

Hashing

- 8.1 Introduction
- 8.2 Static Hashing
 - Hash Tables
 - Hashing Functions
 - Overflow Handling
 - Open addressing
 - **Chaining**
- 8.3 Dynamic Hashing

Chaining

bucket	<i>x</i>	buckets searched
0	acos	1
1	atoi	2
2	char	1
3	define	1
4	exp	1
5	ceil	4
6	cos	5
7	float	3
8	atol	9
9	floor	5
10	ctime	9
...		
25		

- Linear probing
 - Perform poorly;
 - The search for a key involves comparison of identifiers with different hash values : ex) `atol` → ...
- Chained hash table
 - One list per bucket
 - Each list containing all the synonyms for that bucket
 - Searching a key *k*
 - Compute $h(k)$
 - Examine only those keys in the list for $h(k)$
 - Use array & chains

[0] → **acos** **atoi** **atol**
 [1] → *NULL*
 [2] → **char** **ceil** **cos** **ctime**
 [3] → **define**
 [4] → **exp**
 [5] → **float** **floor**
 [6] → *NULL*
 ...
 [25] → *NULL*

Figure 8.6: Hash chains corresponding to Figure 8.4

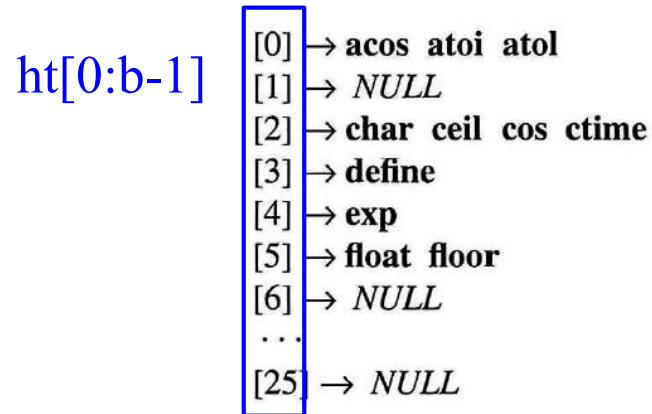


Figure 8.6: Hash chains corresponding to Figure 8.4

Average # of key comparisons for searching k
 $= 21/11 = \mathbf{1.91}$

```

element* search(int k)
{
    /* search the chained hash table ht for k,
    if a pair with this key is found, return a pointer to this pair;
    otherwise, return NULL. */
    nodePointer current;
    int homeBucket = h(k);

    /* search the chain ht[homeBucket] */
    for(current = ht[homeBucket]; current; current = current->link)
        if(current->data.key == k) return &current->data;
    return NULL;
}

```

Program 8.4: Chain search

```

[0] → acos atoi atol
[1] → NULL
[2] → char ceil cos ctime
[3] → define
[4] → exp
[5] → float floor
[6] → NULL
...
[25] → NULL

```

Figure 8.6: Hash chains corresponding to Figure 8.4

- chaining + uniform hash function
 - The expected average number of key comparisons for a successful search:
 $\approx 1 + \alpha/2$, where $\alpha = n/b$
 - Ex) $\alpha = 0.5 \rightarrow 1.25$, $\alpha = 1 \rightarrow 1.5$
 - Performance
 - Depends only on the method used to handle **overflows** (when the keys are selected at random from the key space)
 - In practice, a tendency to make a biased use of **keys**
 - Different **hash functions** result in different performance
 - Generally, the division hash function coupled with chaining yields best performance
 - The worst-case for a successful search
 - $O(n)$
 - Reduced to $O(\log n)$ by sorting synonyms in a balanced search tree

8.3 DYNAMIC HASHING

Motivation for Dynamic Hashing

- Disadvantages of static hashing
 - ... 데이터의 동적 삽입 삭제가 어렵다
충돌이 발생하면 처리방법이 제한적이고, 성능 저하되기가 쉽다
- Dynamic (Extendible) hashing
 - Reduce the rebuild time Rebuild 할때 시간을 줄인다
 - Each rebuild changes the home bucket for the entries
in only 1 bucket
 - Two forms of dynamic hashing:
Using **directory**, **directoryless**

k	$h(k)$
A0	100 000
A1	100 001
B0	101 000
B1	101 001
C1	110 001
C2	110 010
C3	110 011
C5	110 101

Figure 8.7: An example hash function

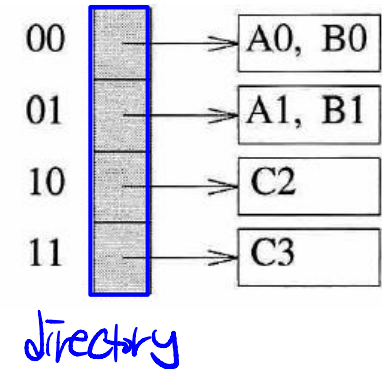
$h(k, p)$ denotes the integer formed by the p LSBs of $h(k)$

$$h(A0, 1) = 0$$

$$h(A1, 3) = 1$$

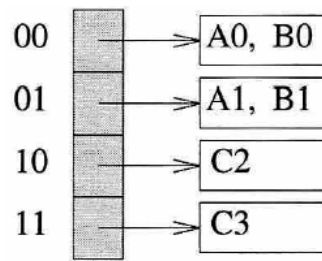
$$h(B1, 4) = 1001 = 9$$

Dynamic Hashing using Directories

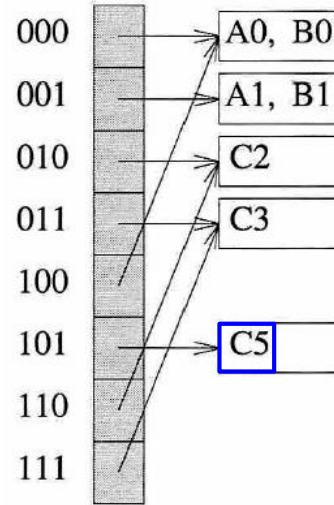


- Use a directory (d): pointers to buckets
- The size of directory
 - Depend on the # of bits of $h(k)$ *비트에 따라 시작 할라점*
 - $h(k,2)$: directory size = $2^2 = 4$
 - $h(k,5)$: $2^5 = 32$
- Directory depth
 - The # of bits of $h(k)$ used to index the directory *비트 수*
- To search for a key k
 - Examine the bucket pointed to by $d[h(k,t)]$

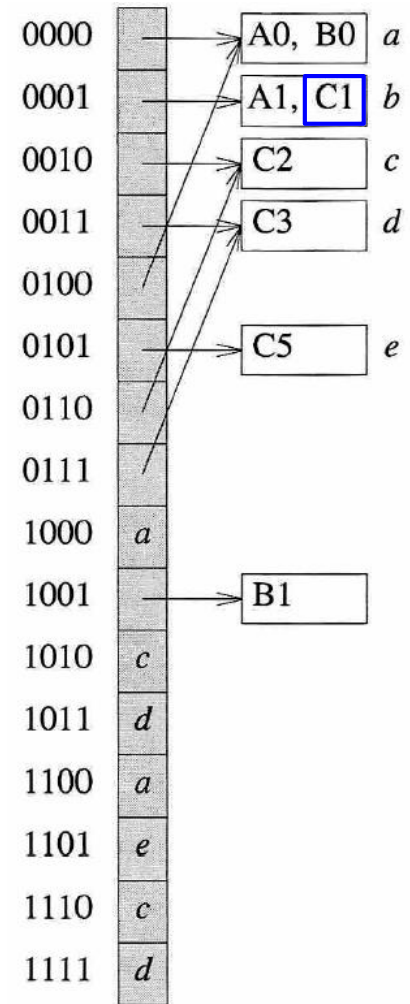
k	$h(k)$
A0	100 000
A1	100 001
B0	101 000
B1	101 001
C1	110 001
C2	110 010
C3	110 011
C5	110 101



(a) depth = 2



(b) depth = 3



(c) depth = 4

Figure 8.8: Dynamic hash tables with directories

다항식

- Insert C5

→ $h(C5, 2) = 01$

- Bucket overflow
- Determine the least u such that $h(k, u)$ is not the same for all keys in the overflowed bucket

→ $u = 3 \Rightarrow h(C5, 3) = 101$

- In case $u > t$:

1) increase directory depth to $u = 3$;

→ double the directory size

→ pointers in the original directory are duplicated

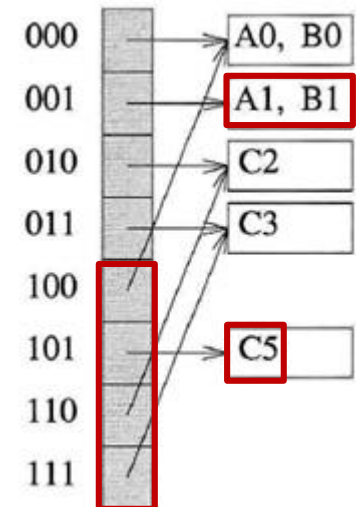
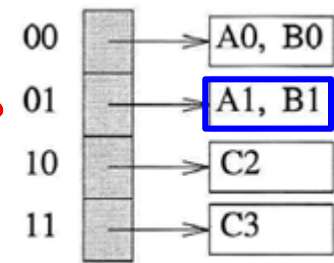
원래 있던 pointer는 유지함

2) split the overflowed bucket using $h(k, 3)$

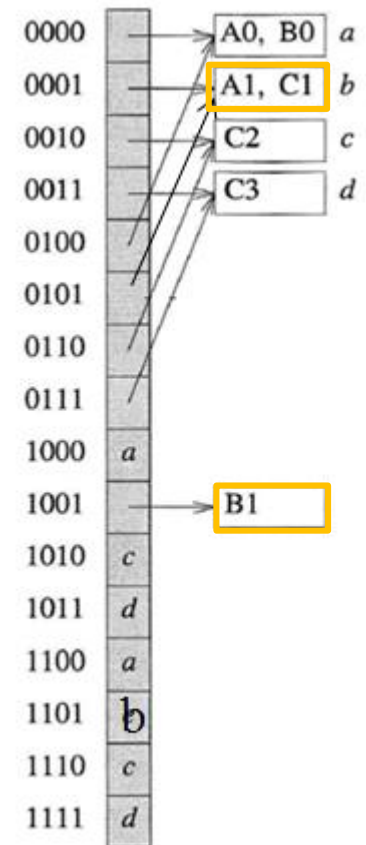
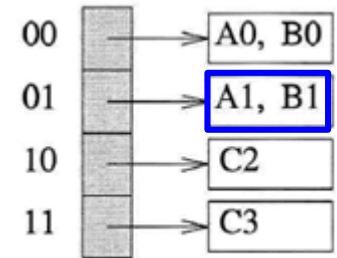
→ 001: A1, B1, 101:C5

→ update d[101] to point to the new bucket

k	$h(k)$
A0	100 000
A1	100 001
B0	101 000
B1	101 001
C1	110 001
C2	110 010
C3	110 011
C5	110 101



k	$h(k)$
A0	100 000
A1	100 001
B0	101 000
B1	101 001
C1	110 001
C2	110 010
C3	110 011
C5	110 101



- Insert C1

→ $h(C1, 2) = 01$

- Bucket overflow;
- Determine u

→ $u = 4$ ($u=3$ 은 overflow)

In case $u > t$:

1) increase directory depth to $u = 4$;

→ quadruple the directory size

→ pointers in the directory are replicated 3 times

2) split the overflowed bucket using $h(k, 4)$

→ 0001: A1, C1, 1001: B1

→ update $d[1001]$ to point to the new bucket

- Insert A4

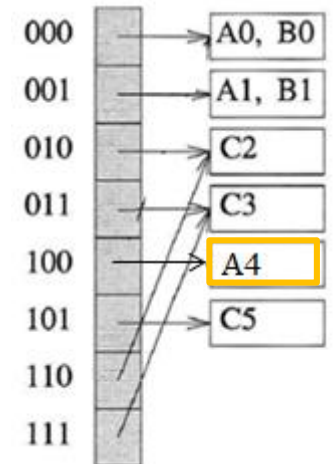
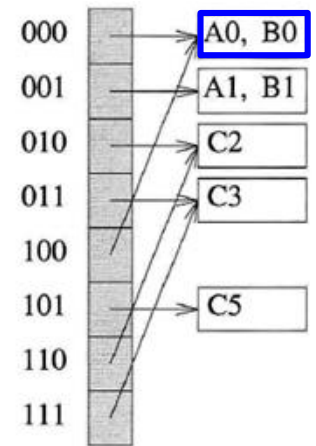
→ $h(A4, 3) = 100$

- Bucket overflow;
- Determine u
- $u = 3$

In Case: $u \leq t$

- The size of directory is not changed
- split the overflowed bucket using $h(k, u)$;
 - 000: A0, B0, 100:A4
- update $d[100]$ to point to the new bucket

k	$h(k)$
A0	100 000
A1	100 001
B0	101 000
B1	101 001
C1	110 001
C2	110 010
C3	110 011
C5	110 101



- Advantages

- The time for array doubling is considerably less than that for the array doubling used in static hashing
- Rehash only the entries in the bucket that overflows rather than all entries in the table

overflow 하는 부분만 rehash 하면 된다

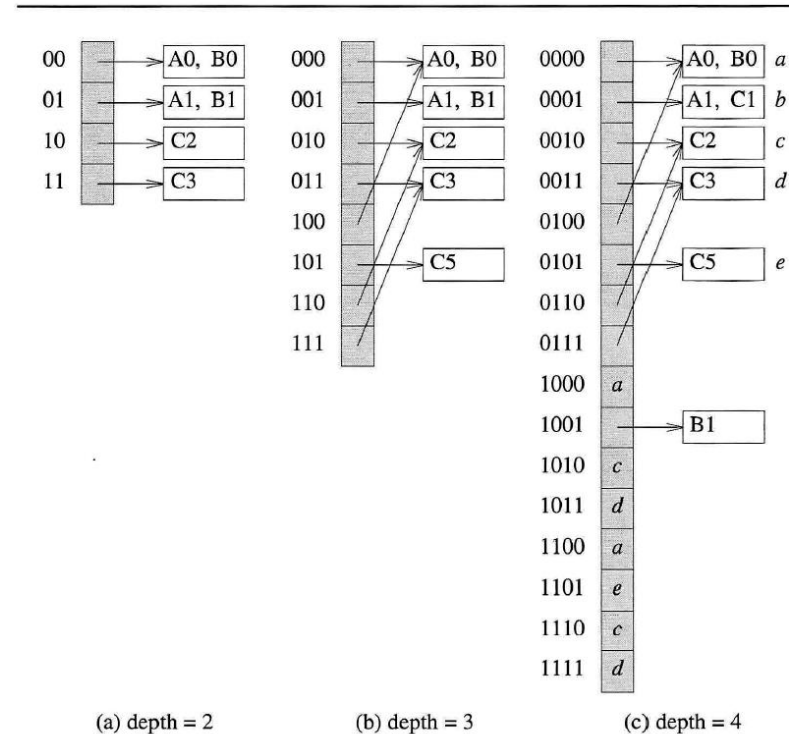


Figure 8.8: Dynamic hash tables with directories

Directoryless Dynamic Hashing

- An array ht of buckets is used
- Assumption
 - Array is as large as possible; 충분한 크기의 배열을 이미 할당해놓음
 - There is no possibility of increasing its size dynamically
- Use two variables q and r , $0 \leq q < 2^r$
 - Keep track of the active buckets 사용하고 있는 bucket
 - r : The # of bits of $h(k)$ used to index into the hash table
 - q : The bucket that will split next
- Only buckets $0 \sim 2^r + q - 1$ are active
 - Each active bucket is the start of a chain of buckets

00	B4 A0
01	A1 B5
10	C2 -
11	C3 -

크기를 동적으로
늘릴 필요 없음

(a) $r = 2, q = 0$

<Insert C5>

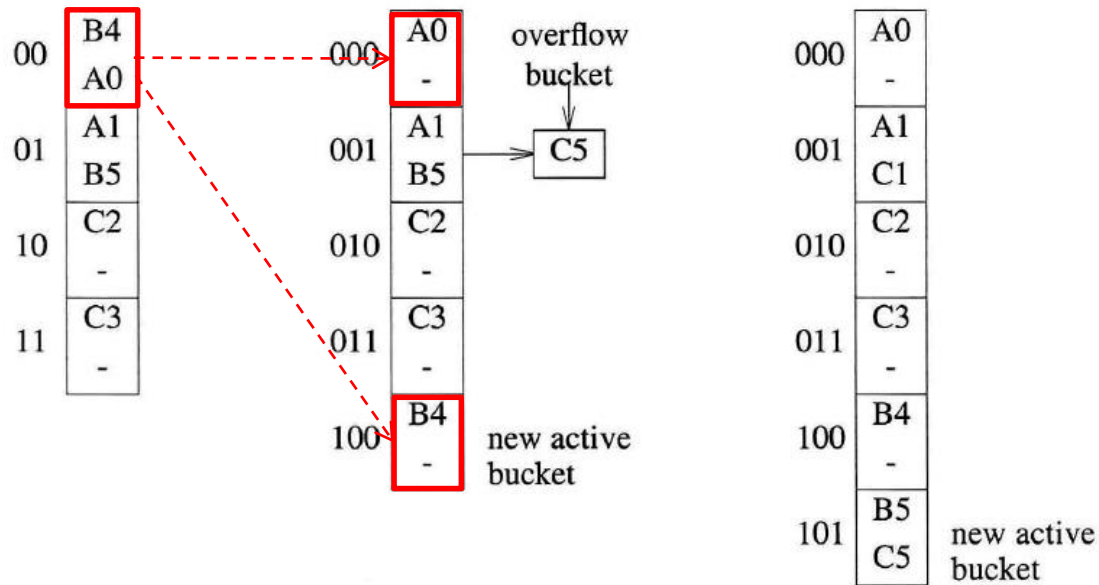
→ $h(C5, 2) = 01$

→ $b[01]$: overflow

→ activating bucket 2^{r+q} ;
reallocating **entries in q** by $h(k, r+1)$

→ $q++$

bucket size is 2
 $h(k, r+1)$ is rehash



C5

2nd bucket
(a) $r = 2, q = 0$

(b) Insert C5, $r = 2, q = 1$

(c) Insert C1, $r = 2, q = 2$

Figure 8.9: Inserting into a directoryless dynamic hash table

<Insert C1>

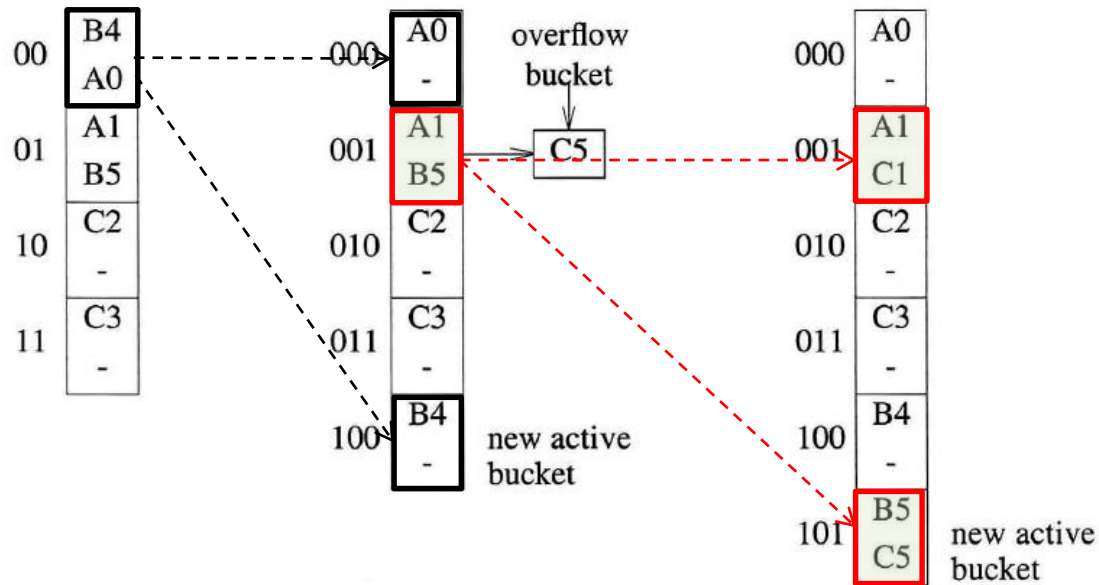
→ $h(C1,2)=01$

→ $d[01]$: overflow

→ Activating 2^r+q ;

reallocating A1, B5, C5 in q by $h(k,r+1)$

→ $q++$



(a) $r = 2, q = 0$

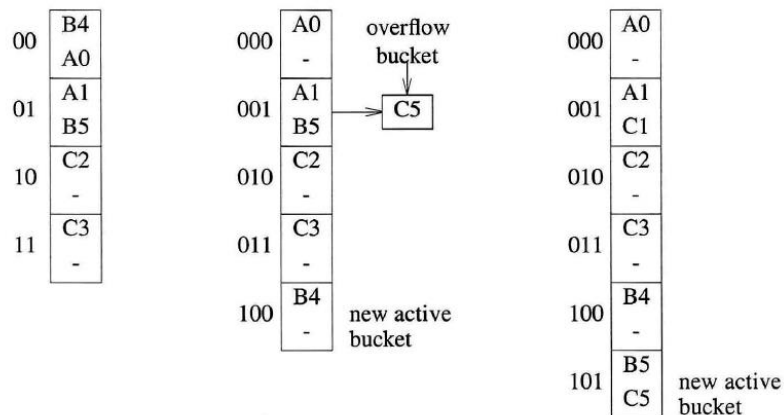
(b) Insert C5, $r = 2, q = 1$

(c) Insert C1, $r = 2, q = 2$

Figure 8.9: Inserting into a directoryless dynamic hash table

- Overflow

- Handled by activating bucket 2^{r+q} , incrementing q by 1
- In case q becomes 2^r , increment r by 1 and reset q to 0



(a) $r = 2, q = 0$

(b) Insert C5, $r = 2, q = 1$

(c) Insert C1, $r = 2, q = 2$

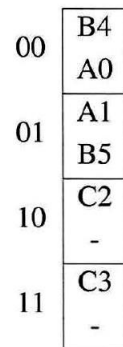
Figure 8.9: Inserting into a directoryless dynamic hash table

- Searching

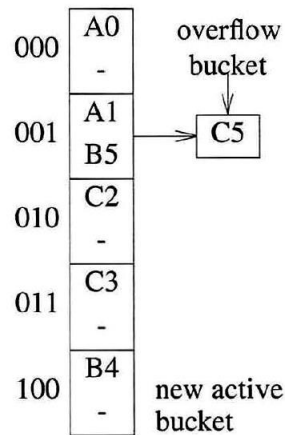
if $(h(k, r) < q)$ search the chain that begins at bucket $h(k, r + 1)$;
else search the chain that begins at bucket $h(k, r)$;

Program 8.5: Searching a directoryless hash table

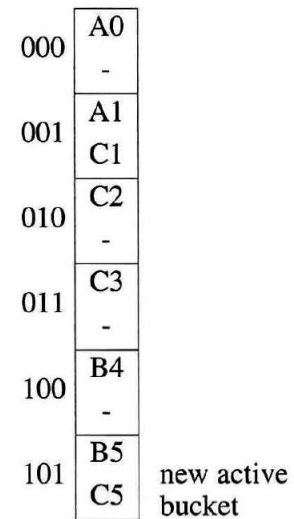
k	$h(k)$
A0	100 000
A1	100 001
B0	101 000
B1	101 001
C1	110 001
C2	110 010
C3	110 011
C5	110 101



(a) $r = 2, q = 0$



(b) Insert C5, $r = 2, q = 1$



(c) Insert C1, $r = 2, q = 2$

Hashing

- 8.1 Introduction
- 8.2 Static Hashing
 - Hash Tables
 - Hashing Functions
 - Mid-square, Division, Folding, Digit Analysis
 - Overflow Handling
 - Open addressing, Chaining
- 8.3 Dynamic Hashing