Mirevi MotionHub User Documentation









Mirevi MotionHub (MMH) is a middleware for multiple body tracking systems and it unifies them in a single plug-in for the Unity game engine.

MMH offers support for several body tracking systems and encompasses a game engine plug-in that connects the MMH with Unity by means of a standardized protocol. The plug-in allows for the usage of a single type of skeleton for any body tracking system and, therefore, facilitates the switch between different tracking systems during app development significantly.

Beyond that, MMH is capable of merging different tracking systems into one in order to combine and use their individual benefits.

MotionHub is developed at the research lab MIREVI from the University of Applied Sciences Düsseldorf within the scope of the project HIVE.

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1. Systems

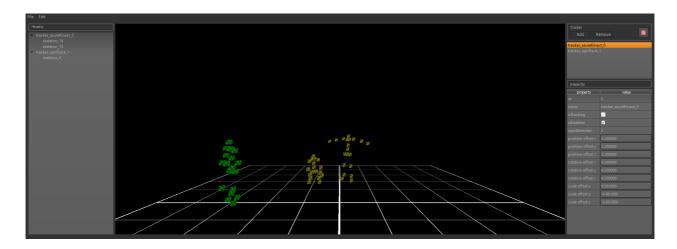
Supported

Azure Kinect

OptiTrack

Planned
Perception Neuron Studio
OpenPose

2. Overview and Navigation



MMH consists of four panels. From left to bottom right:

Name	Usage
tracker and skeleton hirarchy	inspect tracker and detected skeletons
render window	preview transformed tracking data
tracker list	add / remove and start / stop tracker
tracker property inspector	offset tracker

The render window camera can be rotated by holding the left mouse button down in the panel and pulling the mouse left or right.

3. Adding and Removing Tracker



Add a new tracker by pressing the "Add"(1) button. A new popup will appear where you can select the type in a dropdown. Click "Create" to add the tracker to the list.

Remove a tracker by clicking on the name in the tracker list and click "Remove"(2). Trackers can only removed while the system is not tracking.

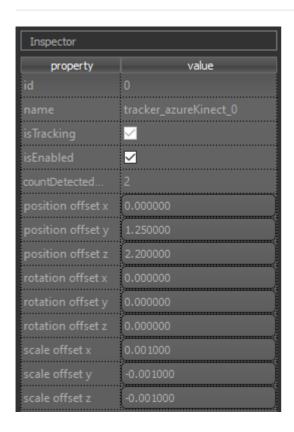
4. Start and Stop Tracking



Start all trackers by pressing the play icon(3). This will start all tracker and the preview in the render window.

Stop all tacker by clicking the same button (now displayed as a stop icon)(3). This will stop all tracker.

5. Offset Tracker



Offset a tracker by selecting one in the tracker list and enter values in the position, rotation and scale fields. This will offset the trackers origin. All values are in meters.

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