



Sharif University of Technology

CE Department

Course: Stochastic Processes

PS. 4

Amirhossein Abedi

Student num. 99105594

# 1

## 1.1 a

First we need to find  $S_x(w)$ :

$$\begin{aligned}
S_x(w) &= \int_{-\infty}^{\infty} 2e^{-\frac{|\tau|}{\alpha}} e^{-jw\tau} d\tau \\
&= \int_{-\infty}^0 2e^{-\frac{-\tau}{\alpha}} e^{-jw\tau} d\tau + \int_0^{\infty} 2e^{-\frac{\tau}{\alpha}} e^{-jw\tau} d\tau \\
&= \frac{2}{\frac{1}{\alpha} + jw} + \frac{2}{\frac{1}{\alpha} - jw} = \frac{\frac{4}{\alpha}}{\frac{1}{\alpha^2} + w^2}
\end{aligned}$$

Define  $a = \frac{1}{\alpha}$  :

$$S_x(w) = \frac{4a}{a^2 + w^2}$$

We can substitute  $a$  later.

Then we need to find  $|H(w)|^2$ :

$$\begin{aligned}
H(w) &= 1 + \frac{e^{-2jw}}{2} \quad , \quad H^*(w) = 1 + \frac{e^{2jw}}{2} \\
\rightarrow |H(W)|^2 &= (1 + \frac{e^{-2jw}}{2})(1 + \frac{e^{2jw}}{2}) = \frac{5}{4} + \frac{e^{-2jw}}{2} + \frac{e^{2jw}}{2}
\end{aligned}$$

Knowing that  $S_y(w) = S_x(w)|H(w)|^2$ :

$$S_y(w) = \frac{5}{2} \times \frac{2a}{a^2 + w^2} + e^{-2jw} \times \frac{2a}{a^2 + w^2} + e^{2jw} \times \frac{2a}{a^2 + w^2}$$

Note that:

$$\mathcal{F}\{\delta(a + \tau)\} = e^{ajw} \quad \rightarrow \quad \delta(a + \tau) = \mathcal{F}^{-1}\{e^{ajw}\}$$

And for positive  $a$ :

$$\mathcal{F}\{e^{-a|\tau|}\} = \frac{2a}{a^2 + w^2} \quad \rightarrow \quad e^{-a|\tau|} = \mathcal{F}^{-1}\{\frac{2a}{a^2 + w^2}\}$$

Then  $R_y$  is given by:

$$\begin{aligned}
R_y(\tau) &= \frac{5}{2}e^{-a|\tau|} + \delta(\tau + 2) * e^{-a|\tau|} + \delta(\tau - 2) * e^{-a|\tau|} \\
\rightarrow R_y(\tau) &= \frac{5}{2}e^{-a|\tau|} + e^{-a|\tau+2|} + e^{-a|\tau-2|}
\end{aligned}$$

## 1.2 b

In an LTI system defined by impulse response  $h(t)$ , output signal in a given point is a linear combination of the input signal.

$$y(t) = \int_{-\infty}^{\infty} h(t - \alpha)x(\alpha) d\alpha$$

Here we can see  $h(t - \alpha)$  as the coefficient of  $x(\alpha)$  in  $y(t)$ . Then because any linear summation of jointly normal random variables is also jointly normal, then any subset of  $y$  is jointly normal. Thus  $y(t)$  is a gaussian process.

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## 2

### 2.1 a

Define  $\Phi_3$  as:

$$\Phi_3(x) = \begin{bmatrix} \Phi_1(x) \\ \Phi_2(x) \end{bmatrix}$$

Then

$$\Phi_3(x)^T \Phi_3(y) = \Phi_1(x)^T \Phi_1(y) + \Phi_2(x)^T \Phi_2(y) = K_3(x, y)$$

So there exists  $\Phi$  s.t  $K_3(x, y) = \Phi(x)^T \Phi(y)$  so  $k_3$  is a valid kernel.

### 2.2 b

First suppose that  $\Phi_1$  and  $\Phi_2$  are as below:

$$\Phi_1 = \begin{bmatrix} \Phi_{11} \\ \vdots \\ \Phi_{1n} \end{bmatrix}$$

$$\Phi_2 = \begin{bmatrix} \Phi_{21} \\ \vdots \\ \Phi_{2m} \end{bmatrix}$$

Then define  $\Phi_3 \in \mathcal{R}^{m \times n}$  as:

$$\Phi_3(x) = \begin{bmatrix} \Phi_{11}(x) \begin{bmatrix} \Phi_{21}(x) \\ \vdots \\ \Phi_{2m}(x) \end{bmatrix} \\ \vdots \\ \Phi_{1n}(x) \begin{bmatrix} \Phi_{21}(x) \\ \vdots \\ \Phi_{2m}(x) \end{bmatrix} \end{bmatrix}$$

$$\begin{aligned} \rightarrow \Phi_3(x)^T \Phi_3(y) &= \sum_{i=1}^n \sum_{j=1}^m \Phi_{1i}(x) \Phi_{1i}(y) \Phi_{2j}(x) \Phi_{2j}(y) = \left( \sum_{i=1}^n \Phi_{1i}(x) \Phi_{1i}(y) \right) \left( \sum_{j=1}^m \Phi_{2j}(x) \Phi_{2j}(y) \right) \\ &= \Phi_1(x)^T \Phi_1(y) \times \Phi_2(x)^T \Phi_2(y) = K_3(x, y) \end{aligned}$$

Then  $k_1 \times k_2$  is also valid.

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### 2.3 c

From (b) we know that if  $k_1$  and  $k_2$  are valid kernels then  $k_1 \times k_2$  is also valid. By induction for any  $n \geq 1$  if  $k_1$  is valid then  $k_1^n$  is valid. Also note that if  $k_1$  is valid then for a positive  $c$ ,  $ck_1$  is also valid. We can prove this by defining  $\Phi = \sqrt{c}\Phi_1$ .

Also from (a) we know that  $\sum k_i$  is a valid kernel. Then the following kernel would be valid:

$$1 + \sum_{i=1}^n \frac{k_1^i}{i!} = e^{k_1}$$

## 3

### 3.1 a

Define  $N(t_1, t_2)$  as the events between  $t_1$  and  $t_2$  and  $N(t_1)$  as the events between 0 and  $t_1$ . First suppose that  $t_1 \leq t_2$ .

$$\begin{aligned} \text{Cov}(N(t_1), N(t_2)) &= \mathbb{E}[N(t_1) \times (N(t_1) + N(t_1, t_2))] - \mathbb{E}[N(t_1)]\mathbb{E}[N(t_2)] = \mathbb{E}[N^2(t_1)] + \mathbb{E}[N(t_1, t_2)N(t_1)] - \mathbb{E}[N(t_1)]\mathbb{E}[N(t_2)] \\ &= \lambda t_1 + \lambda^2 t_1^2 + \lambda^2 (t_2 - t_1)t_1 - \lambda^2 t_2 t_1 = \lambda t_1 \end{aligned}$$

For the general case:

$$\text{Cov}(t_1, t_2) = \lambda \min(t_1, t_2)$$

It is clear that this process is not W.S.S. Additionally  $\mu_N(t) = \lambda t$ .

### 3.2 b

Without Loss of generality suppose that  $t_1 \leq t_2$ :

$$\begin{aligned} \mathbb{P}[N(t_1) = n, N(t_2) = m] &= \mathbb{P}[N(t_1) = n, N(t_1, t_2) = m - n] = e^{-\lambda t_1} \times \frac{(\lambda t_1)^n}{n!} \times e^{-\lambda(t_2 - t_1)} \frac{(\lambda(t_2 - t_1))^{(m-n)}}{(m-n)!} \\ &= e^{-\lambda t_2} \times \frac{(\lambda t_1)^n}{n!} \times \frac{(\lambda(t_2 - t_1))^{(m-n)}}{(m-n)!} \end{aligned}$$

### 3.3 c

Just like the previous section,

$$\begin{aligned} \mathbb{P}[N(t_0) = a_0, \dots, N(t_n) = a_n] &= \mathbb{P}[N(t_0) = a_0, N(t_0, t_1) = a_1 - a_0, \dots, N(t_{n-1}, t_n) = a_n - a_{n-1}] \\ &= e^{-\lambda t_0} \times \frac{(\lambda t_0)^{a_0}}{a_0!} \times e^{-\lambda(t_1 - t_0)} \frac{(\lambda(t_1 - t_0))^{(a_1 - a_0)}}{(a_1 - a_0)!} \dots \times e^{-\lambda(t_n - t_{n-1})} \frac{(\lambda(t_n - t_{n-1}))^{(a_n - a_{n-1})}}{(a_n - a_{n-1})!} \\ &= e^{-\lambda t_n} \times \frac{(\lambda t_0)^{a_0}}{a_0!} \times \frac{(\lambda(t_1 - t_0))^{(a_1 - a_0)}}{(a_1 - a_0)!} \dots \times \frac{(\lambda(t_n - t_{n-1}))^{(a_n - a_{n-1})}}{(a_n - a_{n-1})!} \end{aligned}$$


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### 3.4 d

Now substitute  $a_0 = a, a_n = a + nk$  and  $t_i = t + in$ :

$$\begin{aligned} f(a_0, \dots, a_n) &= e^{-\lambda(t+n^2)} \frac{(\lambda t)^a}{a!} \times \frac{(\lambda n)^{(a_1-a_0)}}{(a_1-a_0)!} \cdots \times \frac{(\lambda n)^{(a+nk-a_{n-1})}}{(a+nk-a_{n-1})!} \\ &= e^{-\lambda t} (e^{-\lambda n})^n \times \frac{(\lambda n)^{nk}}{(a_1-a)! \cdots (a+nk-a_{n-1})!} \end{aligned}$$

Now define  $d_i = a_i - a_{i-1}$  ( $i \in \{1, \dots, n\}$  and  $d_i \in \mathcal{N} \cup \{0\}$ ) such that  $\sum_i d_i = nk$ . Then we have:

$$\text{Argmax}_{a_1, \dots, a_{n-1}} f(a, a_1, \dots, a_{n-1}, a + nk) \propto \text{Max}_{d_1, \dots, d_n} \frac{1}{\prod_i d_i!} \quad \text{s.t.} \quad \sum_i d_i = nk$$

So we need to find:

$$\text{Argmax}_{d_1, \dots, d_n} \frac{1}{\prod_i d_i!} \quad , \quad \sum_i d_i = nk$$

Or:

$$\text{Argmin}_{d_1, \dots, d_n} \prod_i d_i! \quad , \quad \sum_i d_i = nk$$

#### 3.4.1 Claim:

The minimum occurs in  $d_1 = d_2 = \dots = k$ .

#### 3.4.2 Proof:

Suppose that  $d_i < k < d_j$  for some  $i \neq j$ . (Note that if no such  $i, j$  exist then all  $d_i$ 's are equal to  $k$ ).

Define the function that we want to minimize as  $g$ .  $g(d_1, \dots, d_n) = \prod_i d_i!$ . Then it's trivial to see that  $\frac{g(d_1, \dots, d_i+1, \dots, d_j-1, \dots, d_n)}{g(d_1, \dots, d_i, \dots, d_j, \dots, d_n)} = \frac{d_i+1}{d_j} < 1$ . This means that the minimizer of the function  $g$  can not happen where there exists  $i, j$  such that  $d_i < k < d_j$ . Meaning that for all  $d_i, d_i = k$ .

So we have:

$$a_i = a + ik$$

### 3.5 e

$$N(4) = N(0, 3) + N(3, 4) \quad , \quad N(0, 3) \sim \text{Pois}(3\lambda), N(3, 4) \sim \text{Pois}(\lambda)$$

$$N(5) - N(3) = N(3, 4) + N(4, 5) \quad , \quad N(3, 4) \sim \text{Pois}(\lambda), N(4, 5) \sim \text{Pois}(\lambda)$$

Conditioning on  $N(3, 4)$  we can write:

$$\begin{aligned} \mathbb{P}[N(4) < 3, N(5) - N(3) > 3] &= \mathbb{P}[N(0, 3) < 3] \mathbb{P}[N(4, 5) > 3] \mathbb{P}[N(3, 4) = 0] \\ &+ \mathbb{P}[N(0, 3) < 2] \mathbb{P}[N(4, 5) > 2] \mathbb{P}[N(3, 4) = 1] + \mathbb{P}[N(0, 3) < 1] \mathbb{P}[N(4, 5) > 1] \mathbb{P}[N(3, 4) = 2] \\ &= \left( \sum_{k=0}^2 e^{-3\lambda} \frac{(3\lambda)^k}{k!} \right) \left( 1 - \sum_{k=0}^3 e^{-\lambda} \frac{(\lambda)^k}{k!} \right) (e^{-\lambda}) (e^{-\lambda}) + \left( \sum_{k=0}^1 e^{-3\lambda} \frac{(3\lambda)^k}{k!} \right) \left( 1 - \sum_{k=0}^2 e^{-\lambda} \frac{(\lambda)^k}{k!} \right) (e^{-\lambda}) (e^{-\lambda}(\lambda)) \\ &\quad + \left( \sum_{k=0}^0 e^{-3\lambda} \frac{(3\lambda)^k}{k!} \right) \left( 1 - \sum_{k=0}^1 e^{-\lambda} \frac{(\lambda)^k}{k!} \right) (e^{-\lambda}) (e^{-\lambda} \frac{(\lambda)^2}{2!}) \end{aligned}$$

## 4

### 4.1 a

$$2X_t \sim \mathcal{N}(0, 0)$$

$$\rightarrow \mathbb{P}[X = 0] = 1$$

$$\text{Cov}(X_t, X_s) = \frac{\text{Cov}(X_t + X_s, X_t + X_s) - \text{Cov}(X_t, X_t) - \text{Cov}(X_s, X_s)}{2}$$

Note that  $X_t + X_s \sim \mathcal{N}(0, \sqrt{|t-s|})$ .

$$\text{Cov}(X_t, X_s) = \frac{\sqrt{|t-s|} - 0 - 0}{2} = \frac{\sqrt{|t-s|}}{2}$$

### 4.2 b

Because  $X_{t_1}, \dots, X_{t_n}$  are jointly normal then the pdf is given by:

$$X_{t_1}, \dots, X_{t_n} \sim \mathcal{N}(0, \Sigma)$$

$$\rightarrow f_{X_{t_1}, \dots, X_{t_n}}(x_1, \dots, x_n) = \frac{1}{(2\pi)^{\frac{n}{2}} |\Sigma|^{\frac{1}{2}}} e^{\frac{1}{2} x^T \Sigma^{-1} x}$$

And the Sigma matrix is given by:

$$\Sigma_{ij} = \text{Cov}(X_{t_i}, X_{t_j})$$

### 4.3 c

This process doesn't exist because if a random variable takes with  $c$  with probability 1, then it should be independent of any other random variables. Here for every  $t$ ,  $X_t$  takes value 0 with probability 1. So it should be independent of any other  $X_{t'}$  but we saw that  $\text{Cov}(X_t, X_{t'}) \neq 0$  for  $t \neq t'$ . So this process can not exist.

## 5

### 5.1 a

Define  $T_1$  as the time of the first maintenance (  $T_1 \sim \exp(\mu)$  ). Then:

$$\mathbb{P}[\text{Break down before first maintenance}] = \mathbb{P}[T_1 > h] = 1 - (1 - e^{-\mu h}) = e^{-\mu h}$$


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## 5.2 b

Define  $N$  as the number of maintenances before break down. Also define  $X$  as the time before the first maintenance.

$$\mathbb{E}[X|N = n] = \mathbb{E}[h + \sum_{i=1}^n T_i] \quad , \quad T_i \sim \exp(\mu)$$

$$\mathbb{E}[X|N = n] = h + \frac{n}{\mu}$$

Now with conditional expectation we can find  $\mathbb{E}[X]$ . Note that  $N$  has geometric distribution. Because each  $T_i$  is greater than  $h$  with probability  $= e^{-\mu h}$  which is a bernouli trial. So the number of maintenances before a break down is  $\text{Geo}(e^{-\mu h})$

$$\mathbb{E}[X] = \mathbb{E}_N[\mathbb{E}_X[X|N]] = \mathbb{E}_N[h + \frac{N}{\mu}] = h + \frac{\mathbb{E}[N]}{\mu}$$

We also know that  $\mathbb{E}[\text{Geo}(p)] = \frac{1-p}{p}$ . Then:

$$\mathbb{E}[X] = h + \frac{1 - e^{-\mu h}}{\mu e^{-\mu h}}$$

## 5.3 c

Define  $X_{\text{on}}^{(i)}$  as the i'th time interval that the machine is on and  $X_{\text{off}}^{(i)}$  as the i'th interval the machine is off.  $X_{\text{on}}$  is the total time that the machine is on and  $X_{\text{off}}$  is the total time that the machine is off. Suppose that a total of  $n$  off's and on's have happened:

$$\text{Proportion of on} = \frac{\mathbb{E}[X_{\text{on}}]}{\mathbb{E}[X_{\text{on}} + X_{\text{off}}]} = \frac{\mathbb{E}[X_{\text{on}}^{(1)}]}{\mathbb{E}[X_{\text{on}}^{(1)} + X_{\text{off}}^{(1)}]}$$

From the previous section (b) we know that:

$$\mathbb{E}[X_{\text{on}}^{(1)}] = h + \frac{1 - e^{-\mu h}}{\mu e^{-\mu h}}$$

Also  $X_{\text{off}}^{(1)} \sim \exp(\lambda)$ .

$$\mathbb{E}[X_{\text{off}}^{(1)}] = \frac{1}{\lambda}$$

$$\text{Proportion of on} = \frac{\mathbb{E}[X_{\text{on}}^{(1)}]}{\mathbb{E}[X_{\text{on}}^{(1)} + X_{\text{off}}^{(1)}]} = \frac{h + \frac{1 - e^{-\mu h}}{\mu e^{-\mu h}}}{h + \frac{1 - e^{-\mu h}}{\mu e^{-\mu h}} + \frac{1}{\lambda}}$$

## 6

Suppose that we are in car 1 (C1) and we are currently in the queue to enter station 1. Car 2 is already in station 1. Define the following random variables.

$X_1$  = time spent by C1 in station 1.  $X_2$  = time spent by C1 in station 2.  $Y_1$  = time spent by C2 in station 1.  $Y_2$  = time spent by C2 in station 2.

$$X_1, Y_1 \sim \exp(\lambda_1) \quad , \quad X_2, Y_2 \sim \exp(\lambda_2)$$

First we must wait for  $Y_1$  so that we can enter station 1. Then we must wait for  $\text{Max}(X_1, Y_2)$  to enter station 2. ( Max because by that time both C1 and C2 must have finished their works ). Then we must wait for another  $X_2$  so that we can exit.

The total time spent for C1 is given by:

$$T = Y_1 + \text{Max}(X_1, Y_2) + X_2$$

Distribution of  $Y_1$  and  $X_2$  is known. We need to find the distribution of  $\text{Max}(X_1, Y_2)$ :

$$Z = \text{Max}(X_1, Y_2), \quad F_Z(z) = \mathbb{P}[X_1 \leq z] \mathbb{P}[Y_2 \leq z] = (1 - e^{-\lambda_1 z})(1 - e^{-\lambda_2 z}) = 1 - e^{-\lambda_1 z} - e^{-\lambda_2 z} + e^{-(\lambda_1 + \lambda_2)z}$$

$$\begin{aligned} f_Z(z) &= \lambda_1 e^{-\lambda_1 z} + \lambda_2 e^{-\lambda_2 z} - (\lambda_1 + \lambda_2) e^{-(\lambda_1 + \lambda_2)z} \\ \mathbb{E}[Z] &= \int_0^\infty x(\lambda_1 e^{-\lambda_1 x} + \lambda_2 e^{-\lambda_2 x} - (\lambda_1 + \lambda_2) e^{-(\lambda_1 + \lambda_2)x}) dx \end{aligned}$$

Note that:

$$\int_0^\infty x(\lambda e^{-\lambda x}) dx = \frac{1}{\lambda}$$

Then:

$$\begin{aligned} \mathbb{E}[Z] &= \frac{1}{\lambda_1} + \frac{1}{\lambda_2} - \frac{1}{\lambda_1 + \lambda_2} \\ \rightarrow \mathbb{E}[T] &= \frac{2}{\lambda_1} + \frac{2}{\lambda_2} - \frac{1}{\lambda_1 + \lambda_2} \end{aligned}$$

## 7

### 7.1 a

$G_t$  is the time difference between  $t$  and the last event.  $D_t$  is the time difference between  $t$  and the next event.  $(G_t < x, D_t \leq y)$  means that the time difference between  $t$  and the last event is less than  $x$  and the time difference between  $t$  and the next event is less than or equal to  $y$ . This means that at least one event has occurred in the time interval  $[t - x, t]$  and at least one event has occurred in the time interval  $[t, t + y]$ .

This means that  $N_{t-x} < N_t < N_{t+y}$ . As said earlier  $(G_t < x, D_t \leq y)$  means that at least one event has occurred in the time interval  $[t - x, t]$  and at least one event has occurred in the time interval  $[t, t + y]$ .

$$\begin{aligned} \mathbb{P}[G_t < x, D_t \leq y] &= \mathbb{P}[N(t - x, t) > 0, N(t, t + y) > 0] = \mathbb{P}[N(t - x, t) > 0] \mathbb{P}[N(t, t + y) > 0] \\ &= (1 - e^{-\lambda x})(1 - e^{-\lambda y}) \end{aligned}$$

### 7.2 b

If for a given  $t$ ,  $G_t = t$  ( $T_{N_t} = 0$ ) holds this means that no events have occurred in the interval  $[0, t]$ . ( define  $T_0 = 0$  ). Then  $(G_t = t, D_t \leq y)$  means that no events have occurred in  $[0, t]$  and at least one event has occurred in  $[t, t + y]$ .

$$\mathbb{P}[G_t = t, D_t \leq y] = \mathbb{P}[N(0, t) = 0, N(t, t + y) > 0] = (e^{-\lambda t})(1 - e^{-\lambda y})$$


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### 7.3 c

As discussed,  $(D_t \leq y)$  means that at least one event happens in the interval  $[t, t + y]$ .

$$\mathbb{P}[D_t \leq y] = \mathbb{P}[N(t, t + y) > 0] = 1 - e^{-\lambda y} = F_{D_t}(y)$$

$$f_{D_t}(y) = \lambda e^{-\lambda y} \rightarrow D_t \sim \exp(\lambda)$$

### 7.4 d

$(G_t \leq x)$  for  $x \leq t$ , is equivalent to at least one event happening in the interval  $[t - x, t]$ .

$$F_{G_t}(x) = \mathbb{P}[G_t \leq x] = \mathbb{P}[N(t - x, t) > 0] = 1 - e^{-\lambda x}$$

For  $x > t$ ,  $F_{G_t}(x) = 1$ . Because by definition  $G_t$  is always less than  $t$ .

$$f_{G_t}(x) = \frac{\partial(1 - e^{-\lambda x} + e^{-\lambda x}u(x - t))}{dx} = (\lambda e^{-\lambda x})(1 - u(x - t)) + e^{-\lambda x}\delta(x - t)$$

### 7.5 e

$$T_1 \sim \exp(\lambda) \quad , \quad X = \text{Min}(T_1, t)$$

$$F_X(x) = \begin{cases} 1 & \text{if } x \leq t \\ 1 - e^{-\lambda x} & \text{O.W} \end{cases}$$

$$F_X(x) = 1 - e^{-\lambda x} + e^{-\lambda x}u(x - t)$$

$$\rightarrow X \sim G_t$$

### 7.6 f

First consider  $x < t$ . We've shown that  $\mathbb{P}[G_t < x, D_t < y] = \mathbb{P}[N(t - x, t) > 0, N(t, t + y) > 0]$  which equals  $\mathbb{P}[N(t - x, t) > 0]\mathbb{P}[N(t, t + y) > 0]$ . This holds because of poisson properties.

$$\mathbb{P}[N(t - x, t) > 0]\mathbb{P}[N(t, t + y) > 0] = \mathbb{P}[G_t < x]\mathbb{P}[D_t < y]$$

So  $G_t$  and  $D_t$  are independent.

### 7.7 g

$$\begin{aligned} \mathbb{E}[G_t] &= \mathbb{E}[\text{Min}(T_1, t)] = \int_0^\infty \text{Min}(T, t) \lambda e^{-\lambda T} dT \\ &= \int_0^t T \lambda e^{-\lambda T} dT + t \lambda \int_t^\infty e^{-\lambda T} dT = \frac{1 - e^{-\lambda t}}{\lambda} \end{aligned}$$

Also note that  $G_t + D_t = T_{N_t+1} - T_{N_t} \sim \exp(\lambda)$ :

$$\mathbb{E}[G_t + D_t] = \frac{1}{\lambda}$$


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