## Exam 1TD388, 2021-06-02

(!) Det här är en förhandsvisning av den publicerade versionen av quizet

Startad: 13 dec kl 15.36

## Instruktioner för Quiz

In the first question of this quiz, you will be asked to upload an image of some ID (photo of your ID card, driver's license, or passport). This is to verify that you were the person who wrote and handed in the exam. Then, you are supposed to pick the correct statements for each of the questions. An example:

If a question has maximum N points and there are x choices that are correct, then each correct answer awards you N/x points, while every wrong answers will reduce by N/x. But you cannot get less than zero per question! In other words, if a question has 6 points and 4 answers are correct then every correct answer you choose will give you 1.5p. If you do not choose a correct answer you will not get the 1.5p for that choice. But if you choose a wrong answer the total credit will be reduced by 1.5p, but you cannot get less than zero.

Please take as much time as you need to answer the questions as well as possible. However, hand-in time will play a factor if you are less than 1 point from a higher grade: if you completed the exam in less than 2.5 hours (half the time), your score will be rounded up, otherwise, it will be rounded down. The motivation for this is that if you took longer time, you probably had to go back more often and look up things in the book and the course material. But do not feel any stress, and submit the exam when you are satisfied with your answers! Also, let us know if you generally need longer examination time because of dyslexia or similar.

Note that the questions cover the general case: there might be some special case we as teachers have not thought about (but clever students would think of). What should you do then? Remember re not clever students, so answer for the general case!

Grade limits:

5: 35p 4: 28p 3: 20p

You can always email fredrik.nysjo@it.uu.se during the exam if something is unclear!

Good luck!

## Fråga 1 0 poäng

Please upload your ID (e.g. student ID, drivers licence or passport)

Ladda upp Välj en fil

Fråga 2 3 poäng

$$rac{1}{a+bd+cd^2}(K_aL_a+K_dL_d\max\left(\mathbf{N}\cdot\mathbf{L},0
ight)+K_sL_s(\mathbf{R}\cdot\mathbf{V})^lpha)$$

- ☐ The three constants La, Ld, Ls in the equation above usually represents the color of the Material with respect to ambient, diffuse and specular light, respectively.
- $\hfill \square$  The equation above does include the distance falloff.
- ☐ The above equation uses the halfway vector introduced by J. Blinn.
- In the equation above, the diffuse component is computed using the Lambert law of cosines, which defines how much light is spread out over a surface, depending on the angle of the light source direction and the normal.
- ☐ The max function is used in the equation so that the light intensity does not become negative, as there is no such thing as negative light.
- ☐ The exponent (alpha) in the Phong Illumination equation above regulates the size of the specular highlight.

Fråga 3

3 poäng

What features describes Phong shading correctly?

- ☐ It interpolates colours over the polygon
- ☐ It creates better shading than Gouraud
- ☐ It computes the Phong illumination equation per pixel
- ☐ It produces better highlights than Gouraud
- $\hfill \square$  It has worse Mach band problems than Gouraud

Fråga 4	3 poäng
What is true about raytracing?	
☐ It uses the form factor	
☐ It can be used for translucent objects	
☐ It is generally less computationally expensive than Phong shading	
☐ It is often used for specular surfaces	
☐ The phong illumination equation is often replaced by a BRDF or similar	ar
Fråga 5	2 poäng
What is true about the Sutherland-Hodgeman clipper?	
☐ It is a pipeline clipper	
☐ It can clip both triangles and lines	
☐ It does backface culling	
☐ All stages in the pipeline can be done in parallel	
☐ It is based on scissoring	
Fråga 6	2 poäng

☐ Texture mapping	
☐ Environment mapping	
☐ Scissoring	
☐ Bump mapping	
☐ Back face culling	
Fråga 7	2 poäng
If you would make an object that looks like smoo techniques would you typically use so it look	
☐ Bump mapping	
☐ Environment mapping	
☐ Texture mapping	
☐ Scissoring	
☐ Back face culling	
Fråga 8	2 poäng
Fråga 8  In a typical graphics pipeline, what comes after p  Shading Rasterisation	
In a typical graphics pipeline, what comes after p	
In a typical graphics pipeline, what comes after p  Shading Rasterisation	2 poäng

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What is correct about fix point rotations?

Only ONE matrix is used to do all transformations needed to perform the rotation
They are frequently used to be able to animate complex objects
It makes it possible to rotate an object, despite its position in space
They are much faster than rotation around the origin

It is a mix of scaling and rotation operations

What is true about rotation matrices?

They contain the sine and cosine
The norm of all columns are 1
They contain arc functions
Homogenous coordinates are not necessary

**•** 

☐ The matrix looks exactly the same for rotation around any axis. It is just change sign	ist the functions that
Fråga 12	2 poäng
What is true about translation matrices?	
☐ They cannot be combined with scaling matrices trough matrix multipli	cation
☐ They typically have a column or a row where the translation for each	axis is found
☐ Homogenous coordinates are not necessary	
☐ The diagonal is set to 1	
☐ The norm of each row is 0	
Fråga 13	2 poäng
What is true about perspective projection?	
☐ All vertexes are projected onto the front clipping plane	
☐ It is exactly the same as Orthogonal projection	
☐ It is computed by first defining a centre of projection	
☐ In early medieval paintings the perspective is often wrong	
☐ Perspective division will make sure that objects further away looks sm	naller
Fråga 14	3 poäng
What is true about splines?	

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☐ B-splines generally do not intersect the control points
☐ The Utah teapot was created using Bezier Patches
☐ All cubic splines has C3 continuity
☐ They can theoretically be of any positive degree, but 3 is preferred in Computer Graphics
☐ Bernstein polynomials always have degree 3
☐ B-splines can be used to create smooth camera movements in a scene

Fråga 15	3 poäng
What is true about Global Illumination algorithms?	
☐ The so called form factor, is essential for the Half way vector computation.	
<ul> <li>Octrees can be used to divide 3D space so that ray/triangle intersections are faster.</li> </ul>	computed
☐ Bounding spheres are faster to compute than bounding boxes	
Radiosity is usually used for highly specular surfaces and translucent surfaces.	
Raytracing is first of all aimed for matte surfaces (computing diffuse light only	′).
<ul> <li>Bounding objects are typically used to improve the speed in which ray/triangl intersections are computed.</li> </ul>	е

What is true about hidden surface removal and clipping?

Clipping can typically be done either before or after projection. I.e. clipping can be performed in 3D or in 2D.

A typical pipeline clipper divides the space into 9 regions and compute out codes for fast clipping.

Backface culling is a method to improve interpolation over triangles in Gouraud shading.

Clipping can be done for both orthogonal and perspective projections

What is true about render-to-texture and post-processing effects?

The resolution of color and depth attachments in a framebuffer object must be the same as the screen resolution or the window size

Even when using framebuffer objects, post-processing effects can still be expensive because they might require many samples from a texture

Increasing the resolution of a shadow map can help reduce aliasing around edges of shadows

The use of framebuffer objects allows us to render more complex geometry (more triangles)

Ray tracing is often used in shadow mapping to generate the depth image for the shadow map

Fråga 18	2 poäng
What is true about volume rendering?	
☐ The quality of volume rendering is dependant on the resolution of the	ne voxel data
<ul> <li>Volume rendering was used for the cube mapping part of the third a course</li> </ul>	assignment in the
<ul> <li>A GPU with 4 GB video memory can easily store a volume with 102 each voxel takes up 1 byte))</li> </ul>	24^3 voxels (assuming
<ul> <li>Maximum intensity projection (MIP) is typically used to render a sur the volume data</li> </ul>	face representation of