

# MINYOUNG HWANG

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## EDUCATION

<b>Massachusetts Institute of Technology (MIT)</b> M.S. & Ph.D. in AeroAstro & CSAIL	Cambridge, MA 09/2024 - Current
<b>Seoul National University (SNU)</b> M.S. in Electrical and Computer Engineering • Thesis: "Meta-Explore: Exploratory Hierarchical Vision-and-Language Navigation Using Scene Object Spectrum Grounding"	Seoul, Korea 09/2021 - 08/2023
B.S. in Electrical and Computer Engineering • Thesis: "Video Inference for Human Motion with Texture Generation"	03/2017 - 08/2021
<b>Daejeon Science High School for the Gifted</b> Major: Mathematics	Daejeon, Korea 03/2014 - 02/2017

## REPRESENTATIVE HONORS

<b>Kwanjeong Education Foundation (KEF) Scholarship</b> , KEF	2024 - 2029
<b>Presidential Science Scholarship (Field: Mathematics)</b> , Ministry of Science and ICT	2017 - 2020
<b>NeurIPS 2023 Scholar Award</b>	10/2023
<b>Google Student Travel Grants</b> (up to 3 students / year, top international conferences)	03/2023
<b>Talent Award of Korea</b> (Field: Mathematics), Ministry of Education	11/2015
<b>Training Lineup for IMO (International Mathematical Olympiad)</b> , Top 18 students in Korea	05/2016

## PUBLICATIONS

- Masked Inverse Reinforcement Learning for Language Conditioned Reward Learning**  
*Minyoung Hwang, Alex Forsey-Smerek, Andreea Bobu*  
*In Submission, 2025*
- Sample-Efficient Robot Preference Learning with Confidence-Guided Exploration**  
*Chan Woo Kim, Hyeonseong Kim, Minyoung Hwang, Sungjoon Choi, Kyungjae Lee*  
*In Submission, 2025*
- MotIF: Motion Instruction Fine-tuning**  
*Minyoung Hwang, Joey Hejna, Dorsa Sadigh, Yonatan Bisk*  
*IEEE Robotics and Automation Letters (RA-L), 2025*
- Promptable Behaviors: Personalizing Multi-Objective Rewards from Human Preferences**  
*Minyoung Hwang, Luca Weihs, Chanwoo Park, Kimin Lee, Ani Kembhavi, Kiana Ehsani*  
*The IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), June 2024*
- Sequential Preference Ranking for Efficient Reinforcement Learning from Human Feedback**  
*Minyoung Hwang, Gunmin Lee, Hogun Kee, Chan Woo Kim, Kyungjae Lee, Songhwai Oh*  
*Neural Information Processing Systems (NeurIPS), Dec. 2023*
- Meta-Explore: Exploratory Hierarchical Vision-and-Language Navigation Using Scene Object Spectrum Grounding**  
*Minyoung Hwang, Jaeyeon Jeong, Minsoo Kim, Yoonseon Oh, Songhwai Oh*  
*The IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), June 2023*
- Improving Image-Goal Navigation with Visual Language Grounding via Image Captioning**  
*Minyoung Hwang, Songhwai Oh*  
*Conference on Information and Control Systems (CICS), Oct. 2022*
- Geometric Understanding of Reward Function in Multi-Agent Visual Exploration**  
*Minyoung Hwang, Obin Kwon, Songhwai Oh*  
*International Conference on Control, Automation and Systems (ICCAS), Oct. 2021*

## AI Insiders

Gun Ahn, *Minyoung Hwang, et al.*  
Smart Books, 2025

## Wanna be Engineer

34 members of STEM (Including Hwang, M.)  
MegaStudy Books, 2021

## WORK EXPERIENCE

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### Carnegie Mellon University (CMU)

Research Intern

Pittsburgh, PA

01/2024 – 06/2024

- Connecting Language to Actions & the World (CLAW) Lab (Prof. Yonatan Bisk)
- How human preferences are communicated in natural language to a robotic agent

### Allen Institute for Artificial Intelligence (AI2)

Research Intern

Seattle, WA

07/2023 – 12/2023

- Perceptual Reasoning and Interaction Research (PRIOR)
- Promptable Behaviors: Personalizing Multi-Objective Rewards from Human Preferences, sub. to CVPR 2024

### SNU Robot Learning Laboratory

Robotics Researcher (M.S. Student)

Seoul, Korea

09/2021 – 06/2023

- SeqRank for Feedback-efficient RLHF, *accepted to NeurIPS 2023* (01/2023 - 05/2023)
- Meta-Explore for Vision-and-Language Navigation, *accepted to CVPR 2023* (08/2021 - 11/2022)
- Graph Merge for Robust Path Following (08/2021 - 02/2022)

Robotics Research Intern

02/2020 – 08/2021

- Geometric Understanding of Reward Function in Multi-Agent Visual Exploration, *accepted to ICCAS 2021* (02/2021 - 10/2021)
- Video Inference for Human Motion with Texture Generation, Bachelor Thesis (08/2020 - 12/2020)
- Visual Navigation in Gibson Env2 Environment (02/2020 - 07/2020)

### San Jose State University (SJSU) Silicon Valley Innovation

Startup Team CEO, Startup Training Program

San Jose, CA

01/2020

- Led startup team UP-CARE (Use your Phone Camera for Health and Environment).
- Developed fall detection and alert for elderly users.

### STEM, SNU Engineering College

Robotics Engineer

Seoul, Korea

03/2019 – 11/2019

- Robot Dynamics and Control, Motion Planning, Computer Vision
- Developed both software and hardware of robot cleaner using 3D printers, Arduino, and computer vision open source (Google Mediapipe); led the development of control algorithm considering robot dynamics.

## PROJECTS AND RESEARCH

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\* RL: Reinforcement Learning / CV: Computer Vision / HRI: Human-Robot-Interaction

### Promptable Behaviors for Efficient Personalization of Robots | *RL, HRI, CV*

05/2023 – 12/2023

Learning reward weights for multi-objective rewards from human preference.

AI2

### SeqRank for Feedback-efficient RLHF | *RL, HRI, Graph Theory*

01/2023 – 05/2023

RLHF framework that uses sequential preference ranking to enhance the feedback efficiency.

RLLAB, SNU

### Meta-Explore for Vision-and-Language Navigation | *Multimodal, Graph Theory*

07/2022 – 11/2022

Hierarchical decision-making process by recognizing semantically meaningful clues.

RLLAB, SNU

### Text-VLAD | *CV, Visual Localization*

09/2021 – 12/2021

Visual localization using text and visual features

RLLAB, SNU

### Influence based Reward for Communicative Multi-Agent Reinforcement Learning

03/2021 – 07/2021

Giving rewards based on credit assignment among multi agents

RLLAB, SNU

<b>Video Inference for Human Motion with Texture Generation</b>   <i>CV, Motion Estimation</i> <i>Reconstruction of 3D multi-view video from 2D human motion video</i>	08/2020 – 12/2020 RLLAB, SNU
<b>Visual Navigation in Gibson Env2 Environment</b>   <i>RL, Visual Navigation</i> <i>Implementing robust path following of robots in Gibson simulator</i>	02/2020 – 07/2020 RLLAB, SNU
<b>UP-CARE (Use your Phone Camera for Health and Environment)</b>   <i>HRI, CV</i> <i>Fall detection for elderly using phone camera based on human pose estimation</i>	01/2020 – 01/2020 San Jose Univ., CA, US
<b>Scrupulous Robot Cleaner with Mecanum Wheels and Pointed-shaped Inlet</b>   <i>HRI</i> <i>Omnidirectional robot cleaner with autonomous &amp; hand-motion controlled modes</i>	03/2019 – 11/2019 STEM, SNU

## TEACHING EXPERIENCE

<b>Teaching Assistant, Introduction to Intelligent Systems (English Lecture)</b> <i>Head TA for 2022 Spring Lecture.</i> <i>Managed RC car racing projects and taught students how to use ROS and Gazebo</i>	09/2021 – 06/2022 SNU, Korea
<b>Major Tutor, Signals and Systems</b> <i>Tutoring for Seoul National University ECE major subject</i>	03/2021 – 08/2021 SNU, Korea
<b>Undergraduate Teaching Assistant, Introduction to Circuit Theory and Laboratory</b> <i>Supported and guided students to conduct electric circuit experiments</i>	03/2019 – 06/2019 SNU, Korea
<b>Tutor, Basic Calculus</b> <i>Taught Basic Calculus 1, 2, and Basic Calculus for Biological Science.</i>	03/2018 – 12/2020 SNU, Korea

## AWARDS

<b>Lecture-Research Support Scholarship</b> , Full tuition for 2022 Spring, SNU	03/2022
<b>Grand Prize</b> , Silicon Valley Innovation and Startup Program, San Jose State University	01/2020
<b>1st Prize</b> , International Capstone Design Fair, Korea University Innovation Hub Center	11/2019
<b>2nd Prize</b> , SNU College of Engineering Creative Design Fair, SNU College of Engineering	09/2019
<b>Gold Medal</b> , University Students Contest of Mathematics, Korean Mathematical Society	11/2018

## HONORS AFFILIATION AND TRAINING

MIT xPRO Robotics Essentials, Massachusetts Institute of Technology	05/2022 - 07/2022
SNU Tomorrow's Edge Membership (STEM), SNU College of Engineering Honor Society <i>Selects 30 outstanding students from Seoul National University's Engineering College annually since 2010.</i> • 10 <sup>th</sup> President (07/2019 - 06/2020)	04/2019 – Present
Machine Learning Theory Korea	03/2022 – Present
TODAM BOSTON, Global networking club with international graduate students	09/2020 – 12/2021
NorthEast Asia SRT (Student Round Table), International communication partnership	08/2019

## INVITED TALK

<b>UW Computer Science Department</b> <i>Promptable Behaviors: Personalizing Multi-Objective Rewards from Human Preferences</i>	12/2023
<b>CMU Language Technologies Institute</b> <i>Leveraging Human Knowledge to Robots through Interaction: from Vision to Language and Beyond</i>	08/2023

## COMMUNITY INVOLVEMENT

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### **SNU Vision Mentoring**

*Mentoring high school and undergraduate students interested in engineering and science*

07/2019–02/2022

SNU, Korea

### **Blended Science Festival: Motion controlled Robot Cleaner Experience**

*Provided hands-on experience for students to interact with a robot cleaner.*

10/2019

Seoul Science Park, Korea

### **PURME Foundation NEXON Children's Rehabilitation Hospital**

*Assisted disabled children with rehabilitation.*

03/2017–10/2017

Seoul, Korea

## EXTRACURRICULAR ACTIVITIES

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### **Orchestra Club Activities | Violin**

*Seoul National University Philharmonic Orchestra | Violin*

*Music Fountain : Orchestra club in Daejeon Science High School for the Gifted | Concertmaster, 1<sup>st</sup> Violin*

2014 - 2020

## SKILLS

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**Programming:** Python, C/C++, MATLAB, Arduino, OpenGL

**Patent:** Envelope with built-in sieve (**KR20140003720U**, 06/2014)

**Languages:** Korean (native fluency), English (full-professional proficiency)