# Minjong Kim

010-3441-4364 / alswhd1111@gmail.com

## Education

**Seoul National University** Mar. 2026 - present

- Integrated PhD program, Dept. of Electrical and Computer Engineering
- Advisor: Jinsoo Kim, PhD
- Total GPA: 0.00/4.30 In-Major GPA: 0.00/4.30
- Relevant Coursework:
  - ???

**Ulsan National Institute of Science and Technology (UNIST)** Mar. 2020 - Feb. 2026

- B.S. in Mechanical Engineering
- Total GPA: 4.20/4.30 In-Major GPA: 4.26/4.30
- Relevant Coursework:
  - BME307 Biomechanics
  - MEN461 Introduction to robotics
  - MEN573 Advanced Control I

## Research Interests

My research interests include lower-limb wearable robots, gait augmentation, and human–robot interaction. I am particularly focused on improving gait performance and generating optimal motion patterns to enhance human mobility, with long-term applications in sports and performance augmentation.

## Research Experience

**Wearable Robotics Laboratory** Dec. 2024 - present

*Undergraduate Research Intern* Seoul, South Korea

Advisor: Jinsoo Kim, PhD

- Built a gait analysis pipeline using motion capture data, enabling kinematic extraction and gait event detection.
- Implemented a real-time IMU-based gait metric and validated results against motion capture-derived reference measures.

**Ergonomics Laboratory** Jan. 2024 - Dec. 2024

*Undergraduate Research Intern* Ulsan, South Korea

Advisor: Gwanseob Shin, PhD

- Developed a predictive model for floor impact noise using gait acceleration features collected from human walking trials.
- Designed a robotic control algorithm for a shoulder arthroscope based on surgeon head-motion tracking.

## Awards and Honors

National Scholarship for Science and Technology Spring 2024 - present

Dean's List Spring 2023, Fall 2024

UNIST Global Scholarship for the Exchange Student Program 2020

## Activities

Student Council of Mechanical Engineering — Mar. 2023 - July 2025
Social Services Personnel (Alternative Military Service) — Mar. 2021 - Dec. 2022

## Skills

Programming Languages: Python, MATLAB
Software: ROS1, CATIA, Fusion360
Biomechanical Equipment: Motion Capture Systems (OptiTrack, Vicon), Instrumented Treadmill (Bertec), Force Plates (Zebris), IMUs
Fabrication: 3D Printing, Laser Cutting
Languages: Korean (native), English (intermediate)