ 는 electric potential이니, $\nabla^2 u(\vec{r}) = -4\pi e^2 \delta(\vec{r})$ 즉 $-k^2 u(\vec{k}) = -4\pi e^2$

$$\Rightarrow -\frac{4\pi e^2}{k^2} \int d\vec{p} \frac{1}{\omega - \vec{k} \cdot \vec{v}} \left(\vec{k} \cdot \frac{\partial f_0}{\partial p} \right) = 1 \quad \therefore u(k) = \frac{4\pi e^2}{k^2}$$

이제, f_0 가 Gaussian 끝인 항을 이용하면, $\frac{\partial f_0}{\partial p} = -\frac{2\beta \vec{p}}{2m} f_0 = -\beta \vec{v} f_0$.

$$\therefore 1 = \frac{4\pi e^2}{k^2} \int d\vec{p} \cdot \frac{\vec{k} \cdot \vec{v}}{\omega - \vec{k} \cdot \vec{v}} \beta f_0 \quad \left(\frac{\partial f_0}{\partial p} \cdot \frac{\partial E}{\partial p}, f_0 \sim a \cdot e^{-\beta E} \right)$$

$$= \frac{\vec{k} \cdot \vec{v}}{\omega} \cdot \left(\frac{1}{1 - \frac{\vec{k} \cdot \vec{v}}{\omega}} \right) = \frac{\vec{k} \cdot \vec{v}}{\omega} \left(1 + \frac{\vec{k} \cdot \vec{v}}{\omega} + \left(\frac{\vec{k} \cdot \vec{v}}{\omega} \right)^2 + \dots \right)$$

$$\Rightarrow 1 \approx \frac{4\pi e^2}{k^2} \int d\vec{p} \cdot \left[\frac{\vec{k} \cdot \vec{v}}{\omega} + \left(\frac{\vec{k} \cdot \vec{v}}{\omega} \right)^2 + \left(\frac{\vec{k} \cdot \vec{v}}{\omega} \right)^3 + \dots \right] \beta f_0. \quad (\text{Small region } \vec{v} \text{에서 } \vec{k} \text{항은 } 0)$$

0, odd function

0

non zero

$$= \frac{4\pi e^2}{k^2} \cdot 2\pi \int d(\cos\theta) \int_0^\infty dp \cdot p^2 \cdot \frac{k^2 p^2 \cos^2\theta}{m^2 \omega^2} p \cdot n \left[\frac{p}{2\pi m} \right]^{\frac{3}{2}} e^{-\frac{p^2}{2m}}$$

$$= \frac{4\pi e^2 n}{m^2 \omega^2} = \frac{\omega_p^2}{\omega^2}$$

$$\boxed{\omega_p^2 = \frac{4\pi e^2 n}{m^2}}$$

plasma frequency.

So, $\omega_p = \omega$ or ω , plasma frequency > e, n, m 의 합계를 상과이며,

System's wave frequency > 잘 정의된 ω_p 로 진동한다.] Oscillation
 $\omega > 0$. no imaginary, no damping

$$\Rightarrow \text{근자향은 고려하면, 위 식은 죽이 } | = \frac{\omega_p^2}{\omega^2} \left[1 + \frac{k^2}{\omega^2} \langle v^2 \rangle \right] \quad \leftarrow E = \frac{m \langle v^2 \rangle}{2} = \frac{3k_B T}{2}$$

$$\Rightarrow \omega^2 \cong \omega_p^2 + k^2 \langle v^2 \rangle$$



$$\delta f = - \frac{\vec{R} \cdot \vec{u}(\vec{R}) \delta n(\vec{R}, \omega)}{\omega - \vec{R} \cdot \vec{v}} \cdot \left(\frac{\partial f_0}{\partial p} \right)$$

(*) Response function.

$$\delta n(\vec{R}, \omega) = \int \delta f(\vec{R}, \vec{P}, \omega) d\vec{P}$$

$$-i \cdot e \cdot \vec{E} \int d\vec{P} \cdot \frac{1}{\omega - \vec{R} \cdot \vec{v}} \left(\frac{\partial f_0}{\partial p} \right)$$

$$\text{and, we know } \begin{cases} \nabla \cdot \vec{P} = -4\pi \rho_b = -4\pi e \delta n(\vec{r}, t) \\ i \vec{B} \cdot \vec{P} = -4\pi e \delta n(\vec{R}, \omega) \end{cases} \quad \delta n(\vec{R}, \omega) = \delta n(\vec{R}, \omega)$$

$$\therefore \vec{P}(\vec{R}, \omega) = \frac{4\pi e^2}{k^2} \int d\vec{P} \cdot \frac{1}{\omega - \vec{R} \cdot \vec{v}} \left(\frac{\partial f_0}{\partial p} \cdot \vec{v} \right) \vec{E}$$

$$= \chi_e$$

위 식과 같은 형태, 해의 형태 동일.

$$\text{we know } \vec{P}(r, t) = \int dr' dt' \chi(r - r', t - t') \vec{E}(r', t')$$

Green function, susceptibility

$$\vec{P}(\vec{R}, \omega) = \chi(\vec{R}, \omega) \vec{E}(\vec{R}, \omega) \quad \text{Let } \vec{P}, \vec{E} \rightarrow \checkmark \quad \text{방향(영향)}$$

$$\Rightarrow \vec{P}(k, \omega) = \chi_e(k, \omega) \vec{E}(k, \omega)$$

$$(CF) \check{\vec{E}} = \vec{I} + \vec{\chi}$$

$$\therefore K_e = -\frac{\omega_p^2}{\omega^2} \left[1 + \frac{k^2}{\omega^2} \langle v^2 \rangle + \dots \right]$$

$$\Rightarrow \varepsilon_2 = 1 + \chi_2 = 1 - V(k) \cdot \int \frac{dP}{\vec{k} \cdot \vec{v} - \omega} \cdot \left(\frac{\partial f_0}{\partial P} \right) = 1 - \frac{4\pi e^2}{k^2} \int \frac{dP_x k \frac{\partial f_x}{\partial P_x}}{kv_x - \omega - ik} = \varepsilon'_e + i \cdot \varepsilon''_e.$$

↑
Particularization (S) → response.
where $\lim_{\eta \rightarrow 0} \frac{f(z)}{z - ik} dz = P \int_{-\infty}^{\infty} \frac{f(z)}{z} dz + i\pi f(0)$
Cauchy principle value
 $\omega \rightarrow \omega + ik$
 $\vec{k} \parallel \hat{x}$

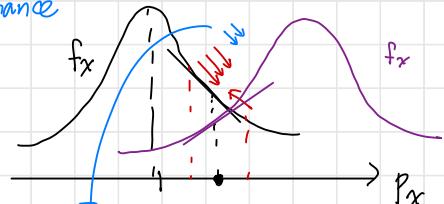
... Sokhotski-Plemelj theorem

$$\Rightarrow \varepsilon''_e = - \frac{4\pi e^2}{k^2} \int \frac{dP_x \cdot k \cdot \frac{\partial f_x}{\partial P_x}}{m u_x} \cdot S(kv_x - \omega) = - \frac{4\pi e^2 m}{k^2} k \cdot \left(\frac{\partial f_x}{\partial P_x} \right)_{u_x = \frac{\omega}{k}}$$

↓
mdu_x resonance

System의 에너지 Loss/Absorption에 대한 지표

(∵ wave & particle 간에 에너지 전달)



$\varepsilon''_e = [+ : \text{Damping (wave lost energy)}]$

$- : \text{Growing (wave gain energy)}$

$$\varepsilon''_e = (-) \times \left(\frac{\partial f_x}{\partial P_x} \right)$$

$\Delta u_x > 0$.
Particle gain energy \leftrightarrow wave losing energy

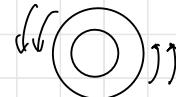
입자간 충돌이 없을 때 (초기 조건) 에너지 잃음.

↓ ← - - + + -

... Landau damping.

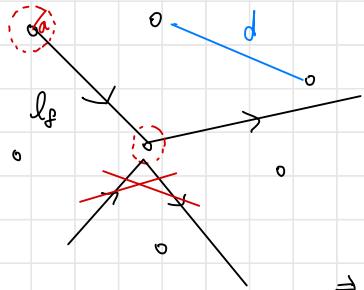
System gaining energy.

(∵ f_x 가 우연방, 전체 입자에 걸쳐, 증가)



4. Boltzmann Equation : Time irreversibility.

- Consider a dilute classical gas undergoing binary collisions.



d = Average distance, a = Interaction range.
 l_f = Mean free path.

- (*) \Rightarrow i) $l_f > d$, collision event rare
 ii) No three particle collision event.

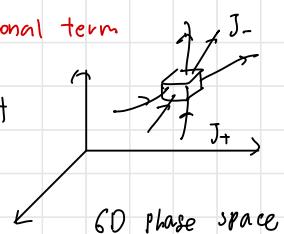
⇒ Using Vlasov equation, one notices

$$\frac{Df_1}{Dt} = J [f_2]$$

$$\frac{Df_2}{Dt} = J [f_1]$$

$$\frac{Df_1}{Dt} = \left(\frac{\partial}{\partial t} + \vec{P} \cdot \frac{\partial}{\partial \vec{r}} + \vec{F} \cdot \frac{\partial}{\partial \vec{P}} \right) f_1 = J [f_2] = J_+ - J_-$$

Influx ↑ Out flux ↑
 Collisional term

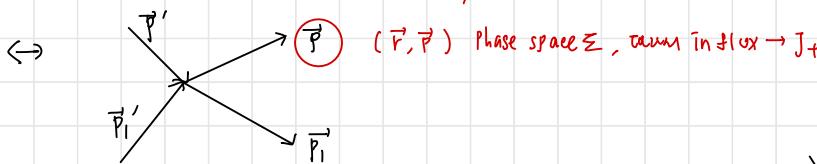


⇒ $J_{\pm}(\vec{r}, \vec{P}, t) = (\text{outgoing flux}) \text{ influx of } f \text{ into the volume element } d\vec{r} d\vec{P} \text{ around } (\vec{r}, \vec{P}) \text{ during } dt.$

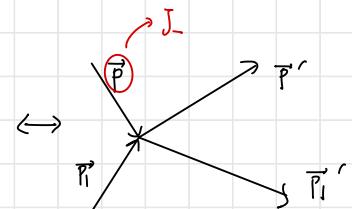
- One notices that;

$$J_+ = \int d\vec{P}_1 d\vec{P}' d\vec{P}_1' W(\vec{P}, \vec{P}_1 | \vec{P}', \vec{P}_1') f_2(\vec{r}, \vec{P}, \vec{r}, \vec{P}_1', t)$$

transmission probability

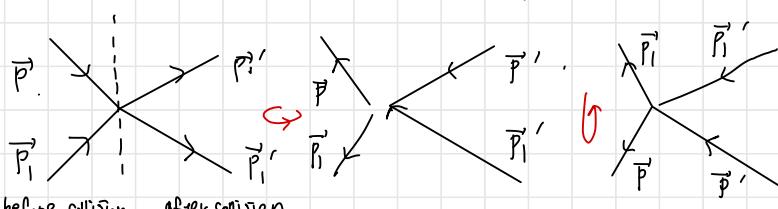


$$J_- = \int d\vec{P}_1 d\vec{P}' d\vec{P}_1' W(\vec{P}', \vec{P}_1' | \vec{P}, \vec{P}_1) f_2(\vec{r}, \vec{P}, \vec{r}, \vec{P}_1, t)$$



- (*) Symmetric Property of Probability.

$$W(\vec{P}', \vec{P}_1' | \vec{P}, \vec{P}_1) = W(\vec{P}, \vec{P}_1 | \vec{P}', \vec{P}_1')$$



And, Boltzmann assumed

Stosszahlansatz

= Collision number hypothesis

$$\Rightarrow f(v_1, v_2) = f(v_1) f(v_2)$$

\Rightarrow Uncorrelated before the collision.

$$f_2(\vec{r}, \vec{P}, \vec{r}, \vec{P}_1, t) = f(\vec{r}, \vec{P}, t) \cdot f(\vec{r}, \vec{P}_1, t)$$

Therefore, we can make above equation as; \rightarrow Not Time-Reversal Invariant.

$$\frac{Df}{Dt} = \frac{\partial f}{\partial t} + \left[\frac{\vec{P}}{m} \cdot \frac{\partial}{\partial \vec{r}} + \vec{F} \cdot \frac{\partial}{\partial \vec{P}} \right] f = J_+ - J_- = \int d\vec{P}' d\vec{P}_1' d\vec{P}' W(\vec{P}', \vec{P}_1' | \vec{P}, \vec{P}_1) [f'_f - f f_1]$$

$$t \rightarrow -t : \vec{P} \rightarrow -\vec{P}$$

$$(f' = f(\vec{r}, \vec{P}, t), f'_1 = f(\vec{r}, \vec{P}_1, t))$$

(*) H-Theorem

$$\text{Let's define } H = \int d\vec{r} d\vec{P} f(\vec{r}, \vec{P}, t) \cdot \ln f(\vec{r}, \vec{P}, t)$$

$$S(\vec{r}, t) = -k_B \int d\vec{P} \cdot f \ln f. \rightarrow \text{Localized entropy density}$$

$$\begin{aligned} \Rightarrow \frac{\partial S}{\partial t} &= -k_B \int d\vec{P} \cdot \frac{\partial}{\partial t} [f \ln f] = -k_B \int d\vec{P} \cdot [1 + \ln f] \left(\frac{\partial f}{\partial t} \right) \\ &= -k_B \int d\vec{P} \cdot (1 + \ln f) \left[-\frac{\vec{P}}{m} \cdot \frac{\partial f}{\partial \vec{r}} - \vec{F} \cdot \frac{\partial f}{\partial \vec{P}} + J[f_2] \right] \end{aligned}$$

① ② ③

BBGKY hierarchy

$$\textcircled{1} = +k_B \int d\vec{P} \cdot \frac{\vec{P}}{m} \cdot (1 + \ln f) \frac{\partial f}{\partial \vec{r}} = k_B \int d\vec{P} \cdot \frac{\vec{P}}{m} \cdot \frac{\partial}{\partial \vec{r}} (f \ln f) = \frac{\partial}{\partial \vec{r}} k_B \int d\vec{P} \cdot \frac{\vec{P}}{m} f \ln f$$

$$= -\vec{J}_S$$

entropy current

$$\textcircled{2} = k_B \int d\vec{P} \cdot (1 + \ln f) \vec{F} \frac{\partial f}{\partial \vec{P}} = k_B \vec{F} \int d\vec{P} \frac{\partial}{\partial \vec{P}} (f \ln f) \propto (f \ln f) \Big|_S = 0.$$

$$\textcircled{3} = -k_B \int d\vec{P} \cdot (1 + \ln f) J[f_2]$$

\Rightarrow 대입하고 이항하여 정리하면, $J = J_+ - J_-$ 이므로

$$\frac{\partial S}{\partial t} + \vec{J}_S \cdot \vec{J}_S = -k_B \int d\vec{P} \cdot d\vec{P}_1 d\vec{P}' d\vec{P}_1' W(\vec{P}' \vec{P}_1' | \vec{P} \vec{P}_1) (f'_f - f f_1) (1 + \ln f) \quad \dots (i)$$

By $P \leftrightarrow P_1$, Symmetry,

$$\left(\dots \right) = -k_B \int d\vec{P} d\vec{P}_1 d\vec{P}' d\vec{P}_1' W(\vec{P}' \vec{P}_1' | \vec{P} \vec{P}_1) (f'_f - f f_1) (1 + \ln f) \quad \dots (i)'$$

\rightarrow Half sum (i) and (i)', we get

$$\left(\frac{\partial S}{\partial t} + \vec{V}_F \cdot \vec{\partial s} \right) = - \frac{k_B}{2} \int d\vec{P} d\vec{P}_1 d\vec{P}' d\vec{P}'_1 W(f'f'_1 - ff_1) (2 + \ln ff_1) \quad \dots (ii)$$

→ Same way, (ii)에서 $(p, p_1) \leftrightarrow (p', p'_1)$ symmetry 이다.

$$\left(\dots \right) = - \frac{k_B}{2} \int d\vec{P} d\vec{P}_1 d\vec{P}' d\vec{P}'_1 W(ff_1 - f'f'_1) (2 + \ln f'f'_1) \quad \dots (ii)'$$

→ Again, half sum

$$\left(\frac{\partial S}{\partial t} + \vec{V}_F \cdot \vec{\partial s} \right) = + \frac{k_B}{4} \int d\vec{P} d\vec{P}_1 d\vec{P}' d\vec{P}'_1 W(f'f'_1 - ff_1) \ln \frac{f'f'_1}{ff_1} \geq 0.$$

$$= \frac{dS(\vec{r}, t)}{dt}$$

→ Total entropy of the system

$$S(t) = \int d\vec{r} S(\vec{r}, t) = -k_B \int d\vec{P} \int d\vec{P}' f \ln f = -k_B H(t).$$

$$\therefore \frac{dS}{dt} \geq 0 \Leftrightarrow \frac{dH}{dt} \leq 0 \text{ 이다.}$$

$$(x-y) \ln \left(\frac{x}{y} \right) \geq 0.$$

$$\begin{cases} x > y \\ y > x \\ x = y \end{cases}$$

(*) Equilibrium Distribution.

• At equilibrium, as required property, $ff_1 = f'f'_1$ ($dH = 0$)

• $\lim_{t \rightarrow \infty} f(\vec{r}, \vec{P}, t) = f_0(\vec{P})$ ($\because \vec{r}$ symmetry) ($\delta f_0(\vec{r}, \vec{P}, t) \rightarrow 0$)

$$\Rightarrow f_0(\vec{P}) f_0(\vec{P}'_1) = f_0(\vec{P}') f_0(\vec{P}'_1')$$

$$\Rightarrow \ln f_0(\vec{P}) + \ln f_0(\vec{P}'_1) = \ln f_0(\vec{P}') + \ln f_0(\vec{P}'_1')$$

= Conserved quantity처럼 보인다. (중립 전류에)

$$\rightarrow \chi(\vec{P}') + \chi(\vec{P}'_1') = \chi(\vec{P}) + \chi(\vec{P}'_1) \quad (\chi = \text{collision invariant})$$

$$\Rightarrow \ln f_0(\vec{P}) = a + \vec{b} \cdot \vec{P} + c \cdot \frac{\vec{P}^2}{2m} \quad (\text{conserved quantity})$$

$$\therefore \int d\vec{P} \cdot f(\vec{r}, \vec{P}, t) = \underline{n(\vec{r}, t)} \quad \text{local density}$$

5 equations. $\rightarrow a, \vec{b}, c$

$$\int d\vec{P} \cdot \vec{V} f(\vec{r}, \vec{P}, t) = n(\vec{r}, t) \cdot \vec{U}(\vec{r}, t)$$

Generalized Boltzmann distribution

Local Temperature \downarrow

$$\int d\vec{P} \cdot \frac{(\vec{P} - m\vec{U})^2}{2m} \cdot f = \frac{3}{2} k_B T(\vec{r}, t) n(\vec{r}, t)$$

... Spacial Variance of T, n exist.

$$f_0(\vec{r}, \vec{P}, t) = \frac{n(\vec{r}, t)}{\left[2\pi m k_B T(\vec{r}, t) \right]^{\frac{3}{2}}} \cdot \exp \left(- \frac{[\vec{P} - m\vec{U}(\vec{r}, t)]^2}{2m k_B T(\vec{r}, t)} \right)$$

($f = 1$ particle distribution function = prob of finding 1 particle in \vec{r}, \vec{p} at t)

5. Hydrodynamic equations

→ a dilute classical gas undergoing binary collisions

duration of collisions

$$\tau_c \ll \Delta t$$

$$f(\vec{r}, \vec{p}, t) \leftarrow \text{Boltzmann equation}$$

⇒ kinetic stage

$$\tau_r \ll \Delta t \quad \text{relaxation time}$$

$$\begin{aligned} n(\vec{r}, t) &: \text{Local density} \\ u(\vec{r}, t) &: \text{Local average velocity} \\ T(\vec{r}, t) &: \text{Local temperature} \end{aligned}$$

→ Hydrodynamic equation

(Hydrodynamic Stage)

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial t} + \frac{\vec{p}}{m} \cdot \frac{\partial f}{\partial \vec{r}} + \vec{F} \cdot \frac{\partial f}{\partial \vec{p}} = \left(\frac{\partial f}{\partial t} \right)_{\text{coll}}$$

(*) Conservation Laws

Let X be a collisional invariant quantity. $X = X(\vec{r}, \vec{p}, t)$

$$\int d\vec{p} \cdot X(\vec{r}, \vec{p}, t) \left(\frac{\partial f}{\partial t} \right)_{\text{coll}} = 0 \quad \text{을 보자. By Boltzmann equation, (LHS) become:}$$

$$\Rightarrow \int d\vec{p} \int d\vec{p}_1 d\vec{p}' d\vec{p}_1' W(\vec{p}', \vec{p}_1' | \vec{p}, \vec{p}_1) [f' f_1' - f f_1] X \quad X_1 = X(\vec{r}, \vec{p}_1, t) \text{ 일뿐, by symmetry,}$$

$$= \frac{1}{2} \int d\vec{p} \int d\vec{p}_1 d\vec{p}' d\vec{p}_1' W(\vec{p}, \vec{p}_1' | \vec{p}, \vec{p}_1) [f' f_1' - f f_1] (X_1 + X) \quad (\text{half sum})$$

⇒ By $(p, p_1) \leftrightarrow (p', p_1')$ symmetry and half sum,

$$= \frac{1}{4} \int d\vec{p} d\vec{p}_1 d\vec{p}' d\vec{p}_1' W(\vec{p}, \vec{p}_1' | \vec{p}, \vec{p}_1) [f' f_1' - f f_1] (X + X_1 - X' - X'_1)$$

$\rightarrow 0$ (\because Collisional invariant, $X = X_1 = X' = X'_1$)

⇒ By Boltzmann equation, Let's rewrite this: $\int d\vec{p} X(\vec{r}, \vec{p}, t) \left(\frac{\partial f}{\partial t} + \frac{\vec{p}}{m} \frac{\partial f}{\partial \vec{r}} + \vec{F} \frac{\partial f}{\partial \vec{p}} \right) = 0$.

⇒ By expanding this equation;

$$\left[\frac{\partial}{\partial t} \int d\vec{p} \cdot (X f) - \int d\vec{p} \cdot f \left(\frac{\partial X}{\partial t} \right) \right] + \left[\frac{\partial}{\partial \vec{p}} \int d\vec{p} \cdot (X \cdot \vec{v} \cdot f) - \int d\vec{p} \cdot \left(\frac{\partial X}{\partial \vec{p}} \right) \cdot \vec{v} \cdot f \right] + \left[\int d\vec{p} \cdot \frac{\partial}{\partial \vec{p}} (X \vec{F} \cdot f) \right]$$

(\because Surface integral이거나 0으로 카운트되는)

$$- \int d\vec{p} \left(\frac{\partial X}{\partial \vec{p}} \right) \vec{F} \cdot f = 0.$$

6/13(목) 시험원정

I.P.M ∼ 4.P.M.

중간 이론 ∼

하지만 전부 이해해놓기

$$\text{Now, Let's define kinetic average of } A \Rightarrow \langle A \rangle = \frac{\int dP \cdot (Af)}{\int dP \cdot f} = \frac{\int dP \cdot (Af)}{n(\vec{r}, t)}$$

⇒ Then, we can get the final equation:

$$\frac{\partial}{\partial t} n \langle x \rangle - n \cdot \langle \frac{\partial x}{\partial t} \rangle + \vec{\nabla} \cdot n \langle x \vec{v} \rangle - n \cdot \langle (\nabla x) \cdot \vec{v} \rangle - n \langle (\nabla_{\vec{P}} x) \cdot \vec{F} \rangle = 0$$

... Conservation Laws

⇒ Now, let's see what happen if we substitute X in invariant quantity.

i) Let $X = m$. and, we know by definition, $\langle \vec{v} \rangle = \vec{u}(\vec{r}, t)$

$$\Rightarrow \frac{\partial}{\partial t} (mn) - n \cdot 0 + \vec{\nabla} \cdot mn \vec{u} = 0 \quad (\nabla m = \nabla_p m = 0) \quad \text{Let } \rho(\vec{r}, t) = mn(\vec{r}, t)$$

$$\Rightarrow \frac{\partial \rho(\vec{r}, t)}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = 0.$$

ii) Let $X = mv_i$ ($i = x, y, z$) similarly,

$$\frac{\partial}{\partial t} mn \langle v_i \rangle + \vec{\nabla} \cdot mn \langle v_i \vec{v} \rangle - n \left\langle \left(\frac{\partial}{\partial P_i} \cdot P_i \cdot \hat{i} \right) \cdot \vec{F} \right\rangle = 0$$

$$\Rightarrow \frac{\partial}{\partial t} \cdot mn v_i (\vec{r}, t) + \vec{\nabla} \cdot (mn \langle v_i v_j \rangle) - \frac{\rho}{m} F_i = 0 \quad (j = 1, 2, 3)$$

$$\Rightarrow \langle v_i v_j \rangle = \langle (v_i - u_i) (v_j - u_j) \rangle + \left(\underbrace{\langle u_i \rangle u_j}_{= u_i} + \underbrace{u_i \langle u_j \rangle}_{u_j} - u_i u_j \right)$$

$$\vec{\nabla} \cdot (\rho \langle v_i v_j \rangle) = \vec{\nabla} \cdot \left\{ \rho \langle (v_i - u_i) (v_j - u_j) \rangle + u_i u_j \rho \right\} = u_i u_j$$

] 이를 대입하면 정리 가능.

$\equiv P_{ij}$ (pressure tensor)

now, for $\forall i = x, y, z$, ① 식을 Vector form으로 정리하면

$$\frac{\partial}{\partial t} (\rho \vec{u}) + \vec{\nabla} \cdot \vec{P}_{ij} + \vec{\nabla} \cdot \rho (\vec{u} \vec{u}) = \frac{\rho}{m} \vec{F}$$

$$\begin{aligned} \cancel{\frac{\partial}{\partial t} (\rho \vec{u})} + \cancel{\rho \cdot \frac{\partial \vec{u}}{\partial t}} &= \vec{u} (\nabla \rho) \cdot \vec{u} + \rho (\vec{u} \cdot \nabla) \vec{u} + \rho (\vec{u} \cdot \nabla) \vec{u} \\ &\quad \boxed{\vec{u} \cdot \left(\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) \right) = 0} \end{aligned}$$

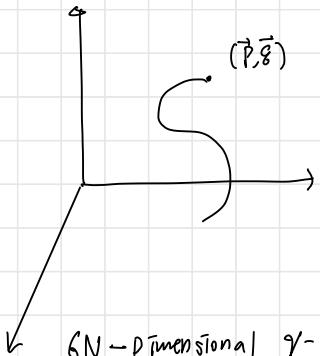
$$\therefore \frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} = \frac{\vec{F}}{m} - \frac{\vec{\nabla} \cdot \vec{P}_{ij}}{\rho}$$

... Euler equation

⇒ 아직도 특별한 결과 X . 결국 F 를 알아야 한다... (perturbative method, hard to deal!)

(*) Summary

N Particle System



$$\Rightarrow \dot{q}_i = \frac{\partial H}{\partial p_i}, \quad \dot{p}_i = -\frac{\partial H}{\partial q_i}$$

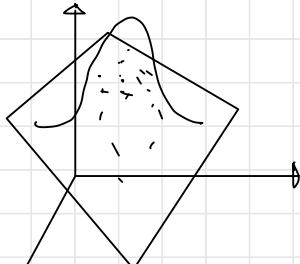


Relation: "Kinetic Theory"
in (9th).

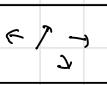
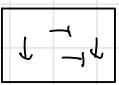
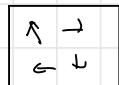
A Few Thermodynamic Variables (E, T, N, V, P, ...)
Via S, W, Q.

IV. Foundation of 'Equilibrium' Statistic Mechanics

1. Statistical Ensemble .



• System Macrostate M (E, V, N)



$3 - 6N$
mapping.

Different microstate configurations, same M-state.

• Statistical (Gibbs) Ensemble

⇒ A collection of a large number of copies of identical systems
(Each constructed to have the given M-State)

• $\rho(\vec{p}, \vec{q}, t)$: phase space density

⇒ $d\vec{p} d\vec{q} \rho = \text{number of representative points in the volume elements}$
(μ -states)

Remind) $\int \frac{dp}{dt} + \nabla \cdot (\rho \vec{v}) = 0$. (∇ = phase space operator)

$$\frac{\partial \rho}{\partial t} + \sum_i \left(\frac{\partial \rho}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial \rho}{\partial p_i} \frac{\partial H}{\partial q_i} \right) = \underbrace{\frac{\partial \rho}{\partial t} + \{ \rho, H \}}_{= \frac{d\rho}{dt}} = 0. \quad \dots \text{Liouville thm.}$$

($\because \dot{p}_i = -\frac{\partial H}{\partial q_i}, \dot{q}_i = +\frac{\partial H}{\partial p_i}$)

2. Statistical Postulate

• Consider a physical quantity $\Theta(\vec{p}, \vec{q})$ → physical meaningful: average.

$$\langle \Theta \rangle = \int d\vec{p} d\vec{q} \rho(\vec{p}, \vec{q}, t) \Theta(\vec{p}, \vec{q}), \quad \frac{d\langle \Theta \rangle}{dt} = \int d\vec{p} d\vec{q} \left(\frac{\partial \rho}{\partial t} \right) \Theta(\vec{p}, \vec{q})$$

$$\frac{d\langle \Theta \rangle}{dt} = - \int d\vec{p} d\vec{q} \cdot \Theta \cdot \sum_{i=1}^N \left(\frac{\partial \rho}{\partial q_i} \frac{\partial H}{\partial p_i} - \frac{\partial \rho}{\partial p_i} \frac{\partial H}{\partial q_i} \right)$$

부분적분
omit \int .

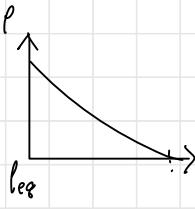
$$- \Theta \cdot \rho \left. \frac{\partial H}{\partial p_i} \right|_S + \int d\vec{p} d\vec{q} \cdot \rho \cdot \frac{\partial \Theta}{\partial q_i} \frac{\partial H}{\partial p_i} + \int d\vec{p} d\vec{q} \cdot \rho \cdot \Theta \cdot \frac{\partial^2 H}{\partial q_i \partial p_i}$$

$$+ \Theta \cdot \rho \left. \frac{\partial H}{\partial q_i} \right|_S - \int d\vec{p} d\vec{q} \cdot \rho \cdot \frac{\partial \Theta}{\partial p_i} \frac{\partial H}{\partial q_i} - \int d\vec{p} d\vec{q} \cdot \rho \cdot \Theta \cdot \frac{\partial^2 H}{\partial p_i \partial q_i}$$

$\therefore \frac{d\langle \Theta \rangle}{dt} = \langle \{ \Theta, H \} \rangle$

... time dependence of $\langle \Theta \rangle = \int d\vec{p} d\vec{q} \cdot \rho \cdot \{ \Theta, H \}$

• Now, for equilibrium condition $\Leftrightarrow \frac{d\langle \theta \rangle}{dt} = 0$.



(*) Equilibrium (Stationary) Ensemble.

$$\frac{d\langle \theta \rangle}{dt} = 0 \rightarrow \left(\frac{\partial P}{\partial t} \right) = 0 \quad (\text{not } \frac{\partial P}{\partial t}, \text{ this is always } 0 \text{ for incompressible } P)$$

$$\xrightarrow{\text{Liouville}} [P, H] = 0$$

→ These are not rigorous, but physically acceptable.

→ One possible way of satisfying this: To assume $P = P_{eq} (H(\vec{P}, \vec{g}))$

The fundamental assumption of statistical mechanics

(Postulate of a equal priori probability)

In thermodynamic equilibrium, an isolated system is equally likely to be any state

satisfying the given macroscopic conditions \rightarrow 모든 영향 X, E (or H) invariant

$\Rightarrow P_{eq}$ is fixed

$\Rightarrow P_{eq}$ is constant on

constant energy (M state)

Surface

3. Ergodic Hypothesis (Not yet proved rigorously still now)

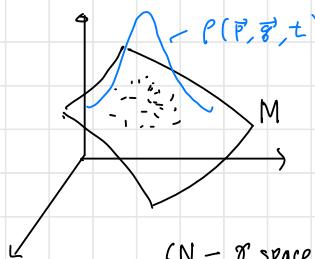
• In statistic, average value (for physical quantity) is meaningful, important.

\Rightarrow 이 같은, 정의대로라면 수많은 sample 준비, 특징해야 범위를 넓힐 수 있다. (Ensemble average)

\Rightarrow but, 실제 실험에서는 Temporal average를 특징. 이를 사용. 왜일까?

• Two different averages

① Ensemble average



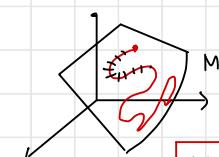
$$\langle \Theta \rangle = \int dP d\vec{g} \Theta \cdot P(P, \vec{g}, t)$$

$\downarrow t \rightarrow \infty$

$$\frac{d\langle \Theta \rangle}{dt} = 0, P_{eq} = P_{eq}(H(\vec{P}, \vec{g})) \rightarrow \text{constant}$$

$$\Rightarrow \langle \Theta \rangle_{eq} = \int d\vec{P} d\vec{g} \Theta \cdot \Theta(\text{const.})$$

② Temporal average



$$\bar{\Theta} = \frac{1}{T} \int_0^T dt \cdot \Theta(P, \vec{g}, t)$$

$\downarrow T \rightarrow \infty$

$$\bar{\Theta} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T dt \cdot \Theta(P, \vec{g}, t)$$

??

• Ergodic hypothesis

after a sufficiently long time, Γ -trajectory passes through every point in the allowed Γ -space with equal number of time.

c) ~~(~~ \rightarrow quasi-ergodic

Spanning time \ll relaxation time scale. Is it ok?

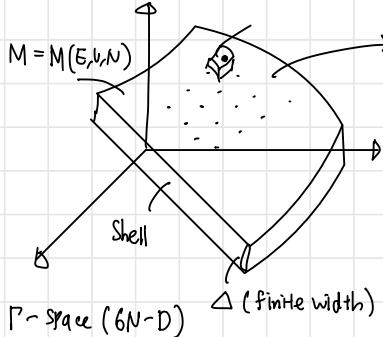


4. Microcanonical Ensemble.

$$M = (E, V, N)$$

- Consider an isolated system (No exchange of Q, W, ...) Based on fundamental assumption

→ Energy Conservation: $P = P_{\text{eq}} = \text{const.} \rightarrow$ equally 被選한 representative points on M . (equally likely)



$$P(\vec{p}, \vec{q}) = \frac{1}{V(E)} \delta(H(\vec{p}, \vec{q}) - E)$$

$$P = \begin{cases} \frac{1}{V(E)} \cdot (E \leq H \leq E + \Delta) \\ 0 \quad \text{otherwise.} \end{cases}$$

($V(E)$ = Surface area of hypersurface)

→ hard to evaluate V ?

⇒ Allow uncertainty Δ in energy.

P-space ($6N - D$)

• Let's define $T \equiv$ Volume of the shell

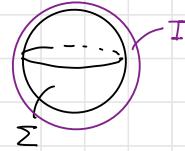
$\Sigma \equiv$ Volume of the enclosed volume

$$\text{then, } T = \sum (E + \Delta) - \sum (E) \cong \frac{\partial \Sigma}{\partial E} \cdot \Delta$$

$$= \bar{V}(E).$$

$$= \int d\vec{p} d\vec{q} \sum_{E \leq H \leq E + \Delta}$$

$$= \int d\vec{p} d\vec{q} \sum_{E \leq H}$$



(Quantum mechanical) $\Delta P \Delta \theta \gtrsim \hbar$. $(\Delta p \Delta q)^{3N} \gtrsim \hbar^{3N}$

$$\Rightarrow P(\vec{p}) = \begin{cases} \frac{1}{\Omega(E)} & \text{if } E \leq H \leq E + \Delta \\ 0 & \text{otherwise} \end{cases}$$

$$(P(\vec{p}, \vec{q}) = P(\vec{p}))$$

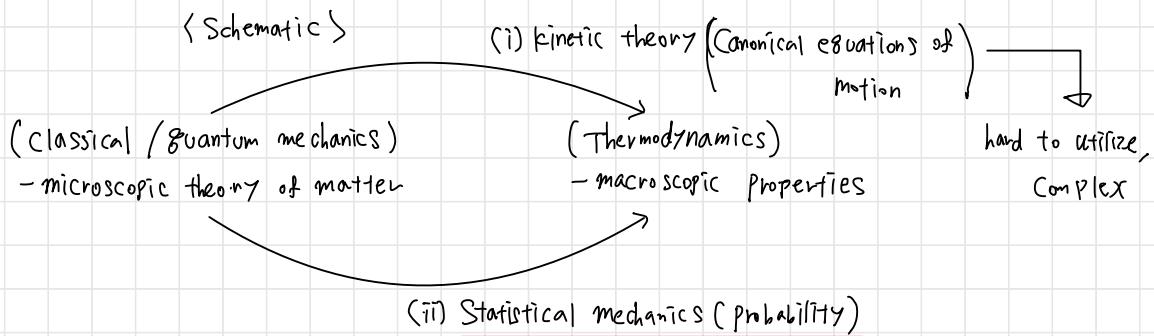
$$\therefore \Omega(E, V, N) \equiv \frac{\Gamma(E, V, N)}{T_0} \rightarrow \text{unit volume}$$

⇒ number of different microscopic states
(that we can distinguish)

$$\left(\int d\vec{p} d\vec{q} P(\vec{p}, \vec{q}) = 1 \right)$$

5. Entropy

- Statistical Mechanics : A probabilistic Approach to equilibrium



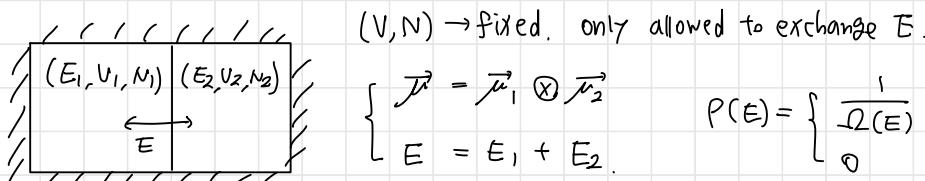
(*) Entropy

$$\begin{aligned}
 S(E, V, N) &= -k_B \cdot \langle \ln P(\vec{\nu}) \rangle = -k_B \cdot \sum_{\vec{\nu}} P(\vec{\nu}) \cdot \ln P(\vec{\nu}) \quad \left(P(\vec{\nu}) = \frac{1}{\Omega(E)} \right) \\
 &= +k_B \cdot \sum \frac{1}{\Omega} \cdot \ln \Omega \\
 &= k_B \cdot \ln \Omega(E, V, N)
 \end{aligned}$$

$\therefore S(E, V, N) = k_B \cdot \ln \Omega(E, V, N)$

(*) Zeroth Law (Power of Entropy)

- When two systems are in thermal equilibrium, the temperatures of the two systems are **the same**.



$$\begin{cases} \vec{\nu} = \vec{\nu}_1 \otimes \vec{\nu}_2 \\ E = E_1 + E_2 \end{cases} \quad P(E) = \begin{cases} \frac{1}{\Omega(E)} & \mathcal{H}_1 + \mathcal{H}_2 = E \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{aligned}
 \Rightarrow \Omega(E) &= \int dE_1 dE_2 \cdot \Omega_1(E_1) \Omega_2(E_2) S(E - E_1 - E_2) \\
 &= \int dE_1 \cdot \Omega_1(E_1) \Omega_2(E - E_1) = \int dE_1 \cdot \exp \left[\frac{1}{k_B} \cdot \left(S_1(E_1) + S_2(E - E_1) \right) \right]
 \end{aligned}$$

$$(\text{Approx}) \quad F = \sum_{i=1}^M F_i, F_i \sim O(e^{N\mu_i}), M \sim N^p, F_{\max} = \max(F_i)$$

$$F_{\max} \leq F \leq M \cdot F_{\max}$$

$$\lim_{N \rightarrow \infty} \left(\frac{1}{N} \ln F_{\max} \leq \frac{1}{N} \ln F \leq \frac{1}{N} \ln F_{\max} + \frac{1}{N} \ln M \right) \rightarrow F \xrightarrow{o} F_{\max}$$

$$Q(E) \simeq e^{\frac{1}{k_B} (S_1(\varepsilon_1^*) + S_2(\varepsilon_2^*))} \quad S(E) = k_B \ln Q = S_1(\varepsilon_1^*) + S_2(\varepsilon_2^*)$$

$$\boxed{S(Q_1(\varepsilon_1)Q_2(\varepsilon_2)) = 0.} \quad Q_2 \cdot \frac{\partial Q_1}{\partial E_1} + Q_1 \cdot \frac{\partial Q_2}{\partial E_1} = 0. \quad \frac{1}{Q_1} \frac{\partial Q_1}{\partial E_1} + \frac{1}{Q_2} \frac{\partial Q_2}{\partial E_1} = 0.$$

$$\Rightarrow \frac{\partial}{\partial E_1} \ln Q_1 \Big|_{E_1^*} = \frac{\partial}{\partial E_2} \ln Q_2 \Big|_{E_2^*}$$

$$\therefore \frac{\partial S_1}{\partial E_1} \Big|_{E_1^*} = \frac{\partial S_2}{\partial E_2} \Big|_{E_2^*} \longrightarrow \frac{1}{T_1} = \frac{1}{T_2}.$$

\uparrow

$$\left(\frac{\partial S}{\partial E} \right) = \frac{1}{T}$$

$$\boxed{\frac{\partial S_1}{\partial E_1} \Big|_{E_1^*} + \frac{\partial S_2}{\partial E_1} \Big|_{E_1^*} = 0.}$$