

Intermediate Exam 1 Signals & Transforms

- 1 a) The Fourier transform can be seen as a decomposition of the aperiodic signal $x(t)$ into components with all possible ω . The transform gives a measure of how strong each component is.
- b) 1. The signal $x(t)$ must be causal.
2. The Fourier transform for $x(t)$ must exist (i.e., the integral must converge).
3. The Laplace transform must be evaluated in $s=j\omega$.
- c) The signal $z(t)$ is a product in the time domain. This will result in a convolution in the frequency domain:

$$Z(\omega) = \mathcal{F}\left\{\frac{2}{\pi} \text{sinc}\left(\frac{2t}{\pi}\right) x(t)\right\}$$

$$= \frac{1}{2\pi} \mathcal{F}\left\{\frac{2}{\pi} \text{sinc}\left(\frac{2t}{\pi}\right)\right\} * \mathcal{F}\{x(t)\}$$

$$= \frac{1}{2\pi} \mathcal{F}\left\{\frac{2}{\pi} \text{sinc}\left(\frac{2t}{\pi}\right)\right\} * X(\omega)$$

$$= \frac{1}{2\pi} \text{rect}\left(\frac{\omega}{2 \cdot 2}\right) * X(\omega)$$

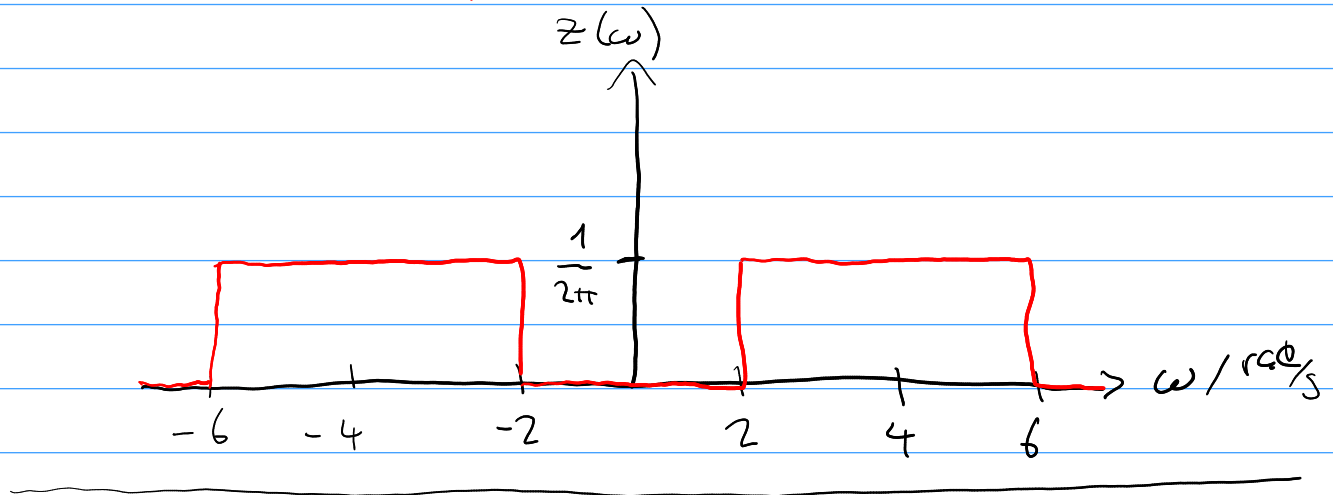
A rect of width 4, centered around 0.

Two Dirac delta funcs. at ± 4 , weight 1.

$$= \frac{1}{2\pi} \text{rect}\left(\frac{\omega}{4}\right) * (\delta(\omega - 4) + \delta(\omega + 4))$$

$$= \frac{1}{2\pi} \left(\text{rect} \left(\frac{\omega - 4}{4} \right) + \text{rect} \left(\frac{\omega + 4}{4} \right) \right).$$

Two rects of width 4 centered at ± 4



2 a) Yes! We see from the figure that

$$\underline{x_3(t) = x_1(t-2) + x_2(t-2) \mapsto y_1(t-2) + y_2(t-2)}$$

b) There are several ways of determining $h(t)$ from the figure. One way is to look at $x_2(t)$, which is $x_2(t) = -\delta(t)$. Hence, $-x_2(t) \mapsto h(t)$ or $x_2(t) \mapsto -h(t)$, that is, inverting the output observed for $x_2(t)$ yields the impulse response.

This yields:

$$\underline{\underline{h(t) = \text{rect} \left(\frac{t-1}{2} \right)}}$$

c) The input is a pure cosine. Hence, we can use the sine in, sine out principle:

$$x(t) = 2\cos\left(\frac{\pi}{2}t\right) \mapsto y(t) = 2|H\left(\frac{\pi}{2}\right)|\cos\left(\frac{\pi}{2}t + \angle H\left(\frac{\pi}{2}\right)\right)$$

where $H\left(\frac{\pi}{2}\right) = |H\left(\frac{\pi}{2}\right)|e^{j\angle H\left(\frac{\pi}{2}\right)}$ is the frequency response evaluated in $\omega = \frac{\pi}{2}$.

$$\begin{aligned} H(\omega) &= \mathcal{F}\{h(t)\} = \mathcal{F}\left\{\text{rect}\left(\frac{t-1}{2}\right)\right\} \\ &= 2e^{-j\omega} \text{sinc}\left(\frac{2\omega}{2\pi}\right) \end{aligned}$$

Time shifting,
rect \rightarrow sinc
(from table)

$$\Rightarrow H\left(\frac{\pi}{2}\right) = 2e^{-j\frac{\pi}{2}} \text{sinc}\left(\frac{2\frac{\pi}{2}}{2\pi}\right) = 2e^{-j\frac{\pi}{2}} \text{sinc}\left(\frac{1}{2}\right) \approx 1.3e^{-j\frac{\pi}{2}}$$

$$\Rightarrow |H\left(\frac{\pi}{2}\right)| = 1.3, \quad \angle H\left(\frac{\pi}{2}\right) = -\frac{\pi}{2}$$

Thus, $y(t) = 2 \cdot 1.3 \cos\left(\frac{\pi}{2}t - \frac{\pi}{2}\right)$

$$\underline{\underline{y(t) = 2.6 \cos\left(\frac{\pi}{2}t - \frac{\pi}{2}\right)}}$$

3 a) $H(s) = \frac{1}{(s+2)(s+3)}$

The system has two real-valued poles. Hence, we can use partial fraction expansion to calculate the inverse transform (and thus the impulse response):

$$h(t) \leftrightarrow H(s).$$

$$\text{Hence: } H(s) = \frac{C_1}{s+2} + \frac{C_2}{s+3} = \frac{C_1(s+3)}{s+2} + \frac{C_2(s+2)}{s+3}$$

$$= \frac{C_1 s + 3C_1 + C_2 s + 2C_2}{(s+2)(s+3)}$$

Hence, we have that

$$s(C_1 + C_2) + 3C_1 + 2C_2 = 1$$

$$\begin{cases} C_1 + C_2 = 0 \\ 3C_1 + 2C_2 = 1 \end{cases} \Rightarrow C_1 = -C_2$$

$$\begin{aligned} 3C_1 + 2C_2 &= 1 \\ -3C_2 + 2C_2 &= 1 \\ -C_2 &= 1 \\ C_2 &= -1 \end{aligned} \quad \rightarrow \quad C_1 = 1, C_2 = -1$$

Hence:

$$H(s) = \frac{1}{s+2} - \frac{1}{s+3}$$

↑ (Transform table)

$$h(t) = e^{-2t} u(t) - e^{-3t} u(t)$$

b) The frequency response is related to the transfer function as

$$H(\omega) = H(s)|_{s=j\omega}$$

Hence,

$$H(\omega) = H(s)|_{s=j\omega} = \frac{1}{(s+2)(s+3)} \Big|_{s=j\omega}$$

$$= \frac{1}{s^2 + 5s + 6} \Big|_{s=j\omega}$$

$$H(\omega) = \frac{1}{(j\omega)^2 + 5j\omega + 6}$$

c) To sketch the Bode plot, we first rewrite the transfer function to Bode form:

$$H(s) = \frac{1}{(s+2)(s+3)} = \frac{1}{2 \cdot 3 \cdot (s/2+1)(s/3+1)}$$

$$= \frac{1}{6} \cdot \frac{1}{(s/2+1)(s/3+1)}$$

Thus, we have three terms:

1. A constant $k_0 = 1/6$
2. A first order term $\frac{1}{s/2+1}$
3. A first order term $\frac{1}{s/3+1}$

Term	Frequency	Magnitude	Phase
k_0	All	$20 \log_{10}(1/6) = -15.6 \text{ dB}$	0°
$\frac{1}{s/2+1}$	$\omega \ll 2$	0 dB	0°
	$\omega \approx 2$	-3 dB	-45°
	$\omega \gg 2$	-20 dB/decade	-90°
$\frac{1}{s/3+1}$	$\omega \ll 3$	0 dB	0°
	$\omega \approx 3$	-3 dB	-45°
	$\omega \gg 3$	-20 dB/decade	-90°

This results in the attached Bode plots.

4a) $\ddot{y}(t) + 6\dot{y}(t) + 13y(t) = \dot{x}(t) + 2x(t)$
! 29.3 (zero initial conditions)

$$sY(s) + 6sY(s) + 13Y(s) = sX(s) + 2X(s)$$

$$Y(s)(s^2 + 6s + 13) = (s + 2)X(s)$$

$$\frac{Y(s)}{X(s)} = H(s) = \frac{s+2}{s^2+6s+13}$$

b) Zeros: Roots of the numerator

$$s+2=0$$

$$s = -2 \Rightarrow \underline{z_1 = -2}$$

Poles: Roots of the denominator

$$s^2 + 6s + 13 = 0$$

Using the quadratic formula:

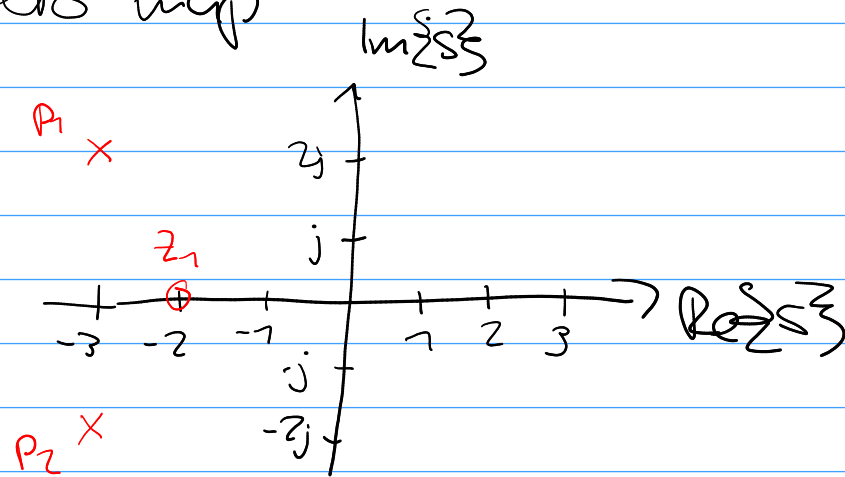
$$p_{1,2} = -\frac{6}{2} \pm \frac{\sqrt{36 - 4 \cdot 13}}{2} = -3 \pm \frac{\sqrt{36 - 52}}{2}$$

$$= -3 \pm \frac{\sqrt{-16}}{2} = -3 \pm j\frac{4}{2}$$

$$= -3 \pm j2$$

Hence: Zeros $z_1 = -2$, poles $p_1 = -3 + j2$, $p_2 = -3 - j2$

Pole-zero map.



The system is stable since all (both) poles have negative real part.

c) The input-output relationship is

$$Y(s) = H(s)X(s).$$

$H(s)$ is as given above, and $x(t) = u(t)$, which yields $X(s) = \frac{1}{s}$.

Hence,

$$Y(s) = \frac{s+2}{s^2+6s+13} \cdot \frac{1}{s}$$

$$= \frac{\cancel{s}}{\cancel{s}(s^2+6s+13)} + \frac{2}{s(s^2+6s+13)}$$

The denominator can be written as

$$s^2+6s+13 = (s+3)^2+4$$

such that

$$Y(s) = \frac{1}{(s+3)^2+4} + \frac{2}{s[(s+3)^2+4]}$$

- For the first term, we can use the transform pair

$$\frac{\omega_0}{(s+a)^2+\omega_0^2} \longleftrightarrow e^{-at} \sin(\omega_0 t) u(t)$$

with $a=3$ and $\omega_0=2$:

$$\frac{1}{2} \frac{2}{(s+3)^2+4} \longleftrightarrow \frac{1}{2} e^{-3t} \sin(2t) u(t)$$

- For the second term, we have to use partial fraction expansion:

$$\begin{aligned} \frac{2}{s[(s+3)^2+4]} &= \frac{C_1}{s} + \frac{C_2 s + C_3}{s^2+6s+13} \\ &= \frac{C_1(s^2+6s+13) + s(C_2 s + C_3)}{s(s^2+6s+13)} \\ &= \frac{C_1 s^2 + 6sC_1 + 13C_1 + C_2 s^2 + C_3 s}{s(s^2+6s+13)} \end{aligned}$$

Hence:

$$s^2(C_1+C_2) + s(6C_1+C_3) + 13C_1 = 2$$

$$\begin{aligned} C_1 + C_2 &= 0 & \Rightarrow C_2 &= -C_1 \\ 6C_1 + C_3 &= 0 & \Rightarrow C_3 &= -6C_1 \\ 13C_1 &= 2 & \Rightarrow C_1 &= 2/13 \end{aligned}$$

$$C_1 = \frac{2}{13}, C_2 = -\frac{2}{13}, C_3 = -\frac{12}{13}$$

hence,

$$\frac{2}{s([s+3]^2+4)} = \frac{2/13}{s} - \frac{2}{13} \frac{s+6}{(s+3)^2+4}$$

$$= \frac{2}{13} \left(\frac{1}{s} - \frac{s+3}{(s+3)^2+4} - \frac{3}{(s+3)^2+4} \right)$$

!

$$\frac{2}{13} \left(u(t) - e^{-3t} \cos(2t) u(t) - \frac{3}{2} e^{-3t} \sin(2t) u(t) \right)$$

Finally, we have:

$$y(t) = \frac{1}{2} e^{-3t} \sin(3t) u(t) + \frac{2}{13} u(t) - \frac{2}{13} e^{-3t} \cos(3t) u(t) - \frac{3}{13} e^{-3t} \sin(3t) u(t)$$

$$y(t) = \left[\frac{1}{2} \sin(3t) - \frac{2}{13} \cos(3t) - \frac{3}{13} \sin(3t) \right] e^{-3t} u(t) + \frac{2}{13} u(t)$$

Bode Diagram

