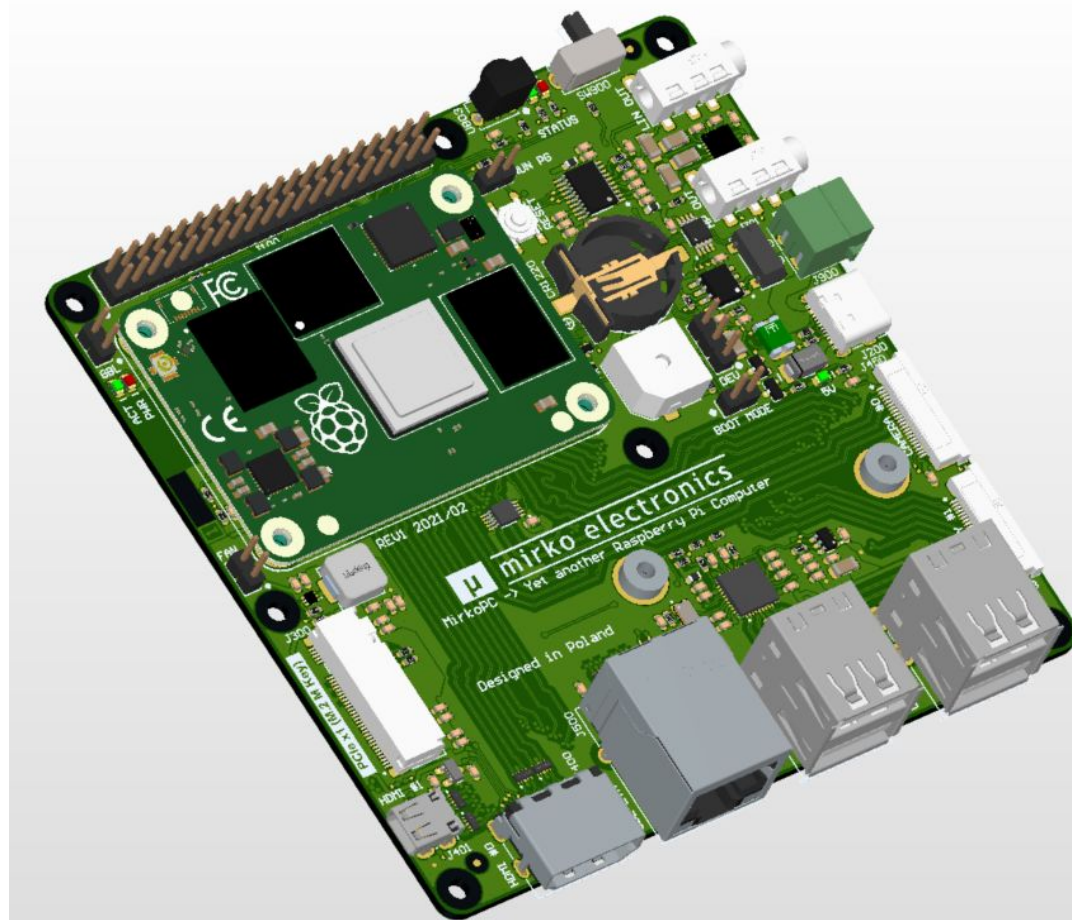


Raspberry Pi MiniPC (CM4 carrier board)

PCB Project: MirkoPC
Version: VER1
Revision: REV1
Project State: Released (2021-02-09)
Variant: STD
Print date: 2021-03-17

Page	Index
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01	Cover page
02	Block diagram
03	Top schematic
04	CM4 module - part #1
05	CM4 module - part #2
06	USB C interface
07	USB Hub
08	PCIe x1 M.2 slot
09	HDMI
10	Camera & Display interfaces
11	100/1000M Ethernet
12	MicroSD card & eMMC memory
13	DAC audio output
14	MISC
15	Power supply
16	PCB marking and mechnics

TOP VIEW




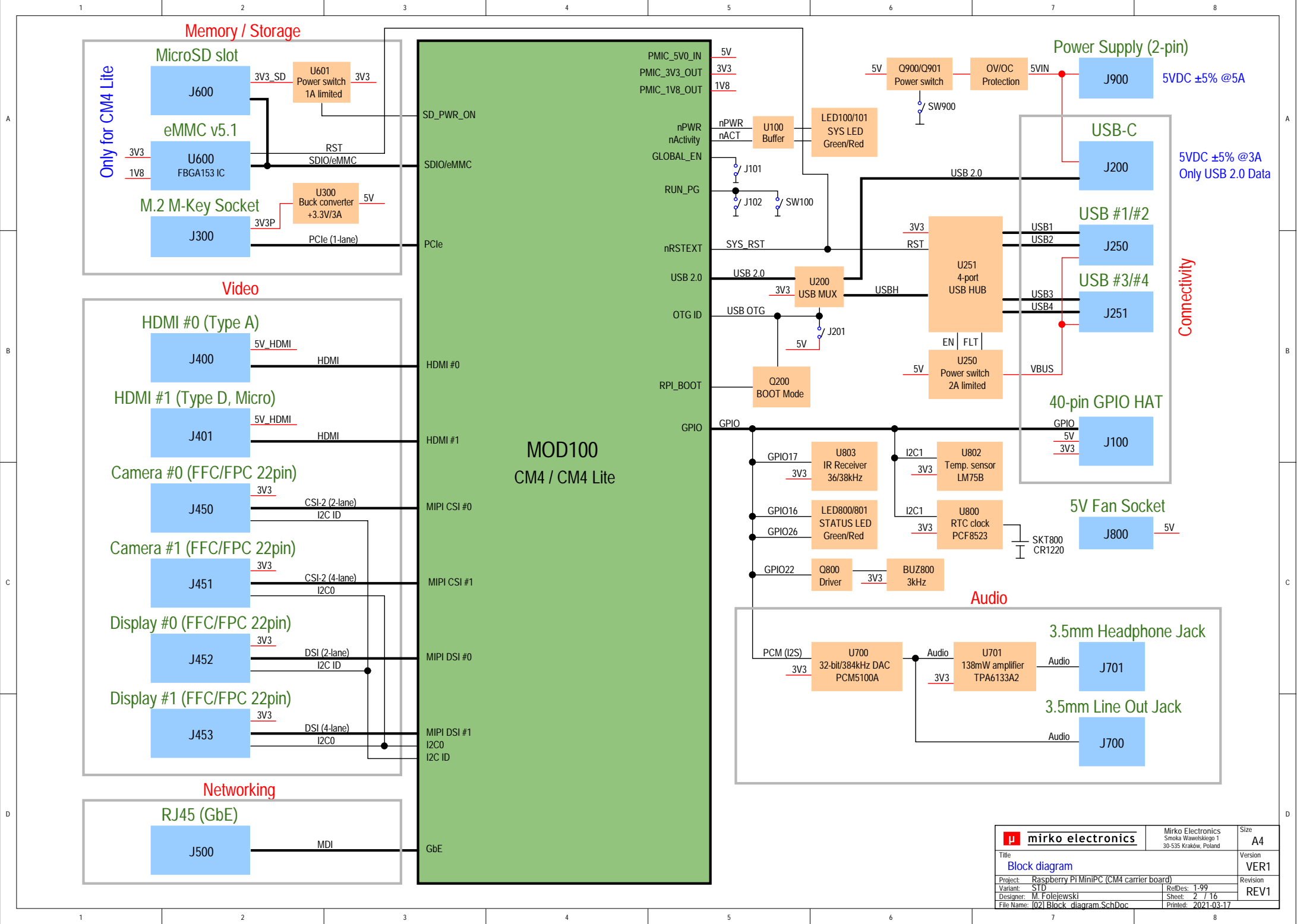
[02] Block diagram.SchDoc


[03] Top.SchDoc

PCB

PCB BARE BOARD

 mirko electronics		Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland	Size A3
Title MirkoPC - Board		Version VER1	Revision REV1
Project: Raspberry Pi MiniPC (CM4 carrier board)		RefDes: -	
Variant: STD		Sheet: 1 / 16	
Designer: M. Folejewski		Printed: 2021-03-17	
File Name: [01] Cover page.SchDoc			



 mirko electronics		Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland	Size A4
Title Block diagram		Project: Raspberry Pi MiniPC (CM4 carrier board)	Version VER1
Variant: STD		Designer: M. Folejewski	Revision REV1
File Name: 1021 Block diagram.SchDoc		Sheet: 2 / 16	Printed: 2021-03-17

A

B

C

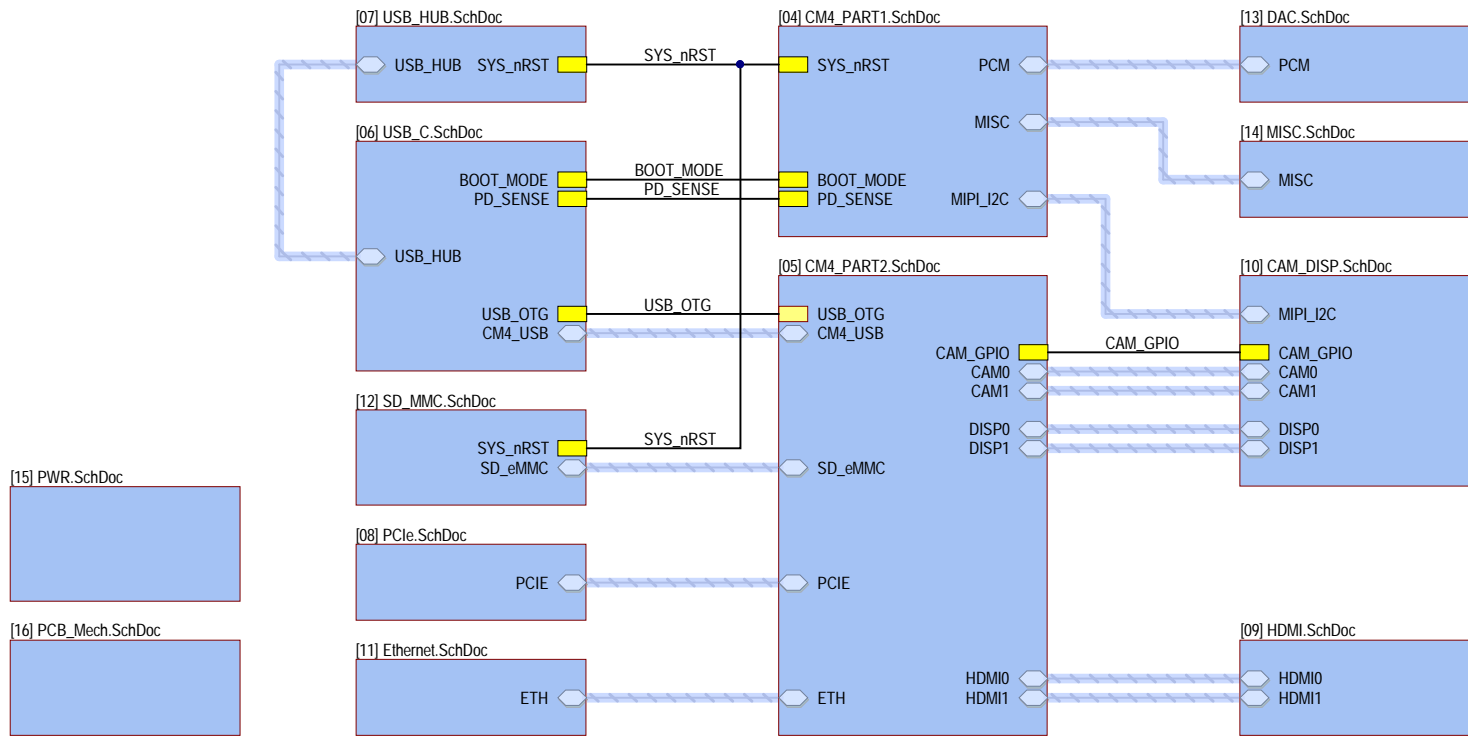
D


A

B

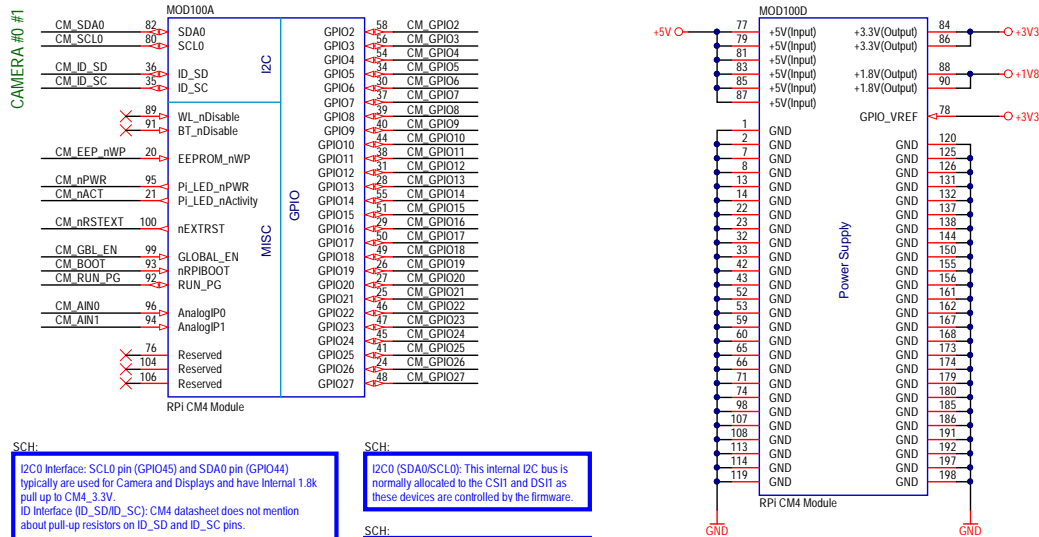
C

D



 mirko electronics		Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland	Size A4
Title Top schematic			Version VER1
Project: Raspberry Pi MiniPC (CM4 carrier board)			Revision REV1
Variant: STD		RefDes: 1-99	
Designer: M. Folejewski		Sheet: 3 / 16	
File Name: [03] TOP.SchDoc			Printed: 2021-03-17

CM4 MODULE (PART #1)



SCH:

I2C0 Interface: SCL0 pin (GPIO45) and SDA0 pin (GPIO44) typically are used for Camera and Displays and have Internal 1.8k pull up to CM4_3.3V.
ID Interface (ID_SD/ID_SC): CM4 datasheet does not mention about pull-up resistors on ID_SD and ID_SC pins.

I2C1 (GPIO2/GPIO3) have 1.8k pull-up resistors added on CM4 module.

SCH:

I2C (ID_SD/ID_SC): This I2C bus is normally used for identifying HATS (HAT ID EEPROM) and controlling CSI0 and DSIO devices.
At boot time this I2C interface will be interrogated to look for an EEPROM that identifies the attached board and allows automatic setup of the GPIOs (and optionally, Linux drivers).
DO NOT USE these pins for anything other than attaching an I2C ID EEPROM. Leave unconnected if ID EEPROM not required.

SCH:

I2C0 (SDA0/SCL0): This internal I2C bus is normally allocated to the CSI1 and DSIO as these devices are controlled by the firmware.

SCH:

nRPBBOOT: A low on this pin force booting from an RPI server. If not used leave floating. Internally pulled via 10K to +3.3V.

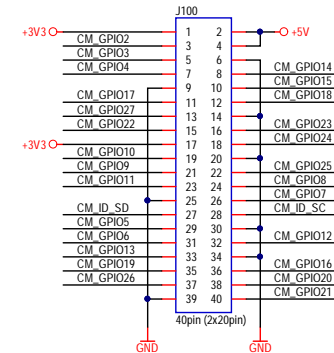
SCH:

EEPROM_nWP pin: Leaving floating NB Internally pulled up to CM4_3.3V via 100k (VIL <0.8V) but can be grounded to prevent writing to the on board EEPROM which stores the bootcode.

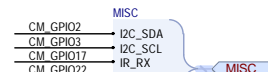
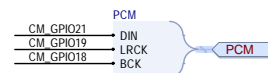
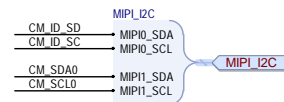
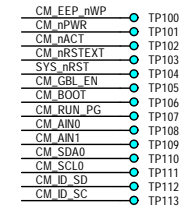
SCH:

1.8V and 3.3V Outputs +2.5%. Power Output max 300mA per pin for a total of 600mA. This will be powered down during power off or GLOBAL_EN being set low.

40-PIN GPIO HEADER



TESTPOINTS (DEBUG)



Raspberry Pi Pinout

3v3 Power	1	2	5v Power
GPIO 2 (I2C1 SDA)	3	4	5v Power
GPIO 3 (I2C1 SCL)	5	6	Ground
GPIO 4 (GCLK0)	7	8	GPIO 14 (UART TX)
Ground	9	10	GPIO 15 (UART RX)
GPIO 17	11	12	GPIO 18 (PCM CLK)
GPIO 27	13	14	Ground
GPIO 22	15	16	GPIO 23
3v3 Power	17	18	GPIO 24
GPIO 10 (SPI0 MOSI)	19	20	Ground
GPIO 9 (SPI0 MISO)	21	22	GPIO 25
GPIO 11 (SPI0 SCLK)	23	24	GPIO 8 (SPI0 CE0)
Ground	25	26	GPIO 7 (SPI0 CE1)
GPIO 0 (EEPROM SDA)	27	28	GPIO 1 (EEPROM SCL)
GPIO 5	29	30	Ground
GPIO 6	31	32	GPIO 12 (PWM0)
GPIO 13 (PWM1)	33	34	Ground
GPIO 19 (PCM FS)	35	36	GPIO 16
GPIO 26	37	38	GPIO 20 (PCM DIN)
Ground	39	40	GPIO 21 (PCM DOUT)

Used GPIOs:

GPIO2 - I2C1 SDA
GPIO3 - I2C1 SCL

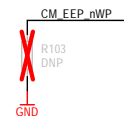
GPIO18 - PCM CLK (BCK)
GPIO19 - PCM FS (LRCK)
GPIO21 - PCM DOUT (DAT)

GPIO17 - IR RX

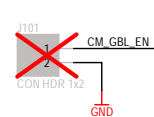
GPIO22 - BUZZER

GPIO16 - STATUS1 LED (Green)
GPIO26 - STATUS2 LED (Red)

EEP WP



GLOBAL EN

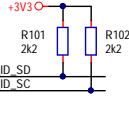


SCH:

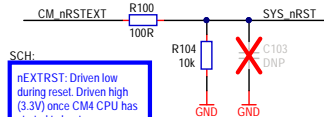
GLOBAL_EN: Drive low to power off CM4. Internally pulled up with a 100K to +5V.

USER:
Power Down jumper 1-2 = CM4 Power Down enabled

ID I2C

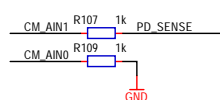


GLOBAL RESET



SCH:
nEXTREST: Driven low during reset. Driven High (3.3V) once CM4 CPU has started to boot.

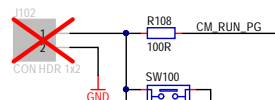
AIN0/AIN1



SCH:
AIN0, AIN1: Analogue inputs of the MAX7704. Typically connected to CC pin of Type C power connector.

SCH:
AIN0 and AIN1 pins connected according to Raspberry Pi 4B schematic.

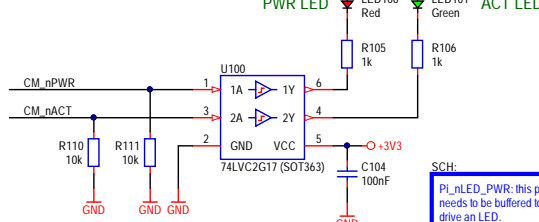
RUN PG



USER:
RESET SWITCH

USER:
RUN_PG pin: This pin when high signals that the CM4 has started. Driving this pin low resets the module, this should be done with caution as if files on a filesystem are open they will not be closed.

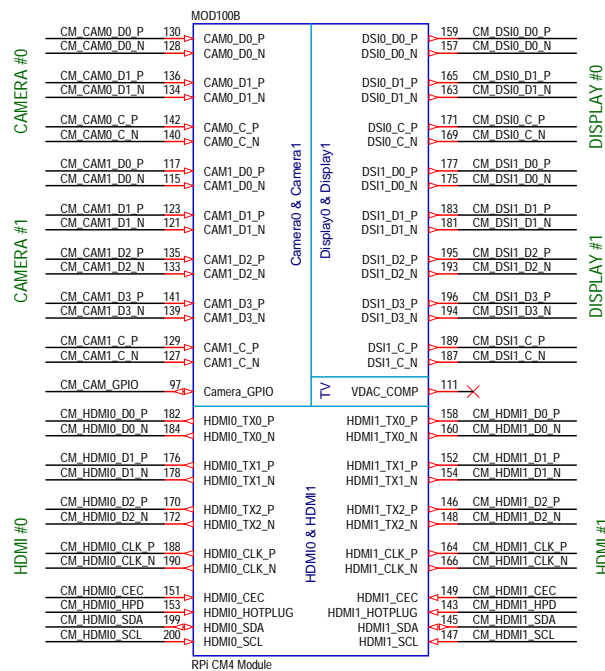
SYS LEDs

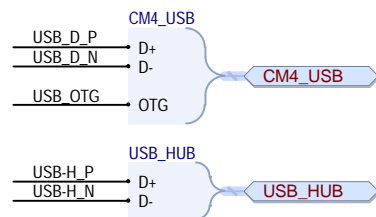
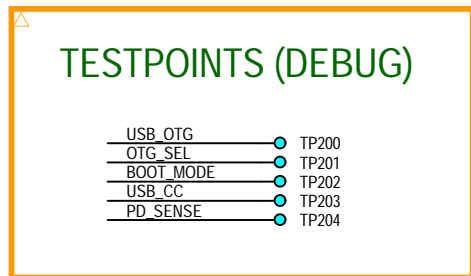
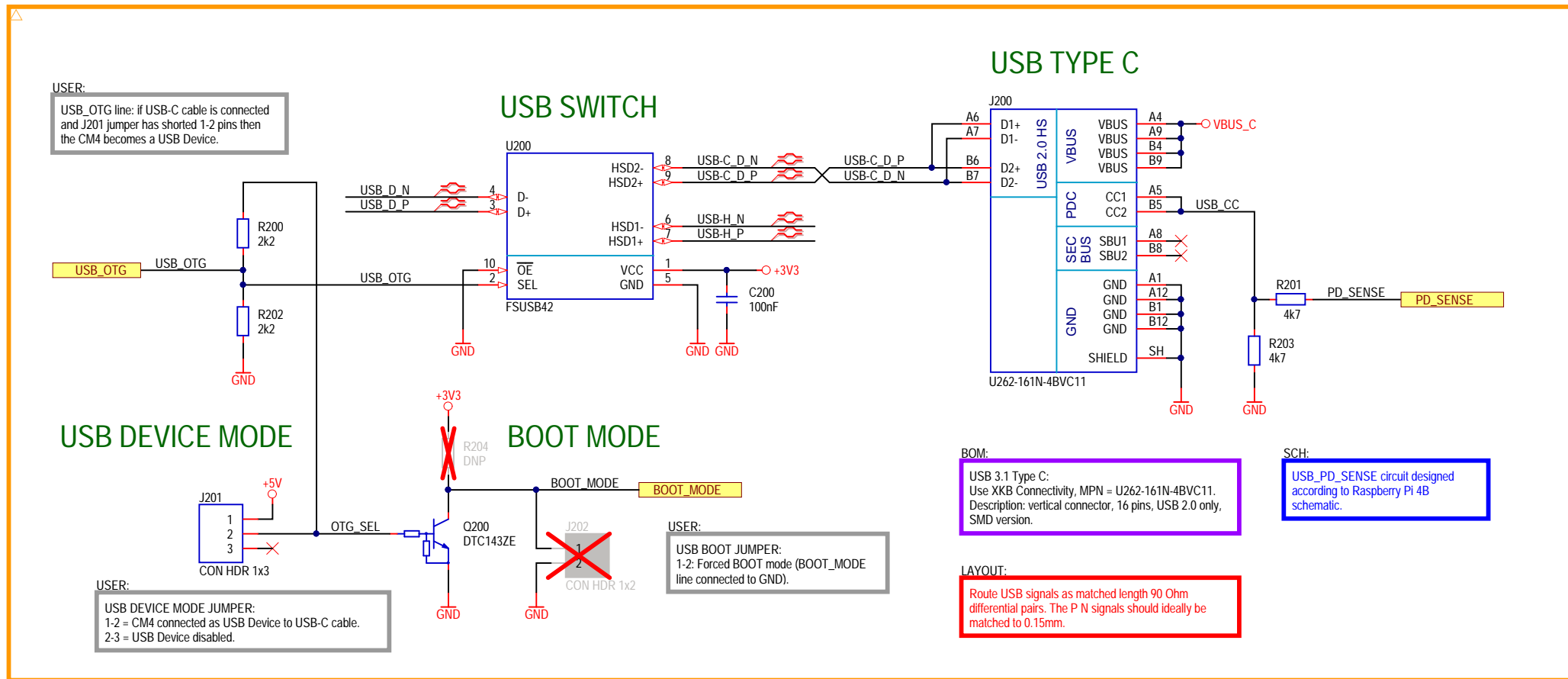



SCH:
PWR_LED: this pin needs to be buffered to drive an LED.

misko electronics		Misko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland		Size A3
Title Compute Module 4 (Part #1)		Version VER1		Revision REV1
Project Raspberry Pi MiniPC (CM4 carrier board)		Sheet 4 / 16		Printed: 2021-03-17
Variant STD		Designer: M. Folejewski		
File Name: 041 CM4 PART1.SchDoc				

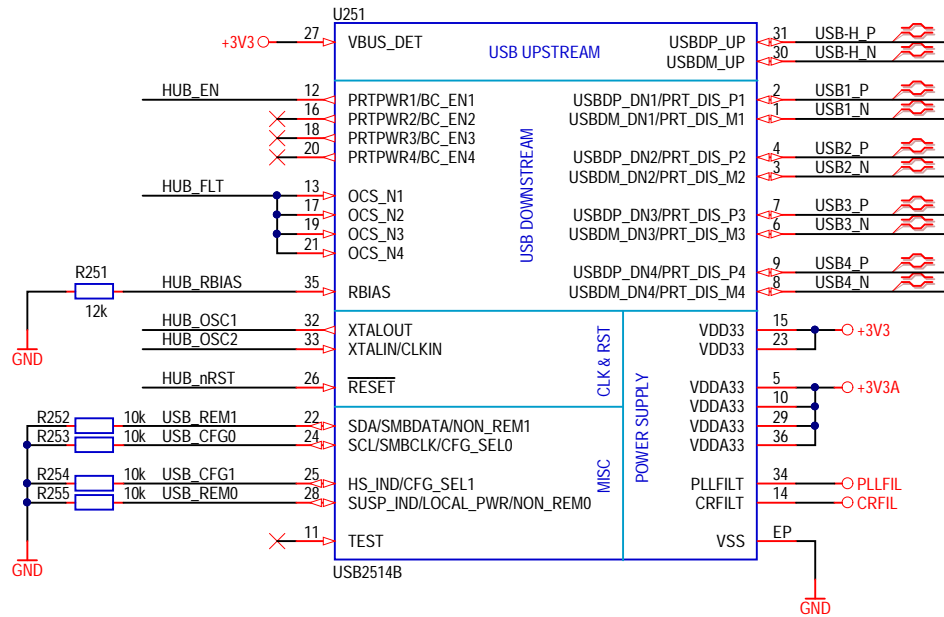
CM4 MODULE (PART #2)



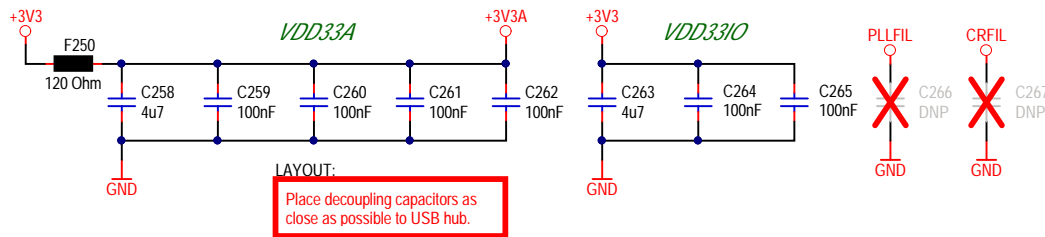


 mirko electronics		Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland	Size A4
Title USB-C interface and USB switch			Version VER1
Project: Raspberry Pi MiniPC (CM4 carrier board)			Revision REV1
Variant: STD		RefDes: 1-99	
Designer: M. Folejewski		Sheet: 6 / 16	
File Name: [06] USB_C.SchDoc		Printed: 2021-03-17	

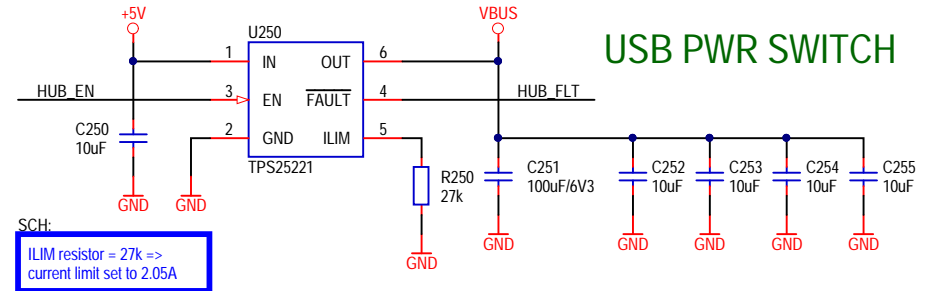
4-PORT USB HUB



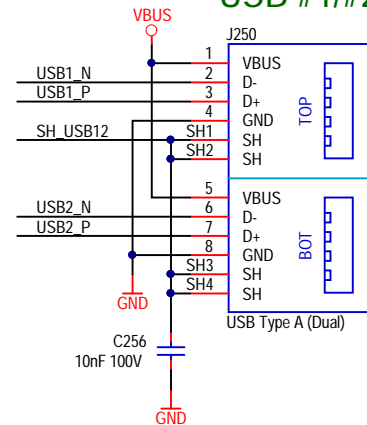
DECOUPLING CAPACITORS



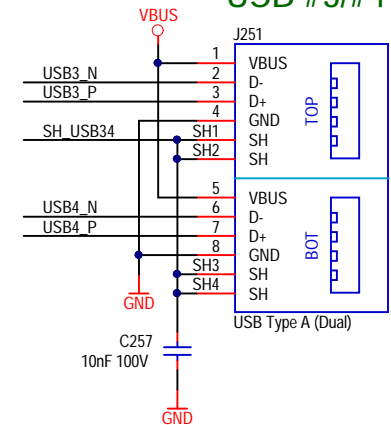
USB PWR SWITCH



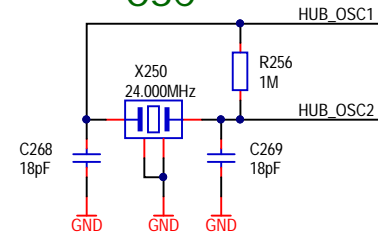
USB #1/#2



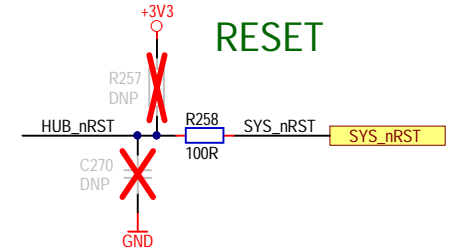
USB #3/#4



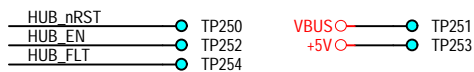
OSC



RESET



TESTPOINTS (DEBUG)



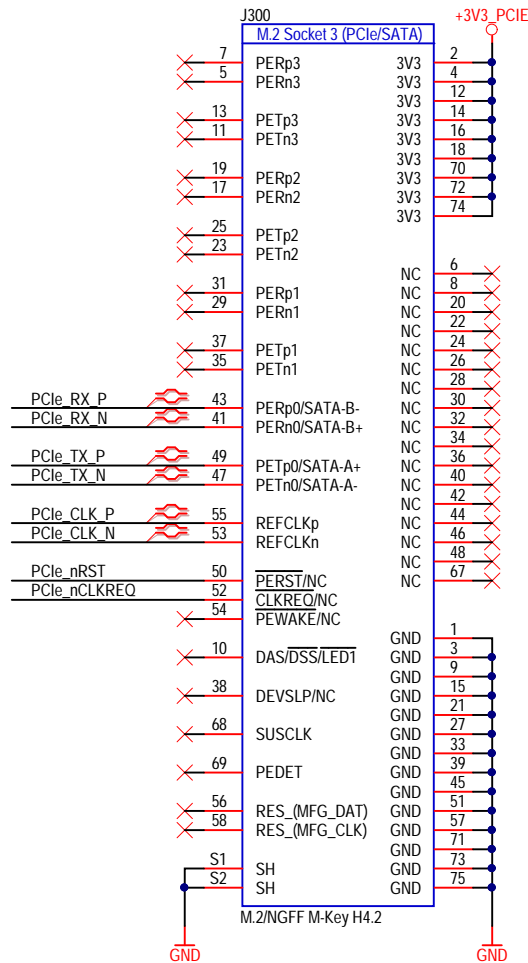
LAYOUT:

Route USB signals as matched length 90 Ohm differential pairs. The P N signals should ideally be matched to 0.15mm.



		Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland	Size A4
Title 4-port USB 2.0 hub		Designer: M. Folejewski File Name: [07] USB_HUB.SchDoc	Version VER1
Project: Raspberry Pi MiniPC (CM4 carrier board) Variant: STD		RefDes: 1-99 Sheet: 7 / 16 Printed: 2021-03-17	Revision REV1

M.2 Socket 3 (M-Key) PCIe x1



LAYOUT:
Route PCIe signals as matched length 90 Ohm differential pairs with suitable clearances. There is no need to match the lengths between pairs, only the signals within a pair need to be length matched ideally to better than 0.1mm.

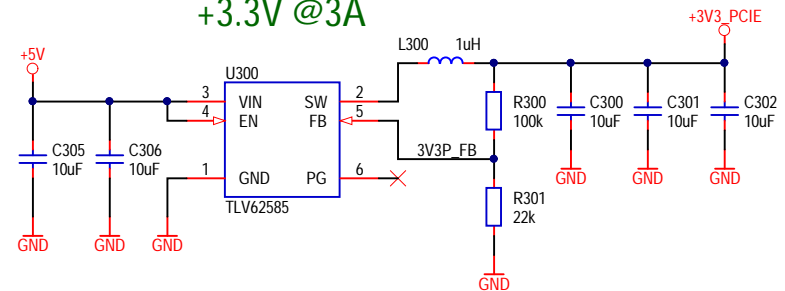
BOM:
NGFF connector:
Description: M.2 (NGFF), M-Key, H4.2.
Lotes, MPN = APC10107-P001A.
TE Connectivity, MPN = 1-2199230-5.

LAYOUT:
Place decoupling capacitors as close as possible to M.2 connector.

PULL-UP



+3.3V @3A



LAYOUT:
Place decoupling capacitors as close as possible to the Buck converter.

BOM:
1.0uH -> compatible components:
PSA (Prosperity Dielectrics), MPN = MCS0630-1R0MN2
Würth Elektronik, MPN = 744 373 460 10 (WE-LHMI, 7030 Series)

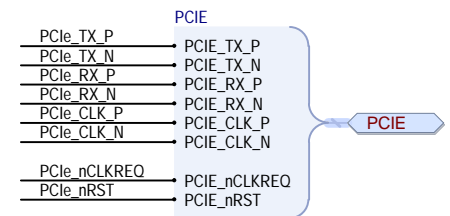
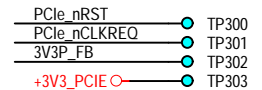
STAND-OFF HEIGHT TABLE

Connector Height Descriptor	L1
H2.3	0.35 ± 0.03
H2.5	0.55 ± 0.03
H2.8	0.80 ± 0.03
H3.2	1.45 ± 0.03
H4.2	2.45 ± 0.03



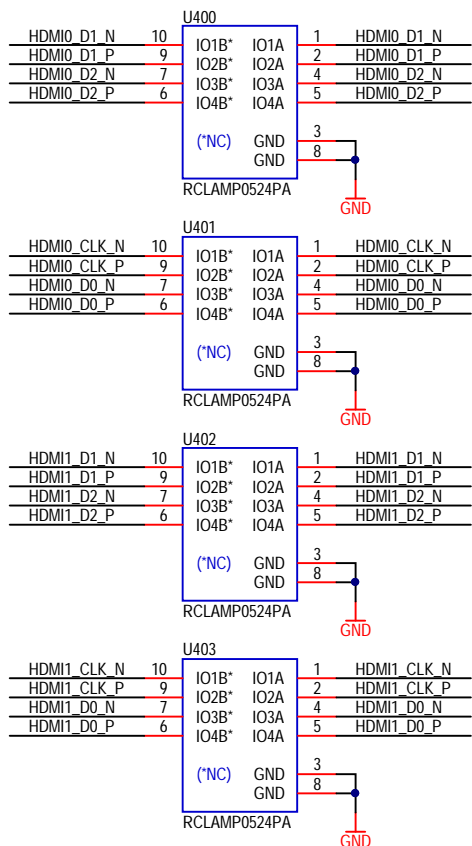
MOD300
SSD HDD
NGFF M.2
MOD_SSD_NGFF

TESTPOINTS (DEBUG)

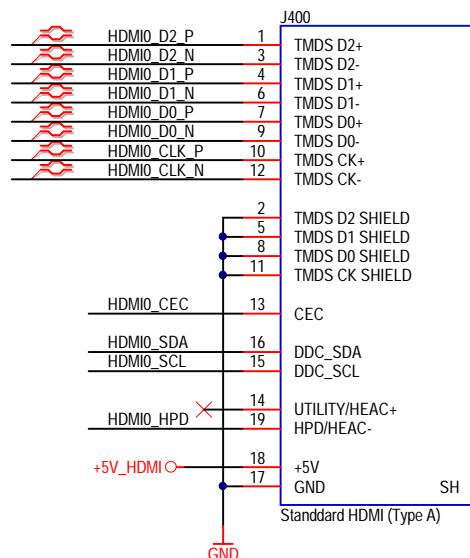


		Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland	Size A4
Title M.2 PCIe x1 Socket		Variant: STD	Version VER1
Project: Raspberry Pi MiniPC (CM4 carrier board)		RefDes: 1-99	Revision REV1
Designer: M. Folejewski		Sheet: 8 / 16	
File Name: [08] PCIe.SchDoc		Printed: 2021-03-17	

ESD PROTECTION



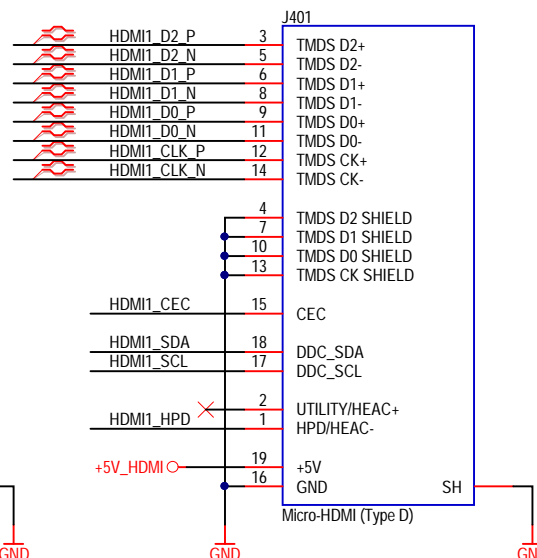
HDMI #0 (TYPE A)



BOM:
HDMI #0 connector:
Wurth Elektronik, MPN = 685 119 134 923
BOOMELE, MPN = HDMI-001
Description: Type A (Standard), 19 pins, 0.50mm pitch, horizontal, SMD.

LAYOUT:
connect IO1A - IO4A on the connector side.

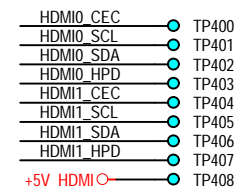
HDMI #1 (TYPE D)



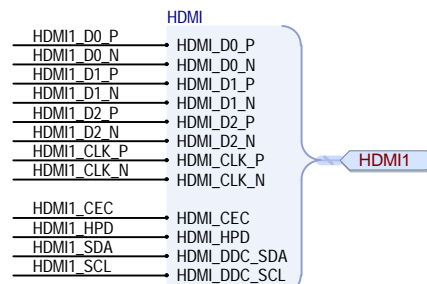
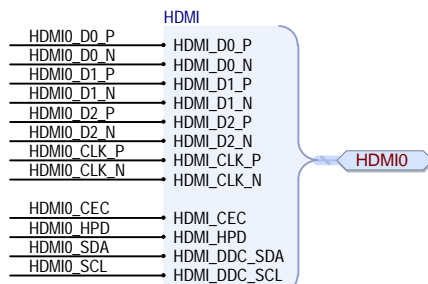
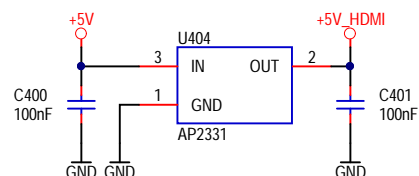
BOM:
HDMI #1 connector:
Wurth Elektronik, MPN = 685 119 248 123
HOAUC, MPN = HYC23-HDMI19-650
Description: Type D (Micro-HDMI), 19 pins, 0.40mm pitch, horizontal, SMD.

LAYOUT:
Route HDMI signals as matched length 100 Ohm differential pairs, each signal within a pair should ideally be matched to better than 0.15mm. Pairs don't typically need any extra matching as they only have to be matched to 25mm.

TESTPOINTS (DEBUG)

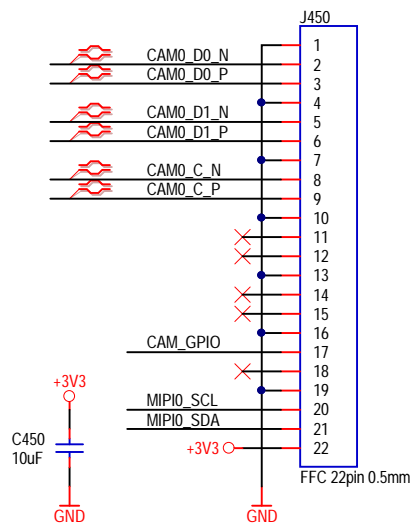


5V POWER SWITCH

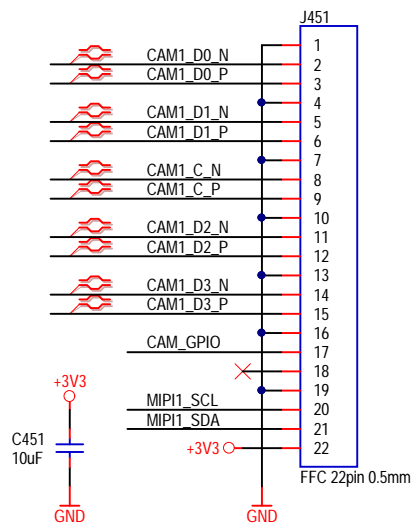


		Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland	Size A4
Title HDMI Interfaces		Designer: M. Folejewski File Name: [09] HDMI.SchDoc	Version VER1
Project: Raspberry Pi MiniPC (CM4 carrier board) Variant: STD RefDes: 1-99		Sheet: 9 / 16 Printed: 2021-03-17	Revision REV1

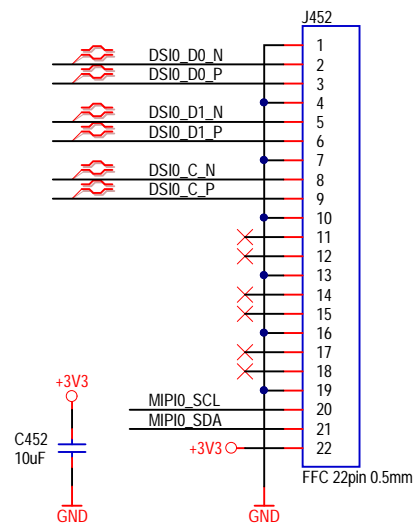
CAMERA #0



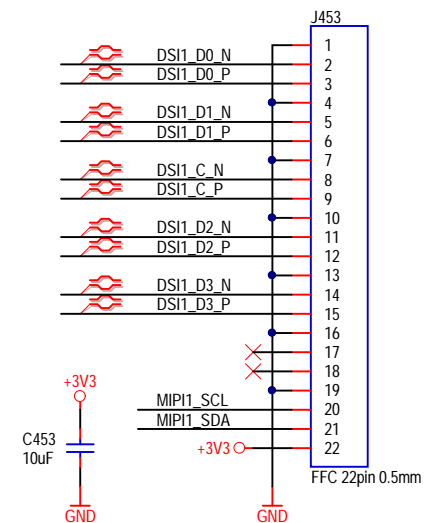
CAMERA #1



DISPLAY #0



DISPLAY #1



LAYOUT:

MIPI CSI and DSI signals should be routed as 100 Ohm differential pairs, each signal within a pair should ideally be matched to better than 0.15mm.

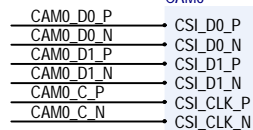
BOM:

FFC/FPC connector for Camera interface:
Use XKB Connectivity, MPN = X05B20L22T.
Description: 22 pins, 0.50mm pitch, horizontal, bottom contact.

TESTPOINTS (DEBUG)

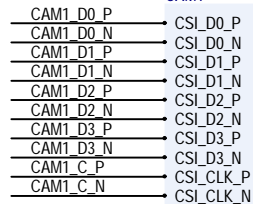
MIPI0_SCL	TP450
MIPI0_SDA	TP451
MIPI1_SCL	TP452
MIPI1_SDA	TP453
CAM_GPIO	TP454

CAM0



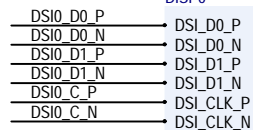
CAM0

CAM1



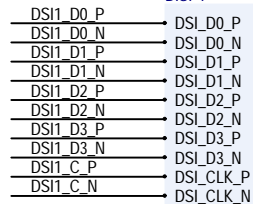
CAM1

DISP0



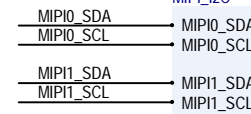
DISP0

DISP1

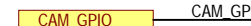


DISP1

MIPI_I2C



MIPI_I2C



CAM_GPIO



mirko electronics

Mirko Electronics
Smoka Wawelskiego 1
30-535 Kraków, Poland

Size
A4

Title
MIPI CSI & DSI (camera and display interfaces)

Version
VER1

Project: Raspberry Pi MiniPC (CM4 carrier board)

Revision

Variant: STD

RefDes: 1-99

Designer: M. Folejewski

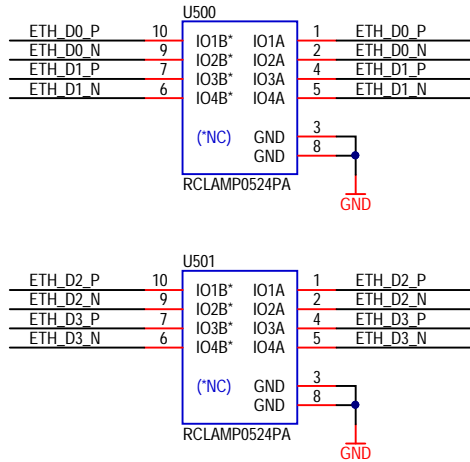
Sheet: 10 / 16

File Name: [10] CAM_DISP.SchDoc

Printed: 2021-03-17

REV1

ESD PROTECTION



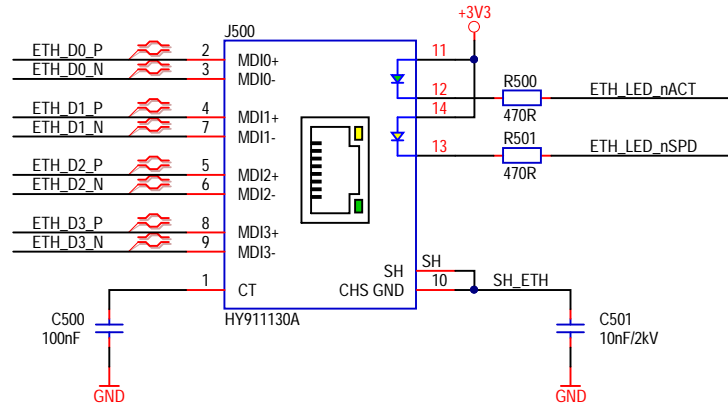
LAYOUT:

connect IO1A - IO4A on the connector side.

LAYOUT:

Place TVS array diodes as close as possible to RJ45 connector.

100/1000M ETHERNET



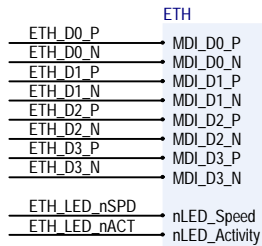
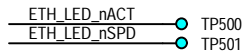
LAYOUT:

Route Ethernet signals as matched length 100 Ohm differential pairs with suitable clearances. Length matching between pairs should be better than 50mm, so in the typical case no length matching is required. However the signals within a pair need to be length matched, ideally to better than 0.15mm.

BOM:

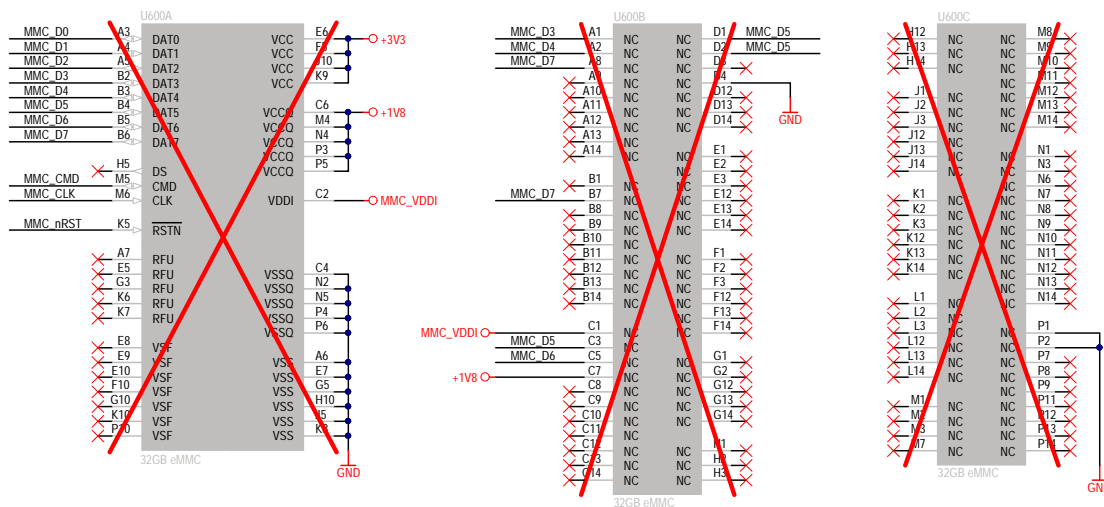
RJ45 -> compatible connectors:
 HanRun, MPN = HR911130A (HY911130A)
 Link-PP, MPN = LPJG0806FBNL
 Description: 100/1000M RJ45, Tab-down, G/Y LEDs

TESTPOINTS (DEBUG)

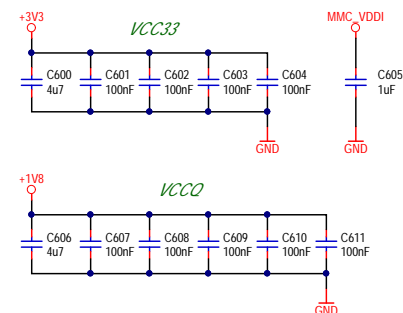


	Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland		Size A4
	Title 100/1000M Ethernet interface		Version VER1
Project:	Raspberry Pi MiniPC (CM4 carrier board)		Revision REV1
Variant:	STD	RefDes:	1-99
Designer:	M. Folejewski	Sheet:	11 / 16
File Name:	[11] Ethernet.SchDoc		Printed: 2021-03-17

eMMC v5.1



DECOUPLING CAPACITORS



SCH:

VCCQ is the power supply line for host interface, have two power mode:
High power mode: 2.7V3.6V.
Lower power mode: 1.7V1.95V.

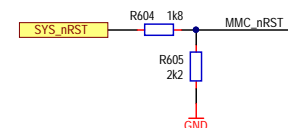
VCC is the power supply line for internal flash memory, its power voltage range is: 2.7V3.6V.

VDDI is internal power node, not the power supply.

LAYOUT:

Place decoupling capacitors as close as possible to eMMC memory.

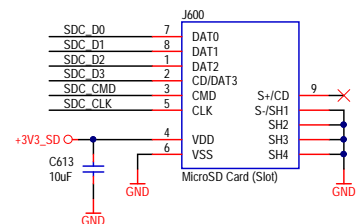
MMC_RST - level conversion 3.3V -> 1.8V



Force eMMC interface to 1.8V signalling



MICRO SD CARD



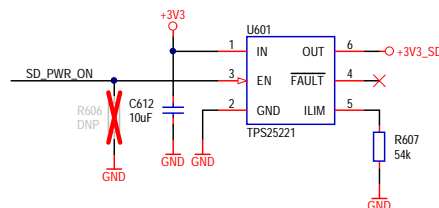
BOM:

MicroSD slot -> compatible components:
GCT, MPN = MEM2055-00-190-01-A
SOFNG, MPN = TF-015
HOAUC, MPN = HVC77-TF09-200
XUNPU, MPN = TF-115

USER:

SD Card only for CM4 Lite module with no on-board Flash memory chip (eMMC).

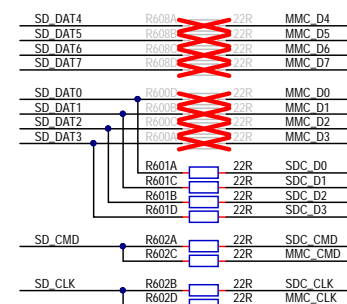
PWR SWITCH



SCH:

ILIM resistor = 54k => current limit set to 1.02A

SD INTERFACE MUX



BOM:

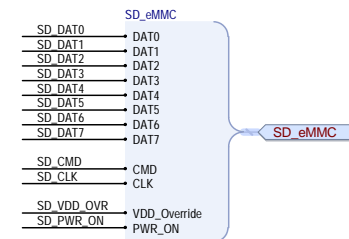
Place only series resistors for SD Card interface or for eMMC memory.


LAYOUT:

Place series resistors as close as possible to CM4 module.

TESTPOINTS (DEBUG)

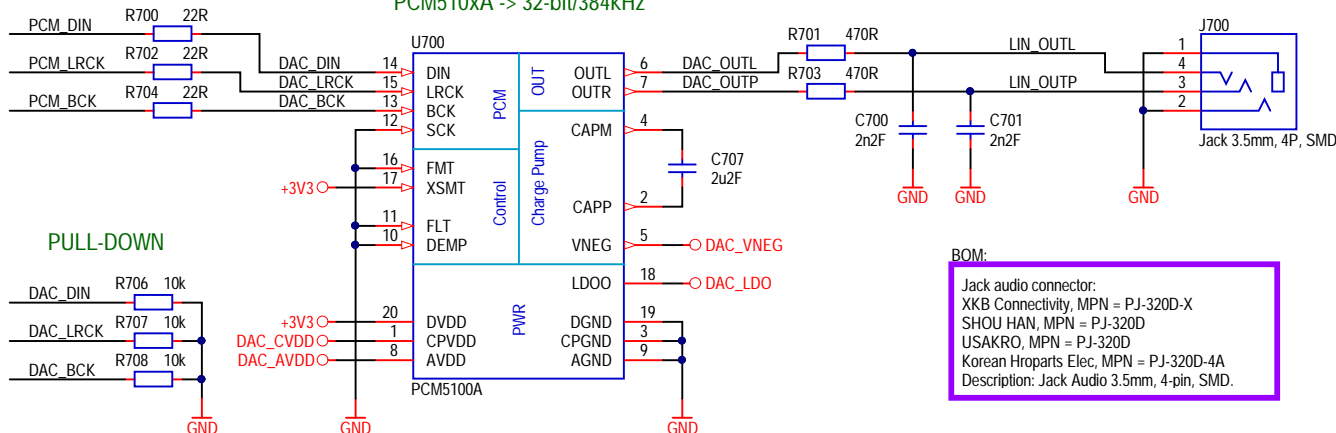
SD_CMD	TP600	SD_PWR_ON	TP601
SD_CLK	TP602	SD_VDD_OVR	TP603
MMC_nRST	TP604	+3V3_SD	TP605



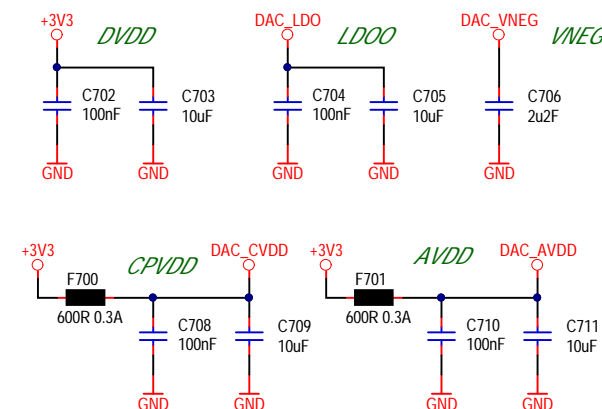
		Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland	Size B
Title MicroSD slot and eMMC memory			Version VER1
Project: Raspberry Pi MiniPC (CM4 carrier board)			Revision REV1
Variant: STD			
Designer: M. Folejewski			
File Name: 121 SD MMC SchDoc			
			RefDes: 1-99
			Sheet: 12 / 16
			Printed: 2021-03-17

DAC Audio

PCM510xA -> 32-bit/384kHz



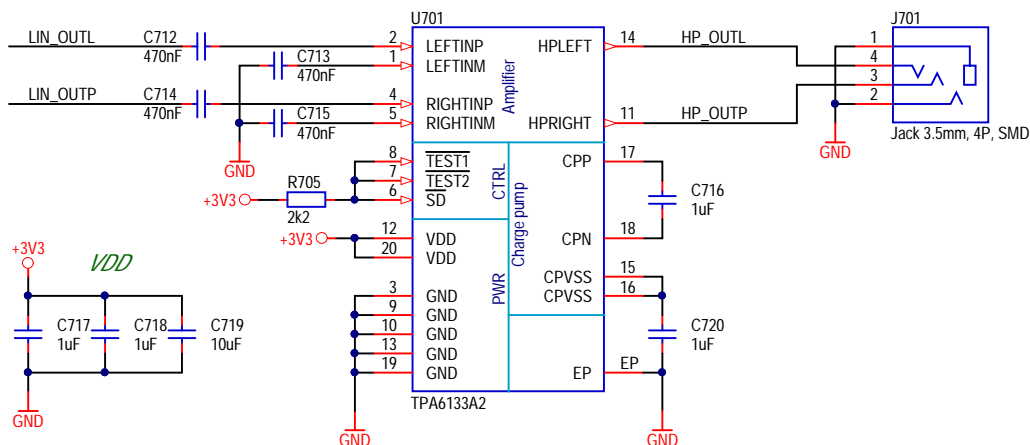
DECOUPLING CAPACITORS



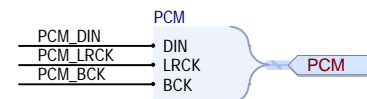
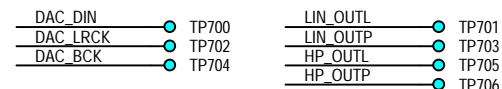
Headphone Amplifier

BOM:

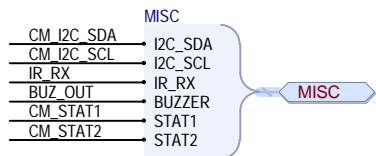
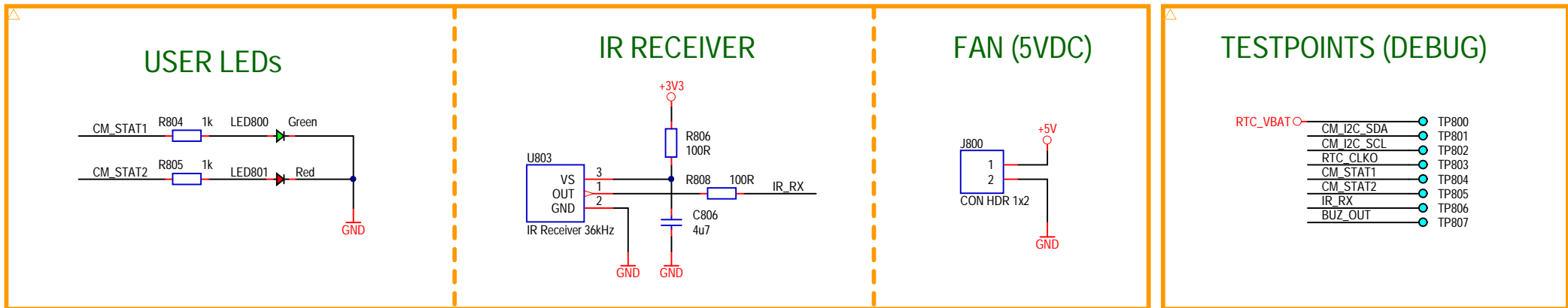
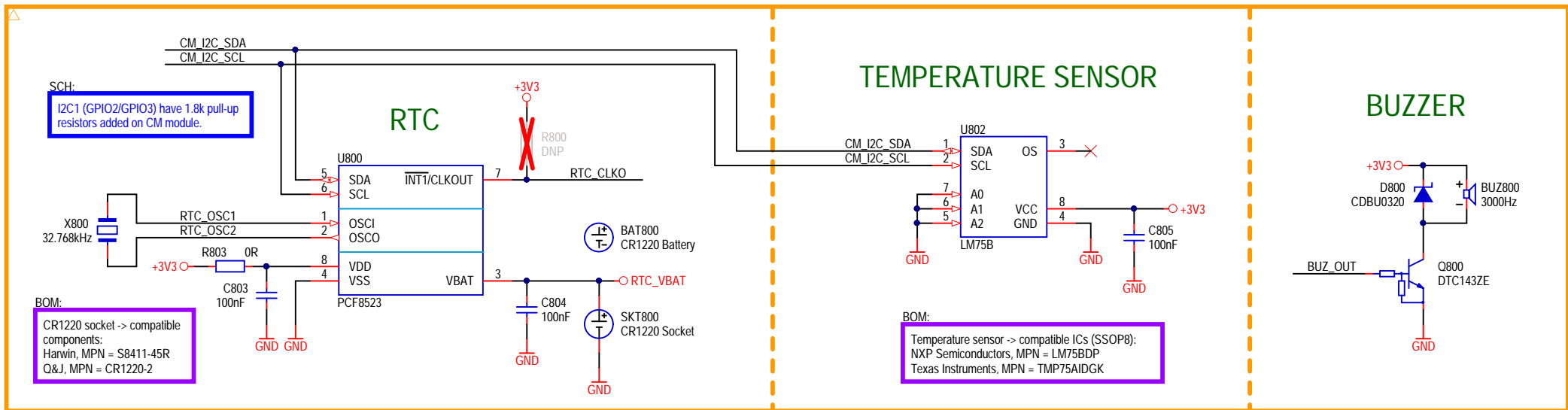
470nF -> use film capacitor
Cornell Dubilier, MPN = FCA1206C474M-H3



TESTPOINTS (DEBUG)

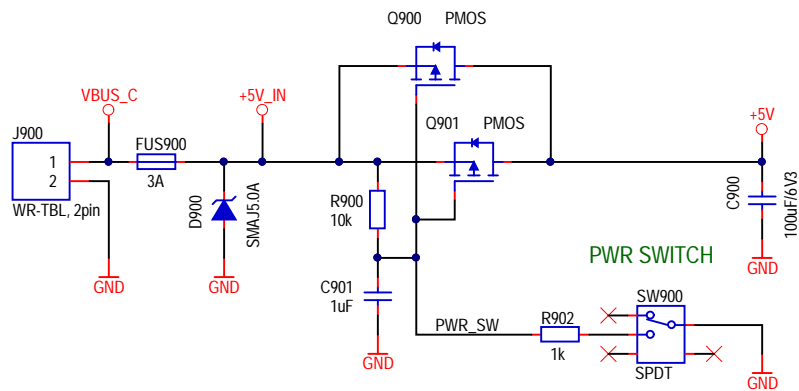


	Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland		Size A4
	Title DAC audio output		Version VER1
Project:	Raspberry Pi MiniPC (CM4 carrier board)		Revision REV1
Variant:	STD	RefDes:	1-99
Designer:	M. Folejewski	Sheet:	13 / 16
File Name:	[13] DAC.SchDoc	Printed:	2021-03-17



		Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland	Size A4
Title MISC			Version VER1
Project: Raspberry Pi MiniPC (CM4 carrier board)		Revision REV1	
Variant: STD		RefDes: 1-99	
Designer: M. Folejewski		Sheet: 14 / 16	
File Name: [14] MISC.SchDoc		Printed: 2021-03-17	

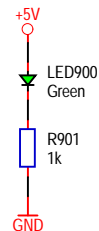
+5V MAIN POWER SUPPLY



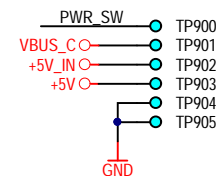
BOM:

P-MOS -> compatible transistors:
LGE, MPN = LGE2305
HUASHUO, MPN = HSS2307

PWR LED



TESTPOINTS (DEBUG)



mirko electronics

Mirko Electronics
Smoka Wawelskiego 1
30-535 Kraków, Poland

Size
A4

Title
+5V power supply

Version
VER1

Project: **Raspberry Pi MiniPC (CM4 carrier board)**

Revision

Variant: **STD**

RefDes: **1-99**

Designer: **M. Folejewski**

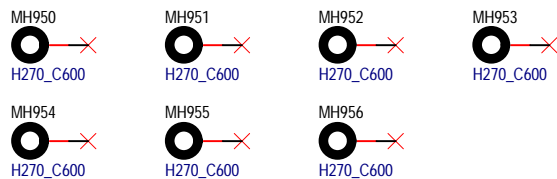
Sheet: **15 / 16**

File Name: **[15] PWR.SchDoc**

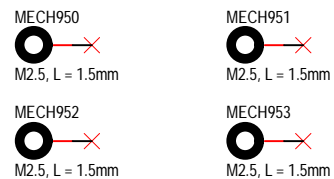
Printed: **2021-03-17**

REV1

PCB MOUNTING HOLES



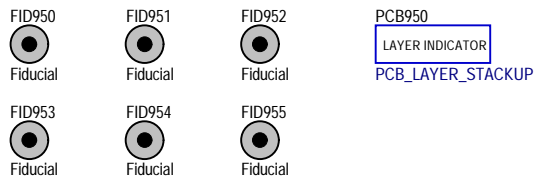
M2.5 STEEL SPACERS



BOM:

SMT Steel Spacer with internal Thread M2.5, L = 1.5mm:
Use Wurth Elektronik, MPN = 977 401 515 1.

PCB MARKING



		Mirko Electronics Smoka Wawelskiego 1 30-535 Kraków, Poland	Size A4
Title PCB marking & mechanical parts			Version VER1
Project: Raspberry Pi MiniPC (CM4 carrier board)			Revision REV1
Variant: STD	RefDes: 1-99		
Designer: M. Folejewski	Sheet: 16 / 16		
File Name: [16] PCB_Mech.SchDoc		Printed: 2021-03-17	