

Real-Time Pose-Based Emote Detection on Raspberry Pi 4

Team VisionMasters

Members: Allen Chen, Marvin
Rivera, Sami Kang





Marvin Rivera
(Team Lead)

Coordination,
Documentation,
Presentation.

Team & Role

Allen Chen
(Hardware)

RPi setup, Camera
integration,
Deployment.



Sami Kang
(Software)

Model training,
Optimization,
Metrics.

Shared Responsibility: Evaluation, Benchmarking,
Data Collection.

Project Motivation & Use Case

The Challenge: Real-time recognition (>10 FPS) on CPU-only hardware.

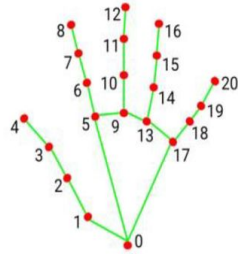
The Use Case: Interactive Gaming/Entertainment.

- *User Pose -> System Detection*
-> *Clash Royale Emote Output.*

Why Edge AI? Privacy, low latency, and offline capability.

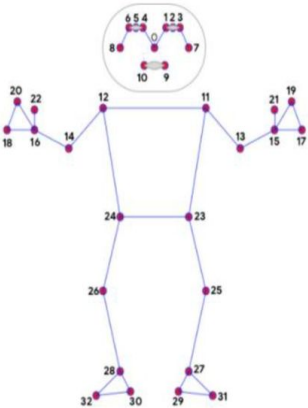


Platform Selection & Methodology



(a)

- 0. Wrist
- 1. Thumb_CMC
- 2. Thumb_MCP
- 3. Thumb_IP
- 4. Thumb_TIP
- 5. Index_finger_MCP
- 6. Index_finger_PIP
- 7. Index_finger_DIP
- 8. Index_finger_TIP
- 9. Middle_finger_MCP
- 10. Middle_finger_PIP
- 11. Middle_finger_DIP
- 12. Middle_finger_TIP
- 13. Ring_finger_MCP
- 14. Ring_finger_PIP
- 15. Ring_finger_DIP
- 16. Ring_finger_TIP
- 17. Pinky_MCP
- 18. Pinky_PIP
- 19. Pinky_DIP
- 20. Pinky_TIP



(b)

- 0. Nose
- 1. Left_eye_inner
- 2. Left_eye
- 3. Left_eye_outer
- 4. Right_eye_inner
- 5. Right_eye
- 6. Right_eye_outer
- 7. Left_ear
- 8. Right_ear
- 9. Mouth_left
- 10. Mouth_right
- 11. Left_shoulder
- 12. Right_shoulder
- 13. Left_elbow
- 14. Right_elbow
- 15. Left_wrist
- 16. Right_wrist
- 17. Left_pinky
- 18. Right_pinky
- 19. Left_index
- 20. Right_index
- 21. Left_thumb
- 22. Right_thumb
- 23. Left_hip
- 24. Right_hip
- 25. Left_knee
- 26. Right_knee
- 27. Left_ankle
- 28. Right_ankle
- 29. Left_heel
- 30. Right_heel
- 31. Left_foot_index
- 32. Right_foot_index

Edge Platform: Raspberry Pi 4 Model B (4GB RAM, Cortex-A72).

Methodology:

1. **Input:** Logitech Brio Webcam (1080p).
2. **Detection:** MediaPipe Holistic (Lite complexity).
3. **Classification:** Random Forest (Scikit-learn).
4. **Output:** Visual Overlay + Audio.



The Comparative Analysis Goal

EDGE (System A)



Raspberry Pi 4
(Constrained, Thermal limits, ARM-based)



Thermal limits



Constrained



ARM-based

WORKSTATION (System B)



MacBook
(High performance, Active cooling, x86/M-series)



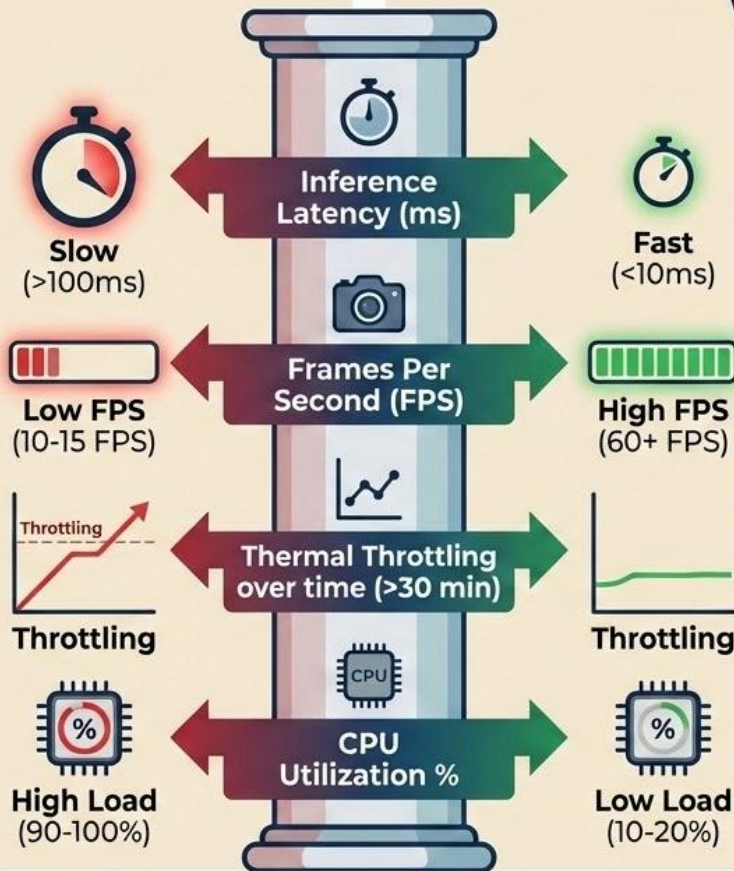
Active cooling



High performance



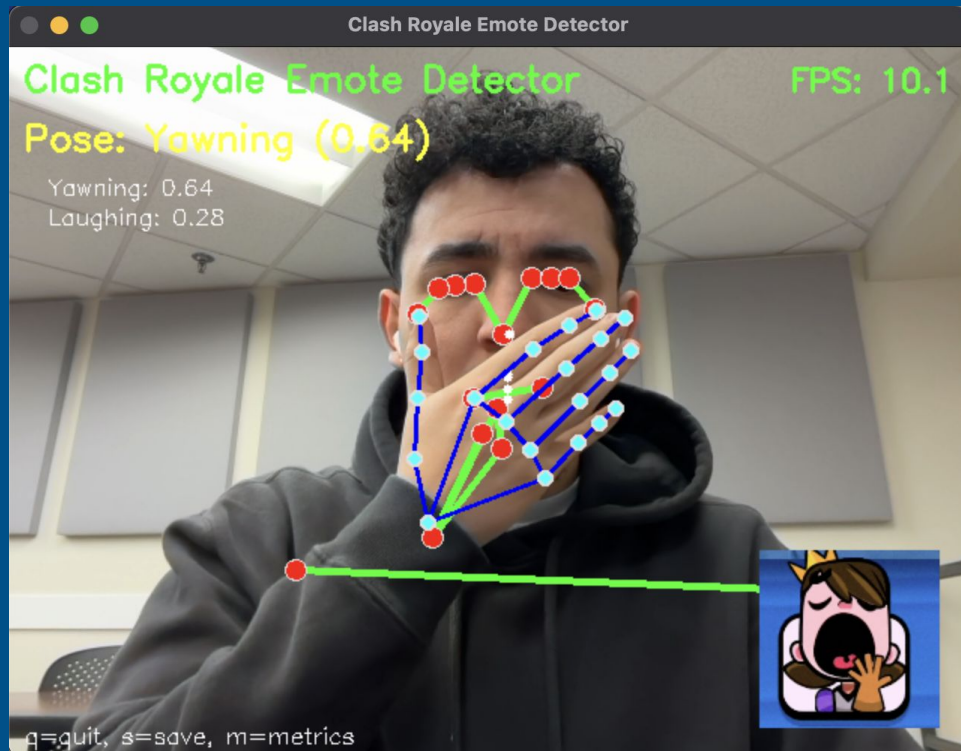
x86/M-series



Current Status (Implementation)

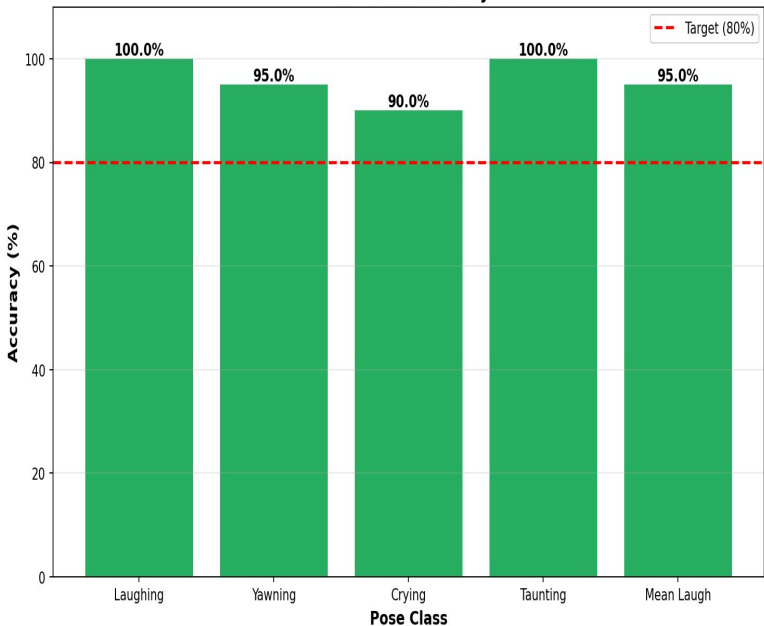
Accomplished:

- Real-time detection running on RPi 4.
- Custom training data collected (~500 samples).
- Interactive display with 5 pose classes (Laughing, Yawning, etc.).
- Metric collection system (FPS, CPU temp) active.



Preliminary Observations

Per-Class Accuracy



Optimization Techniques used so far:

- Reduced Resolution (320x240).
- Model Complexity = 0 (Lite).

Initial Findings:

- Random Forest inference is negligible (<1ms).
- Bottleneck identified: Video rendering and MediaPipe inference.
- Current RPi Performance: ~10-15 FPS (Target met).

Timeline & Next Steps

Remaining Timeline:

- Week 6 (Dec 10): Benchmarking & Analysis (The "MacBook vs Pi" data run).
- Week 7 (Dec 17): Final Presentation & Report.

Upcoming Deliverables:

- Thermal stability charts.
- Latency breakdown graphs.
- Live Demo refinement.

