

ECON 210C PROBLEM SET # 5

MINKI KIM

1. PROBLEMS FROM ROMER

1.1. Romer, Problem 6.13.

- (a)
- (b)
- (c)
- (d)
- (e)
- (f)

1.2. Romer, Problem 7.10.

2. QUADRATIC COST OF ADJUSTING PRICES AND EFFECT OF MONEY (ROTEMBERG 1982)

- (a)
- (b)
- (c)
- (d)
- (e)

3. NEW KEYNESIAN MODEL IN DYNARE

- (a)
- (b)
- (c)
- (d)

4. GOVERNMENT SPENDING MULTIPLIERS IN THE NEW KEYNESIAN MODEL
(CHRISTIANO, EICHENBAUM AND EVANS 2012)

(a) The economy is characterized by the following log-linearized equations:

$$\begin{aligned}\check{C}_t &= E_t \check{C}_{t+1} - \frac{1}{\psi} (i_t - E_t \pi_{t+1}) \\ \pi_t &= \beta E_t \pi_{t+1} + \kappa \left(\frac{\check{W}}{P} \right)_t, \quad \kappa = \frac{(1-\theta)(1-\beta\theta)}{\theta} \\ \left(\frac{\check{W}}{P} \right)_t &= \psi \check{C}_t + \frac{1}{\eta} L_t \\ \check{Y}_t &= \check{L}_t \\ \check{Y}_t &= s_g \check{G}_t + (1-s_g) \check{C}_t \\ i_t &= \phi_\pi \pi_t, \quad \phi_\pi > 1\end{aligned}$$

The first equation is a standard Euler equation. The second equation is a recursive formulation of inflation rate, telling us that current inflation is a present value of future marginal costs. The third equation is household's labor supply. The fourth equation denotes aggregate production function. The fifth equation is national account, where s_g is the share the government spending. Finally, the last equation implies that the central bank follows the Taylor rule.

(b) The reduced system is characterized as follows:

$$\begin{aligned}\check{C}_t &= E_t \check{C}_{t+1} - \frac{1}{\psi} (\phi_\pi \pi_t - E_t \pi_{t+1}) \\ \pi_t &= \beta E_t \pi_{t+1} + \kappa \left(\psi \check{C}_t + \frac{s_g}{\eta} \check{G}_t + \frac{(1-s_g)}{\eta} \check{C}_t \right)\end{aligned}$$

We have two endogenous variables (\check{C}_t, π_t) and one exogenous variable (\check{G}_t) .

(c) Assume that government spending has the following dynamics:

$$\check{G}_t = \rho \check{G}_{t-1} + \epsilon_t, \quad \epsilon_t \sim i.i.d. (0, \sigma^2)$$

Since both \check{C}_t and π_t are jump-variables, the only state variable is \check{G}_t . 1 is not a state variable because the model is log-linearized. Since \check{C}_{t-1} and π_{t-1} do not show up in the system, lagged endogenous variables are also not state variables.

(d) Since rational expectation was introduced to the literature, numerous researchers have commented on the multiplicity of solution paths in linear rational expectation models. Since models with infinite number of solutions which are consistent with rational expectation are evidently unusable, seeking for a solution procedure which can single out a unique, bubble-free solution was a natural flow of the literature.

McCallum(1983) suggests a solution procedure called the *minimum state variable (MSV) criterion*. Since the multiplicity (or sunspots) arises from redundant state variables which are unnecessary but not formally inconsistent with rational

expectations, he suggests to rule out those state variable from the beginning. In our model, the minimum set of state variables is $\{\check{G}_t\}$. The solution equations for \check{C}_t and π_t are expressed as functions of state variable \check{G}_t :

$$\begin{aligned}\check{C}_t &= c_g \check{G}_t \\ E_t \check{C}_{t+1} &= c_g \rho \check{G}_t \\ \pi_t &= \pi_g \check{G}_t \\ E_t \pi_{t+1} &= \pi_g \rho \check{G}_t\end{aligned}$$

Plugging in these guessed form of solution equations into the system:

$$\begin{aligned}c_g \check{G}_t &= c_g \rho \check{G}_t - \frac{1}{\psi} (\phi_\pi \pi_g \check{G}_t - \pi_g \rho \check{G}_t) \\ \pi_g \check{G}_t &= \beta \pi_g \rho \check{G}_t + \kappa \left(\psi c_g \check{G}_t + \frac{s_g}{\eta} \check{G}_t + \frac{(1-s_g)}{\eta} c_g \check{G}_t \right)\end{aligned}$$

With some algebraic effort, we get

$$\begin{aligned}\pi_g &= \frac{\frac{\kappa}{\eta}(1-\rho)s_g}{(1-\beta\rho)(1-\rho) + \frac{\kappa}{\psi} \left[\psi + \frac{1}{\eta}(1-s_g) \right] (\phi_\pi - \rho)} \\ c_g &= \frac{-\frac{\kappa}{\eta\psi} (\phi_\pi - \rho) s_g}{(1-\beta\rho)(1-\rho) + \frac{\kappa}{\psi} \left[\psi + \frac{1}{\eta}(1-s_g) \right] (\phi_\pi - \rho)}\end{aligned}$$

(e) Following the solution obtained in (d),

$$\begin{aligned}\frac{dY}{dG} &= 1 + \frac{dC}{dG} = 1 + \frac{1-s_g}{s_g} \frac{d\check{C}}{d\check{G}} \\ &= 1 + \frac{c_g(1-s_g)}{s_g} \\ &= 1 - \frac{\frac{\kappa}{\eta\psi} (\phi_\pi - \rho) (1-s_g)}{(1-\beta\rho)(1-\rho) + \kappa \left[1 + \frac{1}{\eta\psi} (1-s_g) \right] (\phi_\pi - \rho)} \\ &= 1 - \frac{\frac{\kappa}{\eta\psi} (\phi_\pi - \rho) (1-s_g)}{(1-\beta\rho)(1-\rho) + \kappa(\phi_\pi - \rho) + \frac{\kappa}{\eta\psi} (1-s_g) (\phi_\pi - \rho)} \\ &\quad \text{Let } \frac{\kappa}{\eta\psi} (\phi_\pi - \rho) (1-s_g) = A \\ &= 1 - \frac{A}{(1-\beta\rho)(1-\rho) + \kappa(\phi_\pi - \rho) + A}\end{aligned}$$

(f) Since $(1-\beta\rho)(1-\rho) + \kappa(\phi_\pi - \rho) > 1$, $dY/dG < 1$. The government spending multiplier is smaller than one because the Taylor rule effectively stabilizes the inflation, hence cools down the economy.

(g) When $\phi = 0$, the government spending multiplier is:

$$\frac{dY}{dG} = 1 + \frac{\frac{\kappa}{\eta\phi}\rho(1-s_g)}{(1-\beta\rho)(1-\rho) - \frac{\kappa}{\psi}\left[\psi + \frac{1}{\eta}(1-s_g)\right]} > 1$$

So the government spending multiplier is larger than 1 even for a very low persistence shock. This is because the monetary policy is not raising nominal interest rate enough to make the real interest rate $r_t = i_t - E_t\pi_{t+1}$ also rise. Since the real interest rate is too low, even a small demand shock can make a ripple effect.

(h) Assuming $\phi_\pi = 0$, or generally any value of ϕ_π which violates the Taylor principle ($\phi_\pi > 1$) is problematic because the model becomes explosive.

(i)

(j)

(k)

(l)