

## Program Content

<b>Semester</b>	V	
<b>Course Code:</b>	IT5506	
<b>Course Name:</b>	Mathematics for Computing II	
<b>Credit Value:</b>	3 (3L)	
<b>Core/Optional</b>	Optional	
<b>Hourly Breakdown</b>	Theory	Independent Learning
	45 Hrs	105 Hrs
<b>Course Aim:</b> <ul style="list-style-type: none"> <li>To cover mathematical concepts required to understand and successfully complete the other courses in the degree program, and strengthen the mathematical foundation required in solving problems.</li> </ul>		
<b>Intended Learning Outcomes:</b> After following this course, students should be able to <ul style="list-style-type: none"> <li>apply mathematical concepts to solve problems in the areas of matrices, vector spaces, linear and integer programming.</li> <li>solve statistical problems involving discrete &amp; continuous probability distributions.</li> </ul>		
<b>Course Content: (Main Topics, Sub topics)</b>		
<b>Topic</b>		<b>Theory (Hrs.)</b>
1.	Theory of Matrices, Vector spaces and Linear Transformations	22
2.	Linear Programming and Integer Programming	12
3.	Basic Statistics	11
<b>Total</b>		<b>45</b>

## **1. Theory of Matrices, Vector spaces and Linear Transformations (22 hours)**

- 1.1 Different ways of looking at system of  $n$  linear equations in  $n$  unknowns (2 hours) [Ref 5: Pg. (1-5)] [Ref 6: Pg. (1-4)]
  - 1.1.1 Geometric way (row picture)
  - 1.1.2 linear combination of column vectors (Column picture)
  - 1.1.3 Representing in matrix form
- 1.2 Matrices (2 hours) [Ref 3: Pg. (79-110, 115-123)] [Ref 5: Pg. (6-27)] [Ref 6: Pg. (91-132)]
  - 1.2.1 Defining various types of matrices
  - 1.2.2 Addition and scalar multiplication of matrices
  - 1.2.3 Different ways of defining (or understanding) matrix multiplication
  - 1.2.4 Special type of matrices and their properties.
  - 1.2.5 Inverse of a square matrix (if it exists) and related results.
- 1.3 Solving systems of linear equations using elementary row operations (Gaussian Elimination) and backward substitution in matrix form considering different cases (2 hours) [Ref 3: Pg. (1-17, 41-72)] [Ref 5: Pg. (3-27)] [Ref 6: Pg. (1-46)]
  - 1.3.1 existence of unique solution
  - 1.3.2 existence of infinitely many solution
  - 1.3.3 no solution
- 1.4 Elementary row operations and their corresponding matrices (2 hours) [Ref 3: Pg. (1-17, 41-72)] [Ref 5: Pg. (3-27)] [Ref 6: Pg. (1-46)]
  - 1.4.1 Finding row-echelon form of a matrix (Gaussian Method)
  - 1.4.2 Finding row reduced-echelon form of a matrix (Gauss - Jordan Method)
  - 1.4.3 Defining row rank and column rank of a matrix
  - 1.4.4 Computing the inverse of a square matrix (if it exists) using Gauss - Jordan Method.
- 1.5 The Determinant of a square matrix (2 hours) [Ref 3: Pg. (459-482)] [Ref 6: Pg. (163-184)]
  - 1.5.1 Defining the determinant of a square matrix through its basic properties (through elementary operation).
  - 1.5.2 Calculating the determinant of any square matrix using elementary operations
  - 1.5.3 Properties of determinant.
  - 1.5.4 The big formula for calculating the determinant and inverse of a square matrix (if it exists).

- 1.6 Vector spaces (6 hours) [Ref 3: Pg. (159-201)] [Ref 5: Pg. (28-66)] [Ref 6: Pg. (189-242)]
  - 1.6.1 Axiomatic definition of a vector space and a subspace with suitable examples.
  - 1.6.2 Identifying all possible subspaces of  $\mathbb{R}^2$  and  $\mathbb{R}^3$ .
  - 1.6.3 linear combination and linear span
  - 1.6.4 Finite dimensional vector space, fundamental subspaces associated with a matrix
  - 1.6.5 Linear independence and dependence, linear independence and the rank of a matrix.
  - 1.6.6 Basis of a finite dimensional vector space and constructing basis.
- 1.7 Linear transformations (4 hours) [Ref 3: Pg. (238-245)] [Ref 5: Pg. (49-54, 67-73, 86-89)] [Ref 6: Pg. (62-77, 203-205)]
  - 1.7.1 Examples of linear transformation in finite dimensional spaces.
  - 1.7.2 The matrix representation of a linear transformation
  - 1.7.3 The rank-nullity theorem and its applications.
  - 1.7.4 Ordered bases, matrix of a linear transformation and similarity of matrices.
- 1.8 Orthogonality (2 hours) [Ref 3: Pg. (269-299, 307-310, 429-439)] [Ref 5: Pg. (270-286)] [Ref 6: Pg. (329-382)]
  - 1.8.1 Dot/Inner product in a vector space
  - 1.8.2 Orthogonal Vectors and Subspaces
  - 1.8.3 Projections onto Lines
  - 1.8.4 Orthogonal Bases and Gram-Schmidt orthogonalization process and the QR- decomposition.
  - 1.8.5 Least square solution of a non-consistent linear system and the orthogonal projections.

## **2. Linear Programming and Integer Programming (12 hours)**

- 2.1 Introduction to Linear Programming (7 hours) [Ref 7: Pg. (24-308)]
  - 2.1.1 Assumptions
  - 2.1.2 Graphical method and Simplex algorithm with standard and general linear programming problems
  - 2.1.3 Duality
- 2.2 Introduction to Integer Programming (5 hours) [Ref 7: Pg. (576-653)]
  - 2.2.1 Assumptions
  - 2.2.2 Graphical method
  - 2.2.3 Cutting plane algorithm
  - 2.2.4 Branch and bound algorithm

#### 2.2.5 Knapsack problems

### 3. Basic Statistics (11 hours)

Prerequisite(s): Need the basic knowledge on integration.

- 3.1 Random variables (1 hour) [Ref 2: Pg. (34-39)], [Ref 8: Pg. (45-73, 108-185)], [Ref 9: Pg. (97-140)]
  - 3.1.1 Discrete random variables
  - 3.1.2 Continuous random variables
- 3.2 Cumulative Distribution Function (1 hour) [Ref 2: Pg. (34-39)], [Ref 8: Pg. (45-73, 108-185)], [Ref 9: Pg. (97-140)]
- 3.3 Probability distribution of a discrete random variable (1 hour) [Ref 2: Pg. (34-39, 75-78)], [Ref 8: Pg. (45-73, 108-185)], [Ref 9: Pg. (97-140)]
  - 3.3.1 Definition
  - 3.3.2 Mean and Variance
- 3.4 The Binomial probability distribution (1 hour) [Ref 2: Pg. (108-150)], [Ref 8: Pg. (45-73, 108-185)], [Ref 9: Pg. (97-140)]
- 3.5 The Poisson probability distribution (1 hour) [Ref 2: Pg. (108-150)], [Ref 8: Pg. (45-73, 108-185)], [Ref 9: Pg. (97-140)]
- 3.6 Probability distribution of a continuous random variable (1 hour) [Ref 2: Pg. (34-39, 75-78)], [Ref 8: Pg. (45-73, 108-185)], [Ref 9: Pg. (97-140)]
  - 3.6.1 Definition
  - 3.6.2 Mean and Variance
- 3.7 The Uniform probability distribution (1 hour) [Ref 2: Pg. (108-150)], [Ref 8: Pg. (45-73, 108-185)], [Ref 9: Pg. (97-140)]
- 3.8 The Normal probability distribution (2 hours) [Ref 2: Pg. (108-150)], [Ref 8: Pg. (45-73, 108-185)], [Ref 9: Pg. (97-140)]
- 3.9 The Exponential distribution (1 hour) [Ref 2: Pg. (108-150)], [Ref 8: Pg. (45-73, 108-185)], [Ref 9: Pg. (97-140)]
- 3.10 Normal approximation of the Binomial distribution (1 hour) [Ref 2: Pg. (108-150)], [Ref 8: Pg. (45-73, 108-185)], [Ref 9: Pg. (97-140)]

#### Teaching /Learning Methods:

You can access all learning materials and this syllabus in the VLE: <http://vle.bit.lk/>, if you are a registered student of the BIT degree program.

**Assessment Strategy:****Continuous Assessments/Assignments:**

In the course, case studies/Lab sheets will be introduced, and students have to participate in the learning activities.

**Final Exam:**

The final exam of the course will be held at the end of the semester. This course is evaluated using a two-hour question paper consisting of 4 Structured Questions.

**References/ Reading Materials:**

- **Ref 1:** Business Mathematics by Qazi Zameeruddin, V.K Khanna and S.K Bhambri (vikas publishing house)
- **Ref 2:** Schaum's Outline Probability and Statistics, by Murray R. Spiegel, J. Schiller, R. A. Srinivasan, 2<sup>nd</sup> edition, 2000, Mc Graw Hill
- **Ref 3:** Meyer, C.D., 2000. Matrix analysis and applied linear algebra (Vol. 2). SIAM.
- **Ref 4:** Schuam's Outline Series, Theory and Problems of Matrices by Frank Ayres, JR, McGraw-Hill
- **Ref 5:** Linear Algebra (2<sup>nd</sup> edition) by Hoffman, K. and Kunze, R., 1971. Englewood Cliffs, New Jersey
- **Ref 6:** Linear Algebra and Its Applications (4<sup>th</sup> edition) by David C. Lay, 2012. Addison Wesley, Pearson
- **Ref 7:** Introduction to Operations Research (7<sup>th</sup> edition), F S Hillier and G L Lieberman, 2001, McGraw-Hill.
- **Ref 8:** Probability and mathematical statistics, Prasanna Sahoo.
- **Ref 9:** Applied statistics and probability for engineers, Douglas C. Montgomery and George C. Runger.