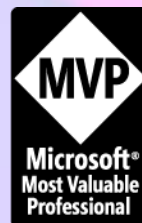


Automatizziamo... con RaspberryPi e .NET



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Sponsor



DEMO



Blazor WEB APP - interactivity server

- "Blazor is a full-stack web UI framework and is recommended for most web UI scenarios."

<https://learn.microsoft.com/en-us/aspnet/core/tutorials/choose-web-ui>

- "Blazor supports interactive server-side rendering (interactive SSR), where UI interactions are handled from the server over a real-time connection with the browser. Interactive SSR enables a rich user experience like one would expect from a client app but without the need to create API endpoints to access server resources."

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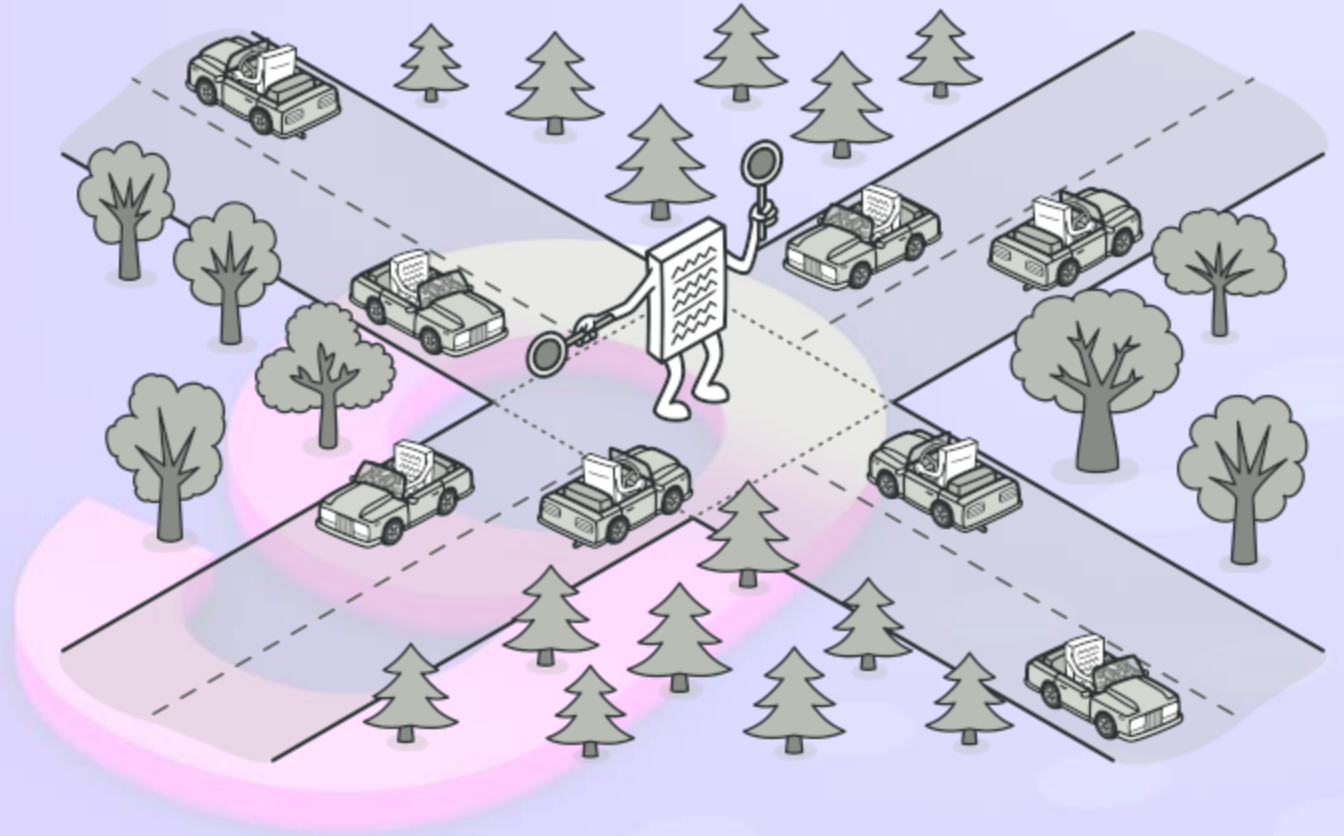
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Mediator pattern

Mediator is a behavioral design pattern that lets you reduce chaotic dependencies between objects. The pattern restricts direct communications between the objects and forces them to collaborate only via a mediator object.



<https://refactoring.guru/design-patterns/mediator>

Mediatr

- "Simple, unambitious mediator implementation in .NET"

<https://github.com/jbogard/MediatR>

- Simple mediator implementation in .NET
- In-process messaging with no dependencies.
- Supports request/response, commands, queries, notifications and events, synchronous and async with intelligent dispatching via C# generic variance.

Complex animation management - workflow-core

- "Lightweight workflow engine for .NET Standard"

<https://github.com/danielgerlag/workflow-core>

- Workflow Core is a lightweight embeddable workflow engine targeting .NET Standard.
- It supports pluggable persistence and concurrency providers to allow for multi-node clusters.
- Fluent API
- JSON / YAML Workflow Definitions

Expose command for third-party integration

- Simplified Integration
 - Standardized communication protocol accessible via HTTP.
- Platform Independence
 - Create API-Rest for expose input and output
 - Enables interaction from anywhere in the network.
- Secure and Controlled Access
 - Use authentication and authorization to manage access to the commands and data.
 - Protect sensitive input/output operations on the Raspberry Pi.
- Ease of Testing and Debugging
 - Use tools like Swagger or Postman to test endpoints directly.

CODE



RASPBERRY PI3 B+

Specification

Processor: Broadcom BCM2837B0, Cortex-A53 64-bit SoC @ 1.4GHz

Memory: 1GB

Connectivity:

- 2.4 GHz and 5 GHz IEEE 802.11b/g/n/ac wireless LAN, Bluetooth 4.2, BLE
- Gigabit Ethernet over USB 2.0 (maximum throughput 300Mbps)
- 4 × USB 2.0 interface

Video and sound:

- 1 x full size HDMI
- MIPI DSI display port
- MIPI CSI camera port
- 4 pole stereo output and composite video port

Multimedia: H.264, MPEG-4 decode (1080p30); H.264 encode (1080p30); OpenGL ES 1.1, 2.0 graphics

SD card support: Micro SD format for loading operating system and data storage

Input Power:

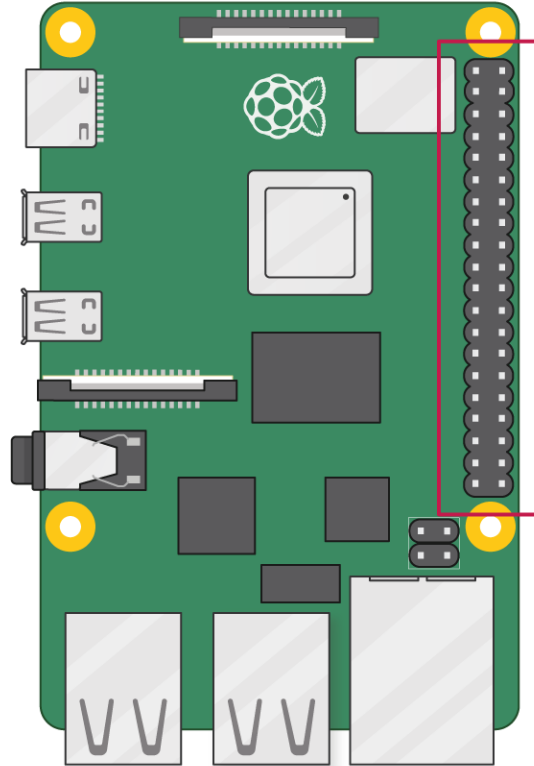
- 5V/2.5A DC via micro USB connector
- 5V DC via GPIO header
- Power over Ethernet (PoE)-enabled (requires separate PoE HAT)

Operating temperature: 0-50°C

Production lifetime: Raspberry Pi 3 Model B+ will remain in production until at least January 2028



RASPBERRY PI3 B+

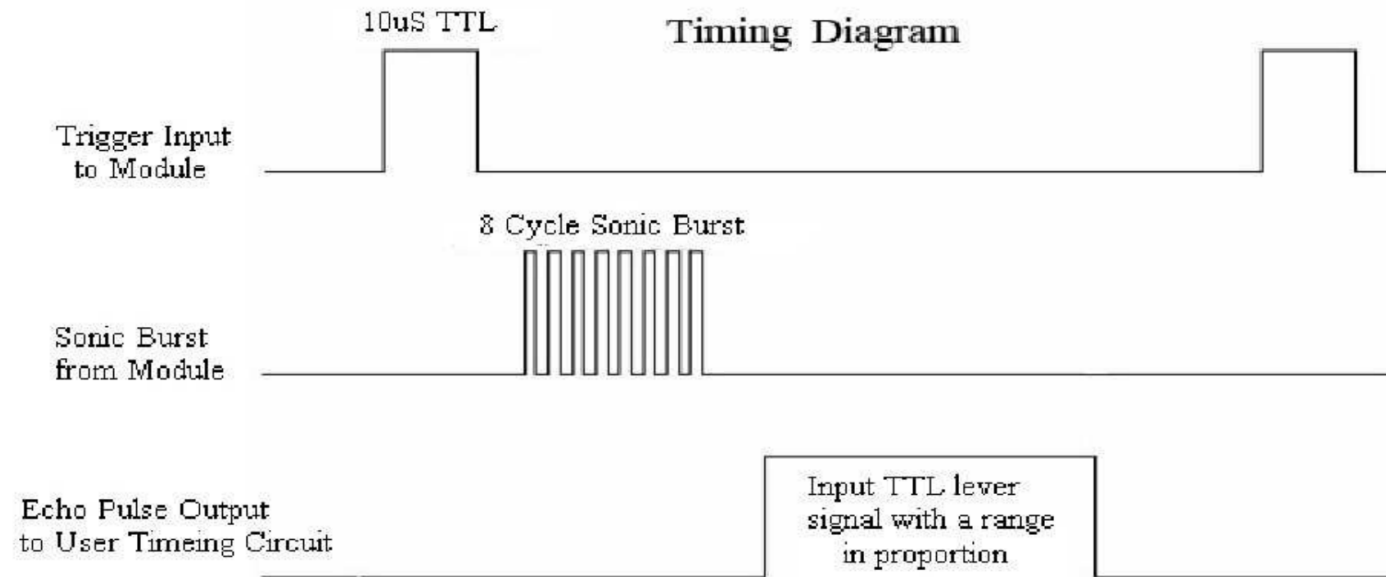


3V3 power	1	2	5V power
GPIO 2 (SDA)	3	4	5V power
GPIO 3 (SCL)	5	6	Ground
GPIO 4 (GPCLK0)	7	8	GPIO 14 (TXD)
Ground	9	10	GPIO 15 (RXD)
GPIO 17	11	12	GPIO 18 (PCM_CLK)
GPIO 27	13	14	Ground
GPIO 22	15	16	GPIO 23
3V3 power	17	18	GPIO 24
GPIO 10 (MOSI)	19	20	Ground
GPIO 9 (MISO)	21	22	GPIO 25
GPIO 11 (SCLK)	23	24	GPIO 8 (CE0)
Ground	25	26	GPIO 7 (CE1)
GPIO 0 (ID_SD)	27	28	GPIO 1 (ID_SC)
GPIO 5	29	30	Ground
GPIO 6	31	32	GPIO 12 (PWM0)
GPIO 13 (PWM1)	33	34	Ground
GPIO 19 (PCM_FS)	35	36	GPIO 16
GPIO 26	37	38	GPIO 20 (PCM_DIN)
Ground	39	40	GPIO 21 (PCM_DOUT)

Ultrasonic Ranging Module HC - SR04



The Timing diagram is shown below. You only need to supply a short 10uS pulse to the trigger input to start the ranging, and then the module will send out an 8 cycle burst of ultrasound at 40 kHz and raise its echo. The Echo is a distance object that is pulse width and the range in proportion. You can calculate the range through the time interval between sending trigger signal and receiving echo signal. Formula: $\mu\text{S} / 58 = \text{centimeters}$ or $\mu\text{S} / 148 = \text{inch}$; or: the range = high level time * velocity (340M/S) / 2; we suggest to use over 60ms measurement cycle, in order to prevent trigger signal to the echo signal.



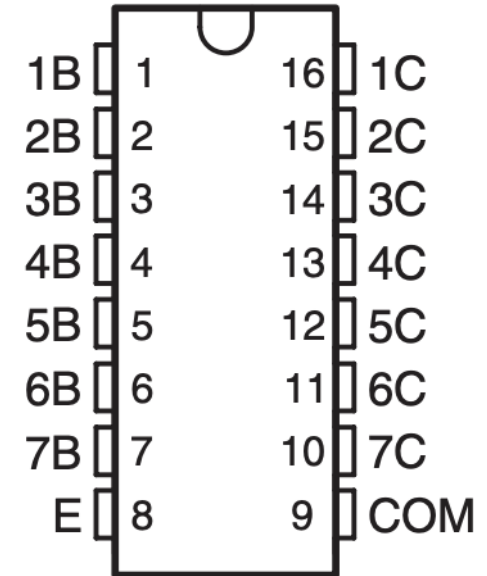
Stepper Motor 5V 4-Phase 5-Wire & ULN2003 Driver Board

FEATURES

- **500-mA-Rated Collector Current (Single Output)**
- **High-Voltage Outputs: 50 V**
- **Output Clamp Diodes**
- **Inputs Compatible With Various Types of Logic**
- **Relay-Driver Applications**



ULN2002A . . . N PACKAGE
ULN2003A . . . D, N, NS, OR PW PACKAGE
ULN2004A . . . D, N, OR NS PACKAGE
ULQ2003A, ULQ2004A . . . D OR N PACKAGE
(TOP VIEW)



Power Supply 15 W 5 V 3 A



15W Single Output Switching Power Supply

RS-15 series



■ Features :

- Universal AC input / Full range
- Protections: Short circuit / Overload / Over voltage / Over temperature
- Cooling by free air convection
- LED indicator for power on
- 100% full load burn-in test
- No load power consumption<0.5W
- All using 105°C long life electrolytic capacitors
- Withstand 300VAC surge input for 5 second
- High operating temperature up to 70°C
- Withstand 5G vibration test
- High efficiency, long life and high reliability
- 3 years warranty

User's Manual



■ GTIN CODE

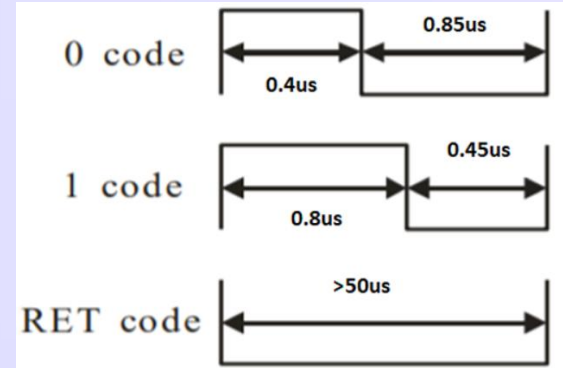
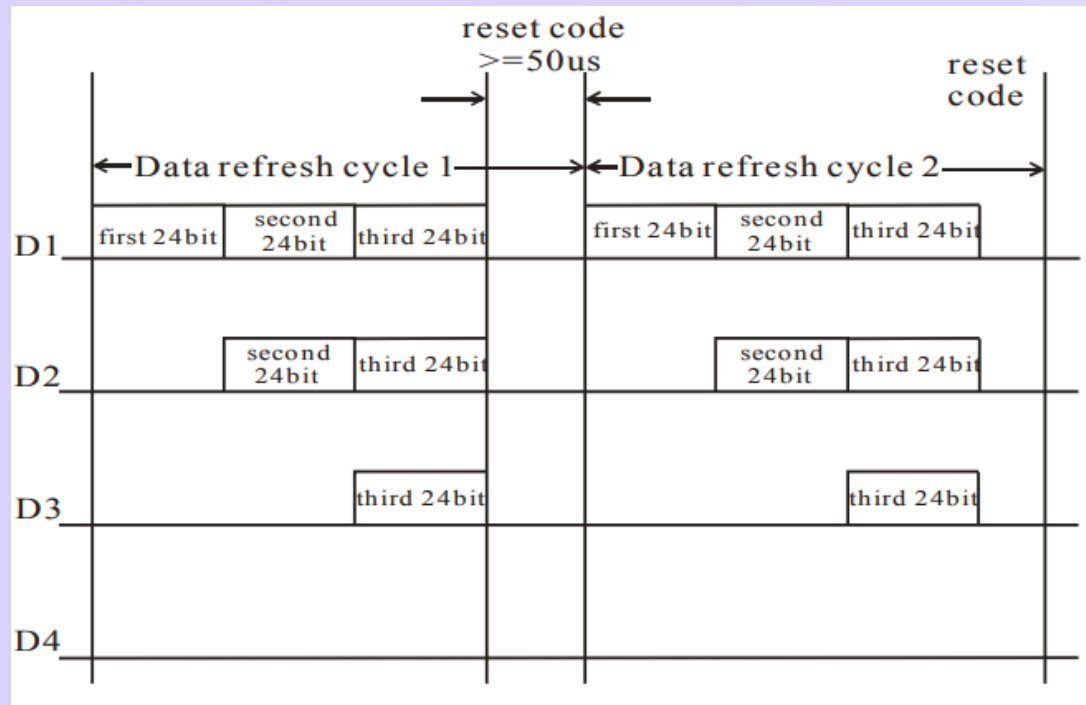
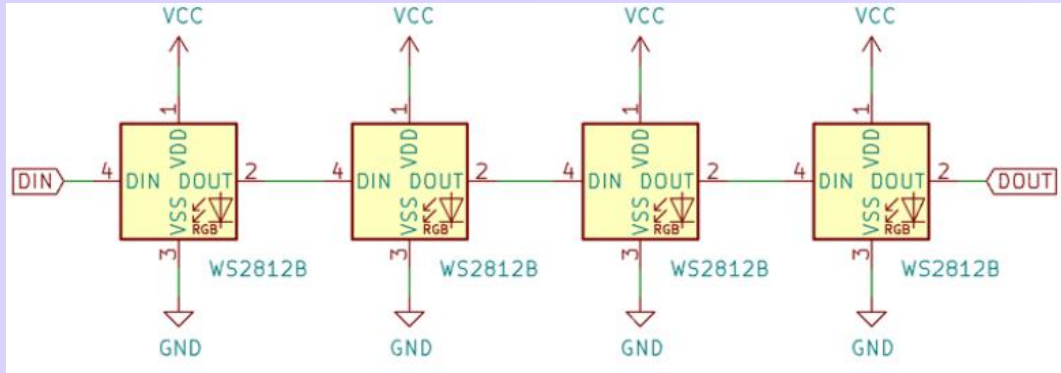
MW Search: <https://www.meanwell.com/serviceGTIN.aspx>



SPECIFICATION

MODEL		RS-15-3.3	RS-15-5	RS-15-12	RS-15-15	RS-15-24	RS-15-48
OUTPUT	DC VOLTAGE	3.3V	5V	12V	15V	24V	48V
	RATED CURRENT	3A	3A	1.3A	1A	0.625A	0.313A
	CURRENT RANGE	0 ~ 3A	0 ~ 3A	0 ~ 1.3A	0 ~ 1A	0 ~ 0.625A	0 ~ 0.313A
	RATED POWER	9.9W	15W	15.6W	15W	15W	15.024W
	RIPPLE & NOISE (max.) <small>Note.2</small>	80mVp-p	80mVp-p	120mVp-p	120mVp-p	200mVp-p	200mVp-p
	VOLTAGE ADJ. RANGE	2.9 ~ 3.6V	4.75 ~ 5.5V	10.8 ~ 13.2V	13.5 ~ 16.5V	22 ~ 27.6V	43.2 ~ 52.8V
	VOLTAGE TOLERANCE <small>Note.3</small>	±3.0%	±2.0%	±1.0%	±1.0%	±1.0%	±1.0%
	LINE REGULATION <small>Note.4</small>	±0.5%	±0.5%	±0.5%	±0.5%	±0.5%	±0.5%
	LOAD REGULATION <small>Note.5</small>	±2.0%	±1.5%	±0.5%	±0.5%	±0.5%	±0.5%
	SETUP, RISE TIME	1000ms, 30ms/230VAC 1000ms, 30ms/115VAC at full load					
HOLD UP TIME (Typ.)	70ms/230VAC 12ms/115VAC at full load						
INPUT	VOLTAGE RANGE	85 ~ 264VAC 120 ~ 370VDC					
	FREQUENCY RANGE	47 ~ 63Hz					
	EFFICIENCY (Typ.)	72%	77%	81%	81%	82%	82%
	AC CURRENT (Typ.)	0.35A/115VAC 0.25A/230VAC					
	INRUSH CURRENT (Typ.)	COLD START 65A / 230VAC					
	LEAKAGE CURRENT	<2mA / 240VAC					

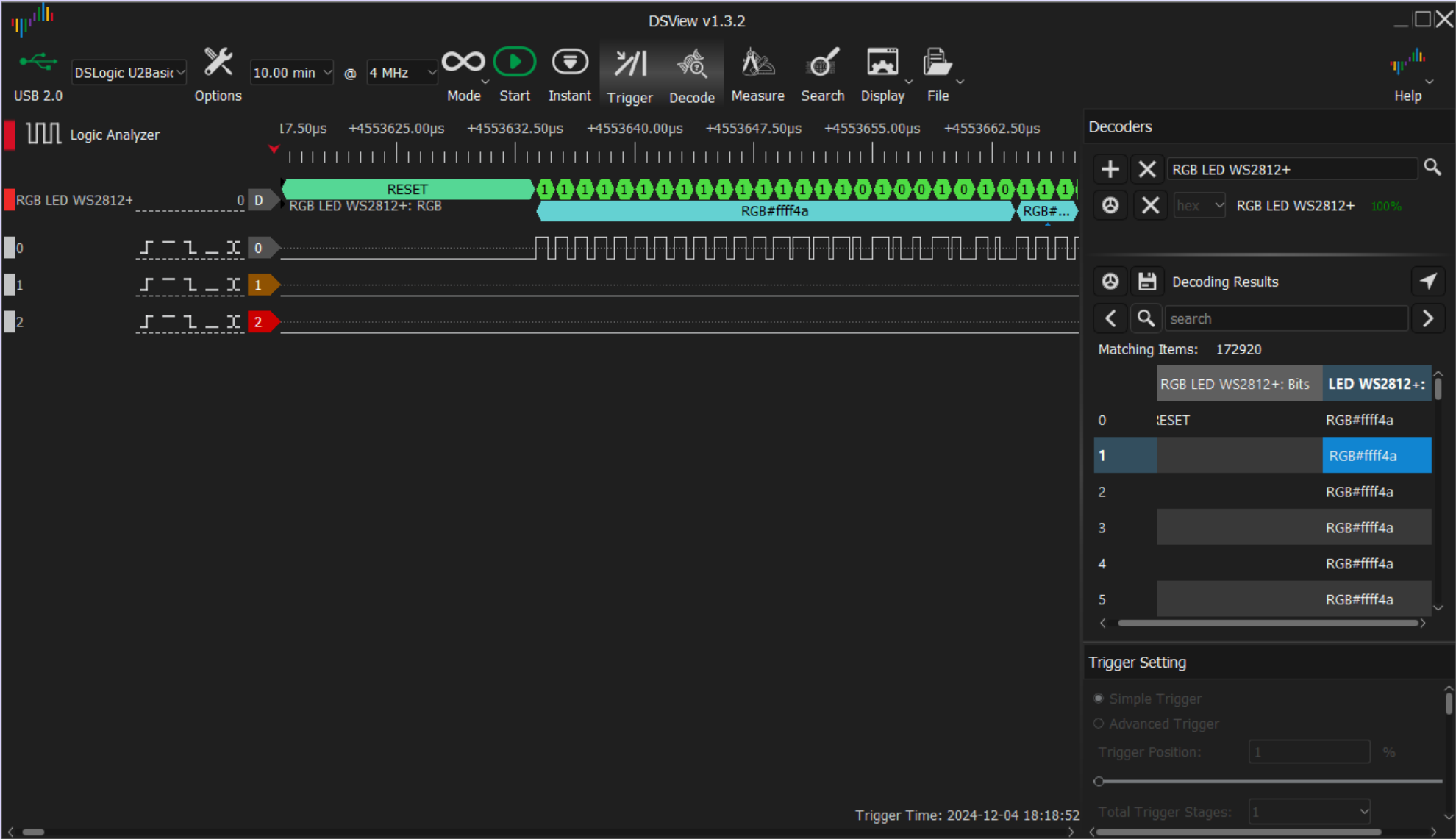
BTF-Lighting WS2812



Serial Peripheral Interface

WS2812B LED Protocol

BTF-Lighting WS2812



.NET for IoT

GPIO APIs: **System.Device.Gpio**

Device bindings: **IoT.Device.Bindings**

Source: [dotnet/iot](https://github.com/dotnet/iot)

System.Device.Gpio library and tests which is the main library that has the implementation for protocols such as: GPIO, SPI, I2C, PWM. This library is fully supported by the dotnet team since it has the same level of support that dotnet/corefx does.

IoT.Device.Bindings device bindings library. This is a collection of types which work as wrappers (or bindings) for devices and sensors which are able to talk to a microcontroller unit (or MCU like a Raspberry Pi for example) using the protocols supported by System.Device.Gpio.

[Learn Internet of Things \(IoT\)](#)

[.NET IoT Libraries documentation](#)

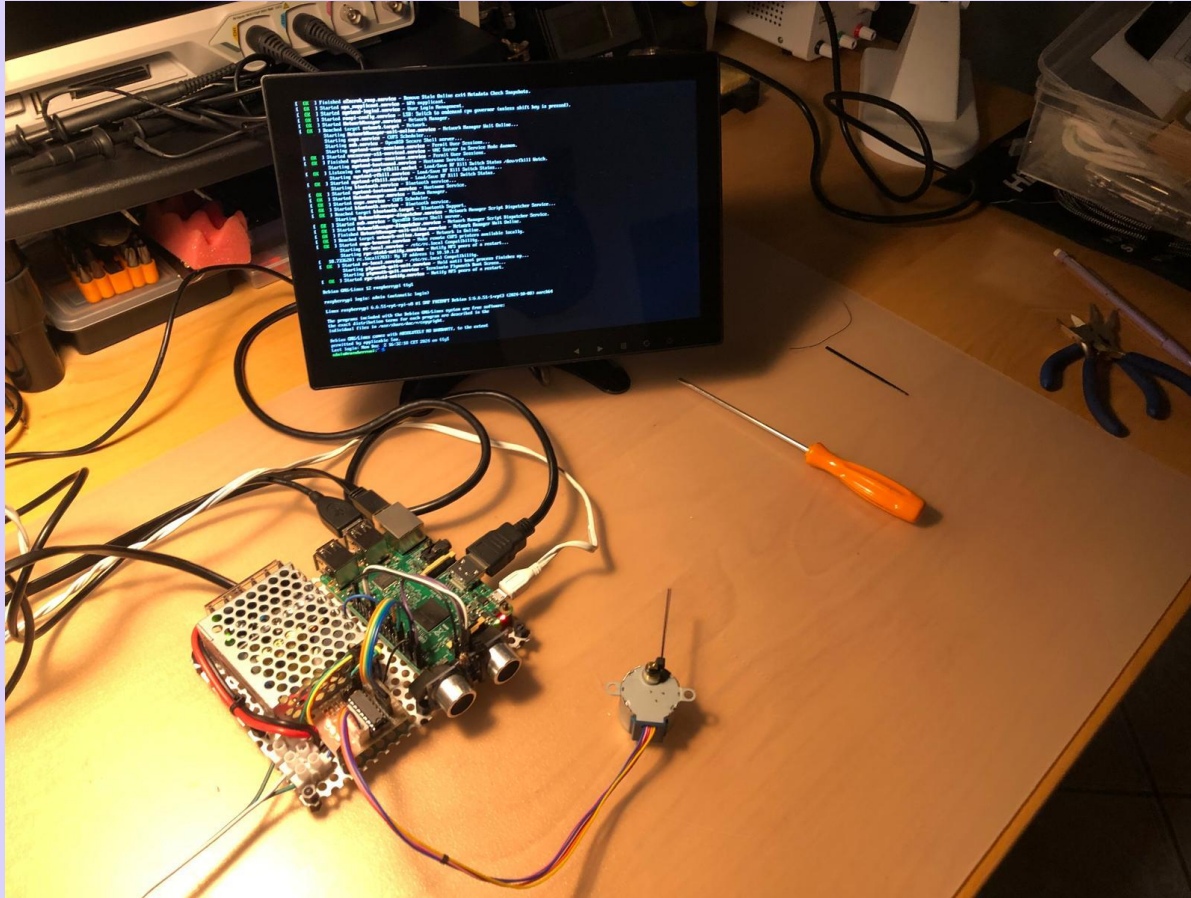
[Deploy .NET apps on ARM single-board computers](#)

[Ws28xx / SK6812 LED drivers](#)

[28BYJ-48 Stepper Motor 5V 4-Phase 5-Wire & ULN2003 Driver Board](#)

[HC-SR04 - Ultrasonic Ranging Module](#)

Work in progress...

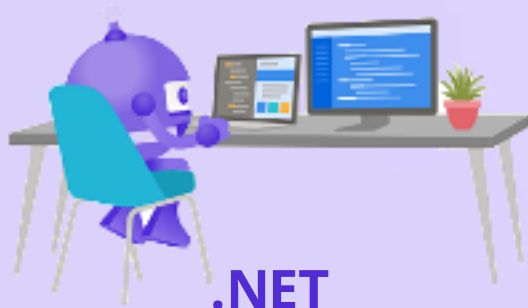


CODE



Q&A

Thanks !



your platform for building anything

Contacts

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```
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  x: @dottor,  
  linkedin: andreadottor  
}
```



Mirco Vanini

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  x: @MircoVanini,  
  linkedin: proxsoft  
}
```

