### **CHAPTER 6**

## **GRAPHS**

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- 6.1 The Graph Abstract Data Type
- 6.2 Elementary Graph Operations
- 6.3 Minimum Cost Spanning Trees

## 6.1.1 Introduction

#### Königsberg bridge problem

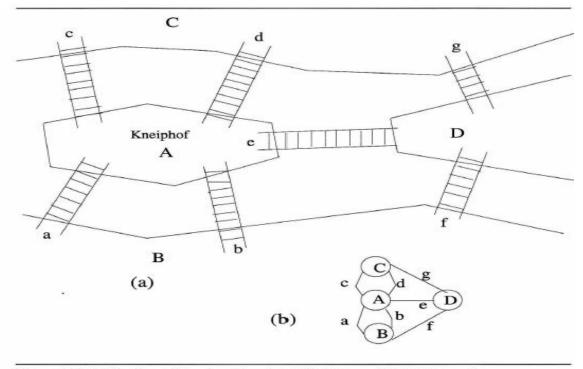
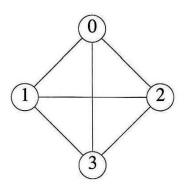


Figure 6.1: (a) Section of the river Pregel in Königsberg; (b) Euler's graph

#### 6.1.2 Definitions

- Graph G=(V, E)
  - V is a finite, nonempty set of vertices
  - E is a set of *edges*
  - An edge is a pair of vertices
  - V(G) is the set of vertices of G
  - E(G) is the set of edges of G

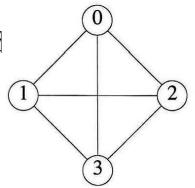




#### Undirected graph

- The pair of vertices in an edge is unordered
  - (u,v) and (v,u): the same edge
- -Ex

$$V(G_1)=\{0,1,2,3\}$$
  
 
$$E(G_1)=\{(0,1),(0,2),(0,3),(1,2),(1,3),(2,3)\}$$



#### Directed graph (digraph)

- Each edge is represented by  $\langle u, v \rangle$ 
  - *u*: tail, *v*: head

- < v, u > and < u, v > represent two different edges
- -Ex

$$V(G_3) = \{0,1,2\}$$
  
 $E(G_3) = \{<0,1>, <1,0>, <1,2>\}$ 



(c)  $G_3$ 

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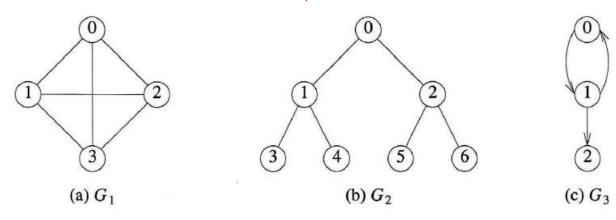


Figure 6.2: Three sample graphs

• 
$$V(G_1) = \{0,1,2,3\}$$
  
 $E(G_1) = \{(0,1),(0,2),(0,3),(1,2),(1,3),(2,3)\}$ 

• 
$$V(G_2) = \{0,1,2,3,4,5,6\}$$
  
 $E(G_2) = \{(0,1),(0,2),(1,3),(1,4),(2,5),(2,6)\}$ 

• 
$$V(G_3) = \{0,1,2\}$$
  
 $E(G_3) = \{<0,1>,<1,0>,<1,2>\}$ 

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#### Restrictions on Graphs

- NOT self edges or self loops
  - (v, v) and  $\langle v, v \rangle$ : Not legal
- NOT multiple occurrences of the same edge

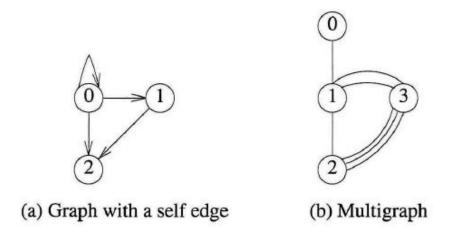


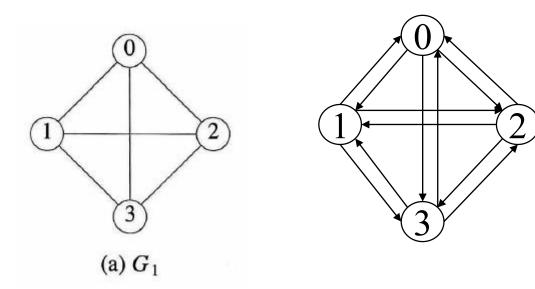
Figure 6.3: Examples of graphlike structures

#### Complete graph

- Has the maximum number of edges;
- An *n*-vertex, undirected graph with exactly n(n-1)/2 edges is said to be *complete*

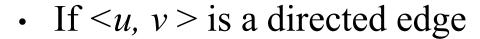
#### Complete directed graph

- The max # of edges is n(n-1)

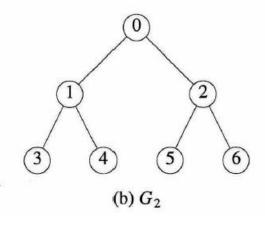


### • If (u,v) is an edge in E(G)

- Vertices u and v are adjacent
- Edge (u, v) is *incident* on vertices u and v
- -Ex
  - Edges incident in vertex 2 in G<sub>2</sub>: ...



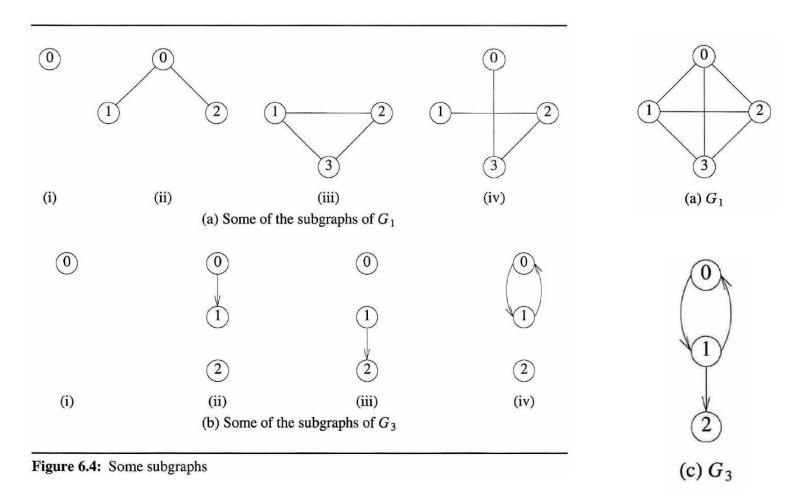
- Vertex u is adjacent to v, and v is adjacent from u
- Edge  $\langle u, v \rangle$  is incident on u and v.
- -Ex
  - Edges incident to vertex 1 in  $G_3$ : ...



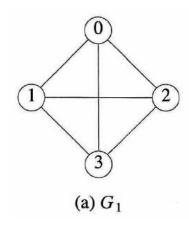
(c)  $G_3$ 

#### Subgraph of G

- A graph G' such that  $V(G') \subseteq V(G)$  and  $E(G') \subseteq E(G)$ 



- A path from vertex u to vertex v in graph G
  - A sequence of vertices u,  $i_1$ ,  $i_2$ , ...,  $i_k$ , v such that  $(u,i_1)$ ,  $(i_1,i_2)$ , ...,  $(i_k,v)$  are edges in E(G)
  - path (0, 2), (2, 1), (1, 3) is also written as 0, 2, 1, 3

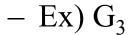


- The *length* of a path
  - The number of edges on it

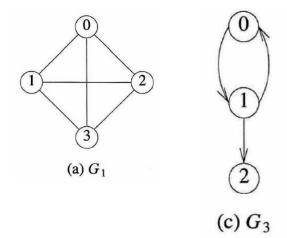
### • Simple path

 A path in which all vertices, except possibly the first and the last, are distinct

- $Ex) G_1$ 
  - path 0, 1, 2, 0: simple path
  - path 0, 1, 3, 2: simple path
  - path 0, 1, 3, 1: NOT simple path

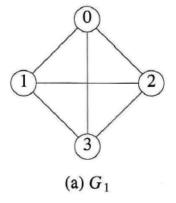


• path 0, 1, 2: simple directed path



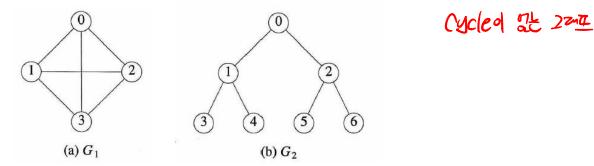
#### Cycle

- A simple path in which the first and the last vertices are the same
- -Ex
  - path 0, 1, 2, 0 ( $G_1$ ), path 0, 1, 0 ( $G_3$ )

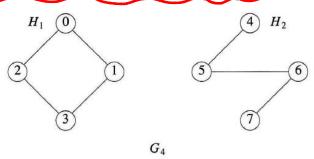




- An undirected graph is said to be *connected* 
  - iff for every pair of distinct vertices u and v in V(G) there is a path from u to v in G
  - A tree is a connected acyclic (no cycles) graph



- (Connected) *component* of an undirected graph
  - A maximal connected subgraph



Connected & 만든 1장 Z Sulgraph

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#### A directed graph is strongly connected

- iff for every pair of distinct vertices u and v in V(G), there is a directed path from u to v and also from v to u
- -Ex)  $G_3:...$  Not stringly corrected



(c)  $G_3$ 

#### Strongly connected component

- A maximal subgraph that is strongly connected

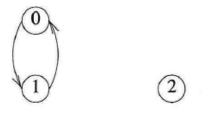
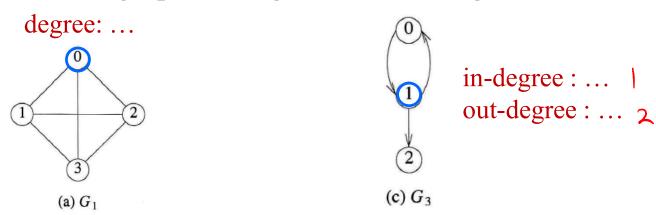


Figure 6.6: Strongly connected components of  $G_3$ 

- degree of vertex
  - The # of edges incident to that vertex
  - For directed graph, in-degree and out-degree



undTrocted

- The # of edges in G with n vertices:  $e = (\sum_{i=0}^{n-1} d_i)/2$ 
  - $-d_i$ : degree of vertex i

#### ADT Graph is

**objects**: a nonempty set of vertices and a set of undirected edges, where each edge is a pair of vertices.

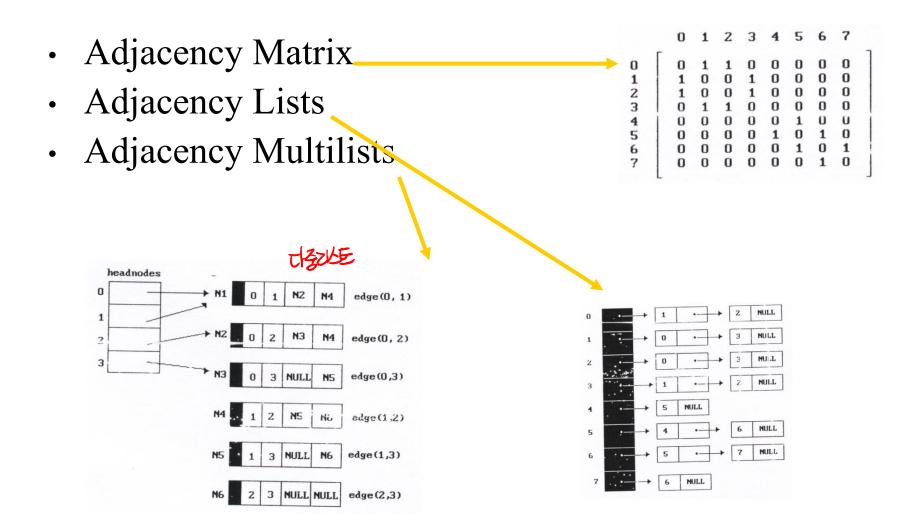
#### functions:

```
for all graph \in Graph, v, v_1, and v_2 \in Vertices
```

Graph Create() → Java 대서 생성과	::=	return an empty graph.
Graph InsertVertex(graph, v)	::=	return a graph with v inserted. v has no incident edges.
Graph InsertEdge(graph, $v_1$ , $v_2$ )	::=	<b>return</b> a graph with a new edge between $v_1$ and $v_2$ .
Graph DeleteVertex(graph, v)	::=	return a graph in which v and all edges incident to it are removed.
$Graph$ DeleteEdge( $graph$ , $v_1$ , $v_2$ )	::=	<b>return</b> a graph in which the edge $(v_1, v_2)$ is removed. Leave the incident nodes in the graph.
Boolean IsEmpty(graph)	::=	if (graph == empty graph) return TRUE else return FALSE.
List Adjacent(graph, v)	::=	<b>return</b> a list of all vertices that are adjacent to $v$ .

ADT 6.1: Abstract data type Graph

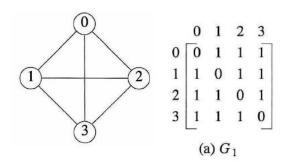
## 6.1.3 Graph Representation

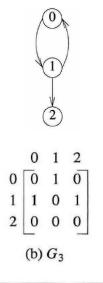


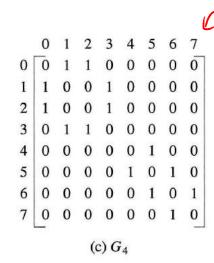
# 6.1.3.1 Adjacency Matrix

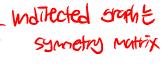
- Adjacency matrix a of G
  - two dimensional  $n \times n$  array
  - -a[i][j]=1 iff edge(i, j) is in E(G)
  - -a[i][j]=0 iff there is no edge(i, j) in E(G)

Space for adjacency matrix: ...









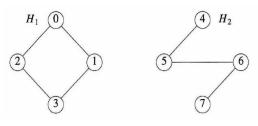
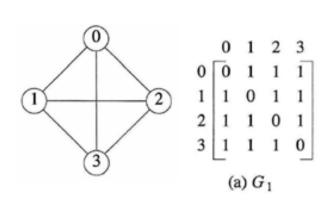


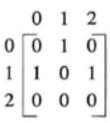
Figure 6.7: Adjacency matrices

#### Properties of Adjacency Matrix

- For a graph, degree of vertex i is its row sum:  $\sum_{j=0}^{n-1} a[i][j]$
- For a *digraph*, the *row sum* is the out-degree, and the *column sum* is the in-degree
- Time complexity: O(...)
  - How many edges are there in G?
  - Is G connected?





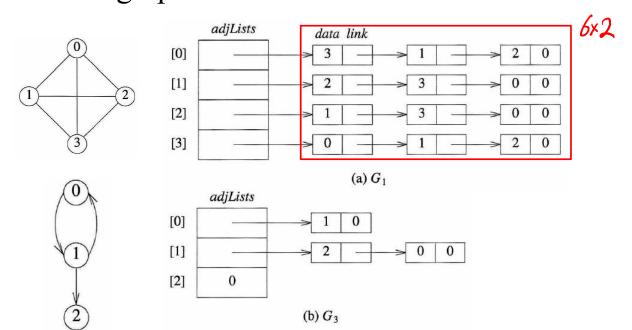


## 6.1.3.2 Adjacency Lists

- Chain Representation
  - The *n* rows of the adjacency matrix are represented as *n* chains

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- Graph with n vertices and e edges
  - Requires *n* head nodes and 2*e* list nodes
- For a digraph: e nodes



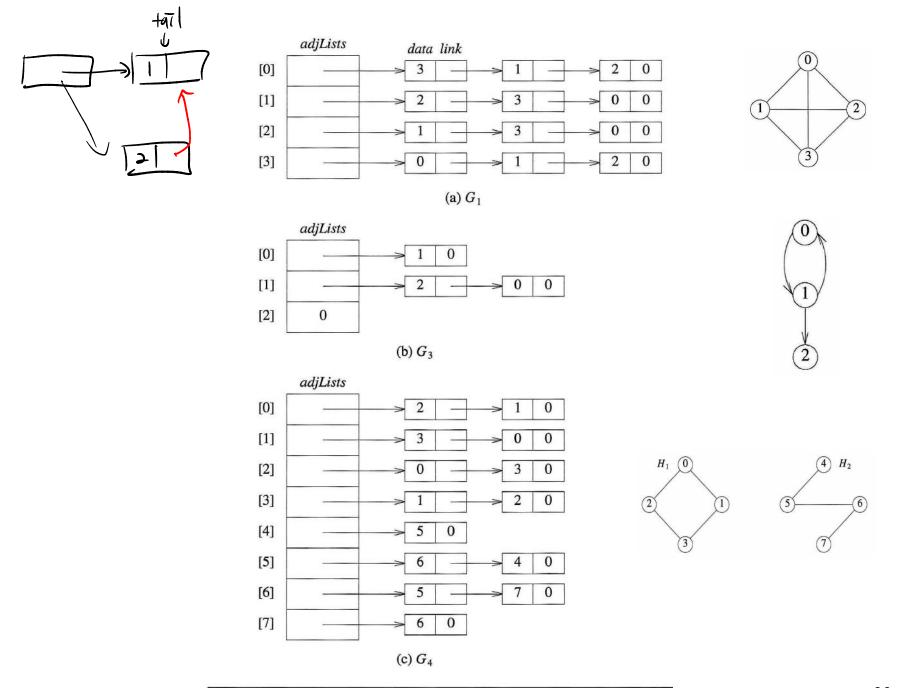
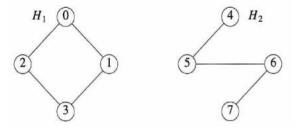
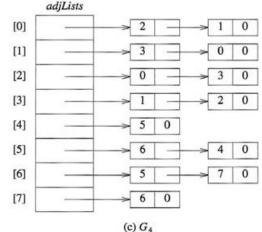


Figure 6.8: Adjacency lists

#### At the 23 advacency list Fertugat



- Sequential Representation
  - The adjacency lists may be packed into an integer array node[n + 2e + 1]
  - -node[i]: the starting point of the list for vertex i
    - 0 <= i < n
  - node[n] = n+2e+1
  - The vertices adjacent from vertex i
    - Stored in node[node[i]], ..., node[node[i+1]-1]



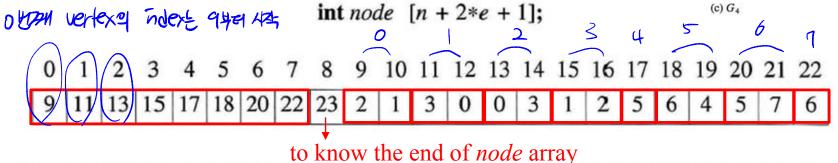
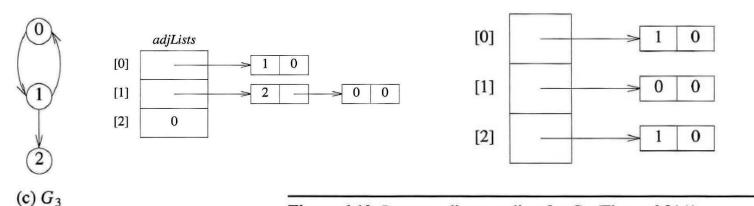


Figure 6.9: Sequential representation of graph  $G_4$   $\Rightarrow$   $\exists$   $\exists$ 

- The degree of any vertex
  - In undirected graph
    - Determined by just counting the # of nodes in its adjacency list
  - In digraph
    - Out-degree: the # of nodes on its adjacency list
    - In-degree: the # of nodes on its inverse adjacency list



**Figure 6.10:** Inverse adjacency lists for  $G_3$  (Figure 6.2(c))

- Alternate node structure of adjacency lists
  - Each node
    - edge(head/tail)
    - link for column chain, link for row chain

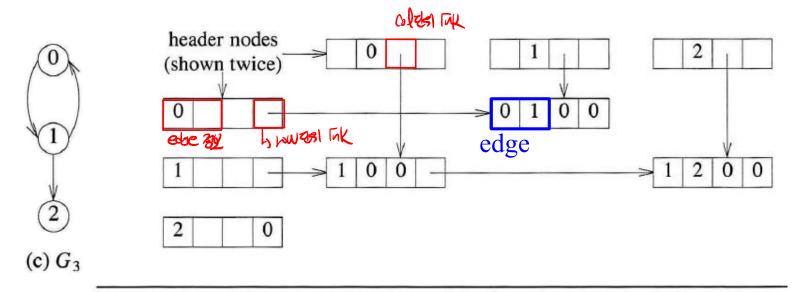


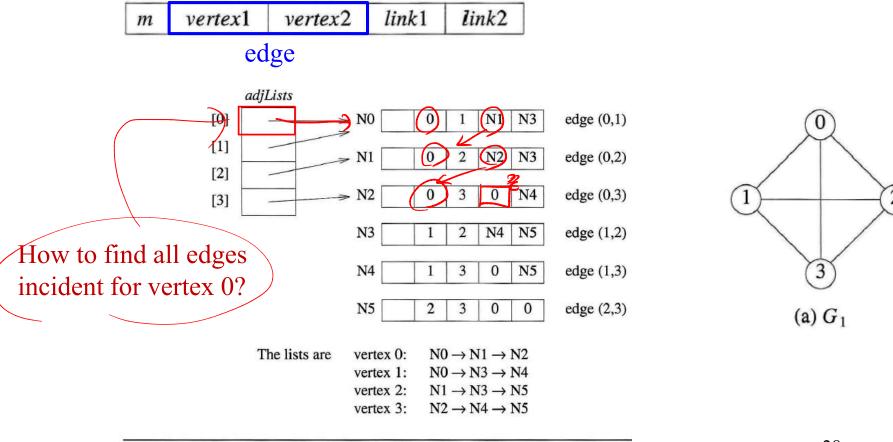
Figure 6.11: Orthogonal list representation for  $G_3$  of Figure 6.2(c)

## 6.1.3.3 Adjacency Multilists

- An edge (u, v) in an undirected graph
  - Represented by two nodes in adjacency list representation;
  - One on the list for u and the other on the list for v
- Adjacency multilists
  - There is exactly one node for each edge
  - Lists in which nodes may be shared among several lists (an edge is shared by two different paths)

#### Node structure

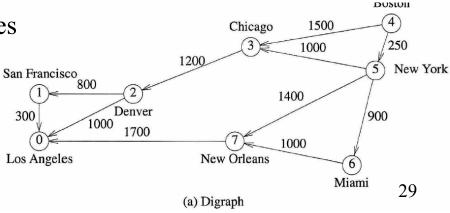
- -m: whether or not the edge has been examined
- link1: the next edge of vertex1
- link2: the next edge of vertex2



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## 6.1.3.4 Weighted Edges

- The edges of a graph have weights assigned to them
- These weights may represent as
  - the distance from one vertex to another
  - cost of going from one vertex to an adjacent vertex.
- Adjacency matrix: a[i][j] would keep the weights.
- Adjacency lists
  - Add a weight field to the node structure
- Network
  - A graph with weighted edges



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- 6.1 The Graph Abstract Data Type
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