

Recordatori: grup simètric permetrems

$$f \in S_p(E) \Leftrightarrow \forall s \in \mathcal{S}_p \quad sf = f$$

$$f \in A_p(E) \Leftrightarrow \forall s \in \mathcal{S}_p \quad sf = -f$$

$\text{car } K \neq 2$

$$\stackrel{\text{Ejerciciu}}{=} f(\dots, v_i, \dots, v_j, \dots) = -f(\dots, v_j, \dots, v_i, \dots) \Leftrightarrow f(\dots, w, \dots, w, \dots) = 0$$

$$\Rightarrow f(\dots, w, \dots, w, \dots) \stackrel{\text{w.p.}}{=} -f(\dots, w, \dots, w, \dots)$$

$$\Rightarrow 2f(\dots, w, \dots, w, \dots) = 0 \stackrel{\text{car } K \neq 2}{\Rightarrow} f(\dots, w, \dots, w, \dots) = 0$$

$$\Leftrightarrow (\dots, v_i + v_j, \dots, v_i + v_j, \dots) \stackrel{\text{w.p.}}{=} 0$$

$$\Rightarrow \underbrace{f(\dots, v_i, \dots, v_i)}_{=0} + \underbrace{f(\dots, v_j, \dots, v_j)}_{=0} + \underbrace{f(\dots, v_i, \dots, v_j)}_{=0} + \underbrace{f(\dots, v_j, \dots, v_i)}_{=0}$$

$$f(\dots, v_i, \dots, v_j, \dots) = -f(\dots, v_j, \dots, v_i, \dots)$$

Ejemplos:

$$(1) T_2(E) \ni f \text{ (forma bilineal)} \rightarrow M_B(f) = A = (f(e_i, e_j))$$

$$B = \{e_1, \dots, e_n\} \text{ base}$$

$$\mathcal{S}_2 = \{I, s = (1, 2)\} \quad \begin{cases} If = f \\ sf = -f \end{cases}$$

$$E(I) = 1 \quad E(s) = -1 \quad sf \rightarrow M_B(sf) = (sf) =$$

$$= (sf(e_i, e_j)) =$$

$$= (f(e_j, e_i)) =$$

$$= A^t$$

► En formas bilineales:

$$f \text{ simétrica} \Leftrightarrow A = A^t \Leftrightarrow A \text{ simétrica.}$$

$$f \text{ antisimétrica} \Leftrightarrow A^t = -A \Leftrightarrow A \text{ antisimétrica}$$

$$\uparrow \text{ diagonal} = 0,$$

(2) $\dim E = n$

$B = \{e_1, \dots, e_n\}$

$E \times \dots \times E \xrightarrow{f} K$

$(u_1, \dots, u_n) \mapsto \det(u_1, \dots, u_n)_B$

• f multilineal ($\Rightarrow f \in T_n(E)$)

• f antisimétrico porque $\det_B(\dots, u_i, \dots, u_j, \dots) = -\det_B(\dots, u_j, \dots, u_i, \dots)$

(Podemos cambiar "un poco" un tensor para que sea simétrico o antisimétrico)

Def Sea E un K -ev.; sea $f \in T_p(E)$ (sup $\text{car } K = 0$)

$$S(f) = \frac{1}{p!} \sum_{s \in S_p} s f$$

(simetrizado de f)

$$A(f) = \frac{1}{p!} \sum_{s \in S_p} \epsilon(s) s f$$

Antisimetrizado de f .

Ejemplos. $E = \mathbb{R}^3$ $B = \{e_1, e_2, e_3\}$

(1) $f = e_1^* \otimes e_2^* \in T_2(E)$

$S(f) = \frac{1}{2} (e_1^* \otimes e_2^* + e_2^* \otimes e_1^*)$

$S_2 = \{I, s = (1, 2)\}$

$A(f) = \frac{1}{2} (e_1^* \otimes e_2^* - e_2^* \otimes e_1^*)$

(2) $g = e_1^* \otimes e_2^* \otimes e_3^*$

$S(g) = \frac{1}{6} (s_1 g + s_2 g + s_3 g + s_4 g + s_5 g + s_6 g) = (\#)$

$S_3 = \{I, (1, 2), (1, 3), (2, 3), (1, 2, 3), (1, 3, 2)\}$

$\begin{matrix} \downarrow & \downarrow & \downarrow & \downarrow & \downarrow & \downarrow \\ s_1 & s_2 & s_3 & s_4 & s_5 & s_6 \end{matrix}$

$\epsilon(s) = \begin{matrix} 1 & -1 & -1 & -1 & 1 & 1 \end{matrix}$

$$S_1^{-1} = S_1$$

$$S_3^{-1} = S_3$$

$$S_5^{-1} = S_5$$

$$S_2^{-1} = S_2$$

$$S_4^{-1} = S_4$$

$$S_6^{-1} = S_5$$

$$(\#) = \frac{1}{6} (e_1^* \otimes e_2^* \otimes e_3^* + e_2^* \otimes e_1^* \otimes e_3^* + e_3^* \otimes e_2^* \otimes e_1^* + e_1^* \otimes e_3^* \otimes e_2^* + e_3^* \otimes e_1^* \otimes e_2^* + e_2^* \otimes e_3^* \otimes e_1^*)$$

(3) E $f \in T_2(E)$ (forma bilineal) \leftarrow tensor de orden 2

B base $A = M_B(f) = (f(e_i, e_j))$

$$M_B(S(f)) = \frac{1}{2} (A + A^t) \quad (\text{hacer el promedio con } A^t)$$

$$M_B(A(f)) = \frac{1}{2} (A - A^t)$$

Obs $f = S(f) + A(f)$ \leftarrow Solo para tensores de orden 2

(+ detalles en Problemas)

Prop. E K-RV

$$T_p(E) \xrightarrow[\text{Antisimetrizar}]{\text{Simetrizar}} T_p(E)$$

(0) S, A son lineales

$$(1) f \in S_p(E) \Rightarrow S(f) = f$$

$$f \in A_p(E) \Rightarrow S(f) = f$$

$$(2) \text{Im } S = S_p(E)$$

$$\text{Im } A = A_p(E)$$

Dem (0) Trivial, por def de S y A .

(1) $S_p(E) \rightarrow e_j$ $f \in A_p(E)$

$$|A_p(E)| \quad A(f) = \frac{1}{p!} \left(\sum_{s \in S_p} \epsilon(s) \cdot s f \right) \stackrel{f \in A_p(E)}{=} \frac{1}{p!} \sum_{s \in S_p} \epsilon(s) (\epsilon(s) f)$$

$$= \frac{1}{p!} \sum_{s \in S_p} \epsilon(s)^2 f = f$$

(2) $\text{Im } S = S_p(E)$ Ejercicio

$$\boxed{\text{Im } A = A_p(E)} \quad (\Delta) \quad \text{fes lo imagen de el mismo}$$

$$\supseteq \quad \text{Si } f \in A_p(E) \Rightarrow f = A(f) \Rightarrow f \in \text{Im } A.$$

$$\subseteq \quad \text{Sea } g = A(h) \in \text{Im } A$$

Hemos que ver que $g \in A_p(E)$

$$\text{Sea } s \in S_p$$

$$\underline{s} \cdot g = \underline{s} \cdot \left(\frac{1}{p!} \sum_{r \in S_p} \varepsilon(r) \underline{r} h \right) \quad \begin{matrix} s \text{ es lineal} \\ \downarrow \end{matrix}$$

$$= \frac{1}{p!} \left(\sum_{r \in S_p} \varepsilon(r) \underline{s} \underline{r} h \right) \overset{\substack{\underline{s} \underline{r} = \underline{s r} \\ \varepsilon(s)^2 = 1 \\ \varepsilon(s r) = \varepsilon(s) \varepsilon(r)}}{=} \varepsilon(s) \cdot \frac{1}{p!} \left(\sum_{r \in S_p} \varepsilon(s r) \cdot \underline{s r} h \right) =$$

$$\overset{\uparrow}{=} \varepsilon(s) \left(\frac{1}{p!} \sum_{t \in S_p} \varepsilon(t) \cdot \underline{t} h \right) = \varepsilon(s) g \Rightarrow g \in A_p(E) \quad \text{reordenaci3 d'6ndexos}$$

Obs $S_p \xrightarrow{\phi} S_p$ (s fije)
 $r \mapsto sr$ biyectiva

$$\{r \in S_p\} = \{sr \in S_p\} = \{t \in S_p\}$$

Recorda: En lloc de calcular les transposicions de una permutaci3 per a obtenir el signe de la permutaci3, podem fer el següent:

$$s = (1, 2, 3) = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}$$

transposicions

$$\text{fem: } \Rightarrow \det \begin{pmatrix} 1 & 2 & 3 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} = \varepsilon(s)$$

$$\varepsilon(s) = (-1)^{\# \text{ transposicions}}$$